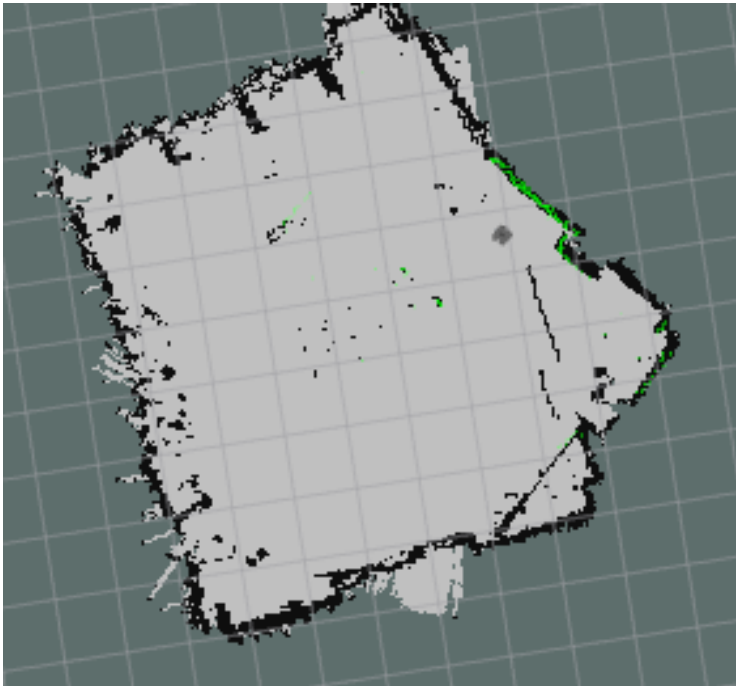
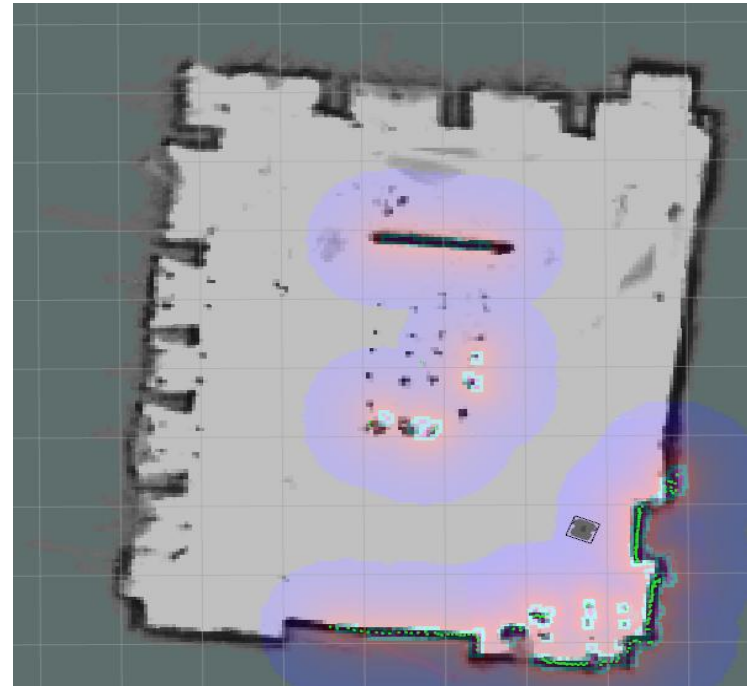


- 코딩룸 Map

Gmapping

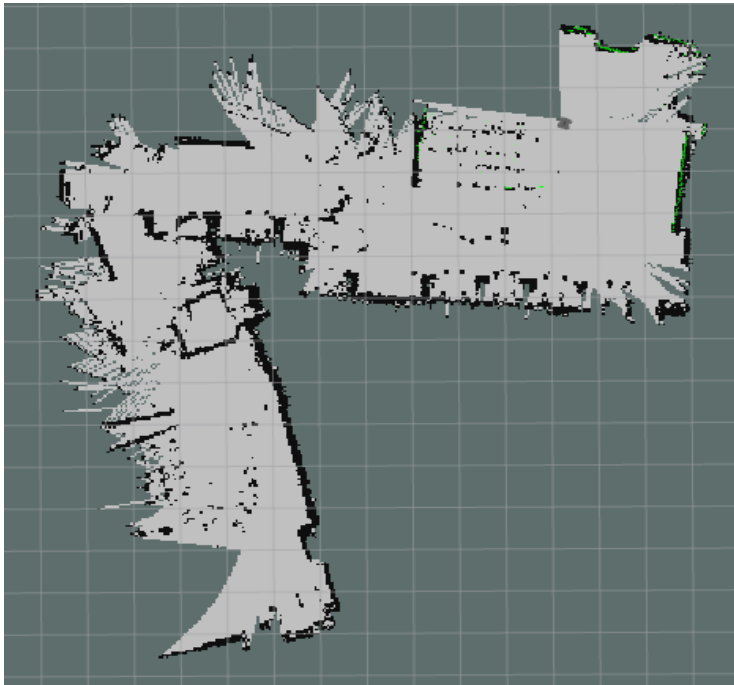


Google Cartograph

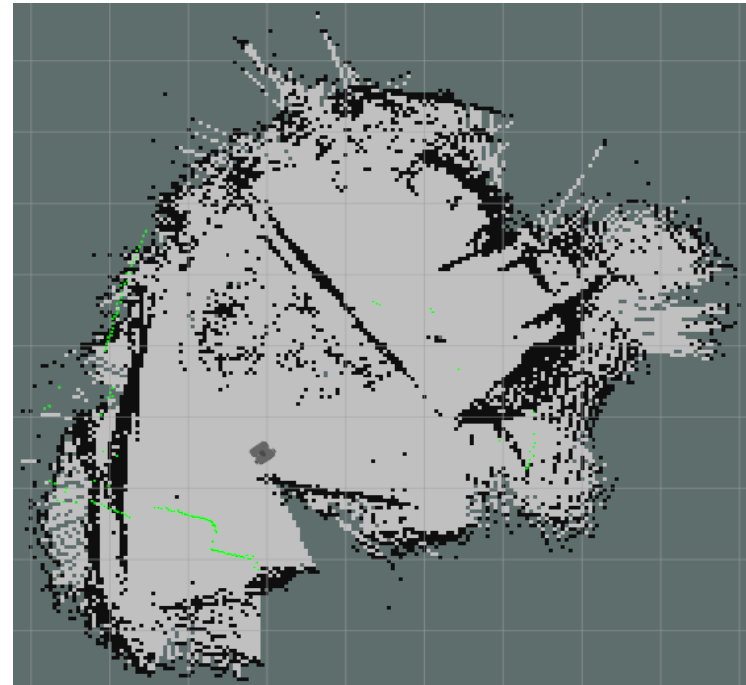


- 코딩룸 Map

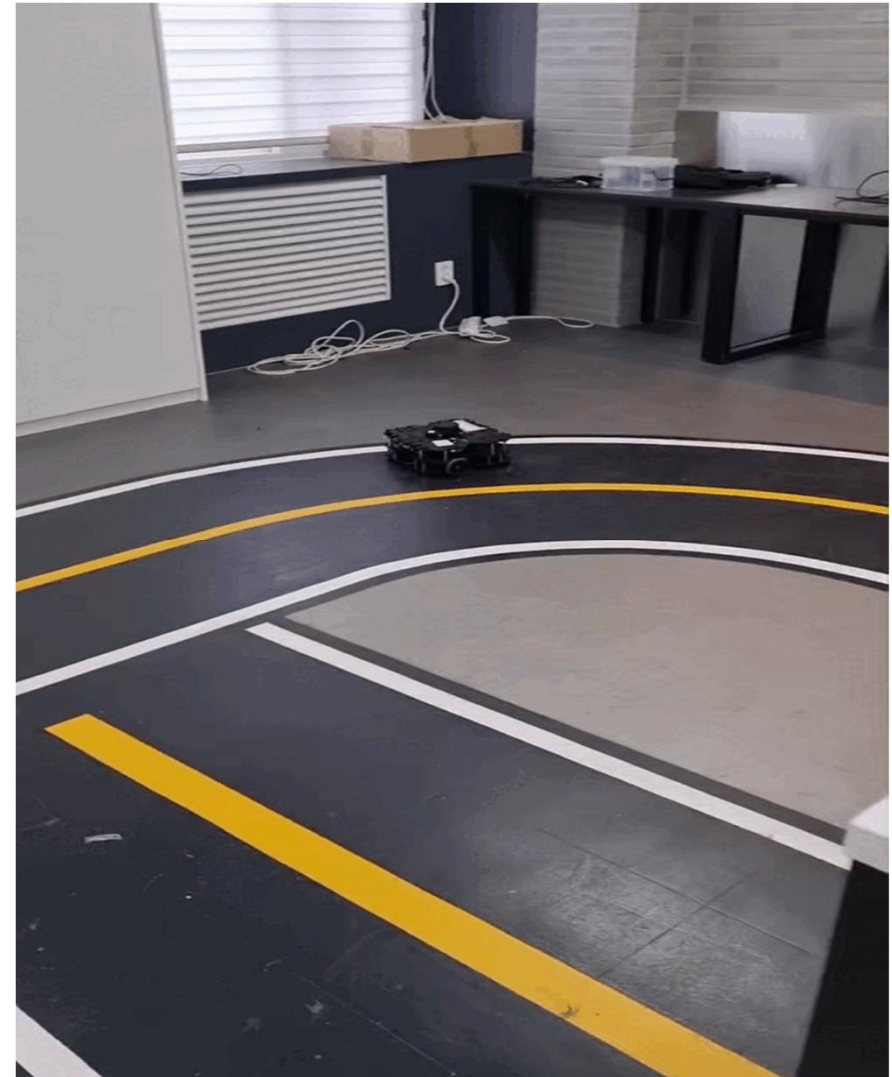
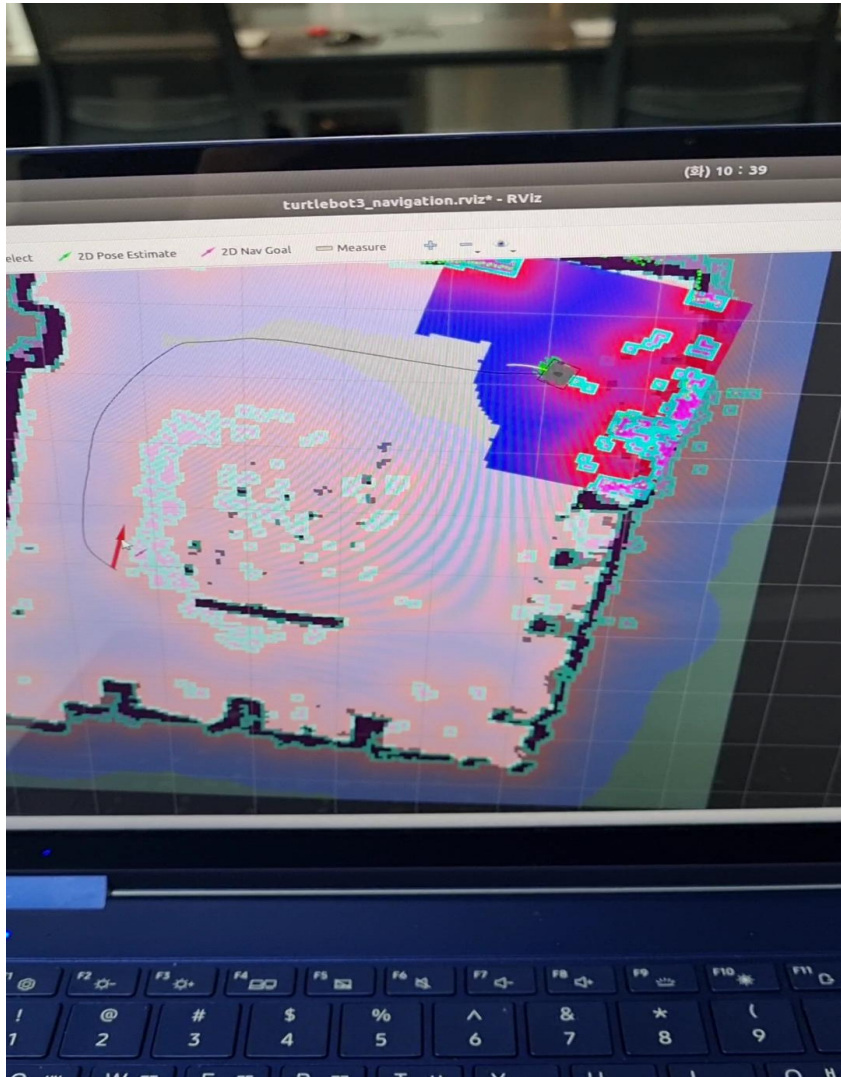
hector



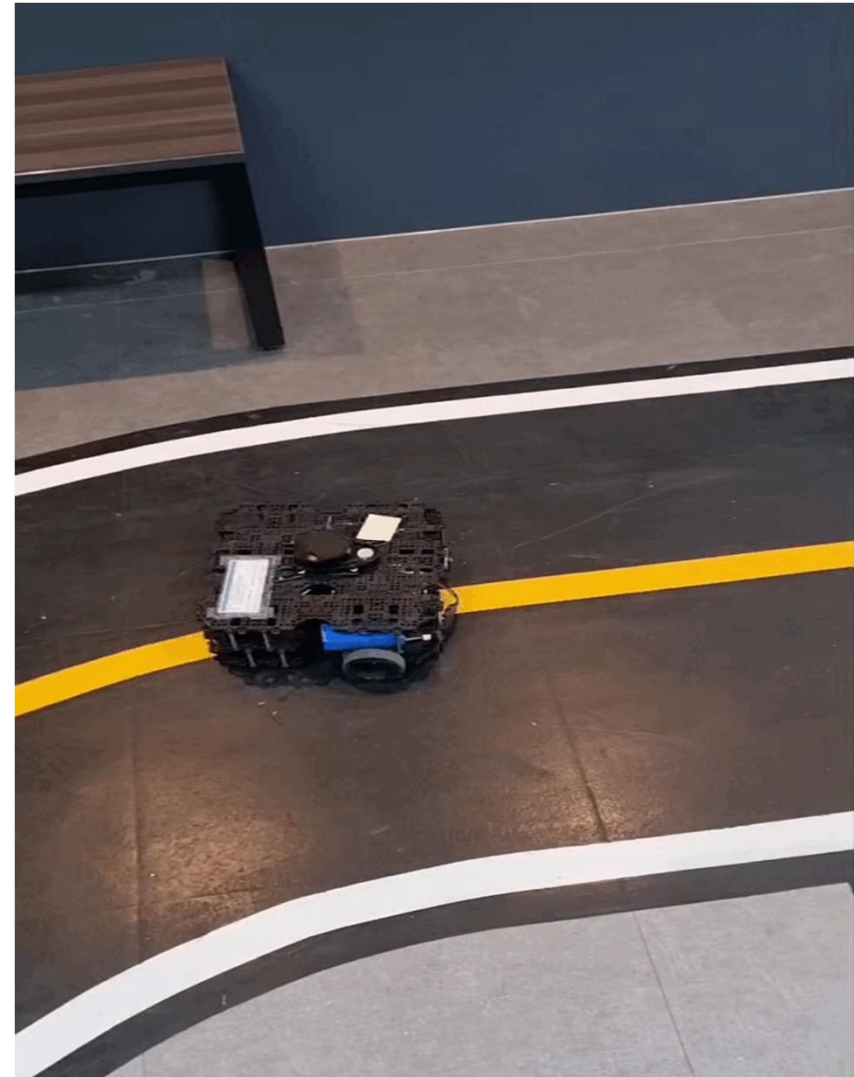
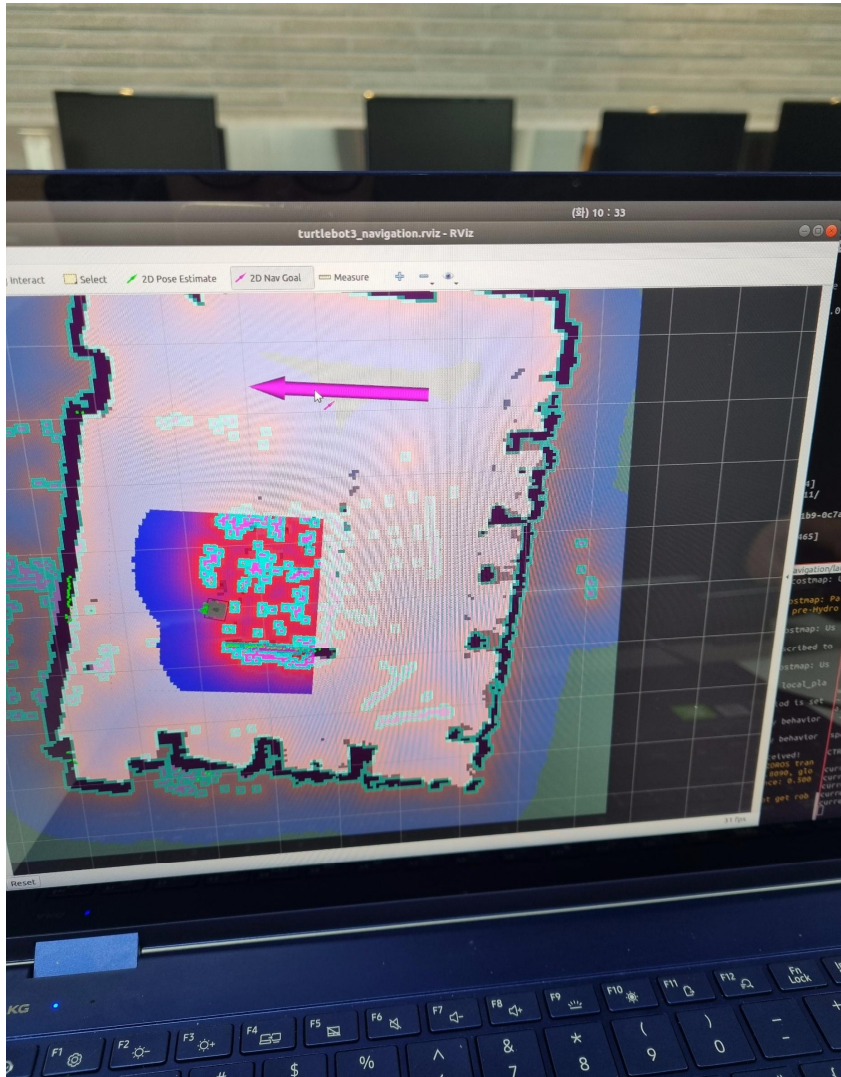
karto



[박주형] Week 6 ~ 7



[박주형] Week 6 ~ 7



[박주형] 방학 중 학습 계획 및 주요 일정

2022.02.10 기준

- 1. 학습 목표: Turtlebot을 사용하여 Mapping, Navigation, Static Obstacle Avoidance를 한다.
- 2. 추진 전략
 - Github에서 코드를 가져온다.

일정		주요 계획	주요 산출물
월(month)	주(week)		
1	2	- ROS publish, subscribe 숙지 - Desktop, Turtlebot 통신을 위한 세팅	Node간 통신한 그래프
	3~4	SLAM을 이용한 코딩룸 Mapping	코딩룸 Map
	5~1	Navigation	Navigation 영상
2	2~3	Static Obstacle Avoidance -Path Planning 알고리즘 비교 분석	알고리즘 장단점 분석
	4	Static Obstacle Avoidance 진행하기	Static Obstacle Avoidance 영상