## **HW4** Report

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## Measured time using random generated test data

segment size \ n	100	10000	1000000	10000000
n/100	0.11 / 0.00	0.15 / 0.04	3.41 / 3.07	29.13 / 30.91
n/25	0.07 / 0.00	0.12 / 0.03	2.87 / 2.65	27.33 / 27.06
n/10	0.09 / 0.00	0.08 / 0.02	3.03 / 2.39	26.14 / 24.51
n/5	0.07 / 0.00	0.05 / 0.02	3.11 / 2.15	24.59 / 22.04
n/2	0.03 / 0.00	0.02 / 0.02	2.60 / 1.81	22.20 / 19.09
n	0.03 / 0.00	0.05 / 0.01	2.19 / 1.74	25.54 / 17.51

Time format is (real time / user time), measured on csie workstation linux11 using linux's time utility.

## State my findings

Seems like time is shortest when there are only 1 or 2 segments. There isn't much time gain when we increase the number of segments. The reasons may be: 1. When we increase the number of segments, we increase the number of threads, too. So the overhead of creating and joining threads is increased, too. 2. Though the merging process of each thread can overlap, the output process cannot. So for each merging round, each thread still needs to output one by one. Thus the time cost of whole merging process is bound (or bottlenecked) by the output process (because the time spent on outputing cannot overlap).