

Noisy Integration of Value Differences

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Sloan-Nomis Workshop
on the Cognitive Foundations of Economic Behavior

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A souvenir from NY



Price \$9

Size 11 ounces

- ▶ Evaluate alternatives that differ across multiple dimensions
- ▶ We always make comparisons across available alternatives
- ▶ **Integration of separate values, differences, or “both”?**

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\$16

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11 ounces

14 ounces

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Motivation and Context

- ▶ **Noisy integration of decision information**
 - ▶ Choice across multi-dimension alternatives
 - ▶ **Averaging task:** equally relevant dimensions should be integrated with the same weight
 - ▶ Humans deviate systematically: overweight of extreme values under early noise (Spitzer, Waschke, and Summerfield 2017), robust averaging under late noise (Li et al. 2018)
- ▶ **Context effect and Violation of stochastic transitivity**
 - ▶ Commonly found in **trinary choices** when a decoy is introduced (Huber et al. 1982, Heat and Chatterjee 1995)
 - ▶ But also with **binary choices**, if they have multiple dimensions (Tsetsos et al. 2016)
 - ▶ Stochastic transitivity violation would not occur if information was encoded in isolation

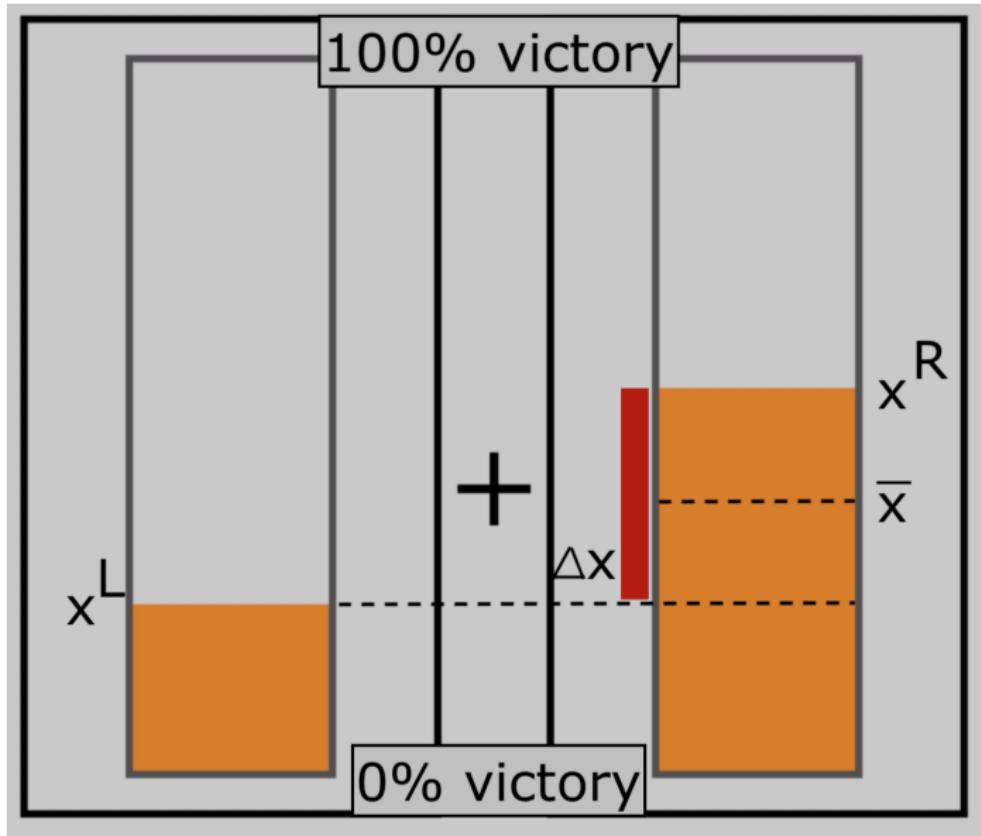
Experimental Design

Experimental Design

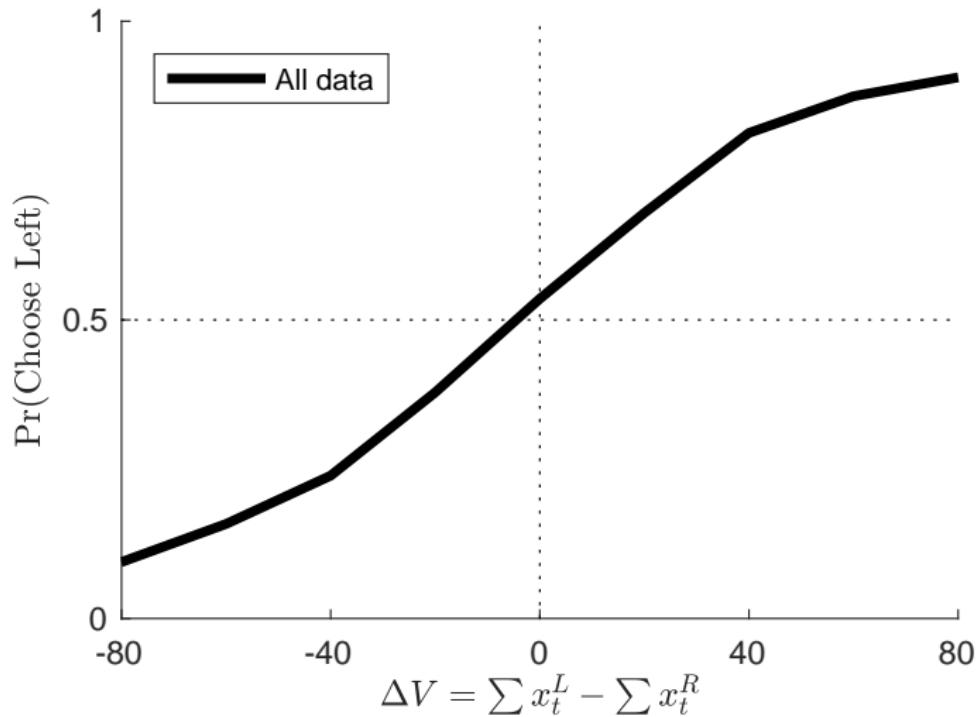
- ▶ **Binary choice:** compound lottery L(left) vs R(ight)
- ▶ Six simple lotteries (dimensions) equally likely to be selected
- ▶ Each sub-lottery is a 10-90% probability of winning one point

- ▶ Lab experiment at CELSS (Columbia University)
- ▶ 800 trials in a session (~ 75 min), including 2 ancillary tasks
- ▶ Incentive: collect number of points across the experiment
- ▶ Payment: $(\# \text{ points} - 300) \cdot 20 \text{ €}$ Avg. payment \$24.20

Experimental Design

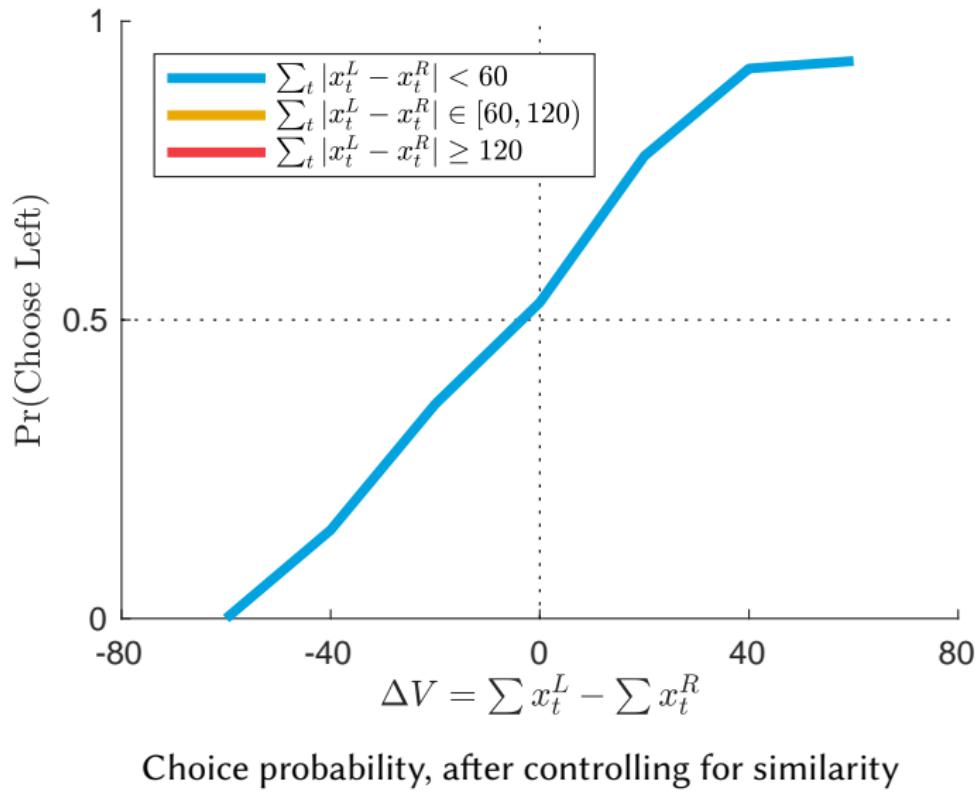


Result 0. Randomness

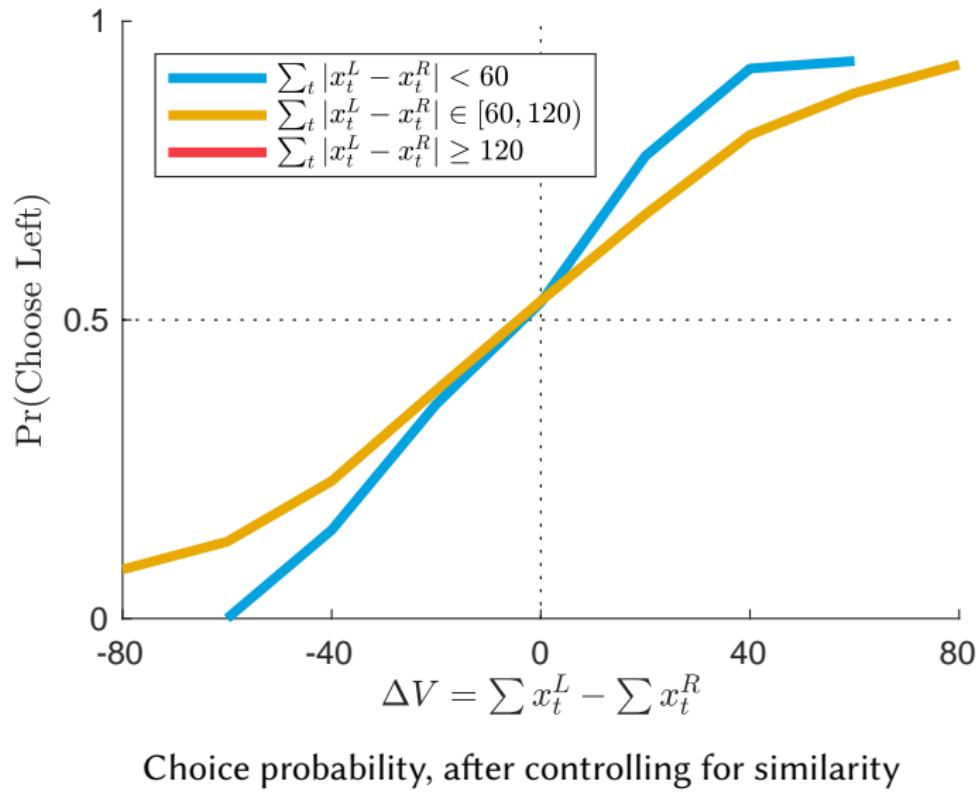


Choice probability in trials with different difficulty

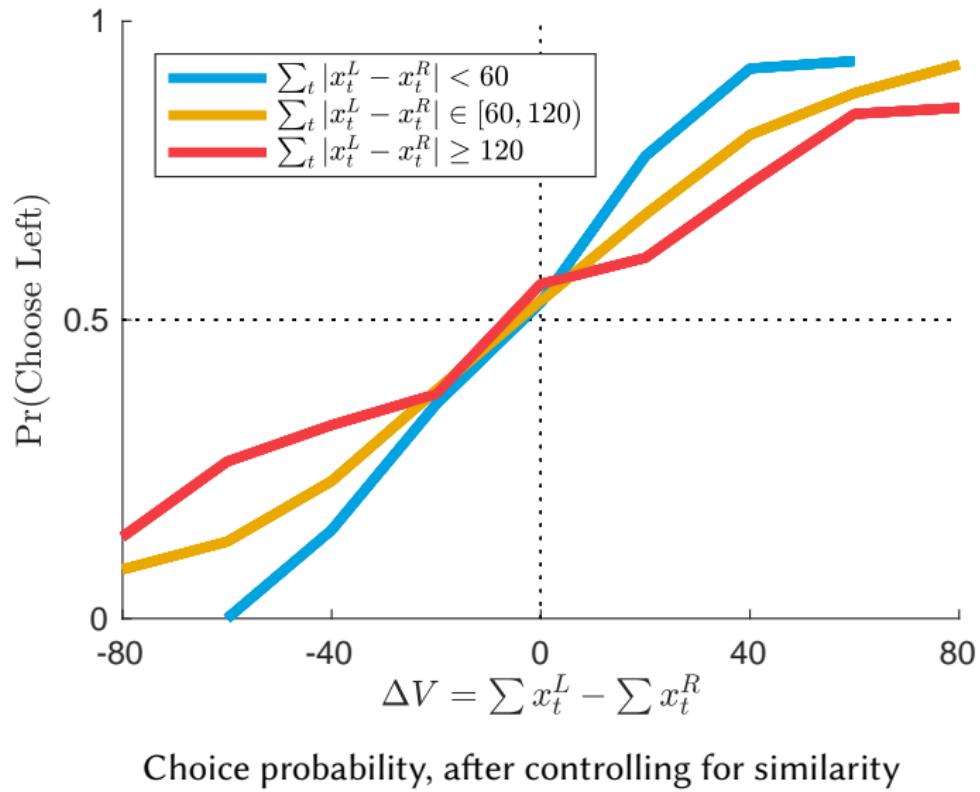
Result 1. Similarity improves Accuracy



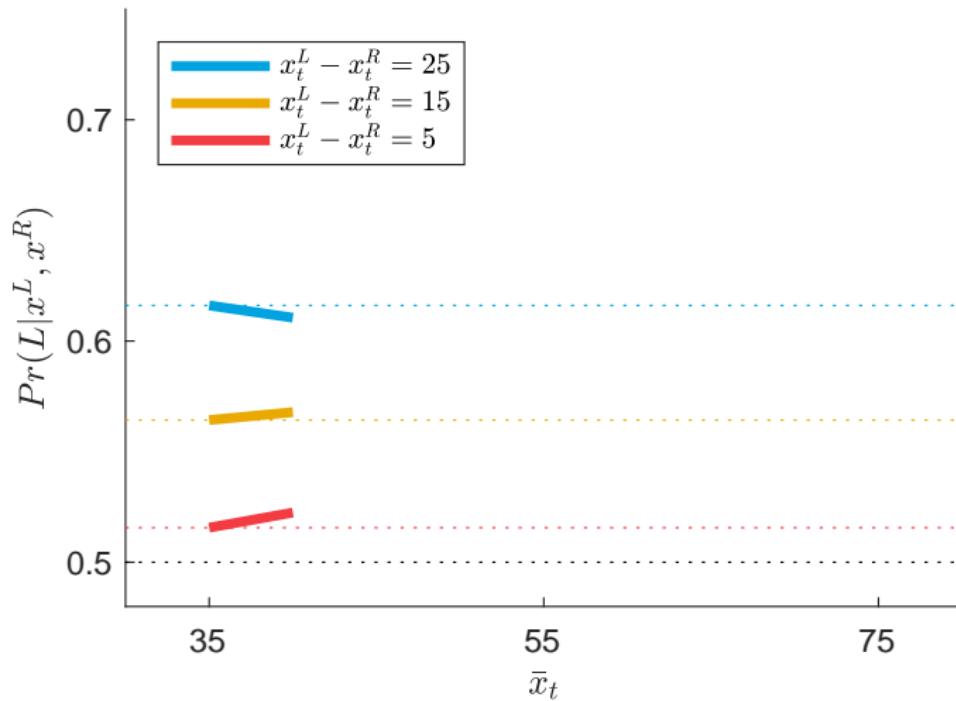
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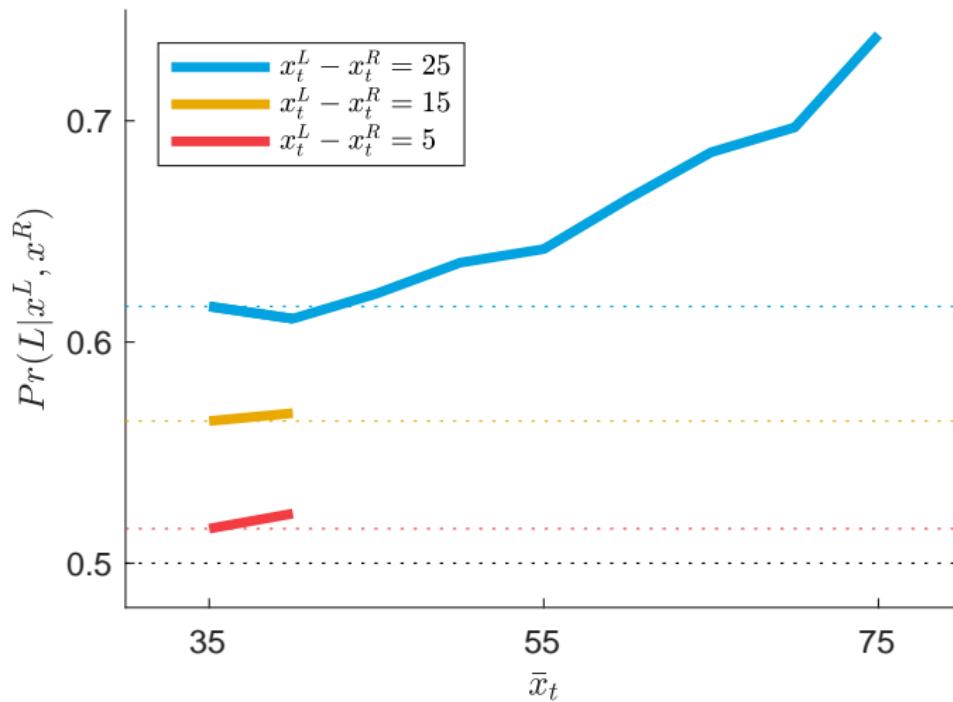


Result 2. Decision Weights



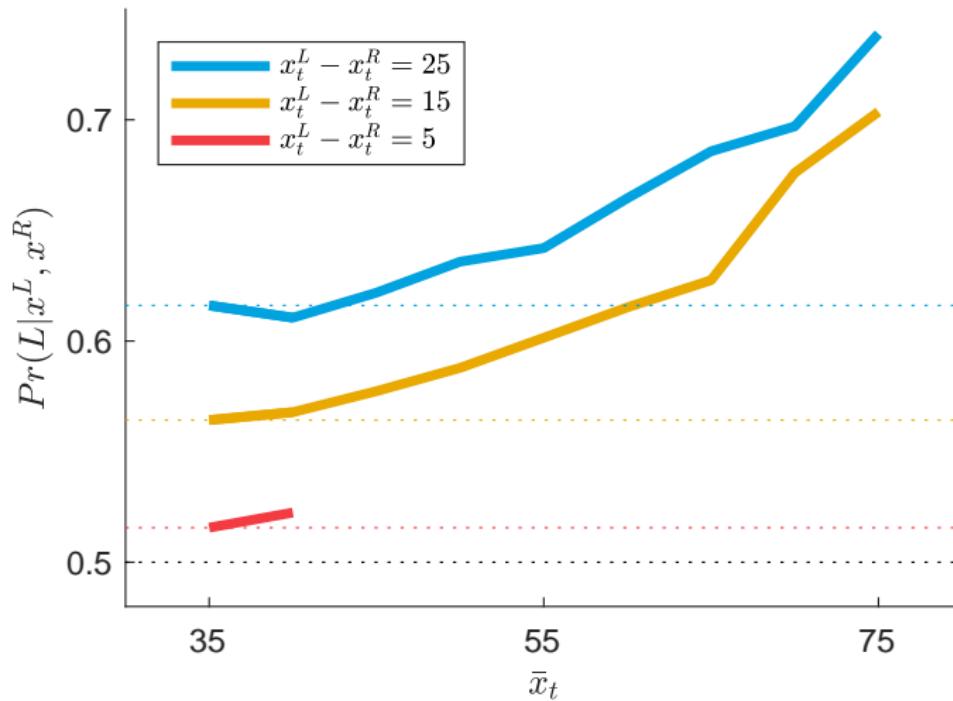
Decision weight $Pr(L|x^L, x^R)$ for different magnitudes \bar{x} and differences Δx

Result 2. Decision Weights



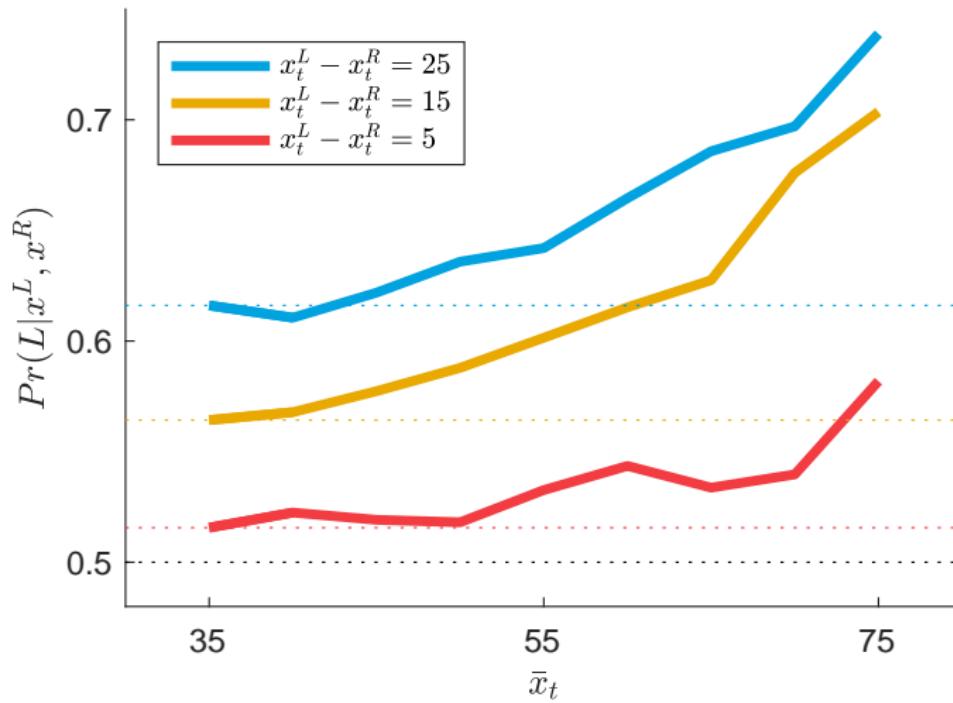
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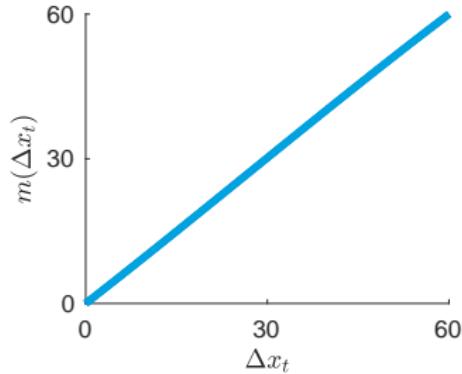


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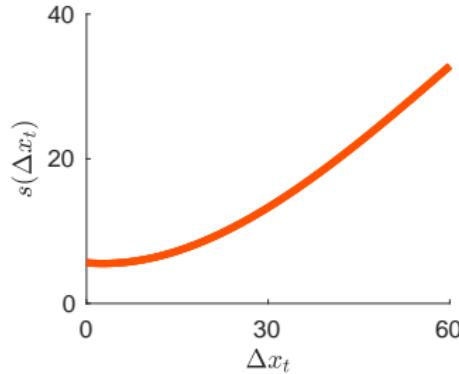
Model Selection (the last mile)

- ▶ At time $t \in 1, \dots, 6$ two values x_t^L and x_t^R are observed
- ▶ **Mental representation of the difference** $\Delta x_t := x_t^L - x_t^R$
 - ▶ Noisy representation $\hat{\Delta x} \sim N(m(\Delta x), s(\Delta x))$
 - ▶ Transformation $m(\Delta x)$, degree 3 polynomial
 - ▶ Varying noise $s(\Delta x)$, degree 3 polynomial
- ▶ **Choice based on** $\Delta V := \sum_{t=1}^T \delta^{T-t} \cdot \hat{\Delta x}_t \cdot \bar{x}_t^\alpha$
- ▶ Focus towards higher values (“good news”): $\alpha > 0$
- ▶ Leaking memory: $\delta < 1$

Model Fit - Noisy integration of value differences



Transformation $m(\Delta x)$

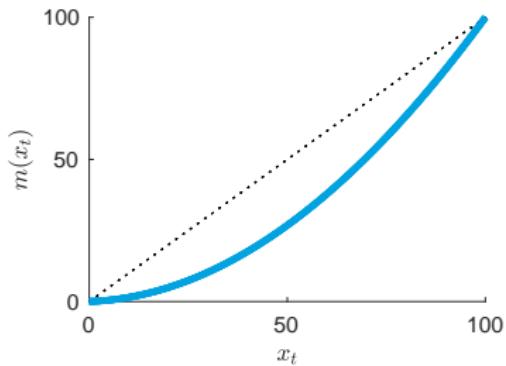


Varying noise $s(\Delta x)$

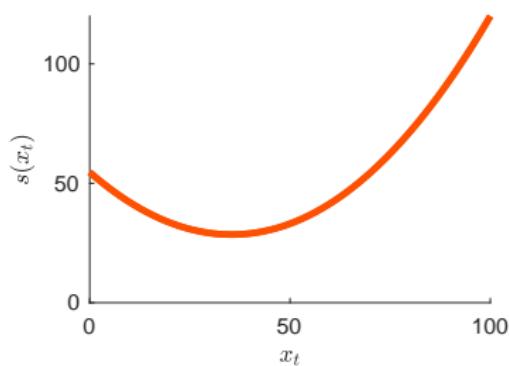
- ▶ Leaking memory $\hat{\delta} = 0.81 < 1$ (recency effect)
- ▶ High-value focusing $\hat{\alpha} = 1.19 > 0$ (magnitude effect)

Model Fit - Noisy integration of individual values

- ▶ **Noisy representation of individual values** $\hat{x} \sim N(m(x), s(x))$
 - ▶ Transformation $m(x)$, degree 3 polynomial
 - ▶ Varying noise $s(x)$, degree 3 polynomial
- ▶ **Choice based on** $\Delta V := \sum_{t=1}^T \delta^{T-t} \cdot (\hat{x}_t^L - \hat{x}_t^R)$
- ▶ Worse fit of data: BIC 12,954 [$>10,969$ noisy integration of Δx]



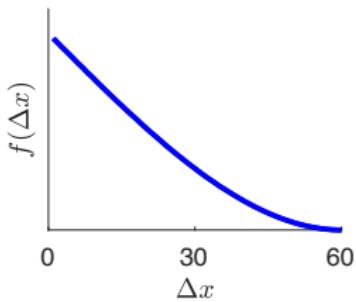
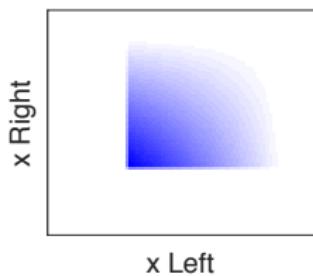
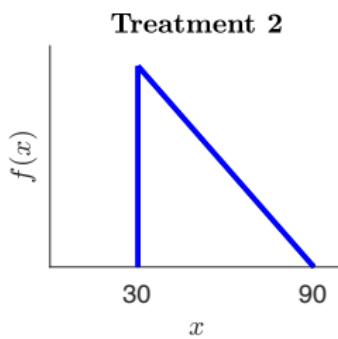
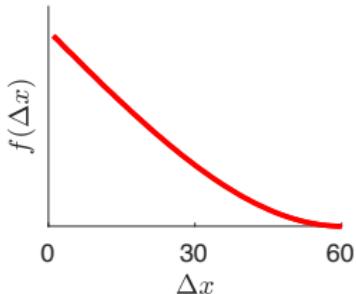
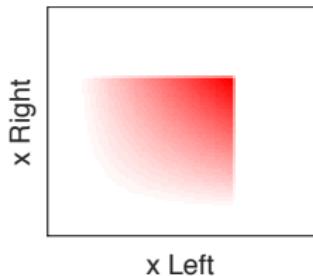
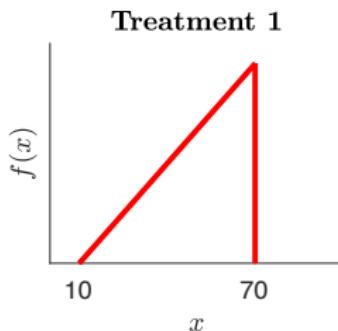
Transformation $m(x)$



Varying noise $s(x)$

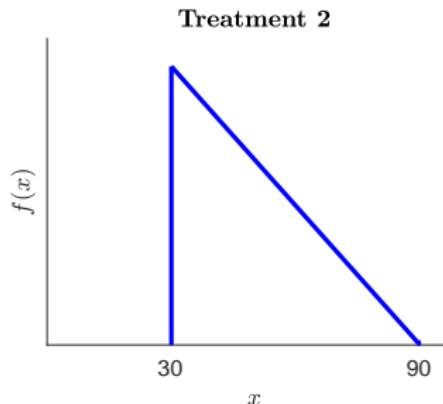
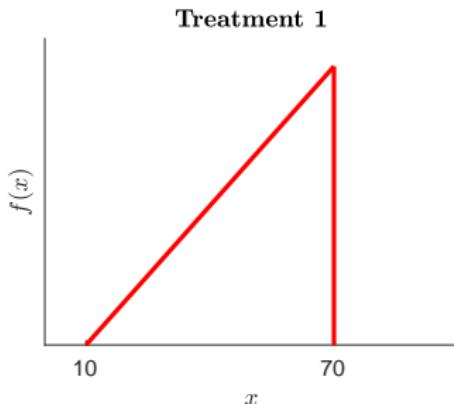
Treatments - Upward/Downward distributions

- ▶ Upward and Downward triangular distributions



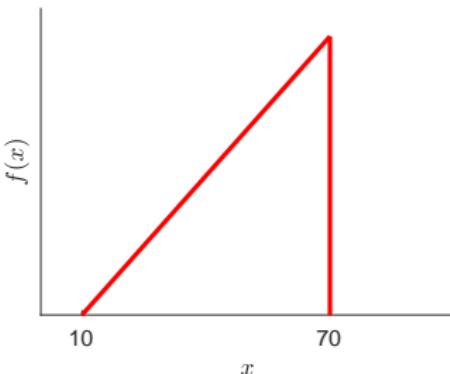
Value distributions used to generate data in the two treatments

Model Fit - Separate treatments

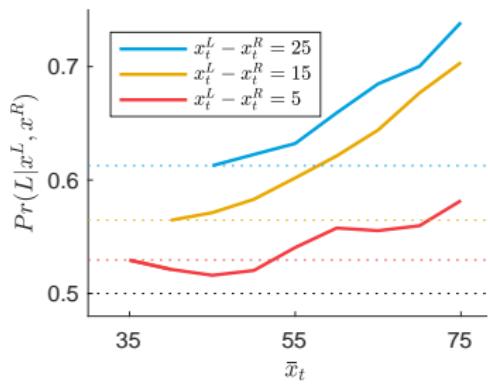
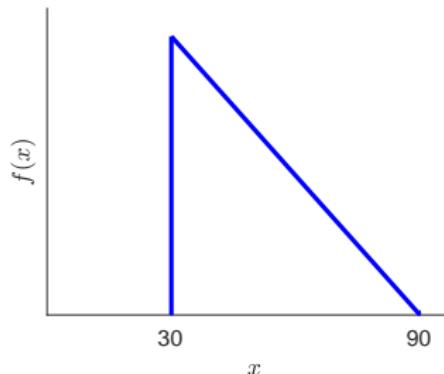


Model Fit - Separate treatments

Treatment 1

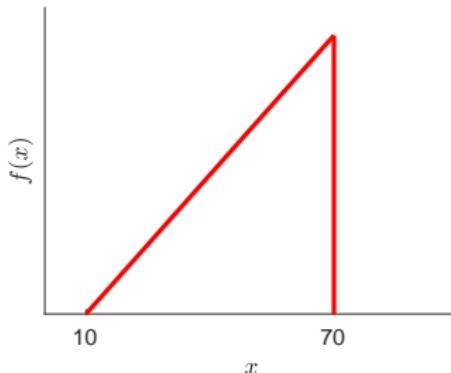


Treatment 2

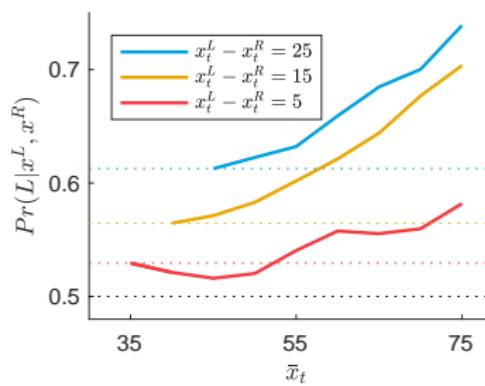
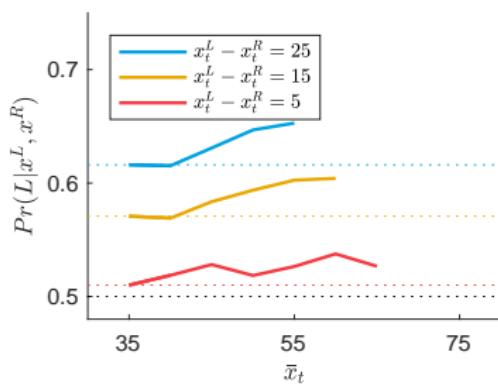
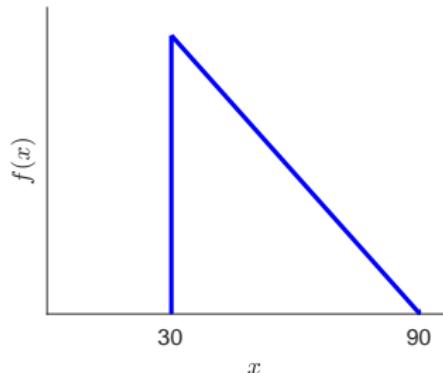


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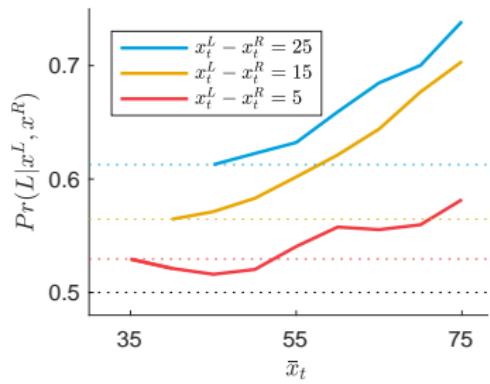
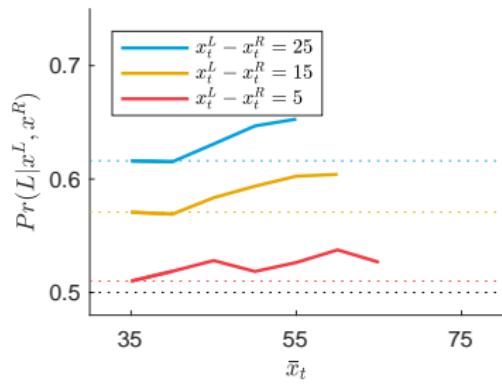
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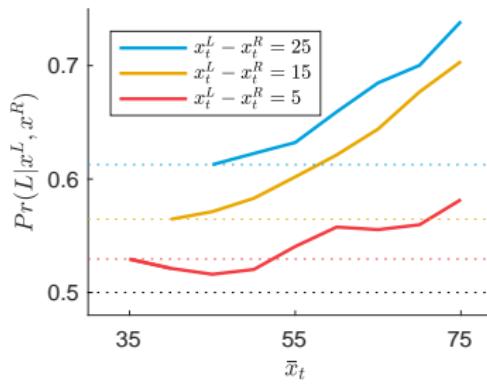
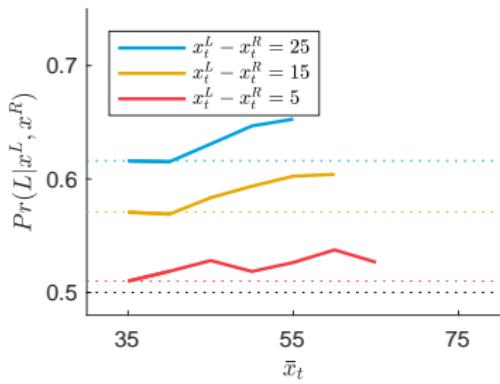
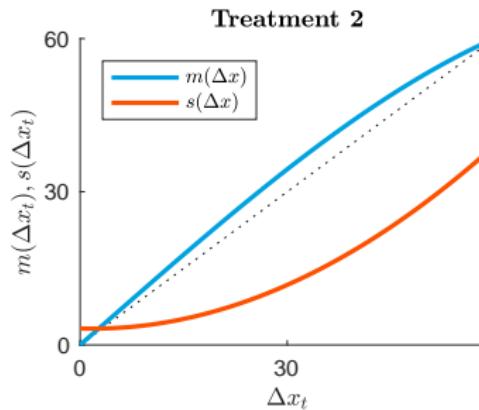
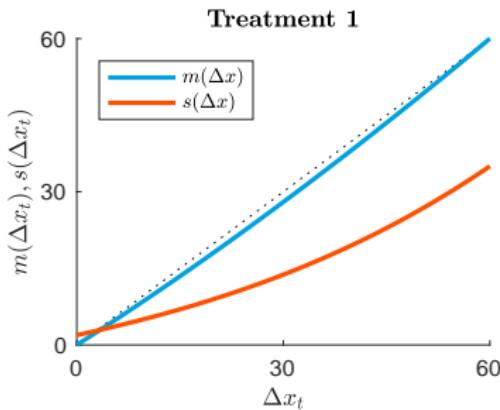
Treatment 2



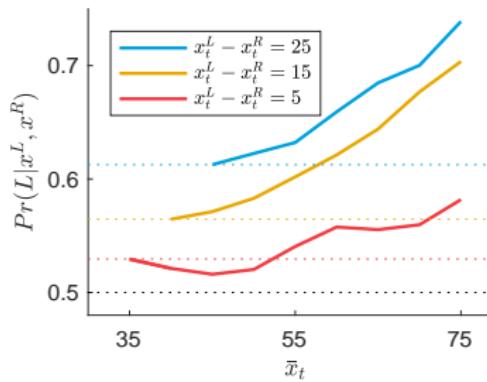
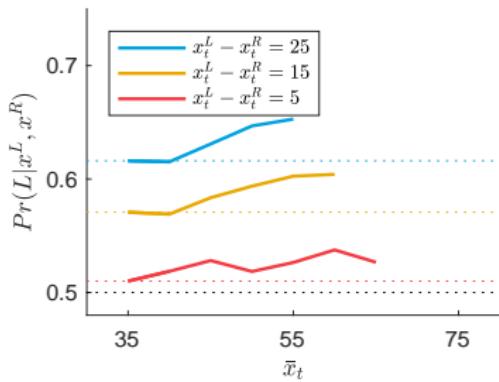
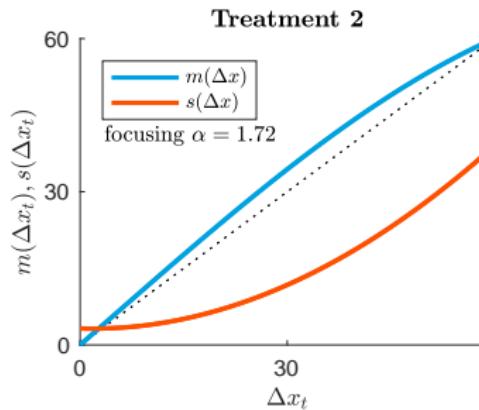
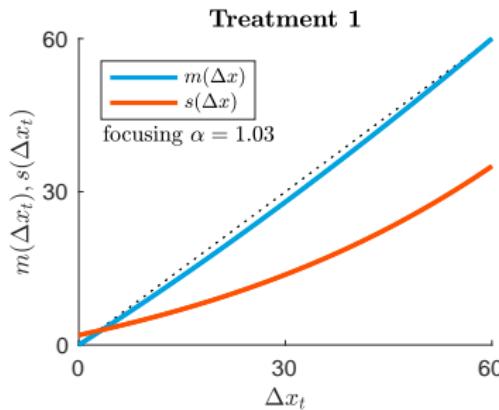
Model Fit - Separate treatments



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Model Fit - Separate treatments



Next Steps

- ▶ Treatments: effect of different underlying distributions
- ▶ Learning during the session
- ▶ Explore individual-level heterogeneity
- ▶ Connect results in main and ancillary tasks
- ▶ Model comparison

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