Introduction to Probabilities and Statistics

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 - Ω , the sample space, is the set of all possible outcomes
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 - E.g., the event of "the DNA corresponds to a girl with blue eyes"
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 - The probability measure $P: \mathcal{F} \to [0,1]$ is a function returning an event's probability (P("having a brown-eyed baby girl") = 0.0005)

Continuous random variable

A random variable associates a numerical value to outcomes

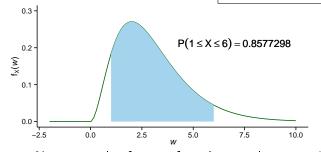
$$X:\Omega \to \mathbb{R}$$

- E.g., the weight of the baby at birth (assuming it solely depends on DNA, which is quite false but it's for the sake of the example)
- Since many computer science experiments are based on time measurements, we focus on continuous variables
- Note: To distinguish random variables, which are complex objects, from other mathematical objects, they will always be written in blue capital letters in this set of slides (e.g., X)
- ullet The probability measure on Ω induces probabilities on the values of X
 - P(X = 0.5213) is generally 0 as the outcome never exactly matches
 - $P(0.5213 \le X \le 0.5214)$ may however be non-zero

Probability distribution

A probability distribution (a.k.a. probability density function or p.d.f.) is used to describe the probabilities of different values occurring

• A random variable X has density f_X , where f_X is a non-negative and integrable function, if: $P[a \le X \le b] = \int_{-b}^{b} f_X(w) \, dw$



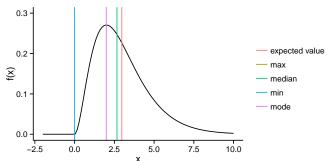
Note: the X in $1 \le X \le 6$ should be in blue...

Note: people often confuse the sample space with the random variable.
 Try to make the difference when modeling your system, it will help you

Characterizing a random variable

The probability density function fully characterizes the random variable but it is also complex object

- It may be symmetrical or not
- It may have one or several modes
- It may have a bounded support or not, hence the random variable may have a minimal and/or a maximal value
- The median cuts the probabilities in half



These are interesting aspects of f_X but they barely summarize it

Expected value and variance

When one speaks of the "expected price", "expected height", etc. one
means the expected value of a random variable that is a price, a height,
etc.

$$E[X] = x_1 p_1 + x_2 p_2 + ... + x_k p_k = \int_{-\infty}^{\infty} x f_X(x) dx$$

The expected value of X is the "average value" of X.

It is **not** the most probable value. The mean is $\underline{\text{one}}$ aspect of the distribution of X. The median or the mode are other interesting aspects.

 The variance is a measure of how far the values of a random variable are spread out from each other.
 If a random variable X has the expected value (mean) u = E[X], then

If a random variable X has the expected value (mean) $\mu = E[X]$, then the variance of X is given by:

$$Var(X) = E\left[(X - \mu)^2\right] = \int_{-\infty}^{\infty} (x - \mu)^2 f_X(x) dx$$

• The standard deviation σ is the square root of the variance. This normalization allows to compare it with the expected value

Outline

- Brief reminder on probabilities
- Moment Generating Function Intuitions Properties
- 3 Toward the Central Limit Theorem
 Law of Large Numbers
 Central Limit Theorem
 Central Limit Theorem consequences

Definition

Working with the density function is not always convenient, especially when summing random variables (it implies convolving the pdf). We need an alternate representation.

How could we summarize a random variable?

- ullet By its mean, its variance, its skewness, \dots by its moments $\mu_k = \mathsf{E}(\mathsf{X}^k)$
- It is not clear that it would be sufficient although we would know a lot about f_X .

Let's define the moment generating function $M_X(t)$ as follows:

$$\begin{aligned} \mathsf{M}_{X}(t) &= \mathsf{E}\left(\mathsf{e}^{tX}\right) = \mathsf{E}\left(\sum_{k=0}^{\infty} \frac{t^{k}X^{k}}{k!}\right) = \mathsf{E}\left(\sum_{k=0}^{\infty} \frac{t^{k}X^{k}}{k!}\right) = \sum_{k=0}^{\infty} \mu_{k} \frac{t^{k}}{k!} \\ &= \int e^{tx} f_{X}(x) dx \end{aligned}$$

Deriving moments with the mgf

Remember we have
$$M_X(t) = \sum_{k=0}^{\infty} \mu_k \frac{t^k}{k!}$$

Therefore
$$\frac{d^n M_X}{dt^n}(0) = \mu_n$$

All the moments of X are encoded in $M_X(t)$. Is there more ?

Characterization of a distribution through the mgf

Let's assume that X is discrete $((x_1, p_1), \ldots, (x_n, p_n))$ with $x_1 < \cdots < x_n$

- Then $\mathsf{M}_X(t) = \mathsf{E}\left(e^{tX}\right) = \sum_{j=1}^n p_j e^{tx_j} = \sum_{j=1}^n p_j (e^t)^{x_j}$
- Therefore $M_X(t) \underset{t \to \infty}{\sim} p_n e^{tx_n}$ and $M_X'(t) \underset{t \to \infty}{\sim} p_n x_n e^{tx_n}$. $\longrightarrow \frac{M_X'(t)}{M_X(t)} \xrightarrow{t \to \infty} x_n$
- Hence, we can determine x_n , then p_n , substract $p_n e^{tx_n}$ from $M_X(t)$ and proceed to find x_{n-1} .

X is fully characterized by its mgf M_X

Proving the same results when X is continuous, requires to go through Fourier transform.

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Convenient properties

$$M_{aX+b}(t) = E\left(e^{t(aX+b)}\right) = E\left(e^{bt}e^{atX}\right)$$

= $e^{bt} M_X(at)$

$$\begin{aligned} \mathsf{M}_{X+Y}(t) &= \mathsf{E}\left(\mathsf{e}^{t(X+Y)}\right) = \mathsf{E}\left(\mathsf{e}^{tX+tY}\right) = \mathsf{E}\left(\mathsf{e}^{tX}\mathsf{e}^{tY}\right) = \mathsf{E}\left(\mathsf{e}^{tX}\right) \mathsf{E}\left(\mathsf{e}^{tY}\right) \\ &= \mathsf{M}_{X}(t).\,\mathsf{M}_{Y}(t) \end{aligned}$$

Mgf of usual laws

- Uniform law: $\mathsf{M}_X(t) = \begin{cases} \frac{e^{tb} e^{ta}}{t(b-a)} & \text{for } t \neq 0 \\ 1 & \text{for } t = 0 \end{cases}$
- Exponential law: $f(x; \lambda) = \begin{cases} \lambda e^{-\lambda x} & x \geq 0, \\ 0 & x < 0. \end{cases}$

$$\mathsf{M}_{X}(t) = \mathsf{E}\left(e^{tX}\right) = \int_{0}^{\infty} e^{tx} \lambda e^{-\lambda x} dx = \lambda \int_{0}^{\infty} e^{(t-\lambda)x} dx$$
$$= \lambda \left[\frac{e^{(t-\lambda)x}}{t-\lambda}\right]_{0}^{\infty} = \frac{\lambda}{\lambda - t} \qquad \text{(for } t < \lambda\text{)}$$

This allows to easily compute moments and sum random variables.

The moment generating function is somehow similar to the Fourier transform on periodic signals.

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How to estimate the Expected value?

To empirically estimate the expected value of a random variable X, one repeatedly measures observations of the variable and computes the arithmetic mean of the results

This is called the sample mean and it intuitively converges to the expected value

Unfortunately, if you repeat the estimation, you may get a different value since X is a random variable ...

What can we really say?

On the way to the Law of Large Numbers

Chebyshev Inequality

Let X be a random variable with expected value $\mu=\mathsf{E}(X)$, and let $\varepsilon>0$ be any positive real number. Then $\mathsf{P}(|X-\mu|\geq\varepsilon)\leq \frac{\mathsf{Var}(X)}{\varepsilon^2}$.

Proof

$$\operatorname{Var}(X) = \int (x - \mu)^2 f(x) . dx \ge \int_{|x - \mu| \ge \varepsilon} (x - \mu)^2 f(x) . dx$$

$$\ge \int_{|x - \mu| \ge \varepsilon} \varepsilon^2 f(x) . dx = \varepsilon^2 \underbrace{\int_{|x - \mu| \ge \varepsilon} f(x) . dx}_{P(|X - \mu| \ge \varepsilon)}$$

Law of Large Numbers

Law of Large Numbers

Let X_1, X_2, \ldots, X_n be a sequence of identical and independent random variables with finite expected value $\mu = \mathsf{E}(X_i)$ and finite variance $\sigma^2 = \mathsf{Var}(X_i)$. Let $S_n = X_1 + X_2 + \cdots + X_n$. Then for any $\varepsilon > 0$, $\mathsf{P}(|S_n/n - \mu| \ge \varepsilon) \xrightarrow[n \to \infty]{} 0$.

Proof

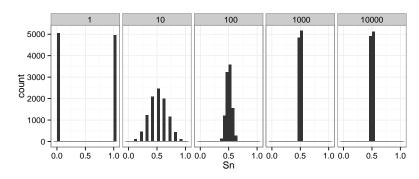
The X_i are i.i.d, hence:

- $Var(S_n) = n.\sigma^2 \rightsquigarrow Var(S_n/n) = \sigma^2/n$.
- $E(S_n/n) = \mu$.

Using Chebyshev's inequality:

$$P(|S_n/n - \mu| \ge \varepsilon) \le \frac{\sigma^2}{n\varepsilon^2} \xrightarrow[n \to \infty]{} 0 \text{ (for a fixed } \varepsilon)$$

Illustration: convergence in probability



So we do converge to a spike, but how?

Assume $\sigma=1$ and we aim at having a precision of $\varepsilon=.1$. For n=500, the previous formula only gives us

$$P(|S_n/n - \mu| \ge \varepsilon) \le \frac{\sigma^2}{n\varepsilon^2} = \frac{100}{n} = 0.5$$

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Law of Large Numbers

Central Limit Theorem

Central Limit Theorem consequences

Central Limit Theorem [CLT]

- Let $\{X_1, X_2, \ldots, X_n\}$ be a random sample of size n (i.e., a sequence of independent and identically distributed random variables with expected values μ and variances σ^2)
- We know that $E(S_n/n) = \mu$ and $Var(S_n) = n\sigma^2$.
- Let's define the standardized mean of these random variables as:

$$S_n^* = \frac{S_n - n\mu}{\sqrt{n\sigma^2}}$$

We have $E(S_n^*) = 0$ and $Var(S_n^*) = 1$.

• For large n^s 's, the distribution of S_n^* is approximately normal

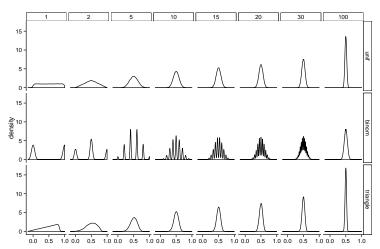
$$S_n^* \xrightarrow[n \to \infty]{} \mathcal{N}(0,1)$$

Or equivalently

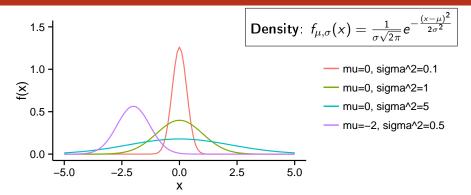
$$\frac{S_n}{n} \xrightarrow[n \to \infty]{} \mathcal{N}\left(\mu, \frac{\sigma^2}{n}\right)$$

CLT Illustration: the mean smooths distributions

Start with an arbitrary distribution and compute the distribution of S_n for increasing values of n.

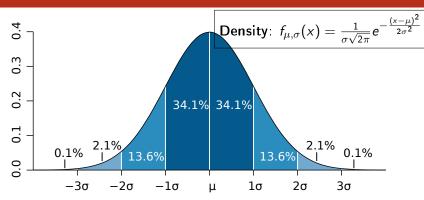


The Normal distribution



The smaller the variance the more "spiky" the distribution.

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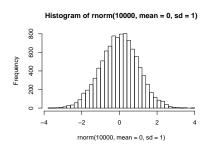


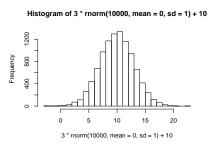
The smaller the variance the more "spiky" the distribution.

- Dark blue is less than one standard deviation from the mean $\approx 68\%$ of the set.
- ullet Two standard deviations from the mean (medium and dark blue)pprox95%
- Three standard deviations (light, medium, and dark blue)≈99.7%

The Normal distribution (property 1)

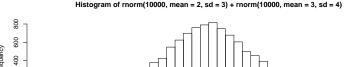
The family of normal distributions is closed under linear transformations: if X is normally distributed with mean μ and standard deviation σ , then the variable Y=aX+b is also normally distributed, with mean $a\mu+b$ and standard deviation $|a|\sigma$.





The Normal distribution (property 2)

Convolution: if X_1 and X_2 are two independent normal random variables, with means μ_1 , μ_2 and standard deviations σ_1 , σ_2 , then their sum $X_1 + X_2$ will also be normally distributed, with mean $\mu_1 + \mu_2$ and variance $\sigma_1^2 + \sigma_2^2$.



norm(10000, mean = 2, sd = 3) + morm(10000, mean = 3, sd = 4)

Intuitively, if S_n^* converges to something (say \mathcal{L}), it "has to" be a normal distribution:

$$\frac{1}{2}\left(\underbrace{S_{1...n}^*}_{\sim \mathcal{L}} + \underbrace{S_{n+1...2n}^*}_{\sim \mathcal{L}}\right) = \underbrace{S_{2n}^*}_{\sim \mathcal{L}}$$

Moment generating function of the normal distribution

Let's assume $X \sim \mathcal{N}(0,1)$.

$$M_{X}(t) = \int e^{tx} f_{N}(x) . dx = \int e^{tx} \frac{e^{-\frac{x^{2}}{2}}}{\sqrt{2\pi}} dx = \int \frac{e^{\frac{1}{2}(-x^{2}+tx)}}{\sqrt{2\pi}} dx$$

$$= \int \frac{e^{\frac{1}{2}(-(x-t)^{2}+t^{2})}}{\sqrt{2\pi}} dx = e^{\frac{x^{2}}{2}} \int \frac{e^{\frac{-(x-t)^{2}}{2}}}{\sqrt{2\pi}} dx = e^{\frac{x^{2}}{2}} \int \frac{e^{\frac{-x^{2}}{2}}}{\sqrt{2\pi}} dx$$

$$= e^{\frac{x^{2}}{2}}$$

Actually, if we assume $X \sim \mathcal{N}(\mu, \sigma^2)$, one can easily prove in the same way that:

$$\mathsf{M}_{\mathsf{X}}(t) = e^{\mu t + \frac{1}{2}\sigma^2 t^2}$$

Proof of the CLT

$$\begin{aligned} \mathsf{M}_{\mathsf{X}}(t) &= \mathsf{E}(e^{t\mathsf{X}}) \approx 1 + \mu t + \sigma^2 \frac{t^2}{2} + o(t^2) \\ &\rightsquigarrow \mathsf{log}(\mathsf{M}_{\mathsf{X}-\mu}(t)) \approx \sigma^2 \frac{t^2}{2} + o(t^2) \end{aligned} \qquad \begin{cases} \mathsf{S}_n &= \mathsf{X}_1 + \dots + \mathsf{X}_n \\ \mathsf{S}_n^* &= \frac{\mathsf{S}_n - n\mu}{\sigma\sqrt{n}} \end{cases}$$

$$\begin{cases} S_n = X_1 + \dots + X_n \\ S_n^* = \frac{S_n - n\mu}{\sigma\sqrt{n}} \end{cases}$$

We have:

$$\mathsf{M}_{S_n^*}(t) = \mathsf{E}(e^{tS_n^*}) = \mathsf{E}(e^{t\frac{S_n - n\mu}{\sqrt{n}\sigma}}) = \mathsf{E}(e^{t\frac{t}{\sigma\sqrt{n}}(S_n - n\mu)}) = \mathsf{M}_{S_n - n\mu}\left(\frac{t}{\sigma\sqrt{n}}\right)$$
$$= \left(\mathsf{M}_{X-\mu}\left(\underbrace{\frac{t}{\sigma\sqrt{n}}}\right)\right)^n \qquad \text{(since } \mathsf{M}_{X+Y}(t) = \mathsf{M}_X(t)\,\mathsf{M}_Y(t))$$

$$= \exp\left(n\log\left(\mathsf{M}_{\mathsf{X}-\mu}\left(\frac{t}{\sigma\sqrt{n}}\right)\right)\right) = \exp\left(n\left(\sigma^2\frac{t^2}{2n\sigma^2} + o\left(\frac{t^2}{n^2}\right)\right)\right)$$

$$=\exp\left(rac{t^2}{2}+o(t^2/n)
ight)rac{1}{n o\infty}e^{t^2/2}$$
, which is the mgf of $\mathcal{N}(0,1)$

CLT = convergence of laws

The law of S_n^* converges to $\mathcal{N}(0,1)$. In other words, whatever the initial law of X:

$$\lim_{n \to \infty} P[a < S_n^* < b] = \int_a^b \frac{1}{\sigma \sqrt{2\pi}} e^{-x^2/2} dx$$

It provides a reasonable approximation when close to the peak of the normal distribution.

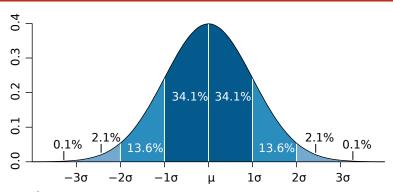
(it requires a very large number of observations to stretch into the tails)

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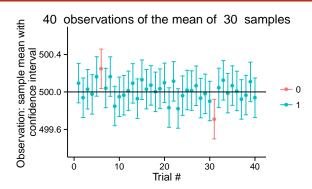
Confidence interval



When n is large:

$$P\left(\mu \in \left[S_n - 2\frac{\sigma}{\sqrt{n}}, S_n + 2\frac{\sigma}{\sqrt{n}}\right]\right) = P\left(S_n \in \left[\mu - 2\frac{\sigma}{\sqrt{n}}, \mu + 2\frac{\sigma}{\sqrt{n}}\right]\right) \approx 95\%$$

Confidence interval

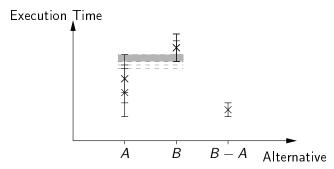


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There is 95% of chance that the true mean lies within $2\frac{\sigma}{\sqrt{n}}$ of the sample mean.

- Assume, you have evaluated two alternatives A and B on n different setups
- You therefore consider the associated random variables A and B and try to estimate their expected values μ_A and μ_B

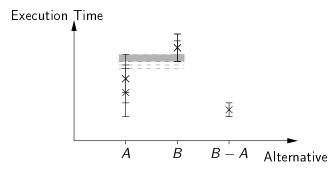


The two 95% confidence intervals do not overlap

 $\rightsquigarrow \mu_A < \mu_B$ with more than 90% of confidence \odot



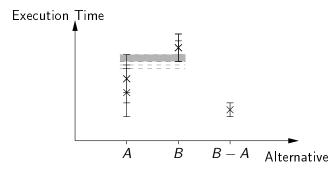
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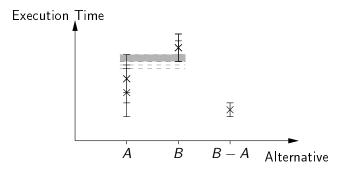
Nothing can be concluded ⊕

- Assume, you have evaluated two alternatives A and B on n different setups
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The two 70% confidence intervals do not overlap $\rightsquigarrow \mu_A < \mu_B$ with less than 50% of confidence $\textcircled{9} \rightsquigarrow$ more experiments...

- Assume, you have evaluated two alternatives A and B on n different setups
- You therefore consider the associated random variables A and B and try to estimate their expected values μ_A and μ_B



The width of the confidence interval is proportional to $\frac{\sigma}{\sqrt{n}}$

You can estimate how much more experiments you need@

4 times more to halve it! Try to reduce variance if you can...