Bias-Variance Decomposition

Machine Learning- CS-433 1 Oct 2025

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(Slide credits: Martin Jaggi & Nicolas Flammarion)



Last time

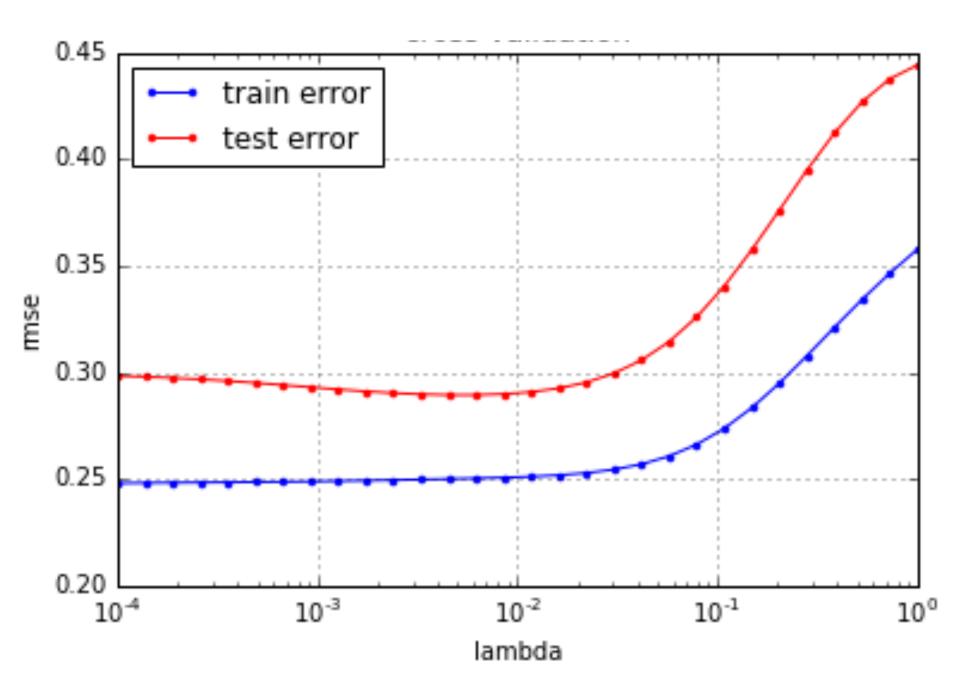
How can we judge if a given predictor is good? How to select the best models of a family?

- →Bound the difference between the true and empirical risks
- ⇒Split data into train and test sets (learn with the train and test on the test)

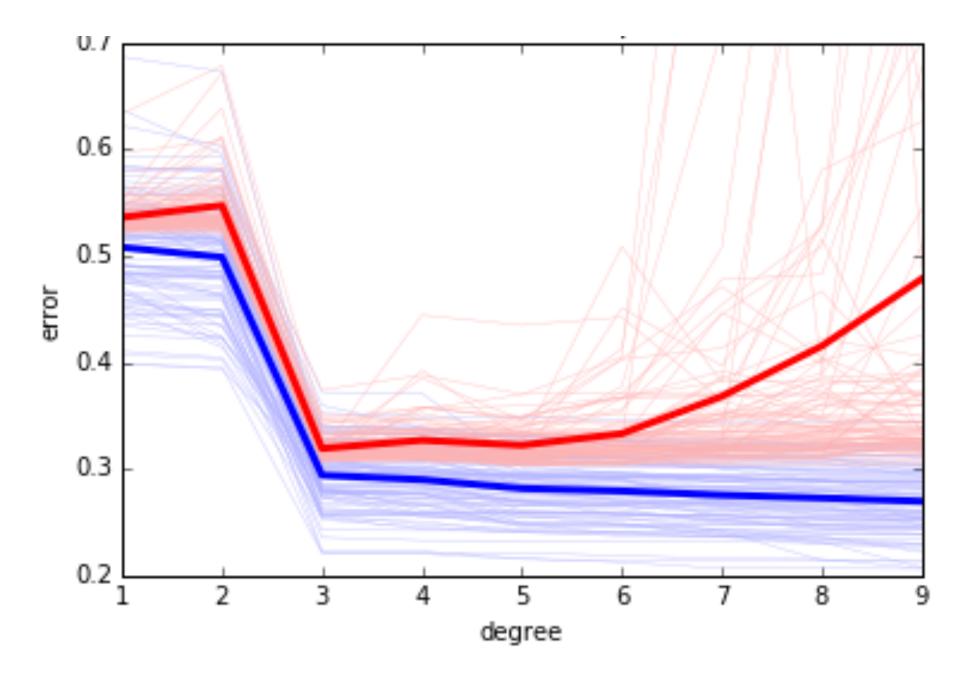
Motivation: Hyperparameter search (where hyperparameters often control model complexity)

But we haven't investigated the role of the complexity of the class

Model selection curves

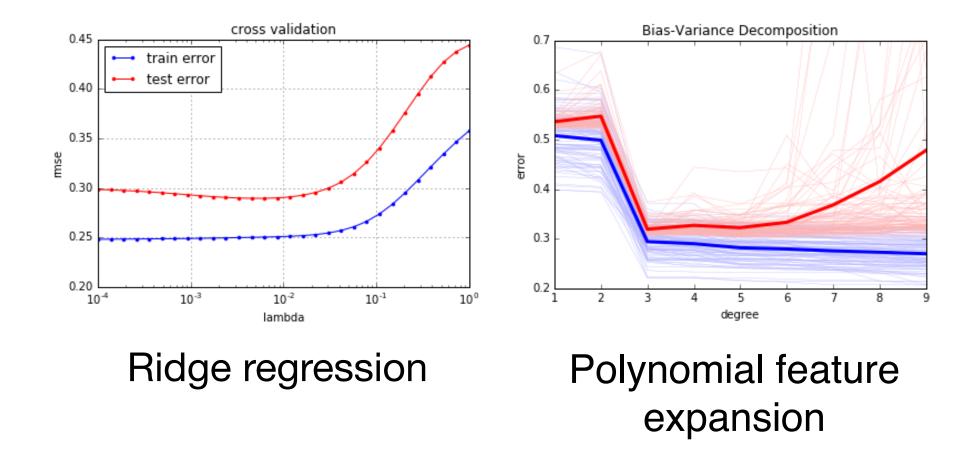


Ridge regression



Degree in case of a polynomial feature expansion

Today



How does the risk behave as a function of the complexity of the model class?

→ Bias-Variance tradeoff

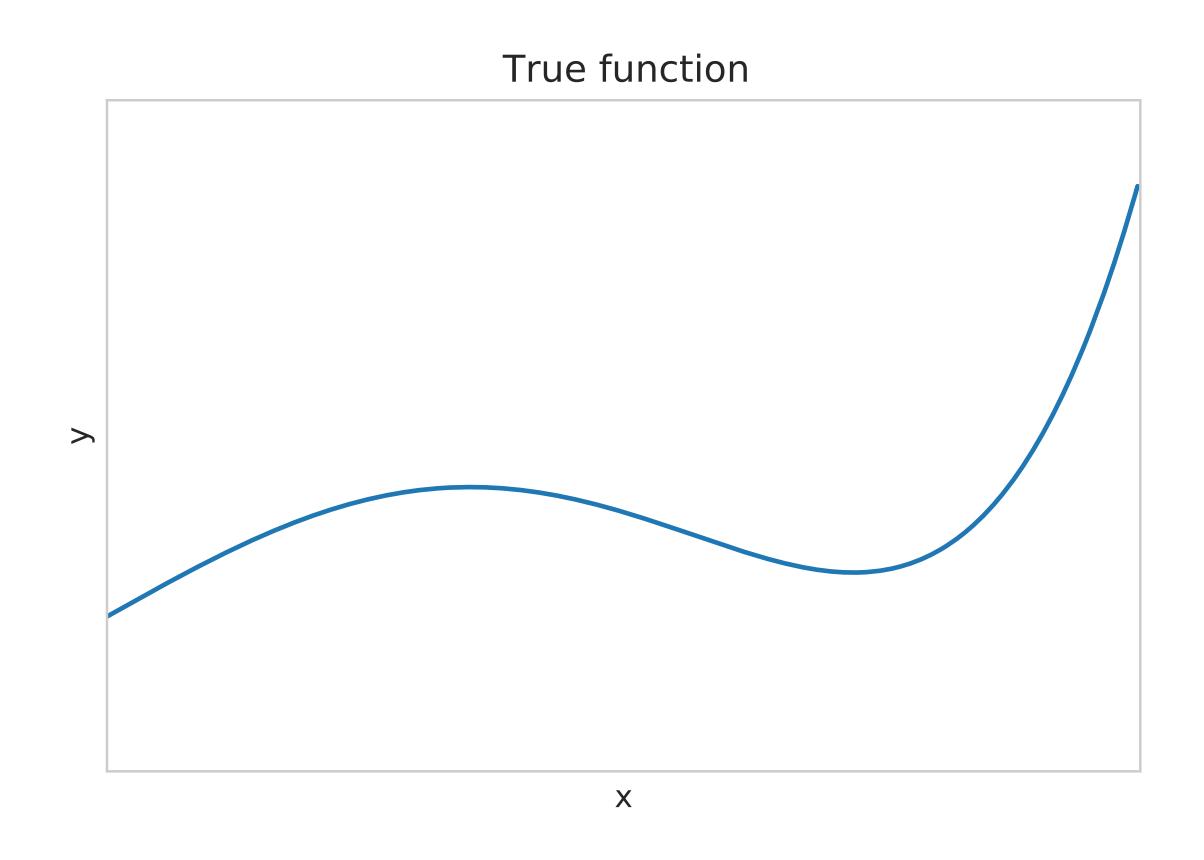
It will help us to decide how complex and rich we should make our model



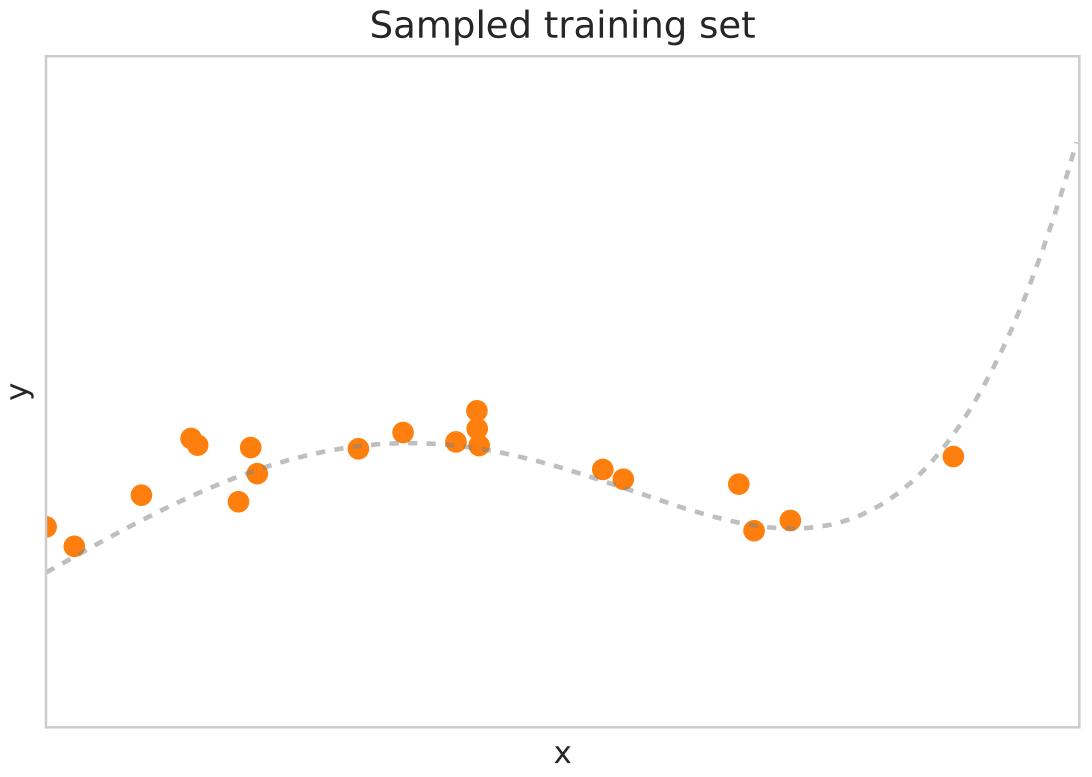
Before: quantitative

Now: qualitative

A small experiment: 1D-regression



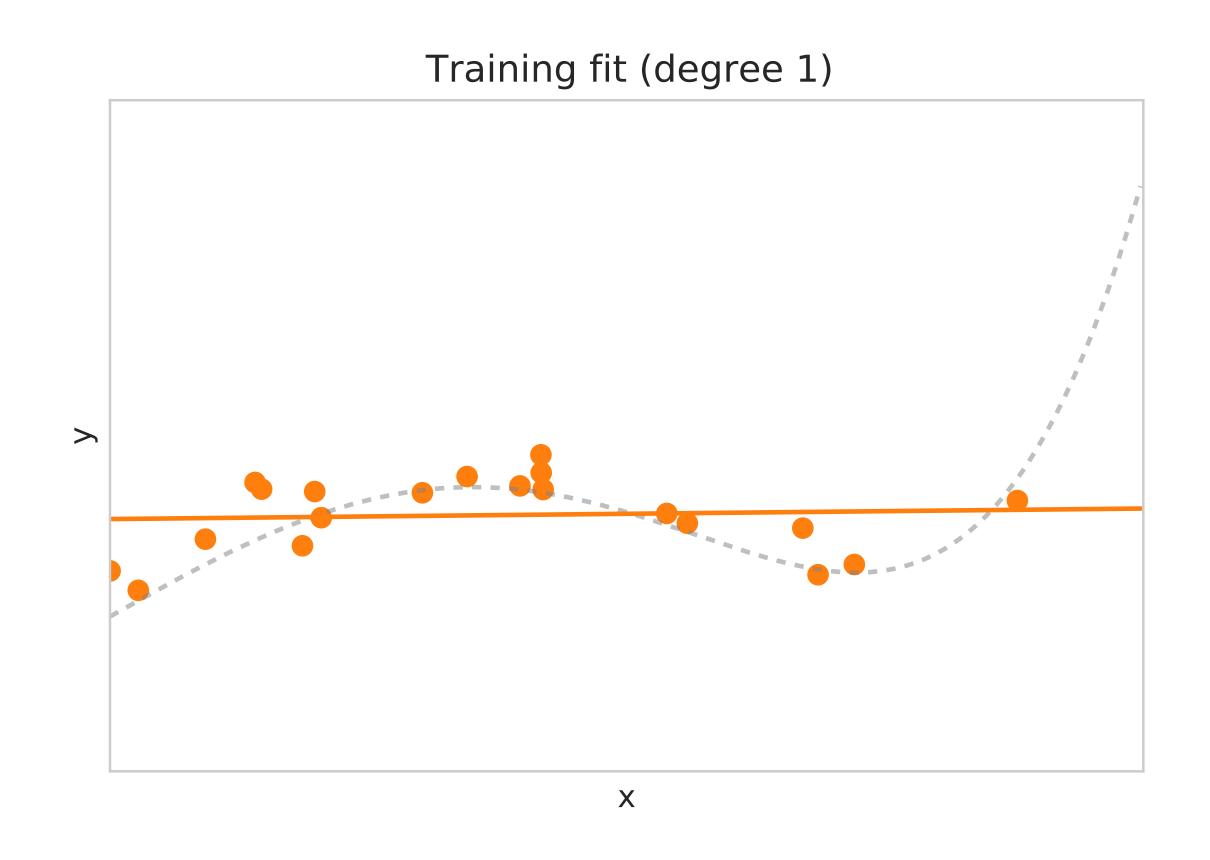
A small experiment: 1D-regression



Linear regression using polynomial feature expansion $(x, x^2, x^3, \dots, x^d)$ The maximum degree d measures the complexity of the class

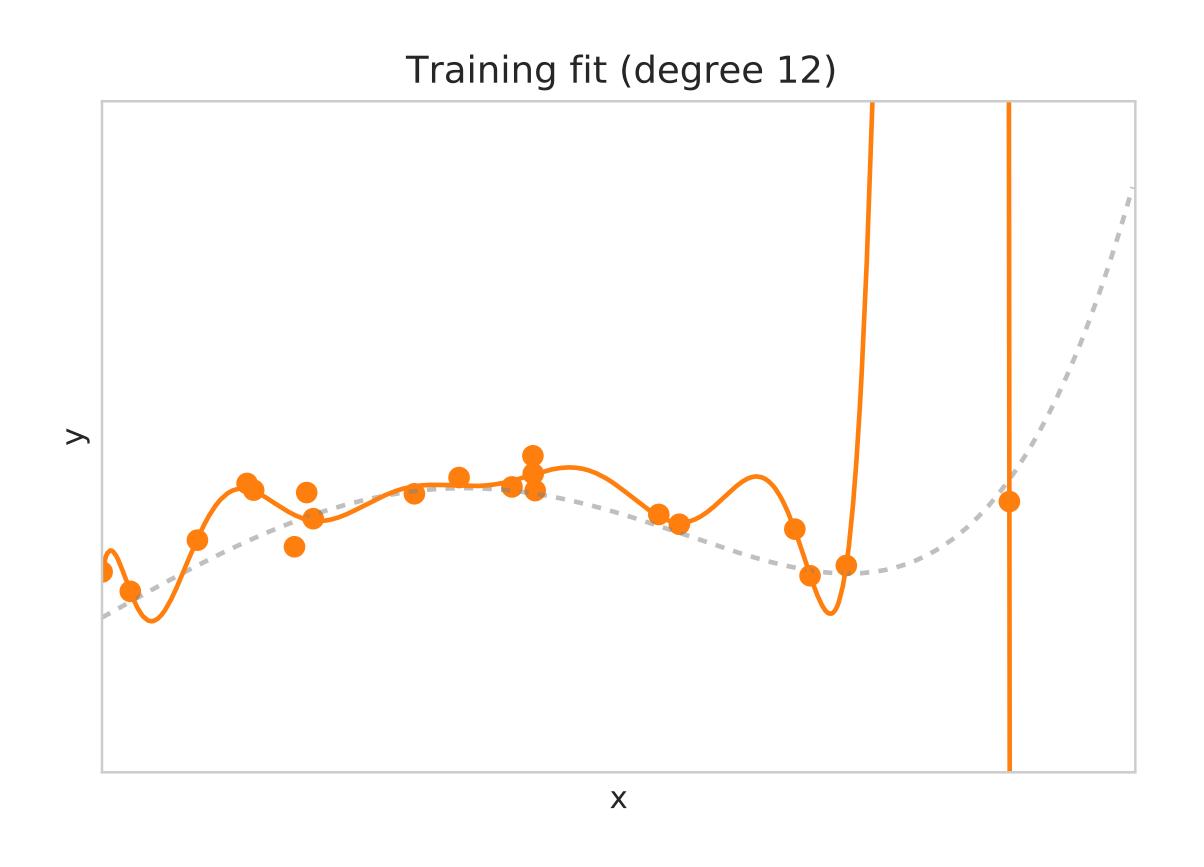
→ How far should you go?

Simple model: bad fit

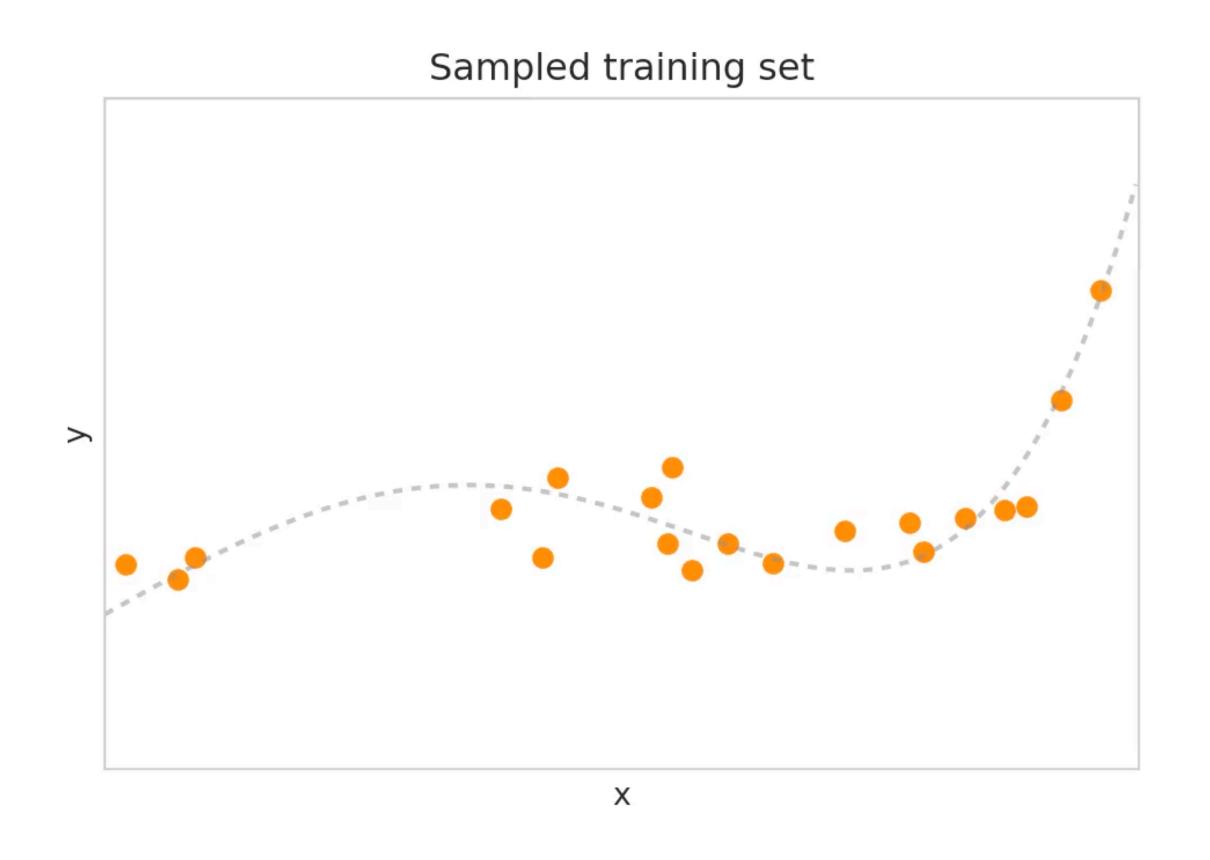


No linear function would be a good predictor. The model class is not rich enough

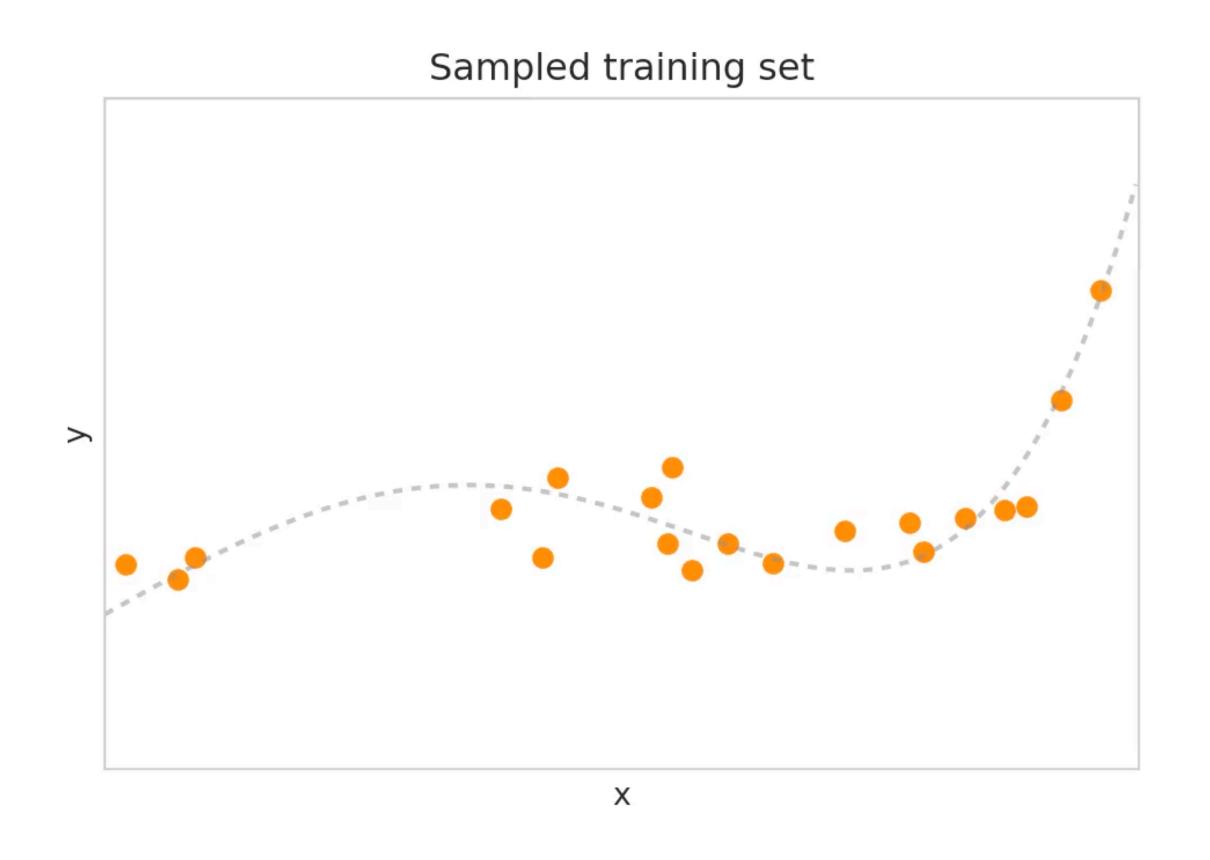
Complex model: good fit?



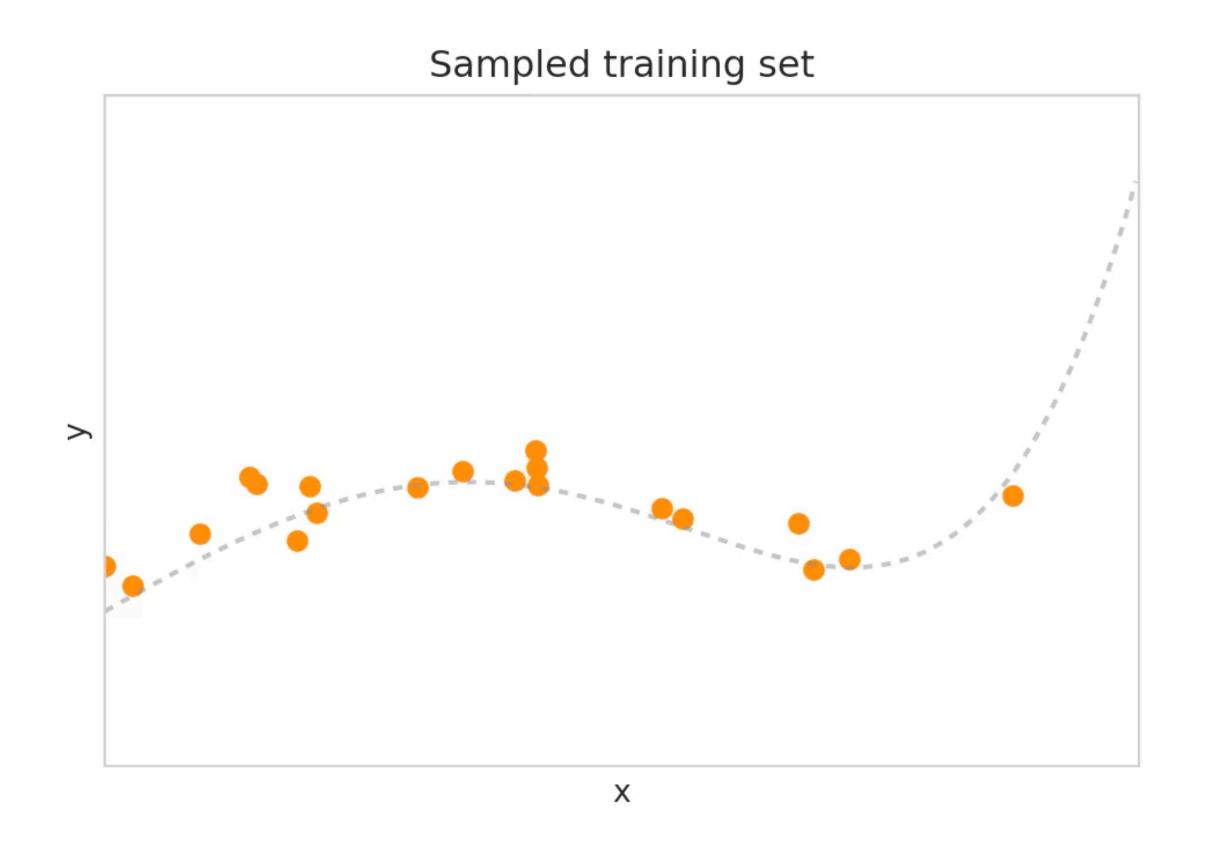
High degree polynomial will be a good fit. But?



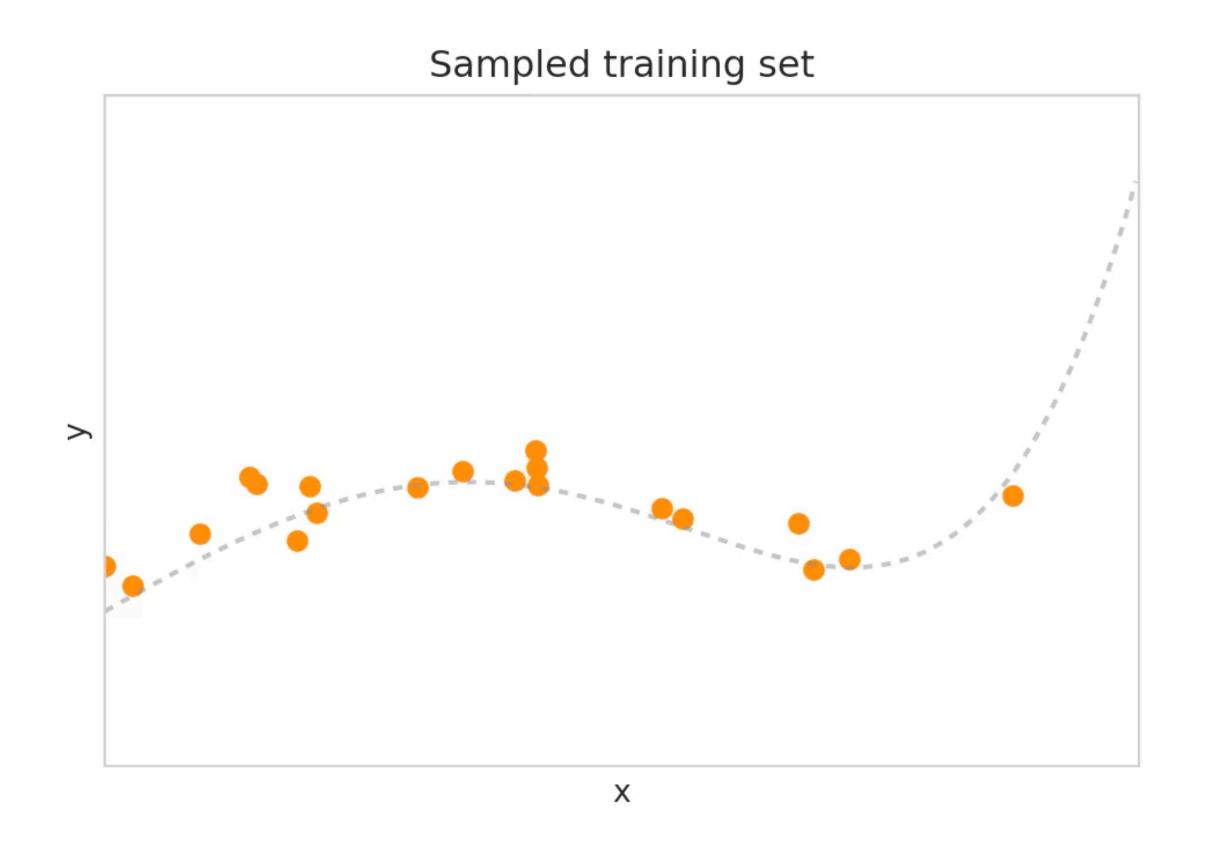
We have observed one particular S_{train} but we could have observed several others!



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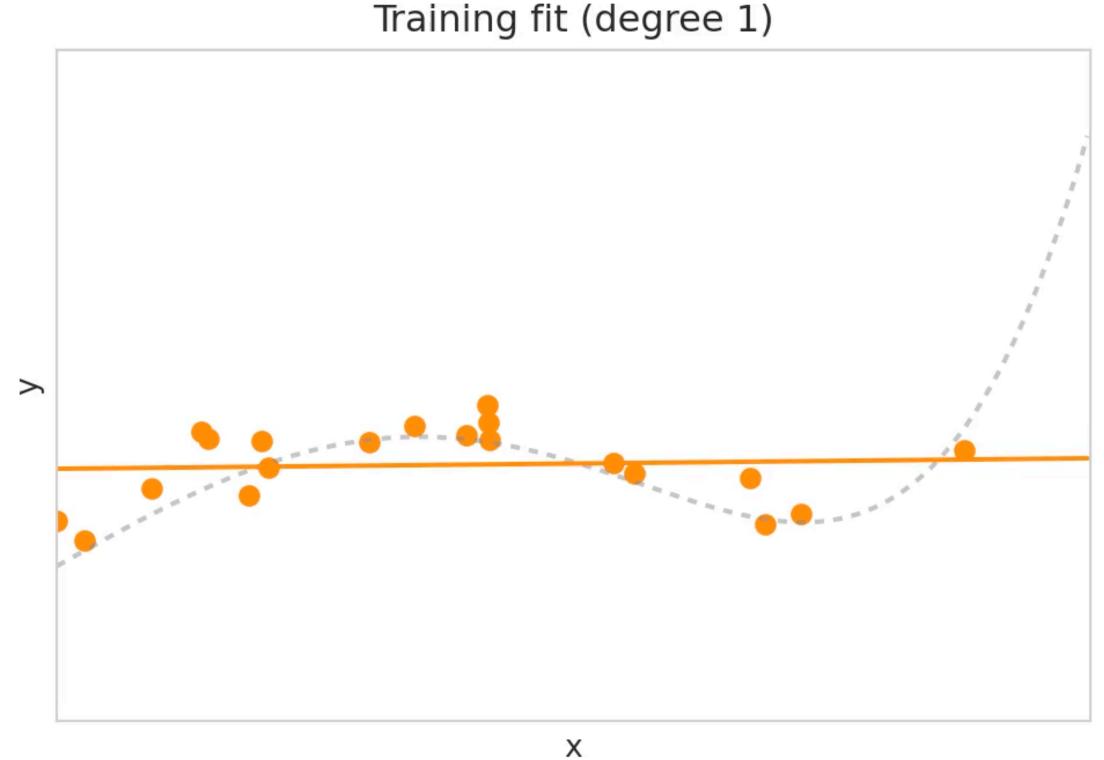


Even if we keep the same (x_1, \dots, x_n) , we have variability in the observed (y_1, \dots, y_n)



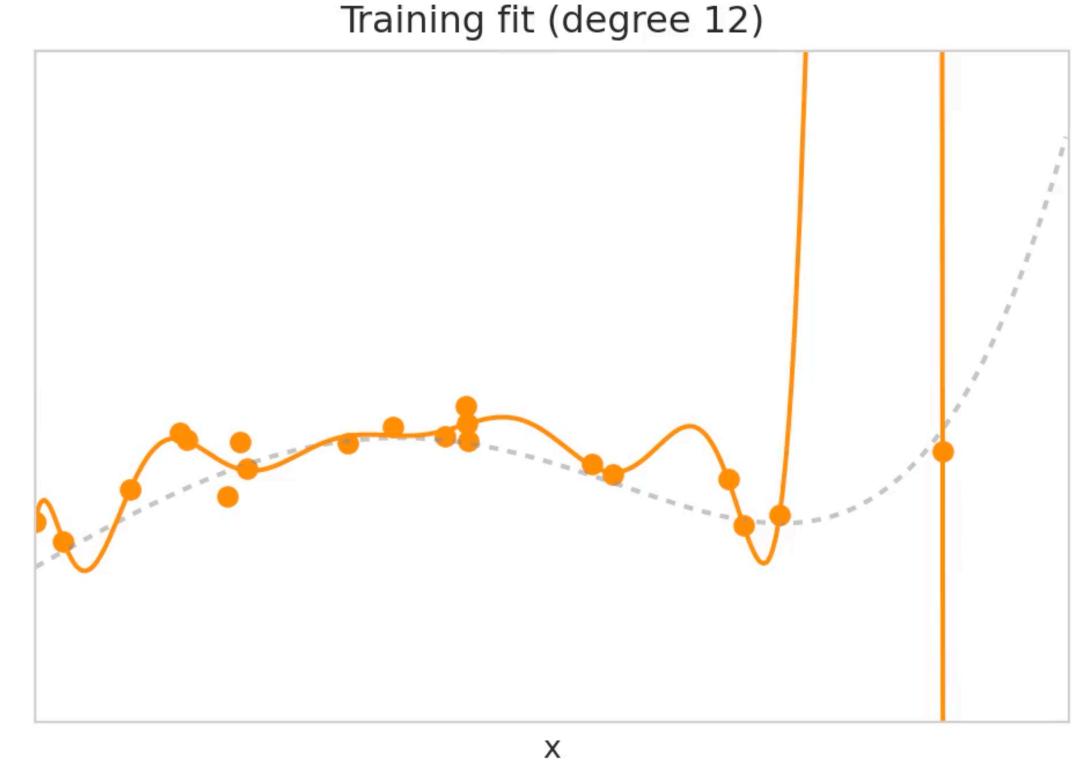
Even if we keep the same (x_1, \dots, x_n) , we have variability in the observed (y_1, \dots, y_n)

Thus there is randomness in the predictions



Moving a single observation will cause only a small shift in the position of the line

Underfitting

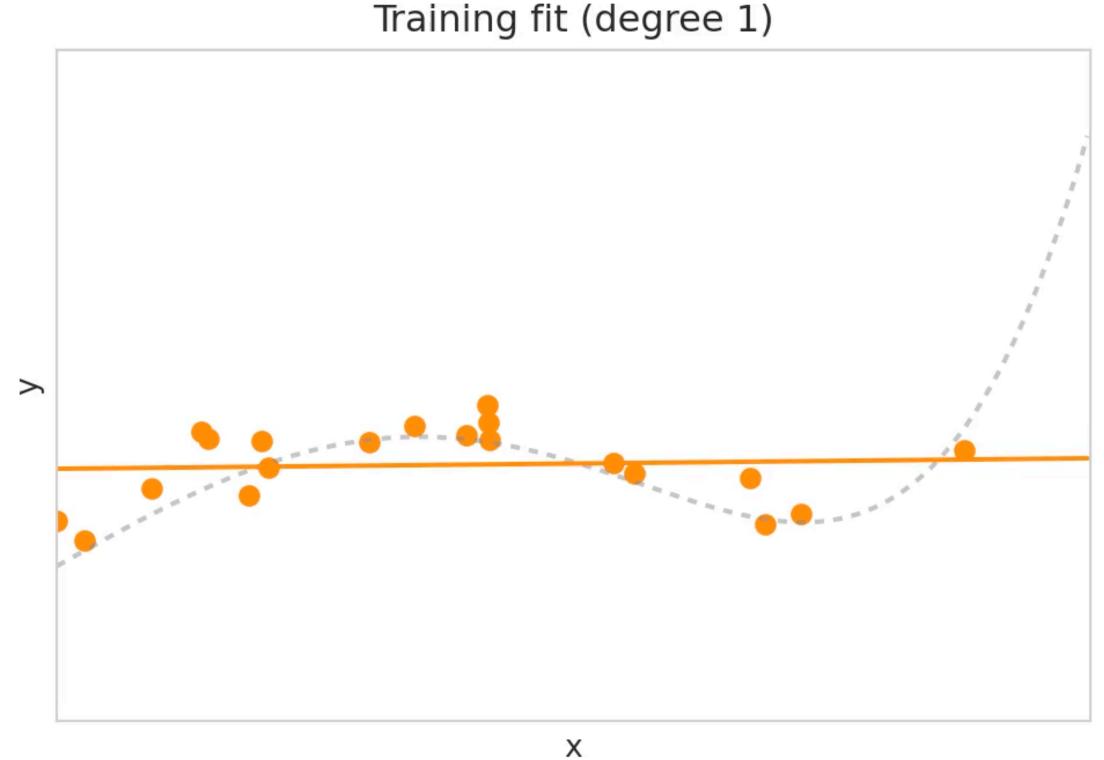


Changing one of the observations may change the prediction considerably

Overfitting

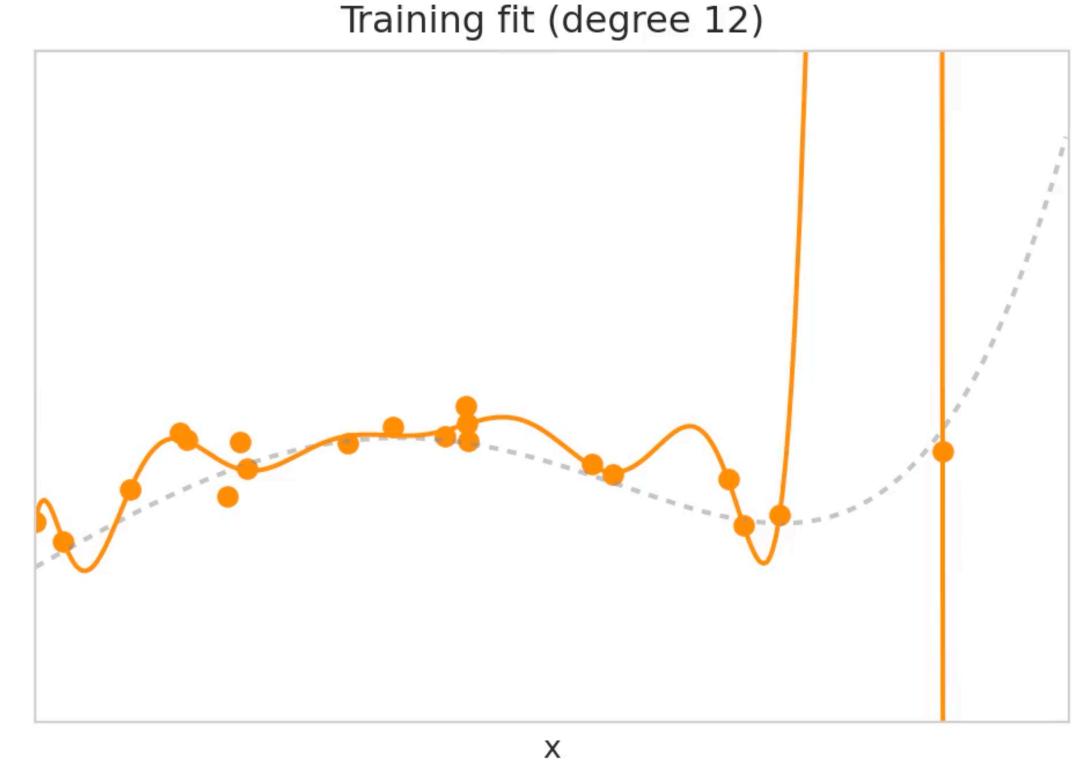
Simple models are less sensitive

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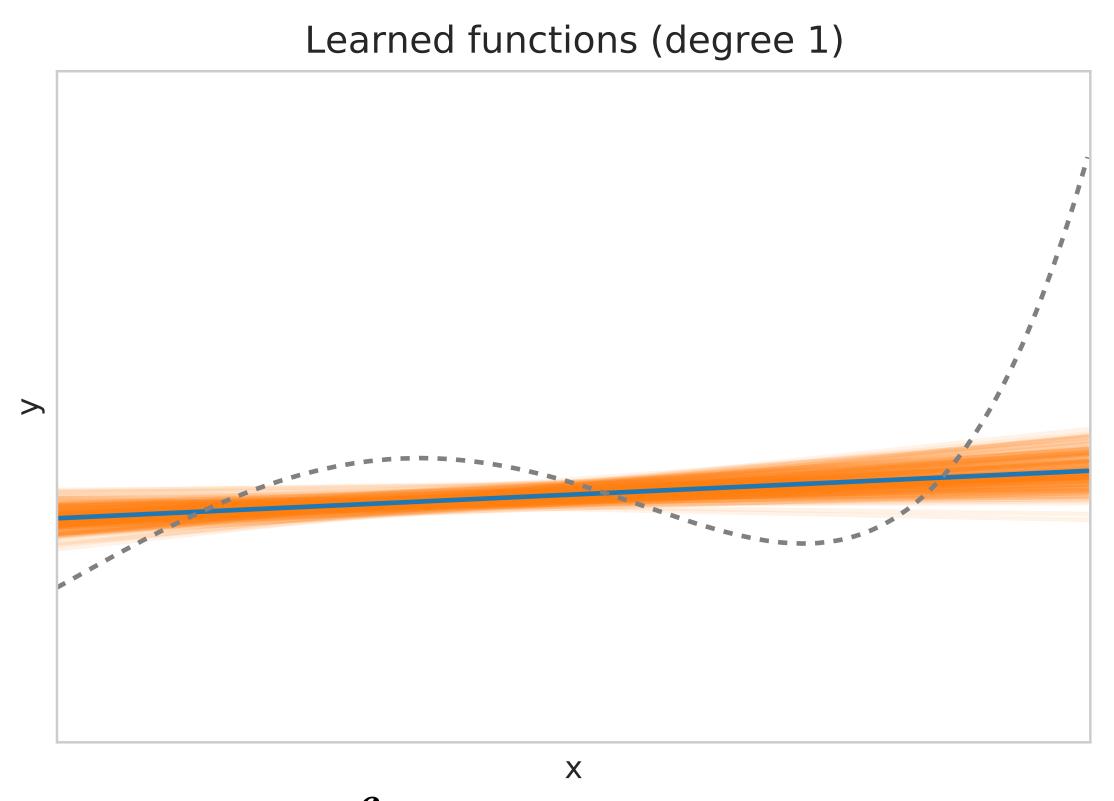


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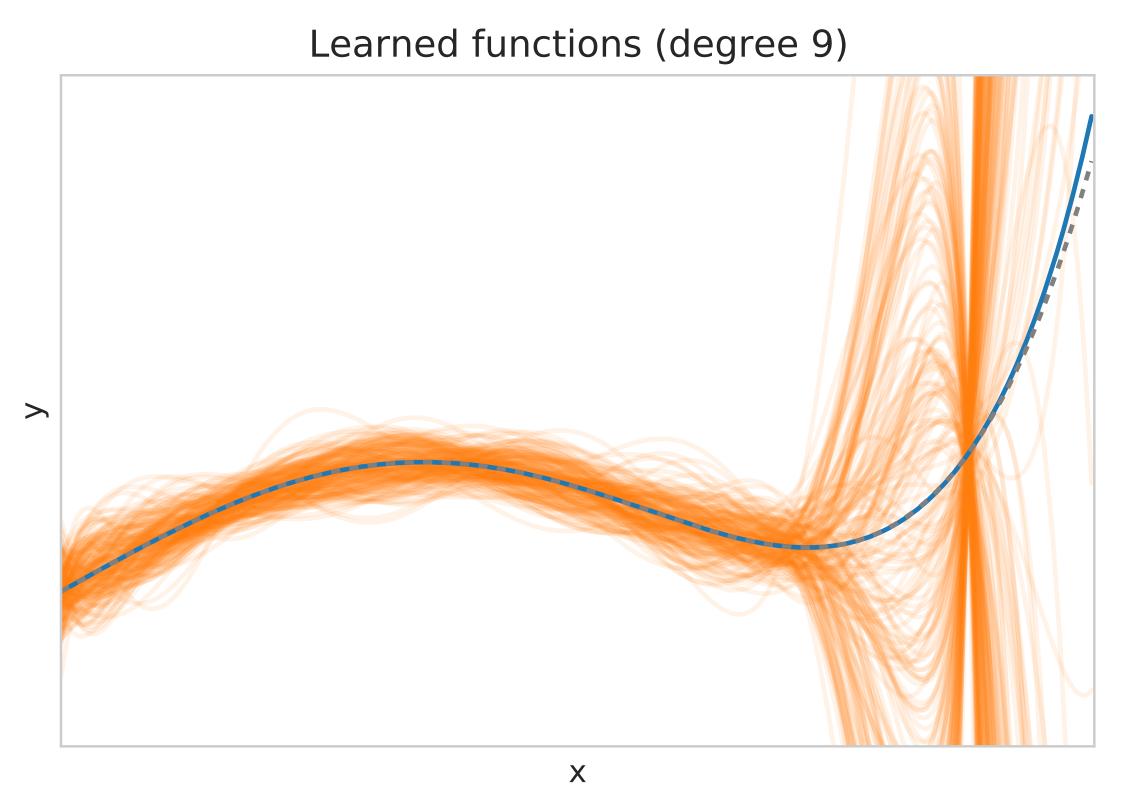
Simple models are less sensitive

Simple models have large bias but low variance



The average of the predictions f_S does not fit the data well: **large bias**The variance of the predictions f_S as a function of S is small: **small variance**

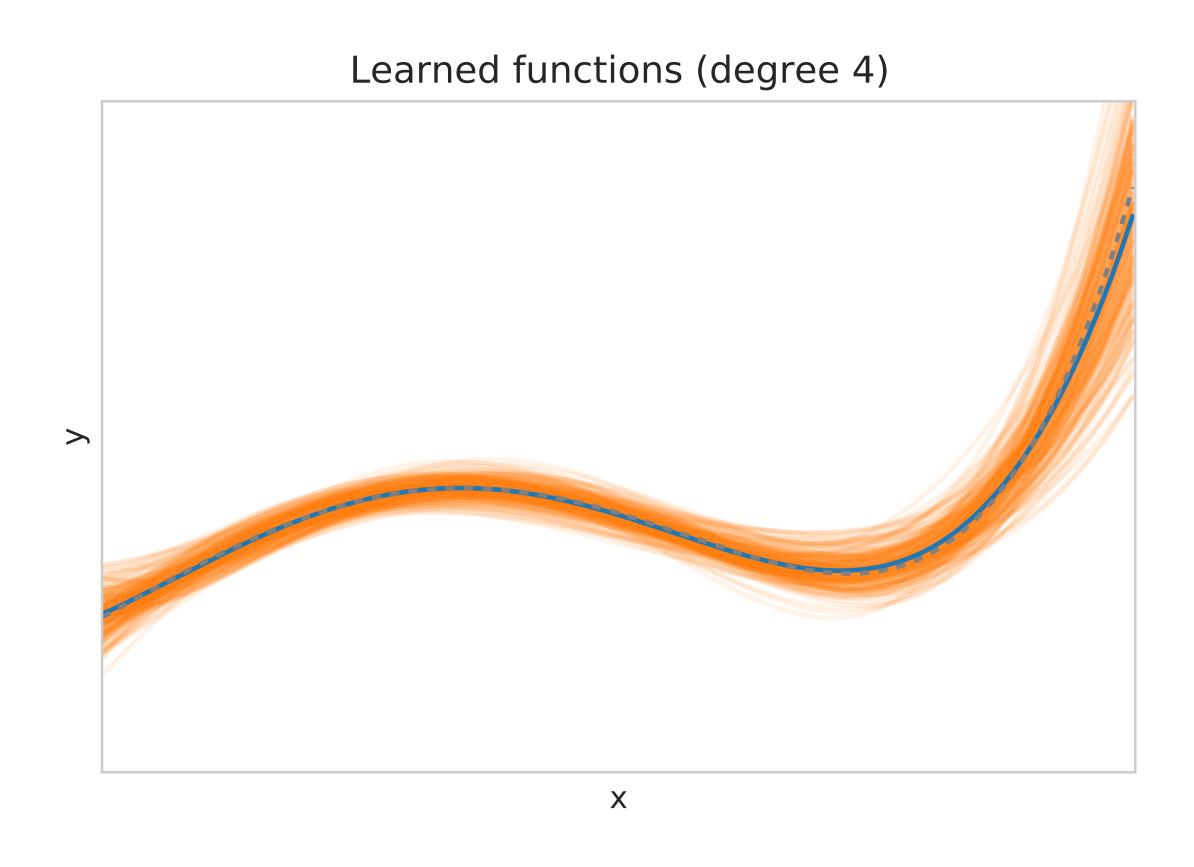
Complex models have low bias but high variance



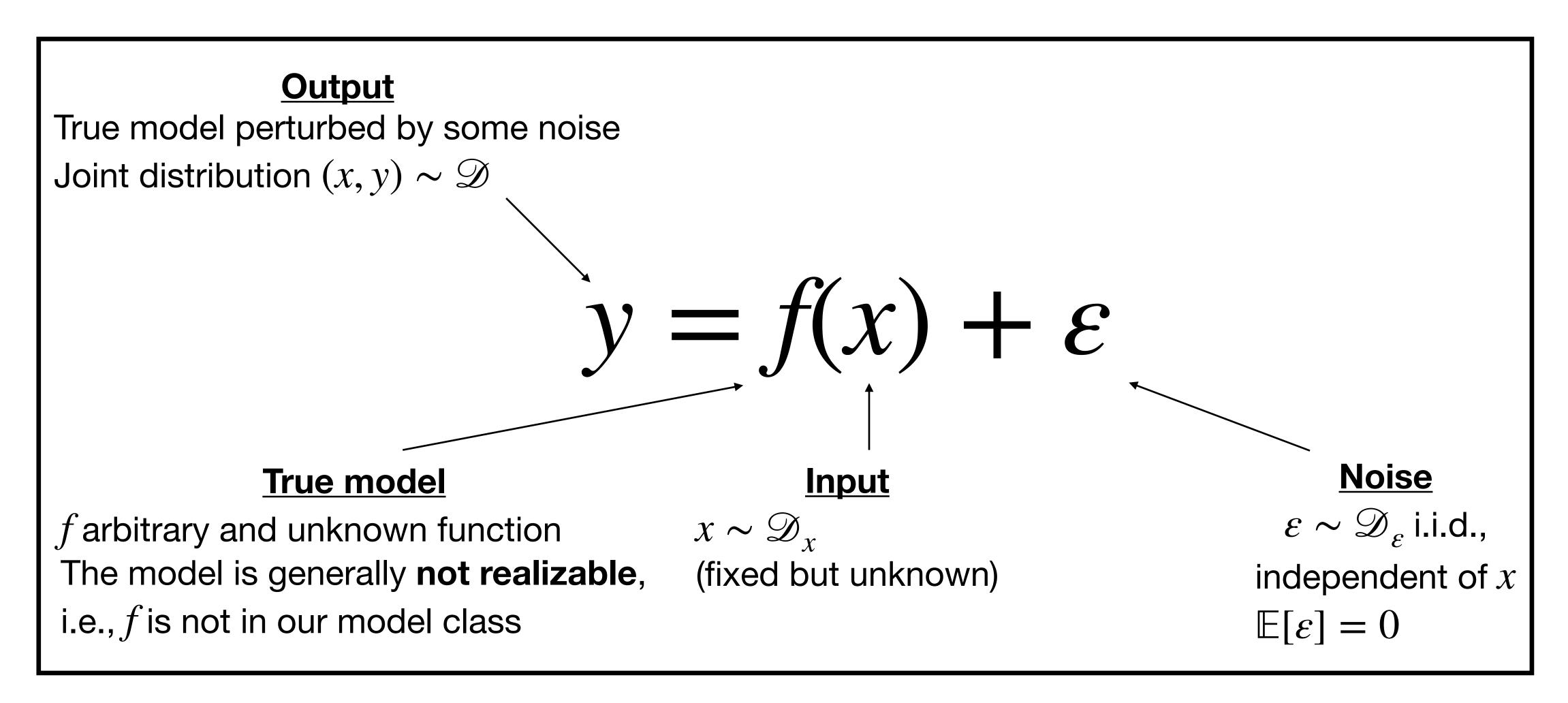
The average of the predictions $f_{\mathcal{S}}$ fits the data well: **small bias**

The variance of the predictions f_S as a function of S is large: large variance

We need to balance bias & variance correctly

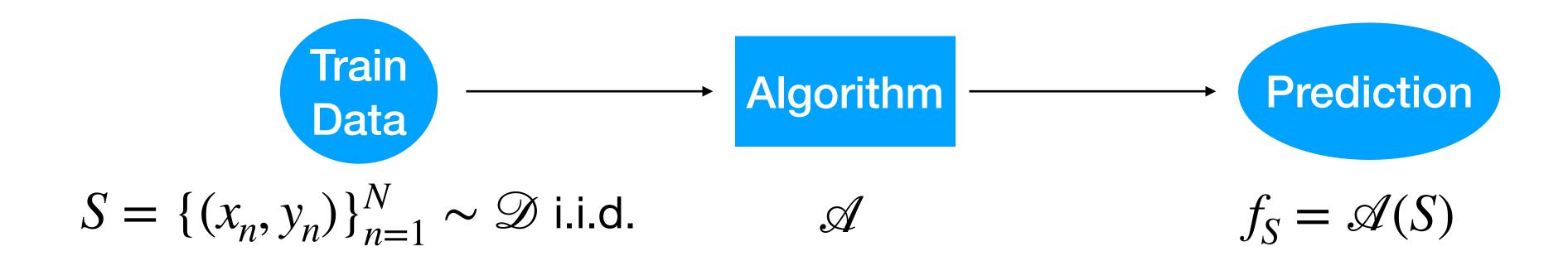


Data model: output perturbed by some noise



We consider the square loss and will provide a decomposition of the true error

Error Decomposition

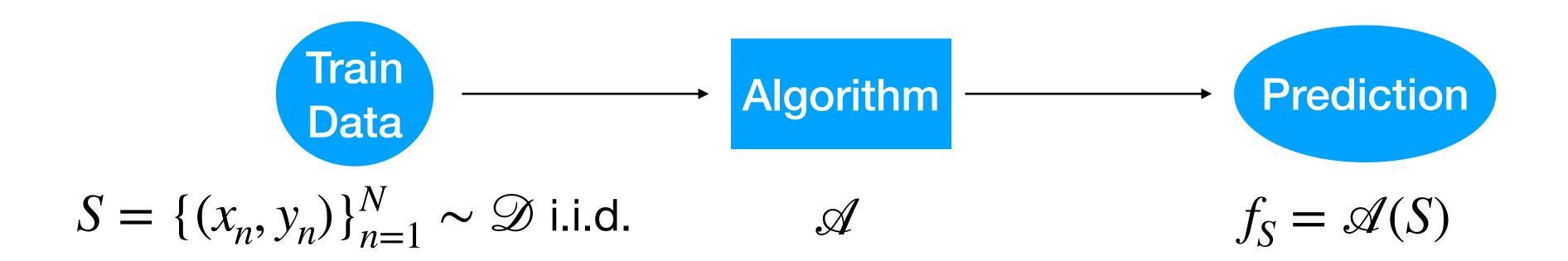


We are interested in how the **expected error** of f_S :

$$\mathbb{E}_{(x,y)\sim \mathcal{D}}[(y-f_{S}(x))^{2}]$$

behaves as a function of the train set S and model class complexity

Error Decomposition

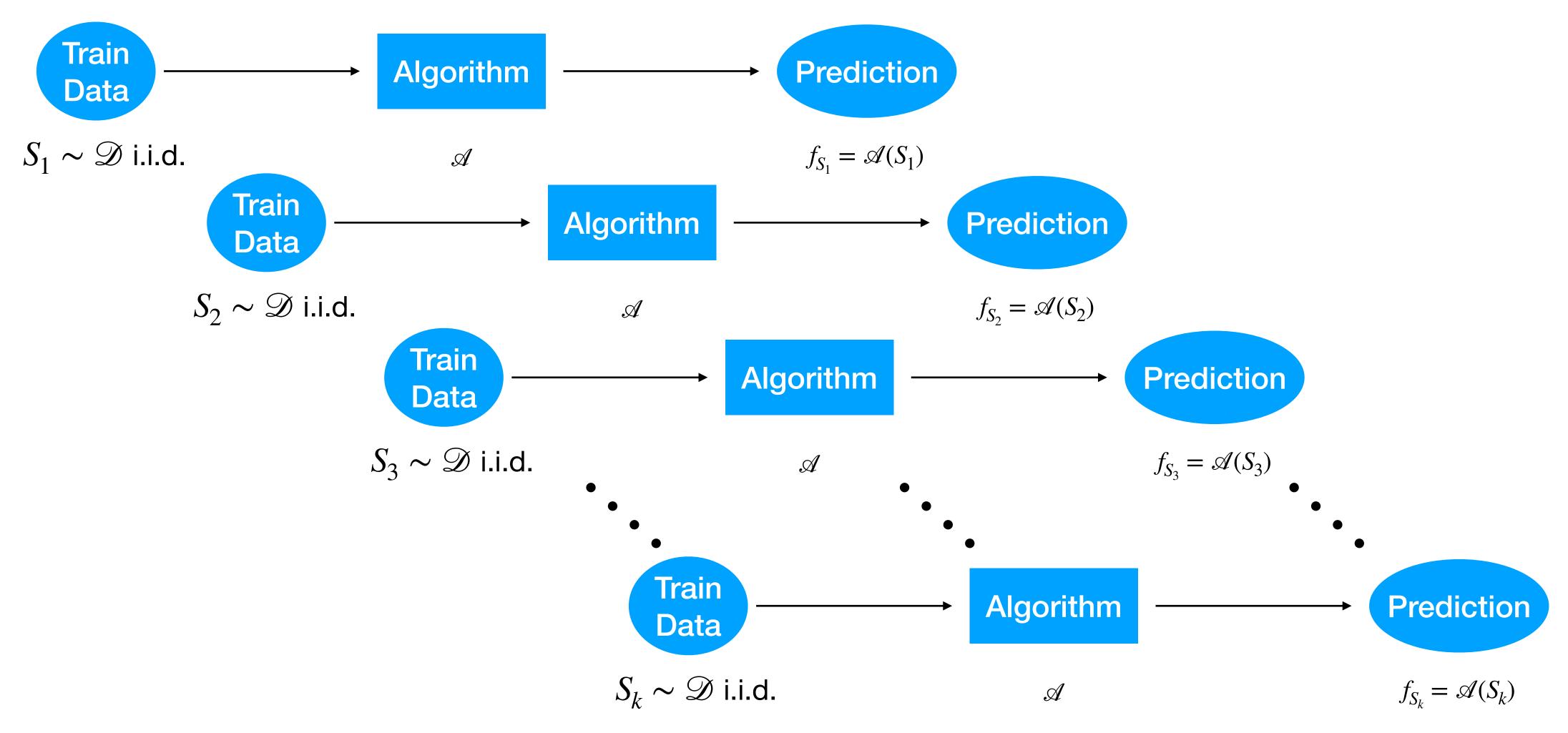


The decomposition will hold true at **every single point** x. Therefore, to simplify, we consider the expected error of f_S for a fixed element x_0 :

$$L(f_S) = \mathbb{E}_{\varepsilon \sim \mathcal{D}_{\varepsilon}}[(f(x_0) + \varepsilon - f_S(x_0))^2]$$

This is a random variable. The randomness comes for the train set S

We run the experiment many times



We are interested in the *average* and the *variance* of the *predictions* $(f_{S_1}, \dots, f_{S_k})$ over these multiple runs

A decomposition in three terms

We are interested in the expectation of the true risk over the training set S

$$\mathbb{E}_{S \sim \mathcal{D}}[L(f_S)] = \mathbb{E}_{S \sim \mathcal{D}}[\mathbb{E}_{\varepsilon \sim \mathcal{D}_{\varepsilon}}[(f(x_0) + \varepsilon - f_S(x_0))^2]]$$
$$= \mathbb{E}_{S \sim \mathcal{D}, \varepsilon \sim \mathcal{D}_{\varepsilon}}[(f(x_0) + \varepsilon - f_S(x_0))^2]$$

We will decompose this quantity in *three non-negative terms* and will interpret each of these terms

First we expand the square:

$$\mathbb{E}_{S \sim \mathcal{D}, \, \varepsilon \sim \mathcal{D}_{\varepsilon}} [(f(x_0) + \varepsilon - f_S(x_0))^2] = \mathbb{E}_{\varepsilon \sim \mathcal{D}_{\varepsilon}} [\varepsilon^2]$$

$$+ 2\mathbb{E}_{S \sim \mathcal{D}, \, \varepsilon \sim \mathcal{D}_{\varepsilon}} [\varepsilon(f(x_0) - f_S(x_0))]$$

$$+ \mathbb{E}_{S \sim \mathcal{D}} [(f(x_0) - f_S(x_0))^2]$$

Using that $\mathbb{E}_{\varepsilon \sim \mathcal{D}_{\varepsilon}}[\varepsilon] = 0$ and $\varepsilon \perp S$:

•
$$\mathbb{E}_{\varepsilon \sim \mathcal{D}_{\varepsilon}}[\varepsilon^2] = \mathrm{Var}_{\varepsilon \sim \mathcal{D}_{\varepsilon}}[\varepsilon]$$

•
$$\mathbb{E}_{S \sim \mathcal{D}, \varepsilon \sim \mathcal{D}_{\varepsilon}} [\varepsilon(f(x_0) - f_S(x_0))] = \mathbb{E}_{\varepsilon \sim \mathcal{D}_{\varepsilon}} [\varepsilon] \cdot \mathbb{E}_{S \sim \mathcal{D}} [f(x_0) - f_S(x_0)] = 0$$

Therefore

$$\mathbb{E}_{S \sim \mathcal{D}, \varepsilon \sim \mathcal{D}_{\varepsilon}}[(f(x_0) + \varepsilon - f_S(x_0))^2] = \operatorname{Var}_{\varepsilon \sim \mathcal{D}_{\varepsilon}}[\varepsilon] + \mathbb{E}_{S \sim \mathcal{D}}[(f(x_0) - f_S(x_0))^2]$$

<u>Trick</u>: we add and subtract the constant term $\mathbb{E}_{S'\sim\mathcal{D}}[f_{S'}(x_0)]$, where S' is a second training set independent from S

$$\mathbb{E}_{S \sim \mathcal{D}}[(f(x_0) - f_S(x_0))^2] = \mathbb{E}_{S \sim \mathcal{D}}[(f(x_0) - \mathbb{E}_{S' \sim \mathcal{D}}[f_{S'}(x_0)] + \mathbb{E}_{S' \sim \mathcal{D}}[f_{S'}(x_0)] - f_S(x_0))^2]$$

$$= \mathbb{E}_{S \sim \mathcal{D}}[(f(x_0) - \mathbb{E}_{S' \sim \mathcal{D}}[f_{S'}(x_0)])^2 + (\mathbb{E}_{S' \sim \mathcal{D}}[f_{S'}(x_0)] - f_S(x_0))^2$$

$$+2(f(x_0) - \mathbb{E}_{S' \sim \mathcal{D}}[f_{S'}(x_0)])(\mathbb{E}_{S' \sim \mathcal{D}}[f_{S'}(x_0)] - f_S(x_0))$$

Cross-term:

$$\begin{split} \mathbb{E}_{S \sim \mathcal{D}} \Big[\Big(f(x_0) - \mathbb{E}_{S' \sim \mathcal{D}} [f_{S'}(x_0)] \Big) \cdot \Big(\mathbb{E}_{S' \sim \mathcal{D}} [f_{S'}(x_0)] - f_{S}(x_0) \Big) \Big] \\ &= \Big(f(x_0) - \mathbb{E}_{S' \sim \mathcal{D}} [f_{S'}(x_0)] \Big) \cdot \mathbb{E}_{S \sim \mathcal{D}} \Big[\Big(\mathbb{E}_{S' \sim \mathcal{D}} [f_{S'}(x_0)] - f_{S}(x_0) \Big) - f_{S}(x_0) \Big] \\ &= \Big(f(x_0) - \mathbb{E}_{S' \sim \mathcal{D}} [f_{S'}(x_0)] \Big) \cdot \Big(\mathbb{E}_{S' \sim \mathcal{D}} [f_{S'}(x_0)] - \mathbb{E}_{S \sim \mathcal{D}} [f_{S}(x_0)] \Big) = 0. \end{split}$$

$$\left| \mathbb{E}_{S \sim \mathcal{D}} [(f(x_0) - f_S(x_0))^2] = (f(x_0) - \mathbb{E}_{S' \sim \mathcal{D}} [f_{S'}(x_0)])^2 + \mathbb{E}_{S \sim \mathcal{D}} [(\mathbb{E}_{S' \sim \mathcal{D}} [f_{S'}(x_0)] - f_S(x_0))^2] \right|$$

Bias-Variance Decomposition

We obtain the following decomposition into three positive terms:

$$\mathbb{E}_{S \sim \mathcal{D}_{\varepsilon}}[(f(x_0) + \varepsilon - f_S(x_0))^2] = \operatorname{Var}_{\varepsilon \sim \mathcal{D}_{\varepsilon}}[\varepsilon] \leftarrow \operatorname{Noise \, variance}$$

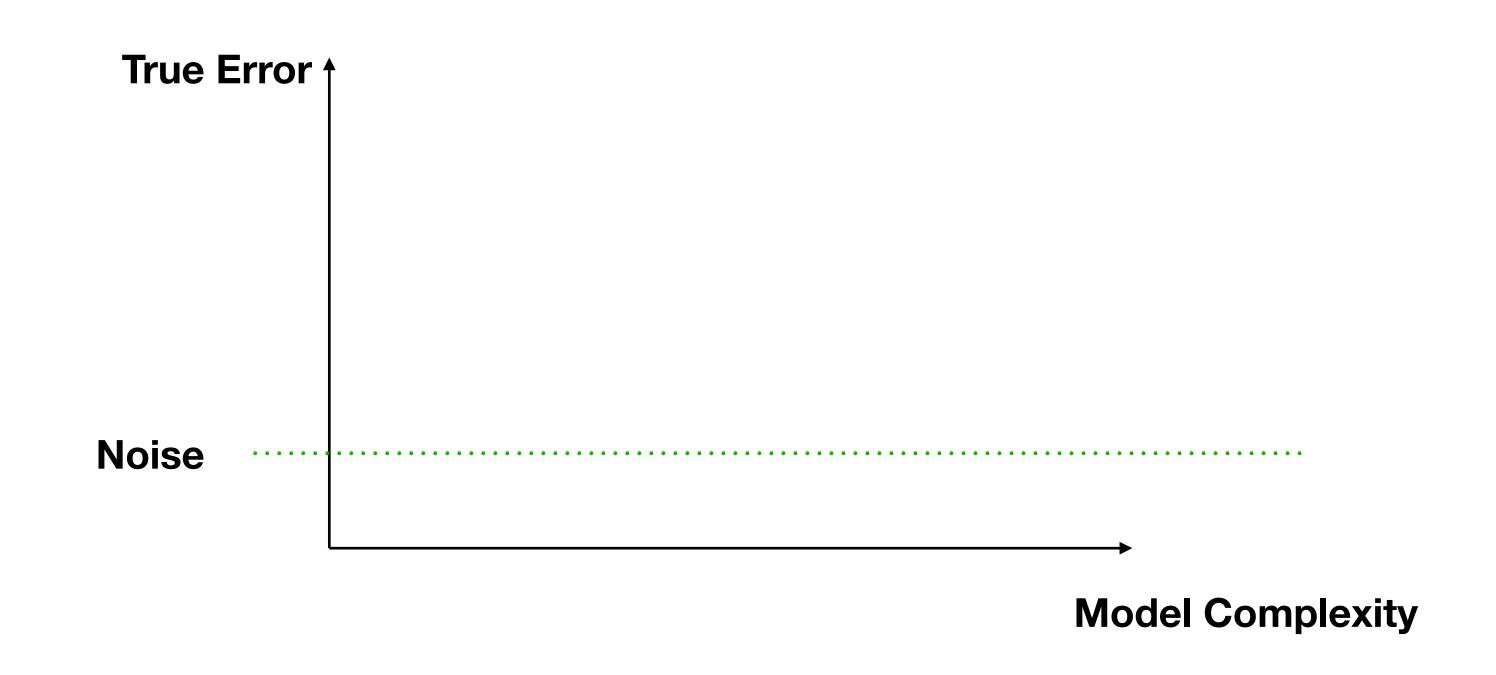
$$\operatorname{Bias} \quad \rightarrow \quad + \quad (f(x_0) - \mathbb{E}_{S' \sim \mathcal{D}}[f_{S'}(x_0)])^2$$

$$\operatorname{Variance} \quad \rightarrow \quad + \quad \mathbb{E}_{S \sim \mathcal{D}}\big[(f_S(x_0) - \mathbb{E}_{S' \sim \mathcal{D}}[f_{S'}(x_0)])^2\big]$$

each of which always provides a lower bound of the true error

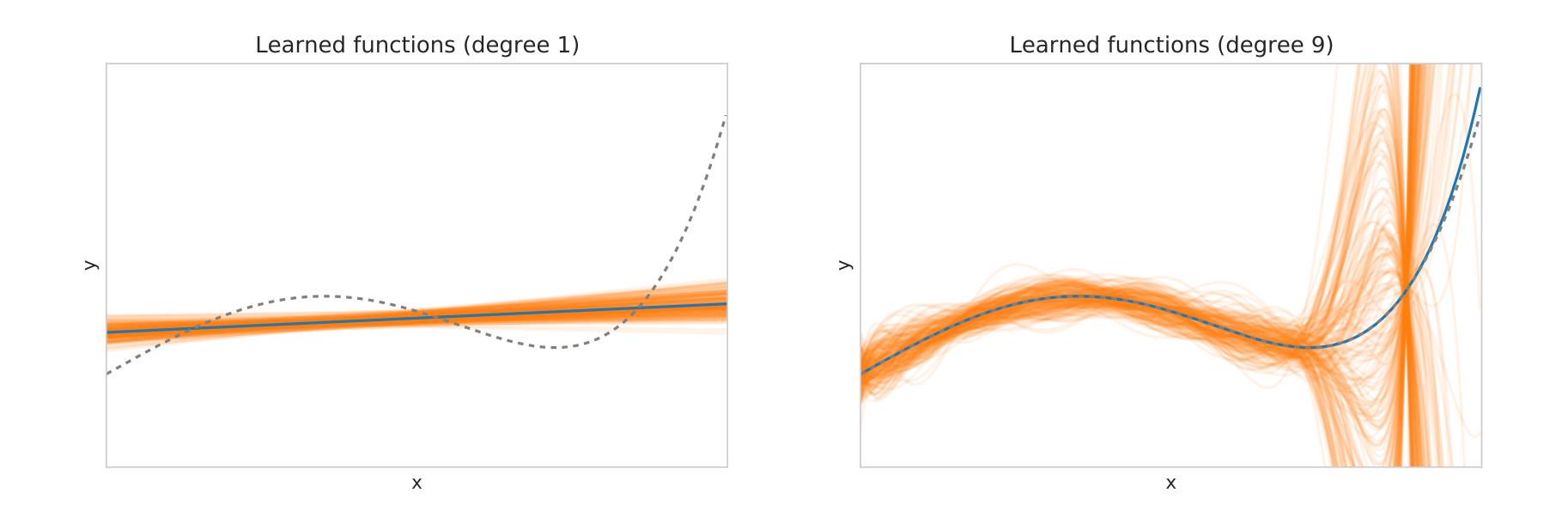
→ To minimize the true error, we must choose a method that achieves low bias and low variance simultaneously

Noise: a strict lower bound on the achievable error



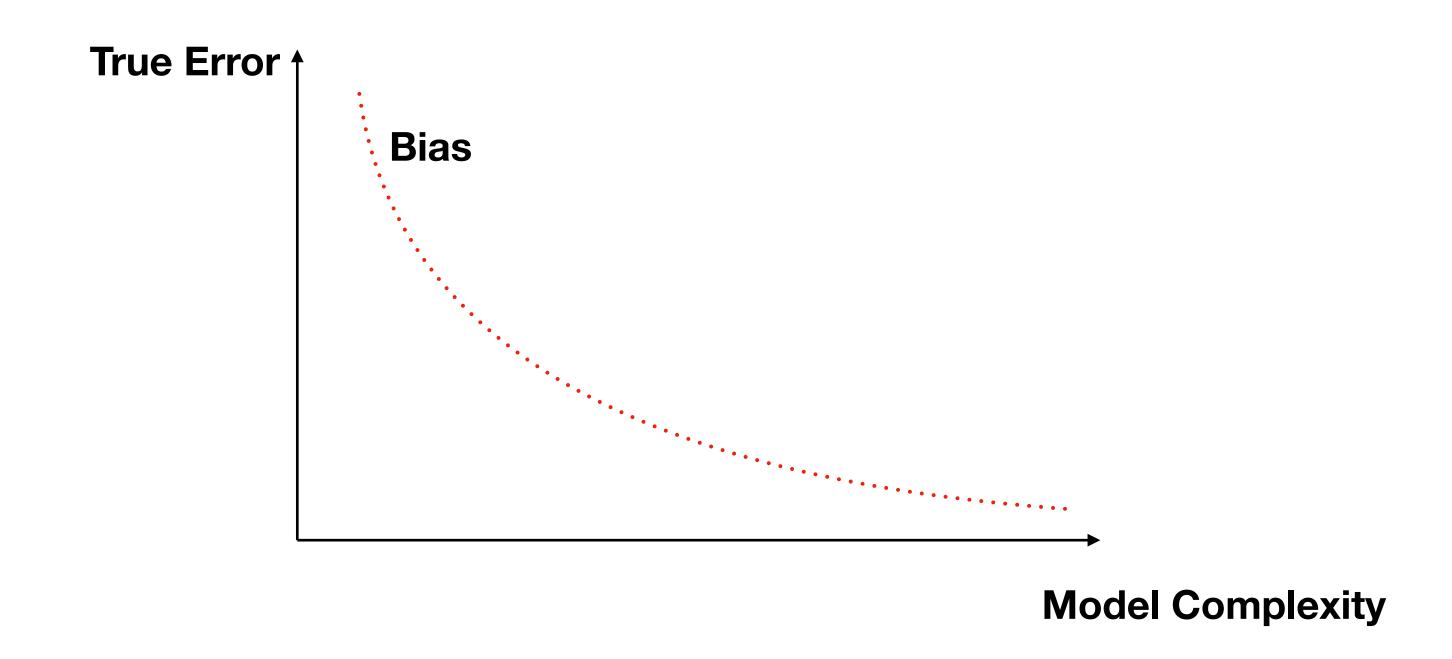
- It is not possible to go below the noise level
- Even if we know the true model f, we still suffer from the noise: $L(f) = \mathbb{E}[\varepsilon^2]$
- It is not possible to predict the noise from the data since they are independent

Bias: $(f(x_0) - \mathbb{E}_{S \sim \mathcal{D}}[f_S(x_0)])^2$



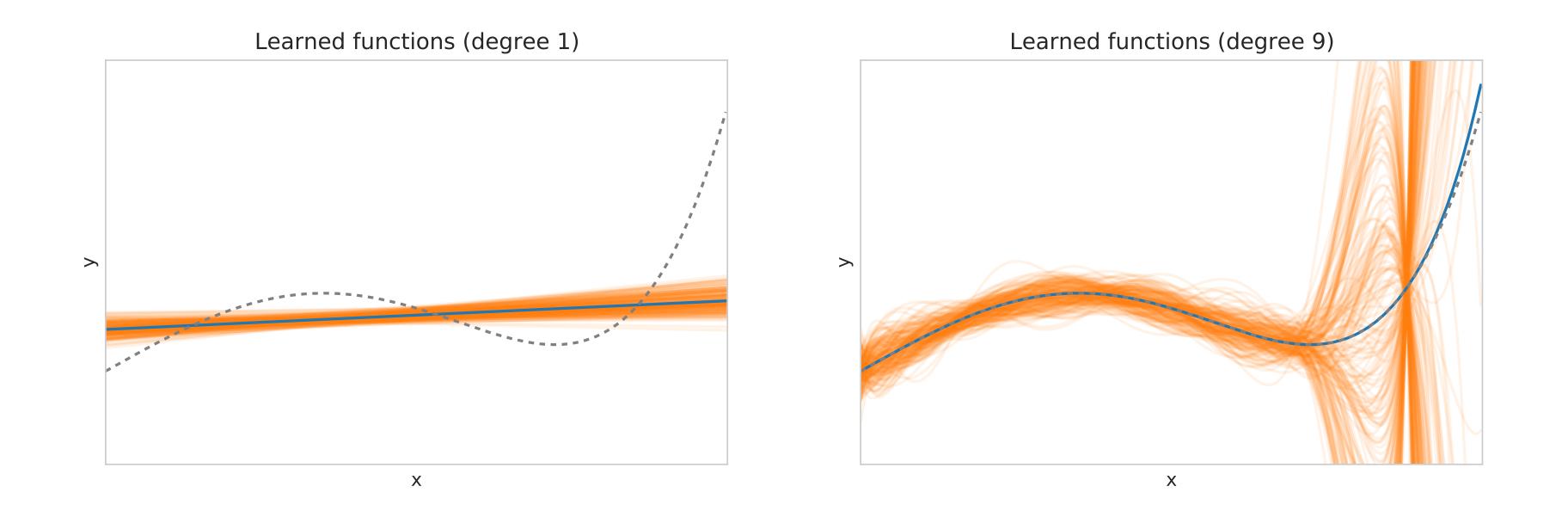
- Squared of the difference between the actual value $f(x_0)$ and the expected prediction
- It measures how far off in general the models' predictions are from the correct value
- If model complexity is low, bias is typically high
- If model complexity is high, bias is typically low

Bias: $(f(x_0) - \mathbb{E}_{S \sim \mathcal{D}}[f_S(x_0)])^2$



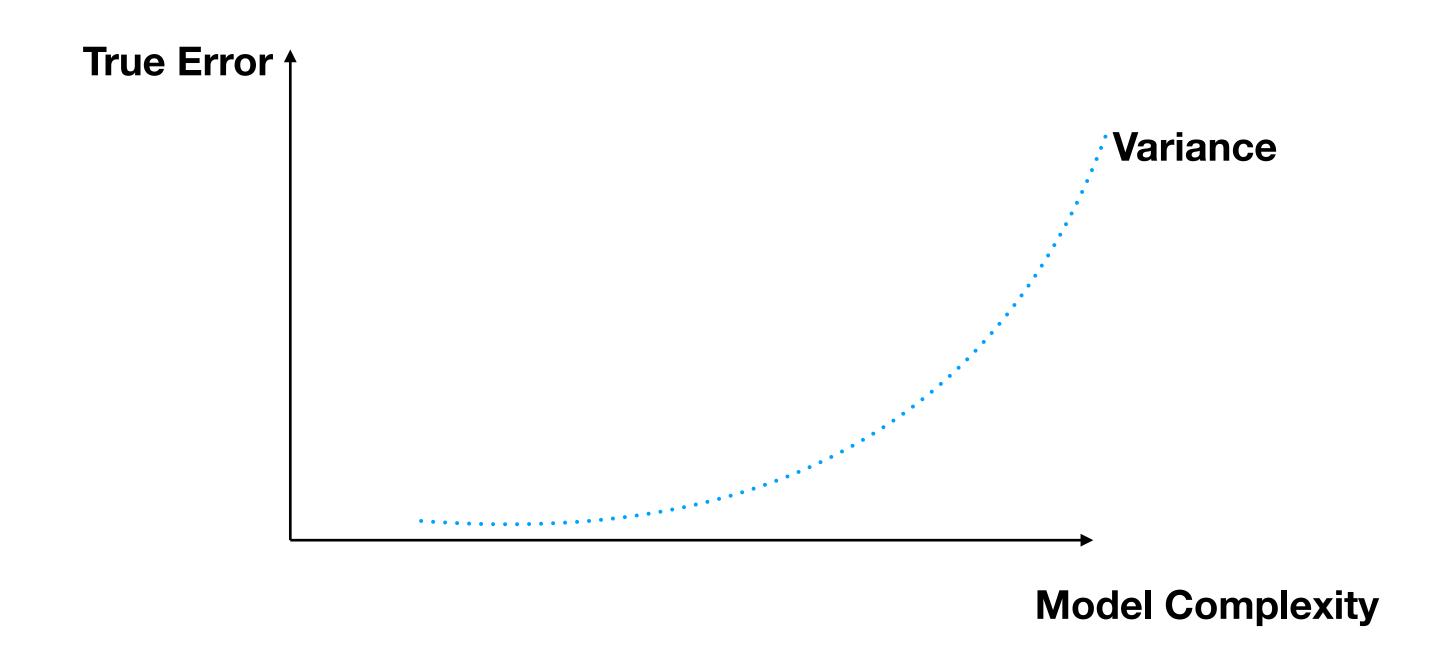
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Variance: $\mathbb{E}_{S \sim \mathscr{D}} \left[(f_S(x_0) - \mathbb{E}_{S' \sim \mathscr{D}} [f_{S'}(x_0)])^2 \right]$



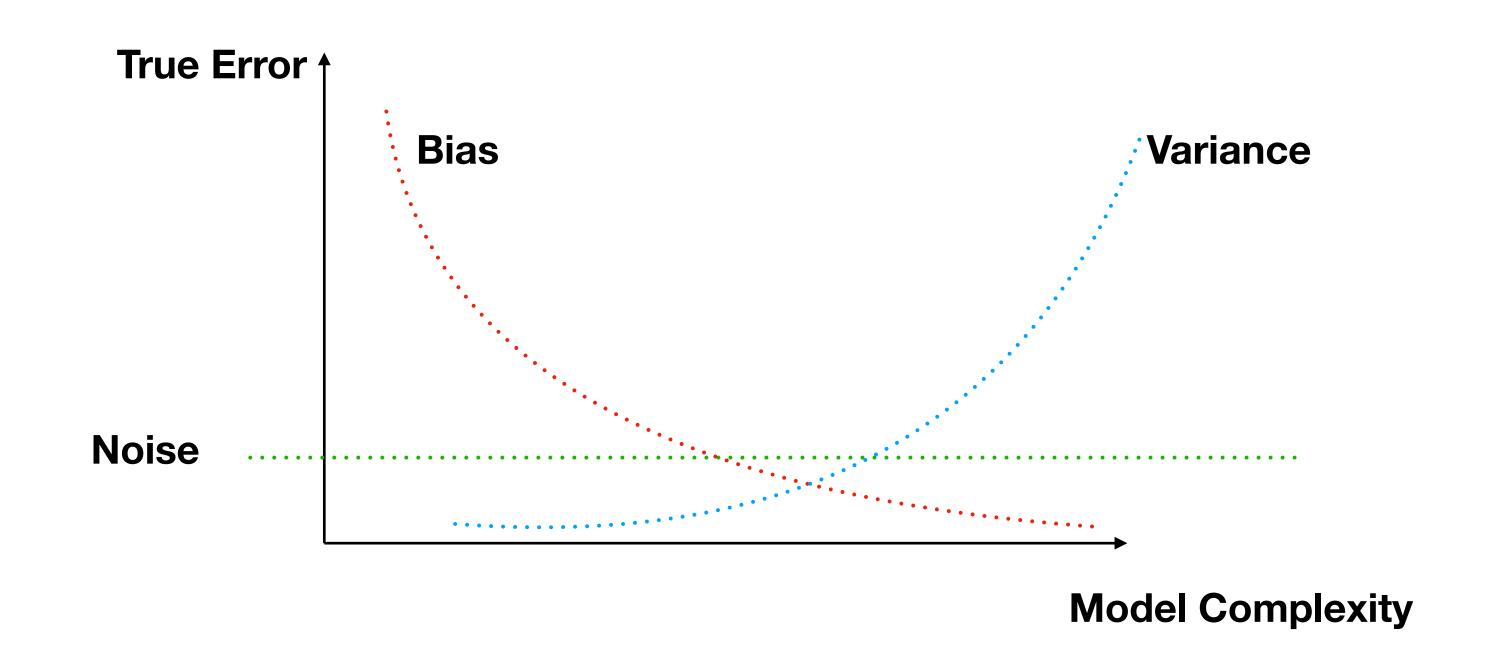
- Variance of the prediction function
- It measures the variability of predictions at a given point across different training set realizations
- If we consider complex models, small variations in the training set can lead to significant changes in the predictions

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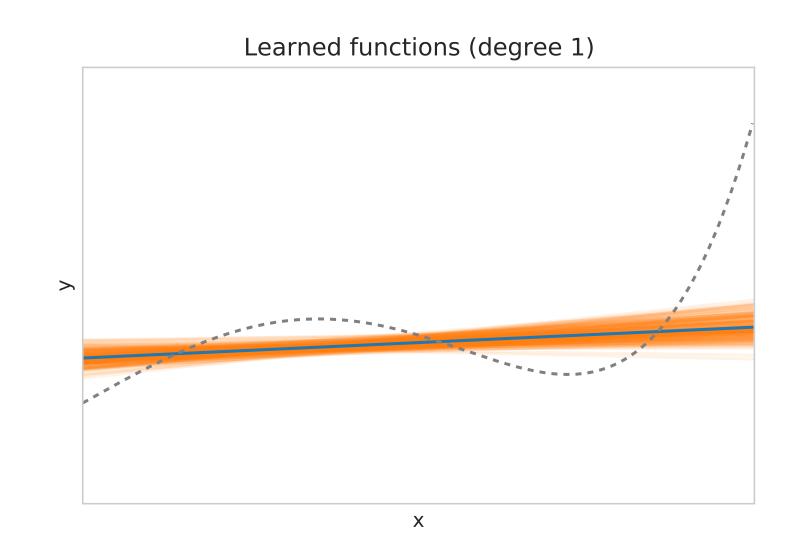
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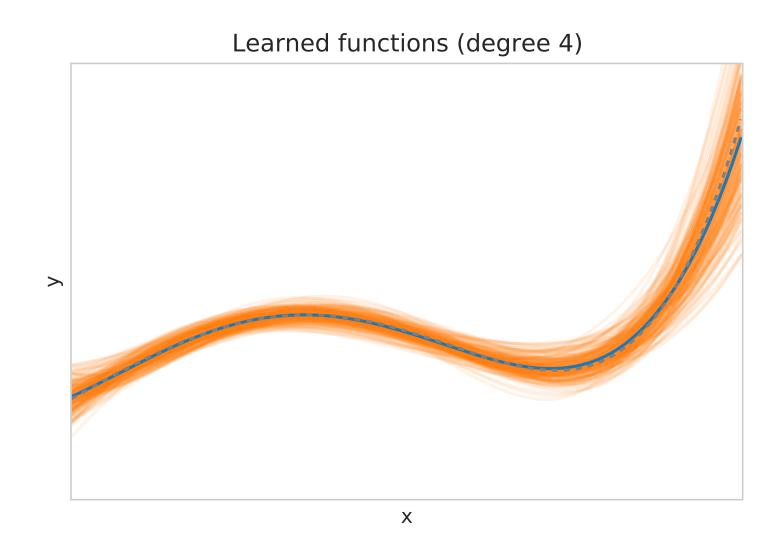
Bias Variance tradeoff and U-shape curve

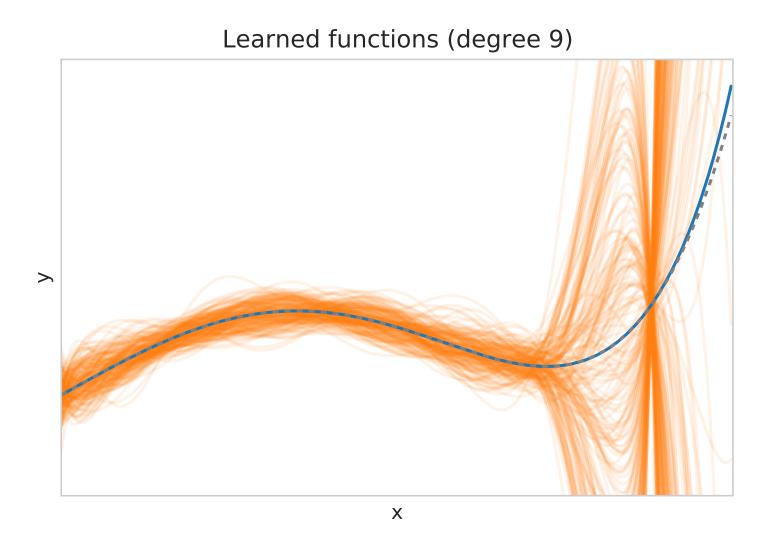


- If model complexity is too low, approximation will be poor (underfitting)
- If model complexity is too high, it may cause issues with variance (overfitting)
 - This phenomenon is known as the bias-variance tradeoff

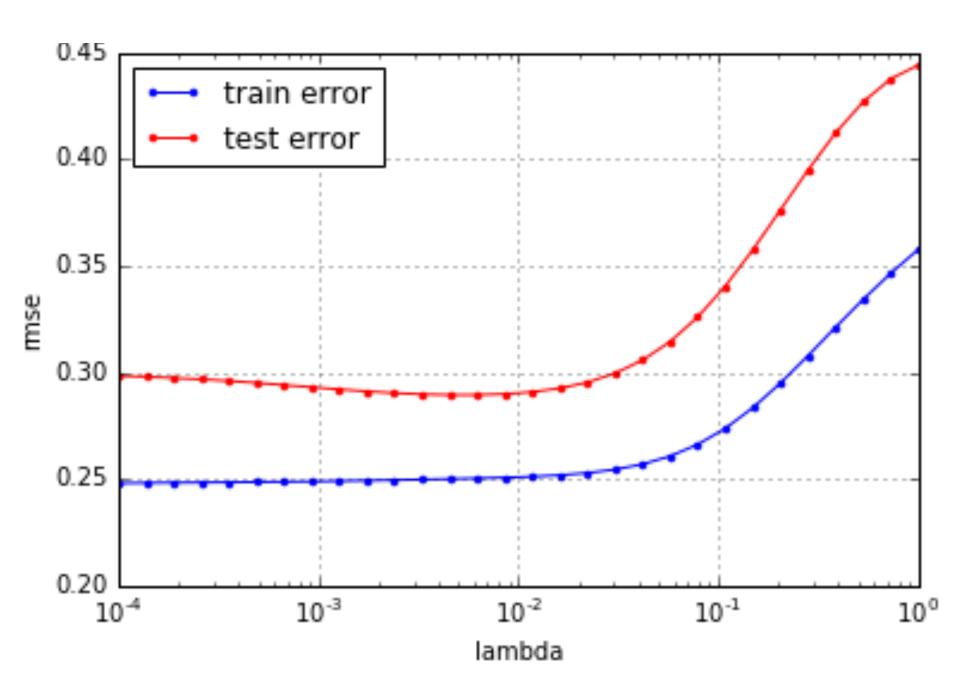
Challenge: Identify a method that ensures both low variance and low bias



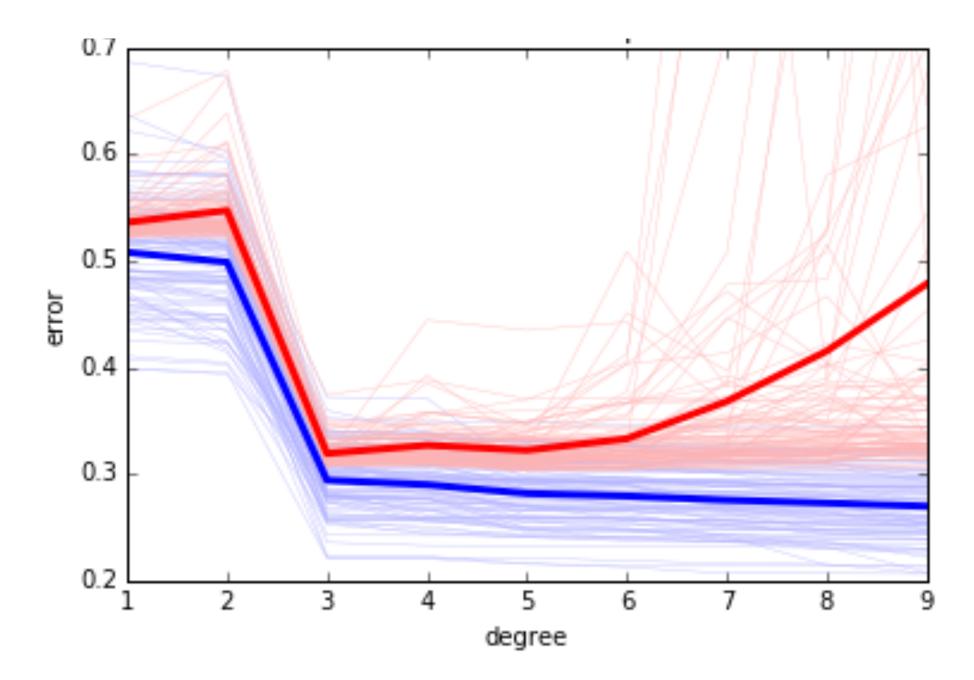




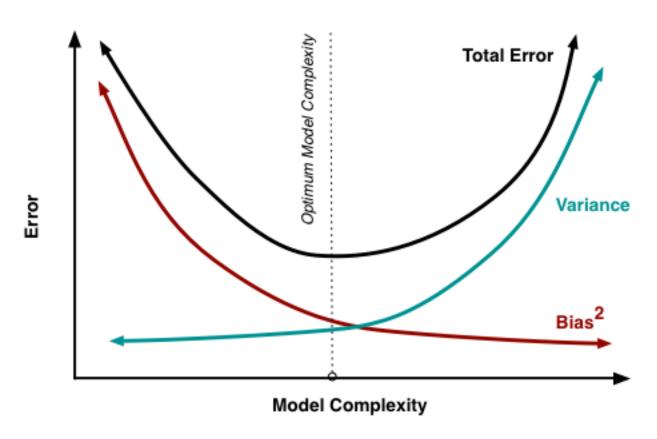
Model selection curves

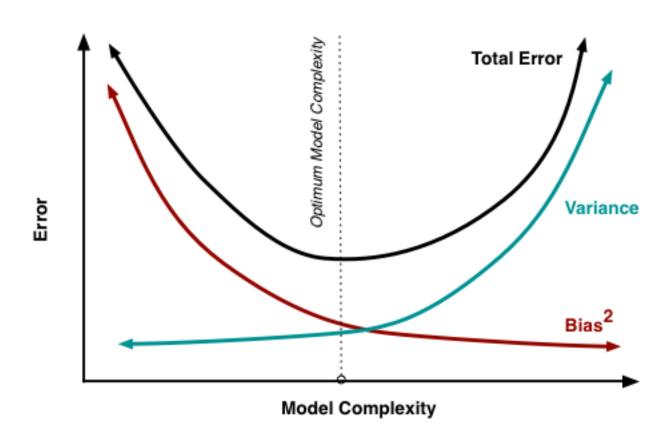


Ridge regression



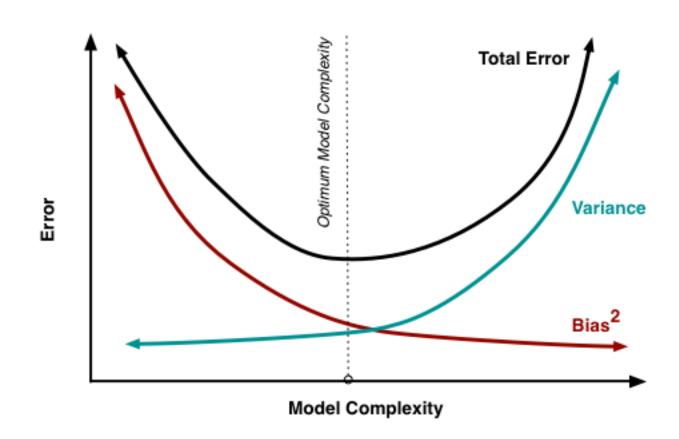
Degree in case of a polynomial feature expansion





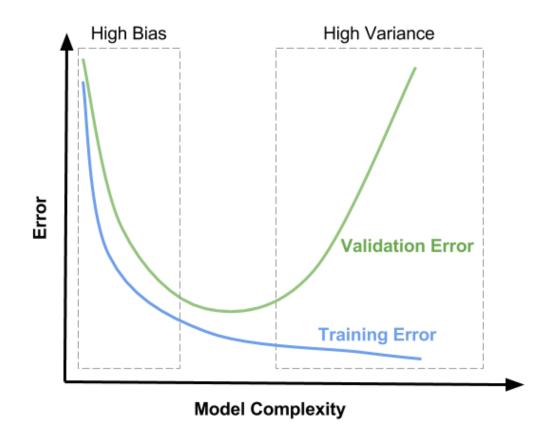
Don't know bias!

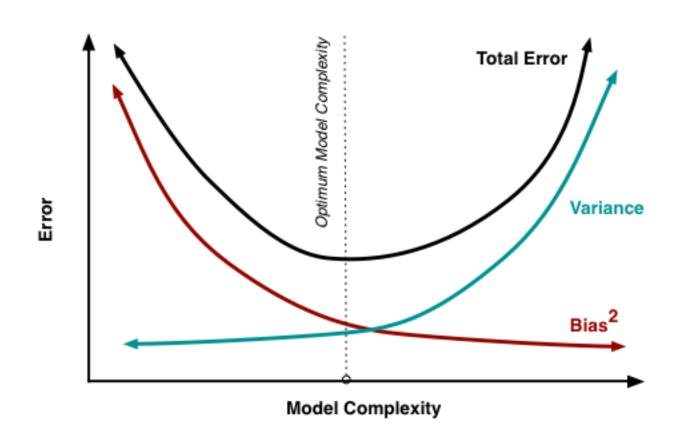
If model is trained only once per complexity level: don't have variance!



Don't know bias!

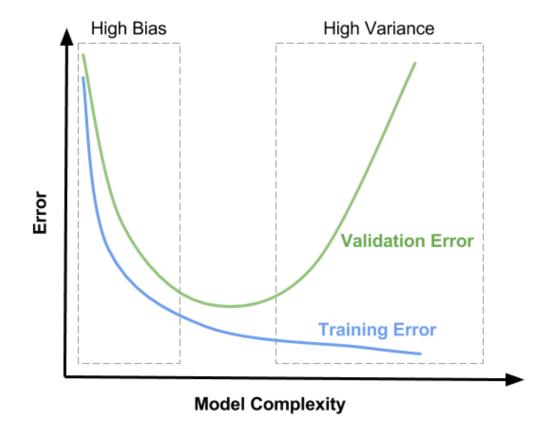
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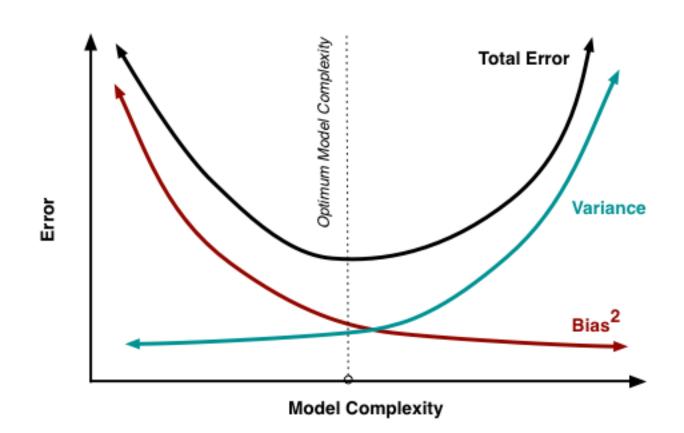


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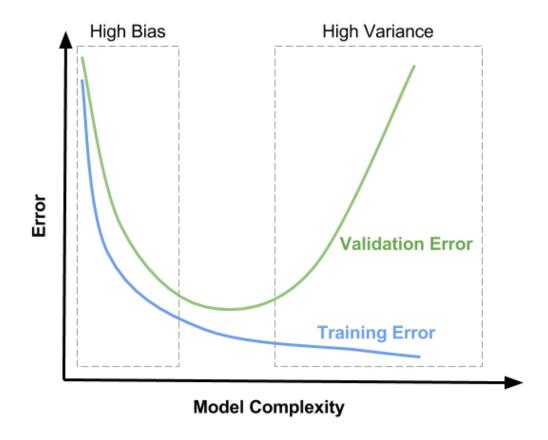


Can't draw curve before sweeping over hyperparameter values!

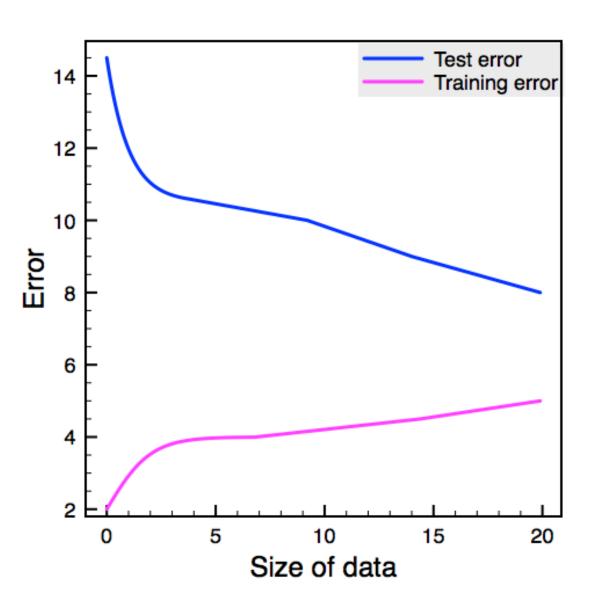


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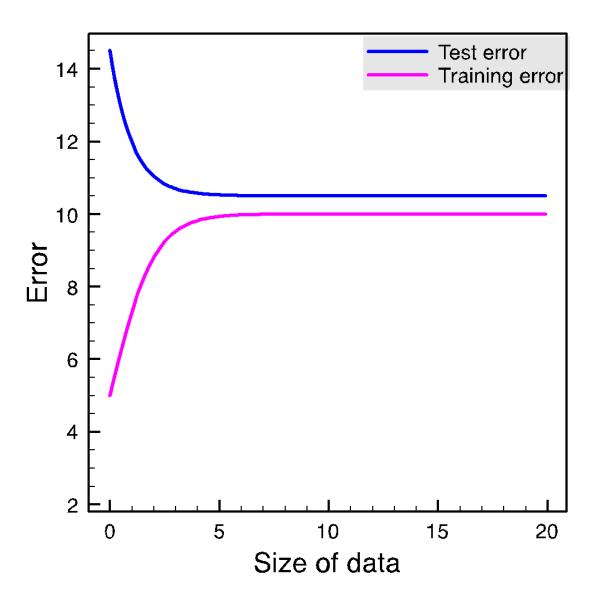
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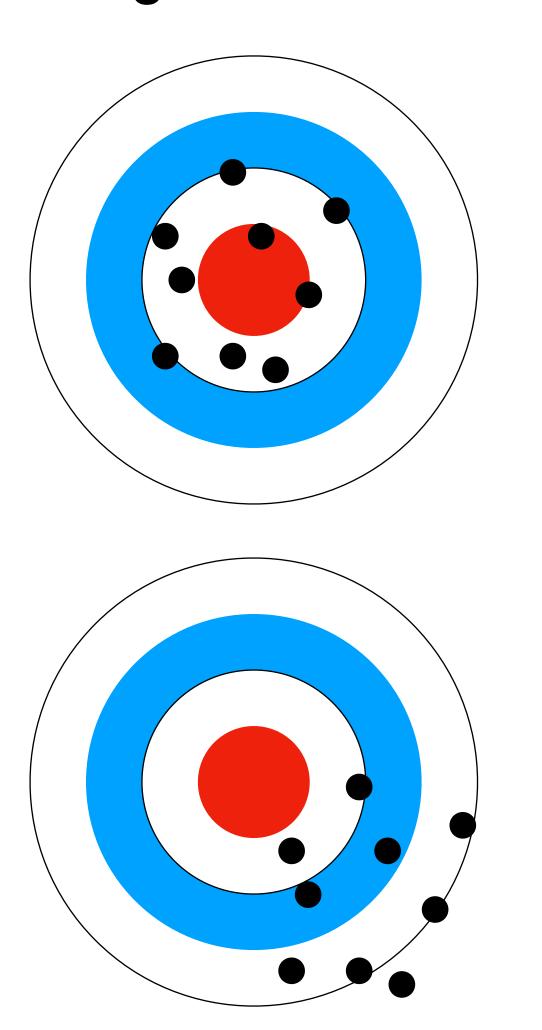
Draw learning curve! (esp. easy w/ SGD)



Conclusion

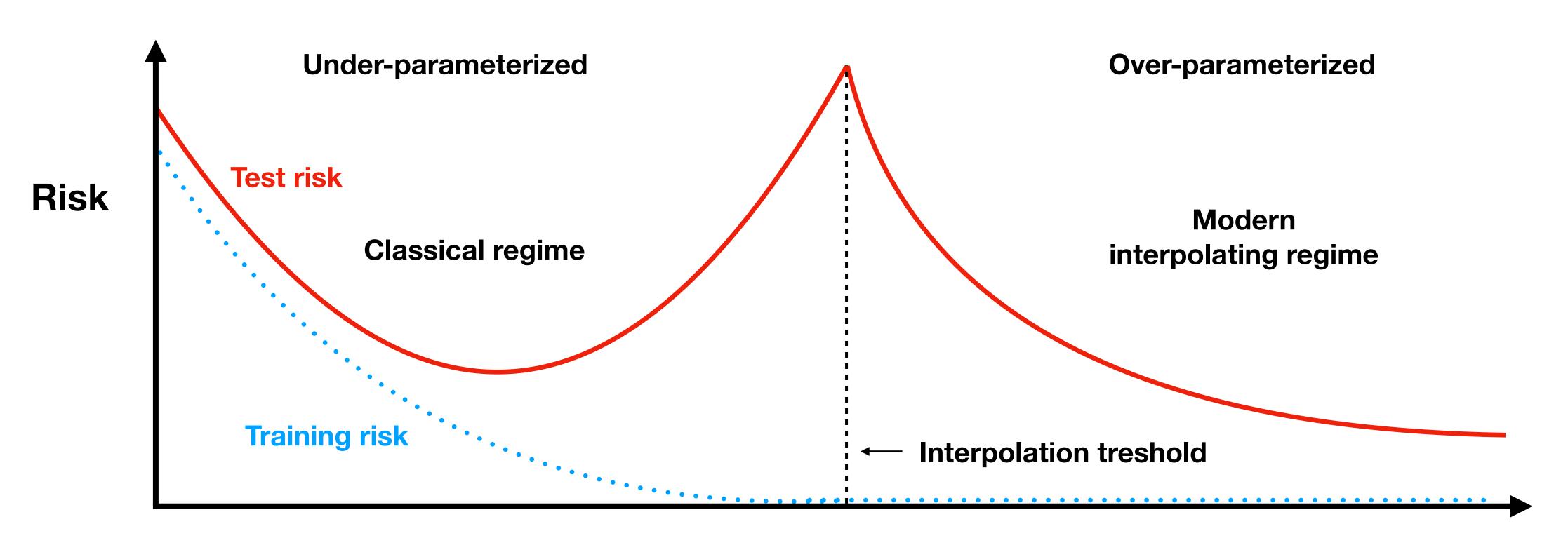
Low Variance Low Bias High Bias

High Variance



But this depends on the algorithm!

Double descent curve



Complexity of the model class