

Computing Steady States with Stan's Nonlinear Algebraic Solver

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Root-finding

Given a function $f(x, \dots)$,

find x^* such that $f(x^*, \dots) = 0$.

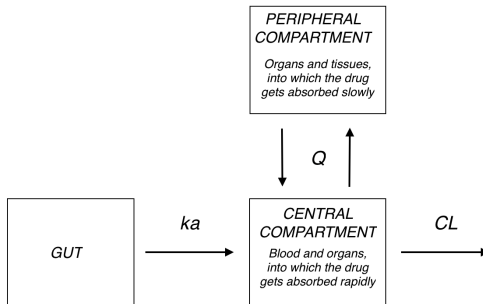
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- physics
- astronomy
- biomedicine
- econometrics
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- and more.

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- physics
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- biomedicine: characterizing patients at steady states.
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- Drug diffusion in the body:



- ODEs describing the drug diffusion model:

$$\frac{dy_{\text{gut}}}{dt} = -k_a y_{\text{gut}}$$

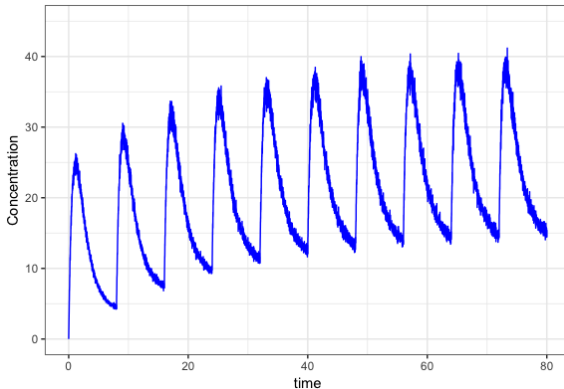
$$\frac{dy_{\text{cent}}}{dt} = k_a y_{\text{gut}} - \left(\frac{CL}{V_{\text{cent}}} + \frac{Q}{V_{\text{cent}}} \right) y_{\text{cent}} + \frac{Q}{V_{\text{peri}}} y_{\text{peri}}$$

$$\frac{dy_{\text{peri}}}{dt} = \frac{Q}{V_{\text{cent}}} y_{\text{cent}} - \frac{Q}{V_{\text{peri}}} y_{\text{peri}}$$

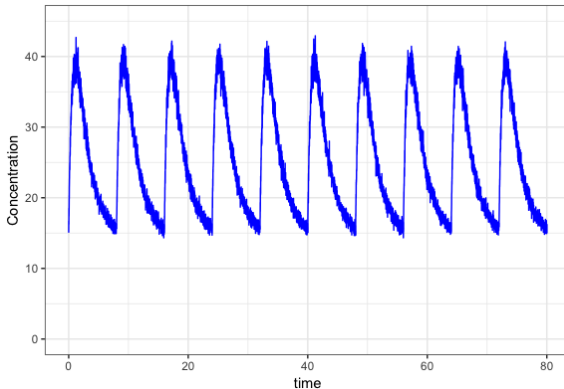
Treatment Cycle

Time	Event
t_0^-	Beginning of the cycle.
t_0^+	Patient receives a dose.
t_0^+ to $t_0 + \tau$	Drug distributes in the body and partially gets cleared.
$t_0 + \tau$	Next cycle begins.

Concentration at the beginning of the treatment



Concentration at steady state



- Let $y(t)$ be the drug mass vector in the patient's body (i.e. in all compartments of the model).
- Let τ be the interdose-interval.
- Steady state is reached when:

$$\mathbf{y}(t + \tau) = \mathbf{y}(t)$$

$$\mathbf{y}(t + \tau) = \mathbf{y}(t)$$
$$\iff \mathbf{y}(t + \tau) - \mathbf{y}(t) = \mathbf{0}$$

The drug mass y depends on:

- y_0 (initial drug mass)
- t : time
- θ : the model parameters
- x : fixed data

Need to find y^* such that:

$$\mathbf{f}(y^*, t, \dots) = \mathbf{y}(y^*, t, \dots) - \mathbf{y}(y^*, t + \tau, \dots) = 0$$

Augmented root-finding problem

For Hamilton Monte Carlo sampling [1, 2, 3] need:

- y^*
- J : the Jacobian of the solution with respect to the parameters θ .

$$J^* = \begin{bmatrix} \frac{\partial y_1^*}{\partial \theta_1} & \cdots & \frac{\partial y_1^*}{\partial \theta_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial y_n^*}{\partial \theta_1} & \cdots & \frac{\partial y_n^*}{\partial \theta_n} \end{bmatrix}$$

A glimpse at the algorithms I

- y^* is computed using a modification of Powell's Hybrid method [4], as implemented in Eigen [5], which is itself based on the MINPACK-1 implementation [6].
- Three tuning parameters:
 - relative tolerance
 - max number of steps
 - Function tolerance: how close is $\|f(y^*)\|$ to 0?

A glimpse at the algorithms II

- The sensitivities is obtained using a lemma of the implicit function theorem:

$$J^* = -[J_y]^{-1} J_\theta$$

- .
- Need J_y to be invertible.
 - Hence the number of unknowns and equations must be the same.

Coding the algebraic equation

```
vector system(vector y, // unknown
              vector theta, // vector of parameters
              real[] x_r, // real data
              real[] x_i) // integer data
{
    vector[2] z;
    z[1] = y[1] - theta[1];
    z[2] = y[1] * y[2] - theta[2];
    return z;
}
```

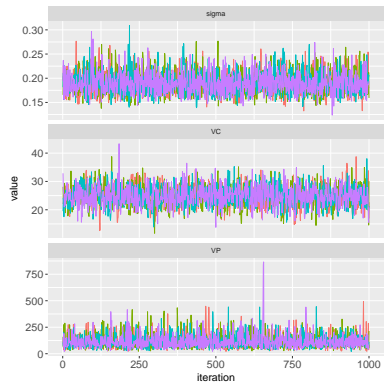
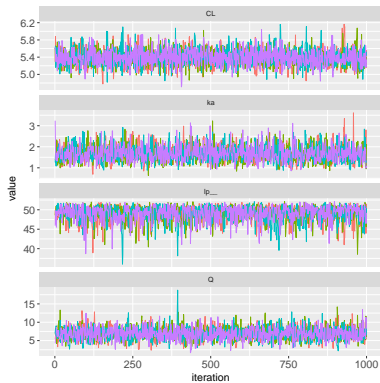
Code for the algebraic equation II

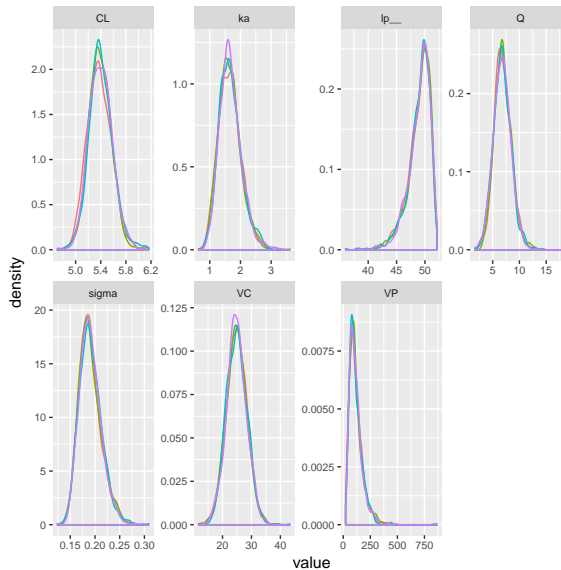
```
vector f(vector y, vector theta, real[] x_r, int[] x_i)
{
    real amt = x_r[2];
    int cmt = x_i[1];
    real y_ii[3] = to_array_1d(y);
    y_ii[cmt] = y_ii[cmt] + amt;
    y_ii = integrate_ode_rk45(twoCptModelODE, y_ii, 0,
                             rep_array(x_r[1], 1),
                             to_array_1d(theta),
                             rep_array(0.0, 1),
                             rep_array(0, 1))[1];

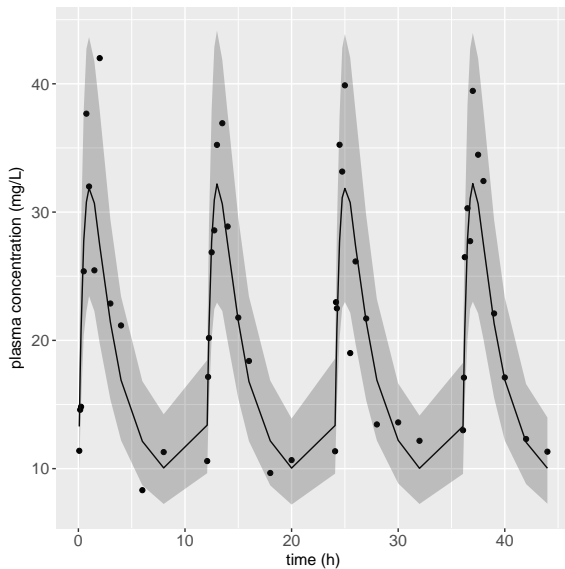
    // return difference between evolved and initial state
    return to_vector(y_ii) - y;
}
```

Example code for algebraic solver

```
y0 = algebra_solver(system, // algebraic equation  
                    y_init,  
                    theta, x_r, x_i,  
                    rel_tol, f_tol, max_num_steps) ;
```







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