

## Unsupervised Learning

### PCA and PCoA

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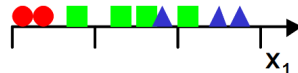
# The Curse of Dimensionality

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- Refers to the problems associated with multivariate data analysis as the dimensionality increases

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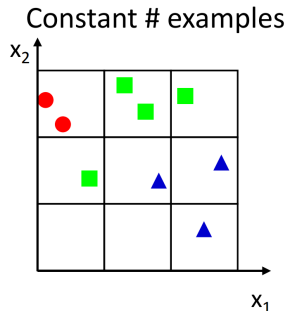
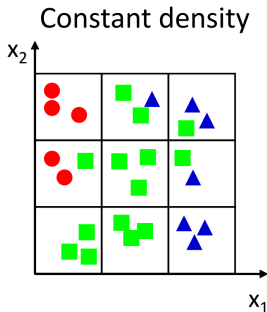
Consider a 3-class pattern recognition problem



- A simple approach would be to
  - Divide the feature space into uniform bins
  - Compute the ratio of examples for each class at each bin and,
  - For a new example, choose the predominant class in its bin
- In our toy problem we decide to start with one single feature and divide the real line into 3 segments
- After doing this, we notice that there exists too much overlap among the classes, so we decide to incorporate a second feature to try and improve separability

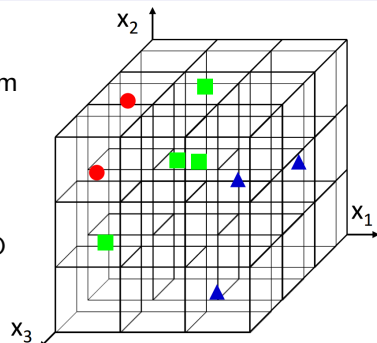
# The Curse of Dimensionality

- Preserving the granularity of each axis results  $3^2 = 9$  bins
- 2 possibilities: maintain the density or maintain the number of examples?
  - Density: increases the number of examples from 9 to 27
  - Examples: results in a 2D scatter plot that is very sparse



# More than two Dimensions

- Moving to three features makes the problem worse:
  - The number of bins grows to  $3^3 = 27$
  - Maintaining the density would require 81 samples
  - For the same number of examples, the 3D scatter plot is almost empty
- Obviously, our approach to divide the sample space into equally spaced bins was quite inefficient
- There are other approaches that are much less susceptible to the curse of dimensionality, but the problem still exists

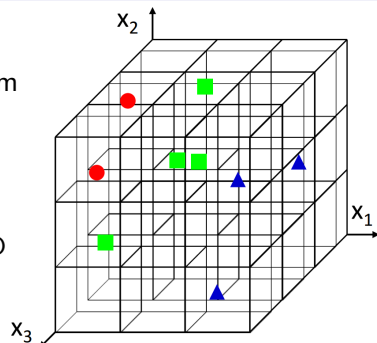


How do we beat the curse of dimensionality?

- In practice, our number of samples and dimensions is fixed
- This is only to demonstrate the problems with dimensionality
- Bottom-line: Reducing the dimensionality can be beneficial

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# Introduction

## A new approach

- The methods we have seen are only feasible for univariate or bivariate data
- For multivariate data, some tricks exist but normally the methods lose a lot of their power
- $\Rightarrow$  We need a different way to cope with multivariate data

# Dimensionality reduction

Two approaches are available to reduce dimensionality

- **Feature extraction** creating a subset of new features by combinations of the existing features
- **Feature selection** choosing a subset of all the features

$$\begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_N \end{bmatrix} \rightarrow \begin{bmatrix} x_{i_1} \\ x_{i_2} \\ \vdots \\ x_{i_M} \end{bmatrix} \quad f \left( \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_N \end{bmatrix} \right) : \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_N \end{bmatrix} \rightarrow \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{bmatrix}$$

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## Feature Extraction

Given a vector  $x$  in feature space  $\mathbb{R}^N$  find a mapping function  $y = f(x) : \mathbb{R}^N \rightarrow \mathbb{R}^M$  with  $M < N$  such that the transformed feature vector  $y \in \mathbb{R}$  preserves most of the information

# Linear Dimensionality Reduction

- In general, the optimal mapping  $y = f(x)$  will be a non-linear function
  - However, there is no systematic way to generate non-linear transforms
  - The selection of a particular subset of transforms is problem dependent
- For these reasons, feature extraction is commonly based on linear transforms, of the form  $y = Wx$

$$\begin{bmatrix} y_1 \\ \vdots \\ y_M \end{bmatrix} = \begin{bmatrix} w_{11} & \cdots & w_{1N} \\ \vdots & \ddots & \vdots \\ w_{M1} & \cdots & w_{MN} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ \vdots \\ x_N \end{bmatrix}$$

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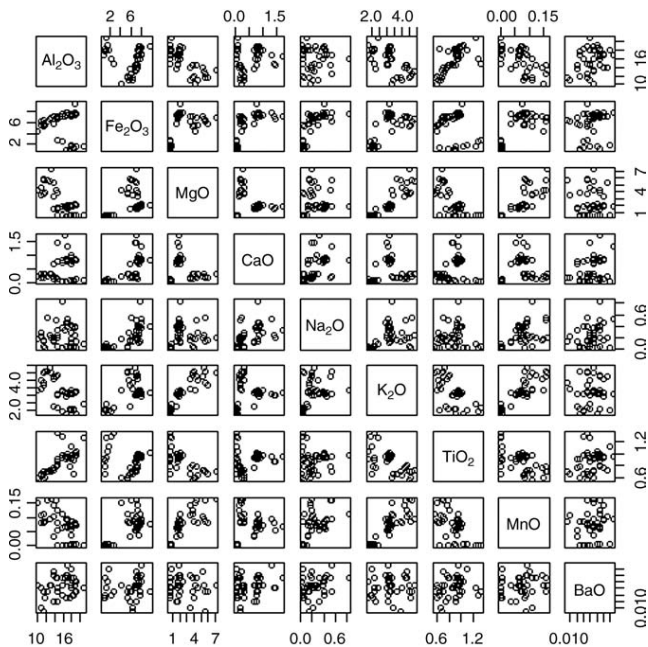
The task of a PCA is to perform a dimensionality reduction in such a way

## Example: Pottery Data

Sample number	Chemical component								
	Al <sub>2</sub> O <sub>3</sub>	Fe <sub>2</sub> O <sub>3</sub>	MgO	CaO	Na <sub>2</sub> O	K <sub>2</sub> O	TiO <sub>2</sub>	MnO	BaO
1	18.8	9.52	2.00	0.79	0.40	3.20	1.01	0.077	0.015
2	16.9	7.33	1.65	0.84	0.40	3.05	0.99	0.067	0.018
3	18.2	7.64	1.82	0.77	0.40	3.07	0.98	0.087	0.014
4	16.9	7.29	1.56	0.76	0.40	3.05	1.00	0.063	0.019
5	17.8	7.24	1.83	0.92	0.43	3.12	0.93	0.061	0.019
6	18.8	7.45	2.06	0.87	0.25	3.26	0.98	0.072	0.017
7	16.5	7.05	1.81	1.73	0.33	3.20	0.95	0.066	0.019
8	18.0	7.42	2.06	1.00	0.28	3.37	0.96	0.072	0.017
9	15.8	7.15	1.62	0.71	0.38	3.25	0.93	0.062	0.017

- The data show the chemical compounds of ancient pottery
- The table is very unintuitive
- Let's look at the scatter-plots

# Pottery Data: Scatter-Plots





**Lower Dimensional Projections**



# How it works?

## Observation

- In the example some structure became suddenly visible
- Now the data suggest to contain 3 clusters
- BUT: How do we derive these components?

## General Approach

- The PCA performs a basis transformation, in which the first basis vector is the vector accounting for most of the variance in the dataset, the second for the most of the remaining variance and so on ...
- These basis vectors can be found by the eigenvalue decomposition of the covariance matrix  $Q$  or the sample correlation matrix  $R$ .
- The eigenvalues  $\lambda_1, \dots, \lambda_d$  indicate the variance of the eigenvectors  $y_1, \dots, y_d$

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# Let's look into details

- Don't panic, we won't go too much into details
- We will perform a small PCA step by step
- Many of the following slides are taken and adapted from:  
<http://www.cse.psu.edu/~rcollins/CSE586Spring2010/>
  - this is a computer vision class ... just so you can see how often you will be faced with a PCA

# The Covariance

- Variance and Covariance are a measure of the “spread” of a set of points around their center of mass (mean)
- Variance – measure of the deviation from the mean for points in one dimension e.g. heights
- Covariance as a measure of how much each of the dimensions vary from the mean with respect to each other
- Covariance is measured between 2 dimensions to see if there is a relationship between the 2 dimensions e.g. number of hours studied & marks obtained
- The covariance between one dimension and itself is the variance

# Covariance

- The covariance is defined as

$$\text{Cov}(X, Y) = \frac{1}{n-1} \sum_{i=1}^n (x_i - \bar{X})(y_i - \bar{Y})$$

- This is the observed covariance for  $n$  observations  $(x_i, y_i)$
- $\bar{X}$  and  $\bar{Y}$  are the observed mean of the two given dimensions, i.e.,

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# The Covariance Matrix

## Definition

- The covariance can be calculated between each pair of dimensions
- We can put all of the in a Matrix, e.g., for three dimensions  $X, Y, Z$ :

$$C = \begin{pmatrix} \text{Cov}(X, X) & \text{Cov}(X, Y) & \text{Cov}(X, Z) \\ \text{Cov}(Y, X) & \text{Cov}(Y, Y) & \text{Cov}(Y, Z) \\ \text{Cov}(Z, X) & \text{Cov}(Z, Y) & \text{Cov}(Z, Z) \end{pmatrix}$$

## Properties

- Diagonal is the variances of  $X, Y$  and  $Z$
- $\text{Cov}(X, Y) = \text{Cov}(Y, X)$  hence matrix is symmetrical about the diagonal
- $d$ -dimensional data will result in  $d \times d$  covariance matrix

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# What does a Covariance mean in the first place?

- The covariance is not bound to a certain range of values (e.g., between  $[0, 1]$ )
- So, what does a covariance of 37.6 mean?
  - In terms of covariance, the sign is more important than the value
  - Positive: Both dimensions increase/decrease together
  - Negative: While one dimension increases the other decreases
  - Zero: The two dimensions are independent of each other

## Remember:

- By finding the eigenvalues and eigenvectors of the covariance matrix, we find that the eigenvectors with the largest eigenvalues correspond to the dimensions that have the strongest correlation in the dataset
- This is the principal component

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# Back to PCA

Let  $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n$  be a set of  $d$  dimensional vectors. Further, let  $\bar{\mathbf{x}}$  be the mean-vector:

$$\mathbf{x}_i = \begin{pmatrix} x_{i1} \\ x_{i2} \\ \vdots \\ x_{id} \end{pmatrix} \quad \bar{\mathbf{x}} = \frac{1}{n} \sum_{i=1}^n \begin{pmatrix} x_{i1} \\ x_{i2} \\ \vdots \\ x_{id} \end{pmatrix}$$

Furthermore, let  $X$  be the  $d \times n$ -matrix of the form

$$X = (\mathbf{x}_1 - \bar{\mathbf{x}} \quad \mathbf{x}_2 - \bar{\mathbf{x}} \quad \dots \quad \mathbf{x}_n - \bar{\mathbf{x}})$$

Which is basically just the dataset centered around the mean

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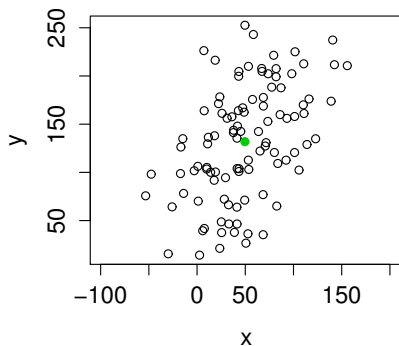
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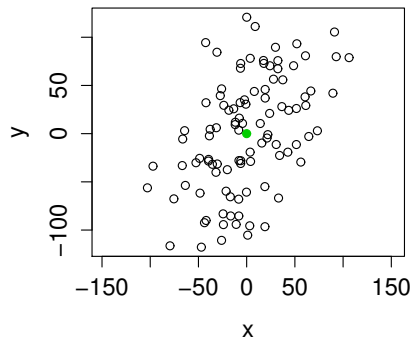
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# What we have so far:

## Original Data



## Centered Data





# The Covariance Matrix

Now, the Covariance matrix  $Q$  can easily be calculated as  $Q = XX^\top$  which is

$$Q = \frac{1}{n-1}XX^\top = \frac{1}{n-1}(\mathbf{x}_1 - \bar{\mathbf{x}} \quad \mathbf{x}_2 - \bar{\mathbf{x}} \quad \dots \quad \mathbf{x}_n - \bar{\mathbf{x}}) \begin{pmatrix} (\mathbf{x}_1 - \bar{\mathbf{x}})^\top \\ (\mathbf{x}_2 - \bar{\mathbf{x}})^\top \\ \vdots \\ (\mathbf{x}_n - \bar{\mathbf{x}})^\top \end{pmatrix}$$

Note:

- $Q$  is square
- $Q$  is symmetric
- $Q$  is a  $d \times d$  matrix

# Perform the PCA

- Now, the Eigenvectors  $e_1, \dots, e_d$  of  $Q$  give us the principal components
- How does us help that?
- Each  $\mathbf{x}_j$  can now be written as

$$\mathbf{x}_j = \bar{\mathbf{x}} + \sum_{i=1}^d g_{ij} e_i$$

where  $e_i$  are the eigenvectors of  $Q$  with non-zero eigenvalues

- The eigenvectors span the eigenspace
- The scalars  $g_{ij}$  are the coordinates of  $x_i$  in the space

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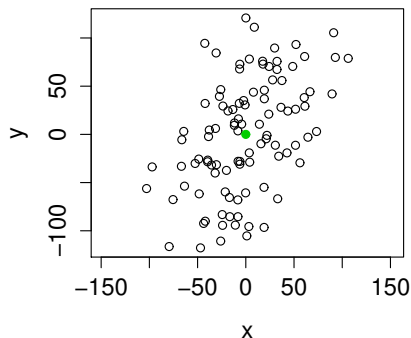
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# Our Small Example

## Centered Data



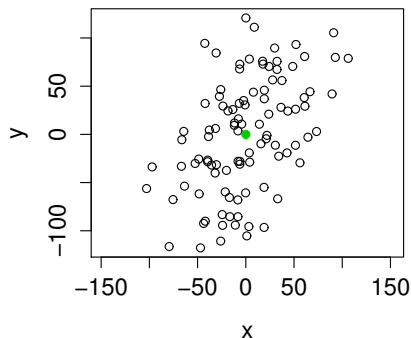
- The basis vectors are

$$e_1 = \begin{pmatrix} 0.45 \\ 0.89 \end{pmatrix}$$

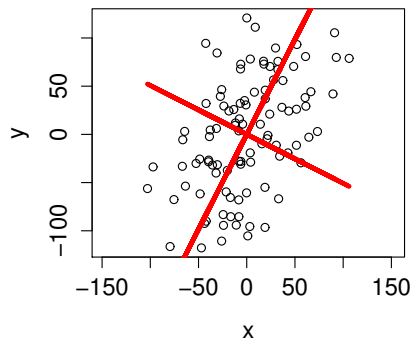
$$e_2 = \begin{pmatrix} -0.89 \\ 0.454 \end{pmatrix}$$

# Our Small Example

## Centered Data



## Principal Components

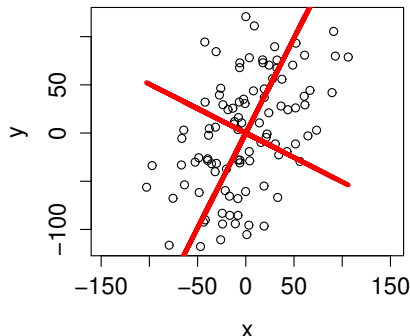


- The basis vectors are

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# We also can rotate the data

## Principal Components



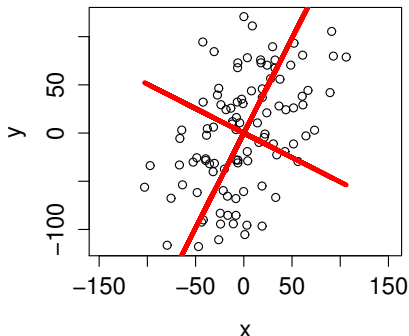
- The rotation points can be calculated by

$$R = E^T \cdot X^T$$

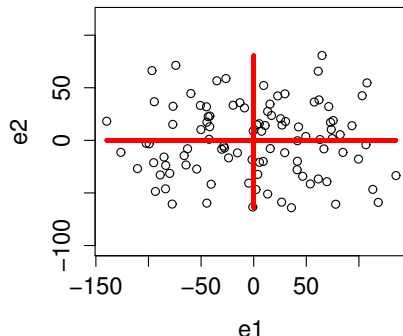
with  $E$  being the matrix of the eigenvectors  $E = (\mathbf{e}_1 \quad \mathbf{e}_2 \quad \dots \quad \mathbf{e}_d)$   
and  $X$  the mean-corrected dataset

# We also can rotate the data

## Principal Components



## Rotated



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# What now? - Using the PCA for Dimensionality Reduction

- Fantastic, all that stuff in order to rotate some data?
- Expressing  $X$  in terms of  $\mathbf{e}_1, \dots, \mathbf{e}_1$  has not changed the size of the data at all, we just performed a basis transformation
- **BUT:** Hopefully, most of the new coordinates have values close to zero (as there is almost no variance "left" when calculating the PCAs)
- That means in turn, the data lie in a lower-dimensional linear subspace ...
- Thus, we don't use all of the eigenvectors to transform the data
- Which ones should we take?

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# Dimensionality Reduction with PCA

- Let  $\lambda_i$  be the eigenvalue belonging to the eigenvector  $\mathbf{e}_i$
- Assume, the list of eigenvectors is sorted such that the according eigenvalues fulfill

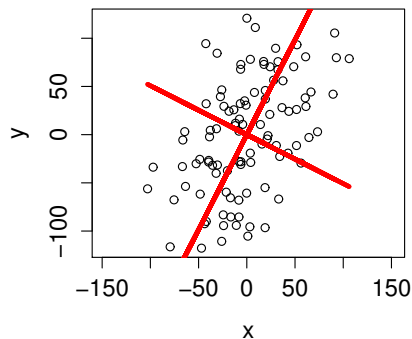
$$\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_n$$

- Assume  $\lambda_i \approx 0$  when  $i > k$
- Then

$$\mathbf{x}_j \approx \bar{\mathbf{x}} + \sum_{i=1}^k g_{ij} \mathbf{e}_i$$

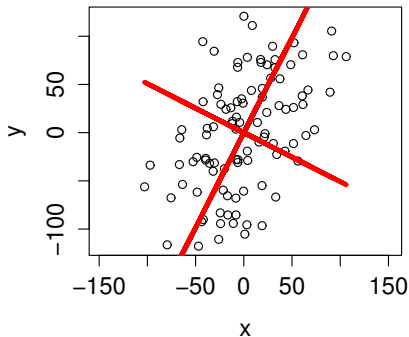
# In Our Example

## Principal Components

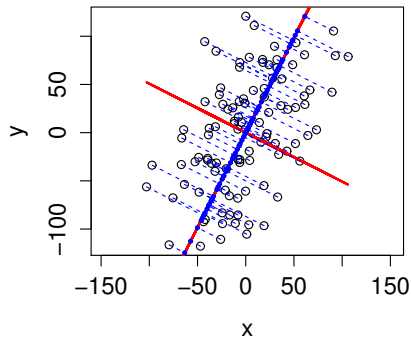


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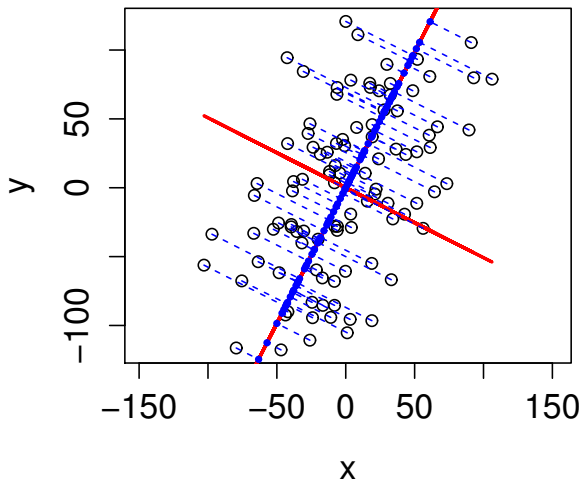


## Lower Dimensional Projection



## Zoom in

## Lower Dimensional Projection



# Some Final Remarks

- Obviously, a PCA makes more sense, when performed on higher dimensional data
- We have not looked at any proofs (i.e., do the eigenvectors actually give us the vectors with the most variance?)
- We haven't discussed how to find eigenvectors efficiently
  - Most programming languages have implementations available
  - For example `eigen(X)` in R
- The lost of variance can actually be calculated by

$$\frac{\sum_{i=0}^k \mathbf{e}_i}{\sum_{i=0}^d \mathbf{e}_i}$$

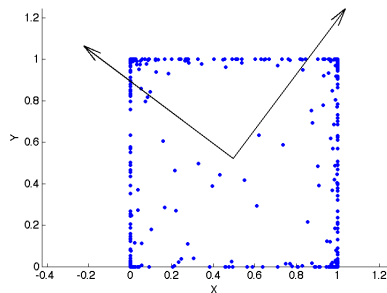
where  $k$  is the number of "used" coordinates

# Problems with PCA

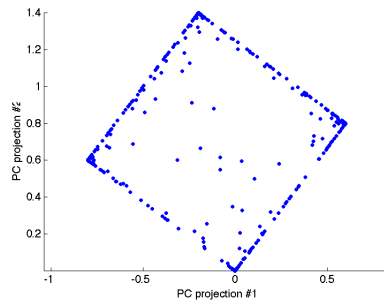
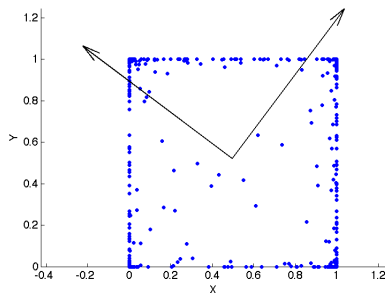
- PCA is not without its problems and limitations
- PCA assumes approximate normality of the input space distribution
- PCA may still be able to produce a “good” low dimensional projection of the data even if the data isn’t normally distributed
- PCA may “fail” if the data lies on a “complicated” manifold
- PCA assumes that the input data is real and continuous



# Problems with PCA



# Problems with PCA



## Lower-Dimensional Projections

# Multidimensional Scaling

# Goal of Multidimensional Scaling

- Detecting underlying structure
- Represent data in lower dimensional space so that distances are preserved
  - Distances between data points are mapped to a reduced space
  - In other words, we are looking for a projection of the data measured with some distance into an Euclidean space
- Typically displayed on a 2-d plot
- We will briefly discuss
  - Metric (or classic) multidimensional scaling
  - Non-metric multidimensional scaling

The following slides are based on <http://www.cs.toronto.edu/~bonner/courses/2007s/csc411/lectures/16mds.pdf> and <http://www.cedar.buffalo.edu/~srihari/CSE626/Lecture-Slides/Ch3-part2-PCA.pdf>

# Metric (or classic) multidimensional scaling

- Recall: given a  $n \times d$  two-mode dataset containing the vectors  $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n$ .
- Assume the data is already centered around 0, i.e.,  $\bar{\mathbf{x}} = \mathbf{0}$ 
  - Just makes the rest easier, performing a shift as seen before is no problem!
- Now consider again the matrix  $X = \{\mathbf{x}_1 \quad \mathbf{x}_2 \quad \dots \quad \mathbf{x}_n\}$
- Recall:  $XX^\top$  gave us the  $d \times d$  Covariance matrix
- The  $n \times n$  Matrix  $B = X^\top X$  is also very useful
- In fact, we will see on the next slide, that the Euclidean distance is given by

$$d_{ij}^2 = b_{ii} + b_{jj} - 2b_{ij}$$

# Metric (or classic) multidimensional scaling

- Recall: given a  $n \times d$  two-mode dataset containing the vectors  $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n$ .
- Assume the data is already centered around 0, i.e.,  $\bar{\mathbf{x}} = \mathbf{0}$ 
  - Just makes the rest easier, performing a shift as seen before is no problem!
- Now consider again the matrix  $X = \{\mathbf{x}_1 \quad \mathbf{x}_2 \quad \dots \quad \mathbf{x}_n\}$
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## Closer look at $X^\top X$

Let  $n = 4, d = 3$ , then

$$B = X^\top X = \begin{pmatrix} x_{11} & x_{12} & x_{13} \\ x_{21} & x_{22} & x_{23} \\ x_{31} & x_{32} & x_{33} \\ x_{41} & x_{42} & x_{43} \end{pmatrix} \times \begin{pmatrix} x_{11} & x_{21} & x_{31} & x_{41} \\ x_{12} & x_{22} & x_{32} & x_{42} \\ x_{13} & x_{23} & x_{33} & x_{43} \end{pmatrix} =$$
$$= \begin{pmatrix} b_{11} = \sum_{d=1}^3 x_{1d}^2 & b_{12} = \sum_{d=1}^3 x_{1d}x_{2d} & b_{13} & b_{14} \\ b_{21} & b_{22} & b_{23} & b_{24} \\ b_{31} & b_{32} & b_{33} & b_{34} \\ b_{41} & b_{42} & b_{43} & b_{44} \end{pmatrix}$$

Remember the definition of the Euclidean distance, we get:

$$d_{ij}^2 = \sum_{d=1}^3 (x_{id} - x_{jd})^2 = b_{ii} + b_{jj} - 2b_{ij}$$

\* note the rather unusual indices in the matrix, because we wrote each vector  $\mathbf{x}_i$  in a column. Sometimes, you find  $X$  being defined as having each vector in a row which only changes the position of the transposed sign.

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# Non-Metric Multidimensional Scaling

- We will just have a brief overview
- Sometimes, distances are not given with metric distance
  - We will learn more about distances later on
- **Given:** A dataset  $X$  and a distance matrix  $D$  containing pair-wise distances obtained in any fashion appropriate for the data
- **Goal:** A representation  $Y$  in 2-D or 3-D space preserving (as good as possible) the pair-wise distances given in  $D$

# Multidimensional Scaling

To write the last slide a little bit more formally

- Let  $\delta_{ij}$  denote the distance between object  $x_i$  and  $x_j$  given in the distance matrix  $D$
- Let  $y_i = (y_{i1}, \dots, y_{id})$  the representation of  $x_i$  in a  $d$ -dimensional euclidean space
- Let  $d_{ij}$  denote the Euclidean distance between  $y_i$  and  $y_j$
- Goal:  $\forall i, j : d_{ij} \approx \delta_{ij}$
- Exact equality generally not possible, so minimize an error function  $J$

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$$J_1 = \frac{\sum_{i < j} (d_{ij} - \delta_{ij})^2}{\sum_{i < j} \delta_{ij}^2}$$

(penalizes large absolute errors)

$$J_2 = \sum_{i < j} \left( \frac{d_{ij} - \delta_{ij}}{\delta_{ij}} \right)^2$$

(penalizes large relative errors)

(a compromise between the two)

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$$J_3 = \frac{1}{\sum_{i < j} \delta_{ij}} \sum_{i < j} \frac{(d_{ij} - \delta_{ij})^2}{\delta_{ij}}$$

(a compromise between the two)

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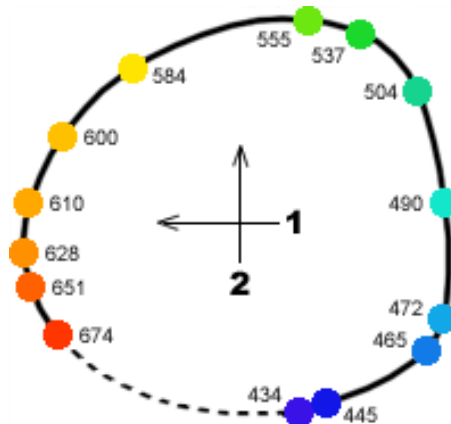
- Normally, an iterative algorithm using some version of steepest descent is employed
- General Procedure:
  - 1 Obtain the distances  $\delta_{ij}$
  - 2 Initialize  $Y$  (e.g., randomly)
  - 3 Calculate gradient updates and update point positions accordingly
  - 4 Repeat
- Gradient formula, e.g.:

# Algorithms

- Normally, an iterative algorithm using some version of steepest descent is employed
- General Procedure:
  - 1 Obtain the distances  $\delta_{ij}$
  - 2 Initialize  $Y$  (e.g., randomly)
  - 3 Calculate gradient updates and update point positions accordingly
  - 4 Repeat
- Gradient formula, e.g.:

$$\nabla J_1 = \frac{2}{\sum_{i < j} \delta_{ij}^2} \sum_{j \neq k} (d_{kj} - \delta_{kj}) \frac{y_k - y_j}{d_{kj}}$$

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- People were ask to judge the similarity between 14 colors
- Circle resembles the well-known color circle

Original Study: MLA Shepard, Roger N. "The analysis of proximities: Multidimensional scaling with an unknown distance function. II." *Psychometrika* 27.3 (1962): 219-246. Colorized picture taken from: <https://www.handprint.com/HP/WCL/color2.html>

## Remarks & Conclusion

## Remarks

- What we have seen here, is the so-called
  - Principal Coordinate Analysis (PCO) or metric multidimensional scaling (MDS) or classical scaling
  - Non-metric multidimensional scaling
- There are even more methods ...

## Limitations

- When there are too many data points structure becomes obscured
- Highly sophisticated transformations of the data (compared to scatter plots and PCA)
  - E.g., introduction of artifacts