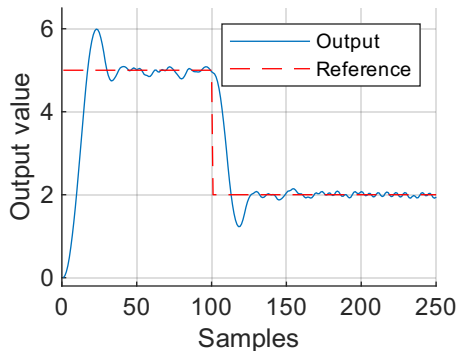
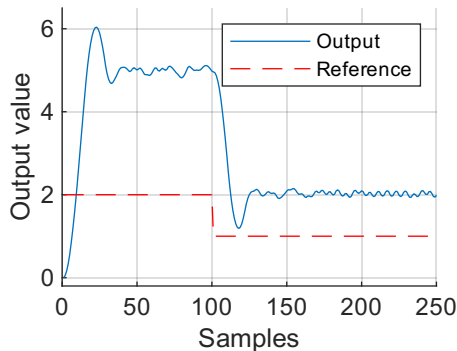
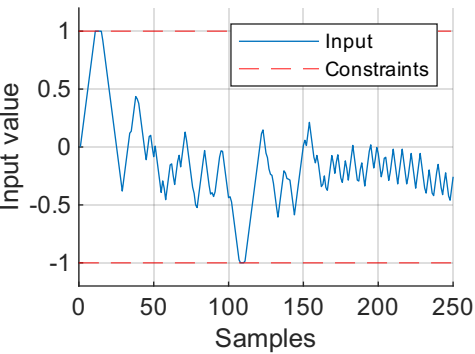


**System output  $y_1$** **System output  $y_2$** **Control input  $u_1$** **Control input  $u_2$** 