

Exercises from Shan Shan's lectures

Simon Holm
AI503: Calculus
Teacher: Shan Shan

Contents

1. Lecture 1	5
1.1. Problem 1	5
1.2. Problem 2	5
1.3. Problem 3	5
1.4. Problem 4	8
2. Lecture 2	9
2.1. Problem 1	9
2.2. Problem 2	9
2.3. Problem 3	10
2.4. Problem 4	10
2.5. Problem 5	11
2.6. Problem 6	12
2.7. Problem 7	12
2.8. Problem 8	12
2.9. Problem 9	13
2.10. Problem 10	13
2.11. Problem 11	14
2.12. Problem 12	14
3. Lecture 3	15
3.1. Problem 1	15
3.2. Problem 2	15
3.3. Problem 3	15
3.4. Problem 4	15
3.5. Problem 5	16
3.6. Problem 6	16
3.7. Problem 7	17
3.8. Problem 8	18
3.9. Problem 9	19
3.10. Problem 10	20
3.11. Problem 11	21
3.12. Problem 12	21
4. Lecture 4	22
4.1. Problem 1	22
4.2. Problem 2	23
4.3. Problem 3	24
4.4. Problem 4	26
4.5. Problem 5	27
4.6. Problem 6	27
4.7. Problem 7	27
4.8. Problem 8	28
4.9. Problem 9	29
4.10. Problem 10	29
4.11. Problem 11	30
4.12. Problem 12	30
4.13. Problem 13	31
4.14. Problem 14	32

5. Lecture 5	33
5.1. Problem 1	33
5.2. Problem 2	33
5.3. Problem 3	33
5.4. Problem 4	34
5.5. Problem 5	34
5.6. Problem 6	35
5.7. Problem 7	36
5.8. Problem 8	36
6. Lecture 6	37
6.1. Problem 1	37
6.2. Problem 2	38
6.3. Problem 3	39
6.4. Problem 4	42
6.5. Problem 5	42
6.6. Problem 6	43
6.7. Problem 7	43
6.8. Problem 8	45
6.9. Problem 7	46
6.10. Problem 8	47
6.11. Problem 9	48
7. Lecture 7	49
7.1. Problem 1	49
7.2. Problem 2	49
7.3. Problem 3	50
7.4. Problem 4	50
7.5. Problem 5	50
8. Lecture 8	51
8.1. Problem 1	51
8.2. Problem 2	51
8.3. Problem 3	52
8.4. Problem 4	53
8.5. Problem 5	53
8.6. Problem 6	54
8.7. Problem 7	54
8.8. Problem 8	55
8.9. Problem 9	55
8.10. Problem 10	56
8.11. Problem 11	56
9. Lecture 9	58
9.1. Problem 1	58
9.2. Problem 2	58
9.3. Problem 3	59
9.4. Problem 4	59
9.5. Problem 5	60
9.6. Problem 6	60
9.7. Problem 7	61

9.8. Problem 8	61
9.9. Problem 9	62
9.10. Problem 10	62
9.11. Problem 11	63
9.12. Problem 12	63
9.13. Problem 13	64
9.14. Problem 14	65
9.15. Problem 15	66
9.16. Problem 16	67
9.17. Problem 17	68
10. Lecture 10	70
11. Lecture 11	70
11.1. Problem 1	70
11.2. Problem 2	71
11.3. Problem 3	71
11.4. Problem 4	71
11.5. Problem 5	72
11.6. Problem 6	73
12. Lecture 12	73

1. Lecture 1

1.1. Problem 1

$f(x)$ linear with $f(2) = 4, f(4) = -2$.

Find $f(x)$.

1.1.1. Solution

$$f(x) = -3x + 10$$

1.2. Problem 2

$g(x)$ linear with slope 6, $g(5) = 9$.

Find $g(x)$.

1.2.1. Solution

$$9 = 6 \cdot 5 + c$$

$$c = 9 - 6 \cdot 5 \Rightarrow c = 21$$

$$g(x) = 6x - 21$$

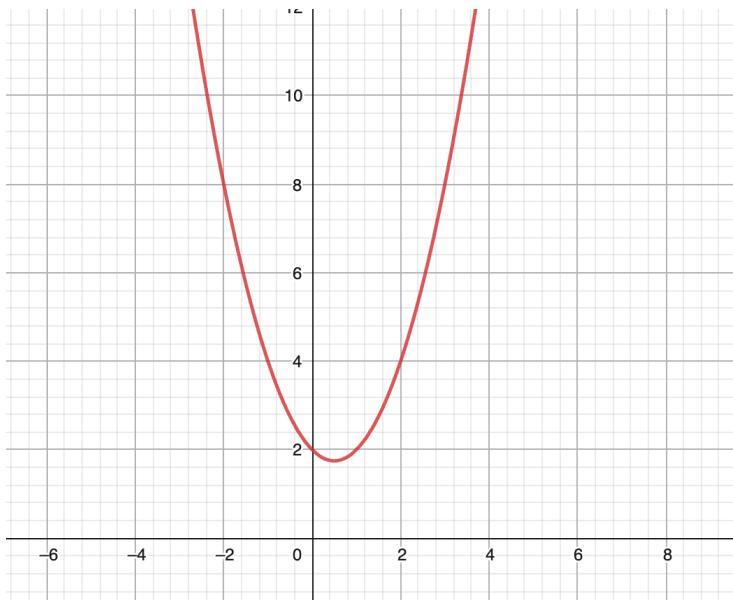
1.3. Problem 3

Draw the following polynomials

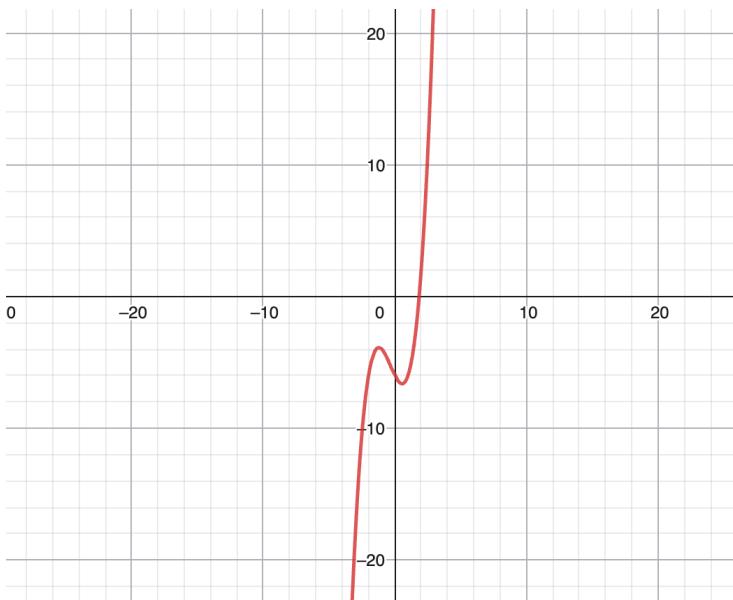
- (a) $y = x^2 - x + 2$
- (b) $y = x^3 + x^2 - 2x - 6$
- (c) $y = x^4 - x^3 - 7x^2 - 2x - 6$
- (d) $y = x^5 - x^4 - 5x^3 + 2x - 6$

1.3.1. Solution

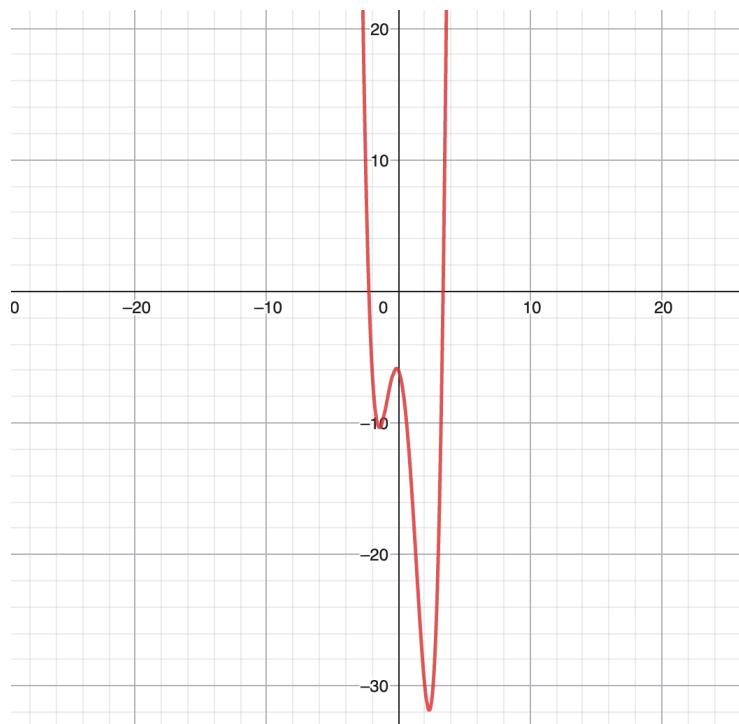
(a) $y = x^2 - x + 2$



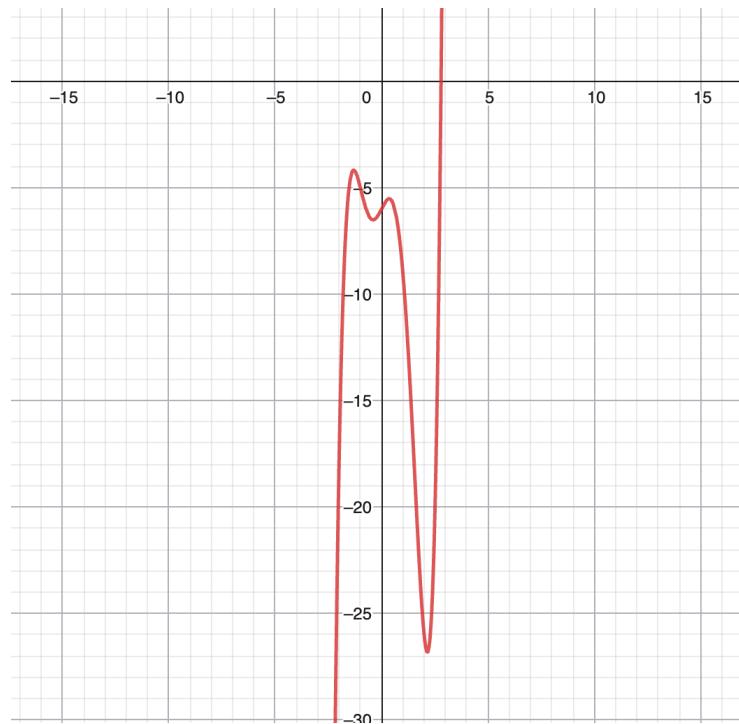
(b) $y = x^3 + x^2 - 2x - 6$



(c) $y = x^4 - x^3 - 7x^2 - 2x - 6$



(d) $y = x^5 - x^4 - 5x^3 + 2x - 6$



1.4. Problem 4

Draw the graph of the following functions

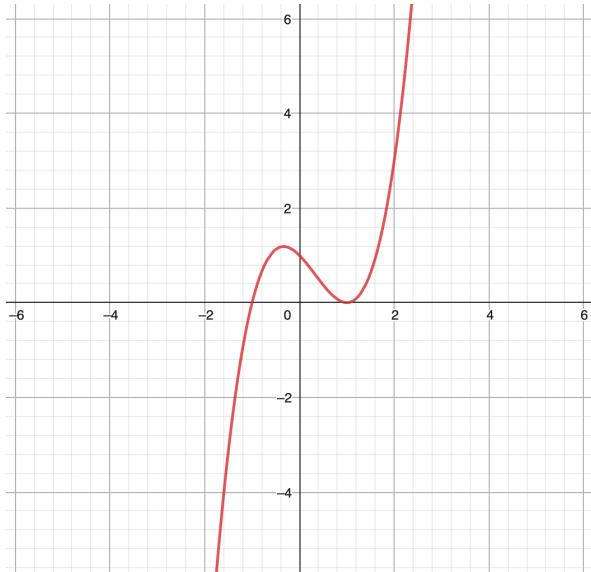
- (a) $y = (x + 1)(x - 1)^2$
- (b) $y = -x^2(x - 1)$

Are these functions polynomials? Why?

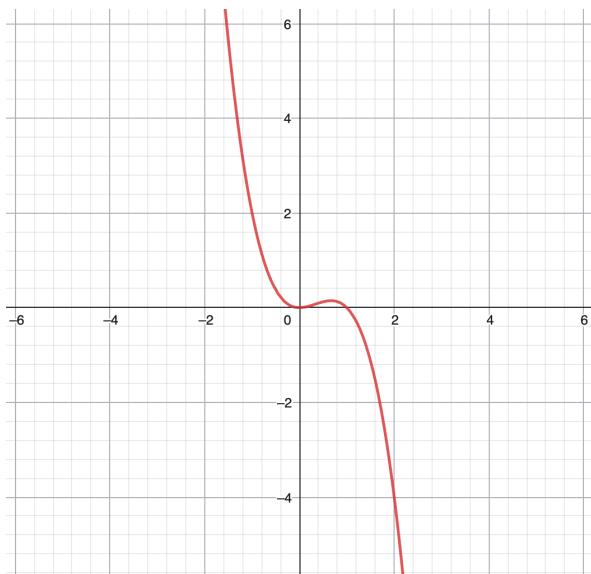
What changes about the behavior of the tails of the graph if its leading coefficient is negative?

1.4.1. Solution

- (a) $y = (x + 1)(x - 1)^2$



- (b) $y = -x^2(x - 1)$



Both are still polynomials. Any power function is a polynomials

Negative flips the entire graph

2. Lecture 2

2.1. Problem 1

Show $f(x) = x^3$ is continuous at every $c \in \mathbb{R}$.

2.1.1. Solution

This is the same as:

show that for every c

$$\lim_{x \rightarrow c} f(x) = c^3$$

Notice that

$$|f(x) - f(c)| = |x^3 - c^3| = |(x - c)(x^2 + c^2 + xc)|$$

if $|x - c| < 1$ (which is when $\lim_{x \rightarrow c}$)

Then we can insert $c + 1$ instead of x

$$|x^2 + c^2 + xc| \leq |x^2| + |c^2| + |x| |c| \leq |(c + 1)^2| + |c^2| + |c + 1| |c| := M$$

We want to show that $|x^3 - c^3| < \varepsilon$, so we choose

$$\delta = \min\left(1, \frac{\varepsilon}{M}\right) \quad \square$$

2.2. Problem 2

Show that $f(x) = x^3 + x - 1$ has a root in $[0, 1]$

2.2.1. Solution

$$f(0) = 0^3 + 0 - 1 = -1 \notin [0, 1]$$

$$f(1) = 1^3 + 1 - 1 = 1 \in [0, 1]$$

Since f is continuous and because $f(0) = -1$ and $f(1) = 1$, f has to pass through $y = 0$ at some point between $x = [0, 1]$

Conclusion: f must have 1 or more roots in $[0, 1]$

2.3. Problem 3

Evaluate $f(x) = x^2$ at $x = 2$

2.3.1. Solution

$$\begin{aligned}f'(x) &= \lim_{h \rightarrow 0} \frac{f(x+h) - f(x)}{h} \\f'(2) &= \lim_{h \rightarrow 0} \frac{f(2+h) - f(2)}{h} \\&= \lim_{h \rightarrow 0} \frac{(2+h)^2 - 2^2}{h} \\&= \lim_{h \rightarrow 0} \frac{4 + h^2 + 4h - 4}{h} \\&= \lim_{h \rightarrow 0} \frac{h^2 + 4h}{h} \\&= \lim_{h \rightarrow 0} h + 4 = 4\end{aligned}$$

2.4. Problem 4

Let $f(x) = \sqrt{x}$.

- Find $f'(4)$

2.4.1. Solution

We know that

$$f'(x) = \frac{1}{2}x^{-\frac{1}{2}}$$

So

$$f'(4) = \frac{1}{2} \cdot 4^{-\frac{1}{2}} = \frac{1}{2} \cdot \frac{1}{2} = \frac{1}{4}$$

The tangent line at $x = 4$ is:

$$y = f(4) + f'(4)(x - 4) = 2 + \frac{1}{4}(x - 4)$$

The error function (difference between $f(x)$ and its tangent approximation at $x = 4$) is:

$$E(x) = f(x) - [f(4) + f'(4)(x - 4)]$$

As x approaches 4, this error approaches 0. Using the tangent line to approximate $\sqrt{4.1}$:

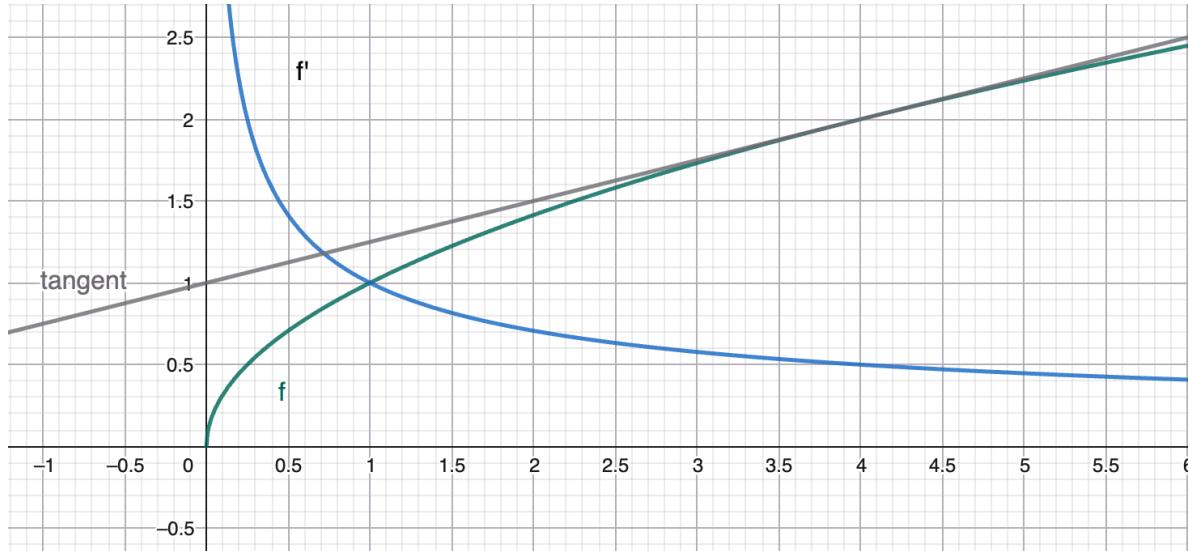
The tangent line at $x = 4$ is $y = 2 + \frac{1}{4}(x - 4)$.

So, for $x = 4.1$:

$$y \approx 2 + \frac{1}{4} \cdot (4.1 - 4) = 2 + \frac{1}{4} \cdot 0.1 = 2 + 0.025 = 2.025$$

The true value is $\sqrt{4.1} \approx 2.0249$, so the tangent line gives a good approximation for values close to $x = 4$.

The image below shows $f(x)$, its derivative $f'(x)$, and the tangent line at $x = 4$:



2.5. Problem 5

- (a) Find and classify all of the local extrema of $f(x) = x^3 - 3x + 4$.

2.5.1. Solution

$$f'(x) = 3x^2 - 3$$

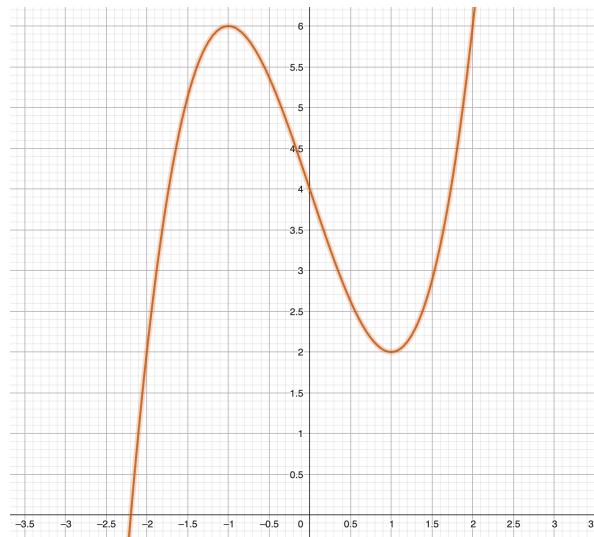
Set to 0

$$0 = 3x^2 - 3$$

$$3 = 3x^2$$

$$1 = x^2$$

$$x = \sqrt{1} = \pm 1$$



$f'(x) = 0$ gives 2 extrema, -1 and 1 , this makes sense given the graph.

2.6. Problem 6

True or False? If $f''(x_0) = 0$, then f has a local max or min at x_0 . Explain.

2.6.1. Solution

Yes, this means that the rate of change is 0 (extrema), at point x_0

2.7. Problem 7

Use the second derivative test to classify the critical points of $f(x) = x^3 - 3x + 4$.

2.7.1. Solution

We know that $f'(x) = 3x^2 + 3$ and that $f'(x) = 0 \Rightarrow x = \pm 1$

Then

$$f''(x) = 6x$$

$$f''(1) = 6$$

$$f''(-1) = -6$$

since $f''(1) > 0 \Rightarrow \text{Local minimum}$

and $f''(-1) < 0 \Rightarrow \text{Local maximum}$

2.8. Problem 8

Consider $f(x) = (x^2 - 4)^7$. Find and classify all local extrema.

2.8.1. Solution

$$f'(x) = 7(x^2 - 4)^6 \cdot 2x$$

then

$$0 = 7(x^2 - 4)^6 \cdot 2x$$

Because of 0-rule either $2x = 0$ or $x^2 - 4 = 0$

so $x = -2, 0, 2$

2.9. Problem 9

Find the global max and min of $f(x) = x(x - 1)$ on $0 \leq x \leq 3$.

2.9.1. Solution

$$x^2 - x$$

$$f'(x) = 2x - 1$$

$$0 = 2x - 1 \Rightarrow x = \frac{1}{2}$$

$$f\left(\frac{1}{2}\right) = -\frac{1}{4}$$

then for the endpoints

$$f(0) = 0$$

$$f(3) = 6$$

Global minimum at $x = \frac{1}{2}$ with $f\left(\frac{1}{2}\right) = -\frac{1}{4}$

Global maximum at $x = 3$ with $f(3) = 6$

2.10. Problem 10

Find the global max and min of $f(x) = x^3 - 7x + 6$ on $-4 \leq x \leq 2$.

2.10.1. Solution

$$f'(x) = 3x^2 - 7$$

$$0 = 3x^2 - 7 \Rightarrow x^2 = \frac{7}{3} \Rightarrow x = \pm\sqrt{\frac{7}{3}}$$

$$f\left(\sqrt{\frac{7}{3}}\right) = -1.13$$

$$f\left(-\sqrt{\frac{7}{3}}\right) = 13.13$$

then for endpoints

$$f(-4) = -30$$

$$f(2) = 0$$

Global minimum at $x = -4$ with $f(-4) = -30$

Global maximum at $x = -\sqrt{\frac{7}{3}}$ with $f\left(-\sqrt{\frac{7}{3}}\right) = 13.13$

2.11. Problem 11

Find the global max and min of $g(x) = \ln(1 + x^2)$ on $-1 \leq x \leq 2$.

2.11.1. Solution

$$f'(x) = \frac{1}{1+x^2} \cdot 2x$$

When $f'(x) = 0 \Rightarrow x = 0$

$$f(0) = 0$$

now for endpoints

$$f(-1) = 0.69$$

$$f(2) = 1.61$$

Global minimum at $x = 0$ with $f(0) = 0$

Global minimum at $x = 2$ with $f(2) = 1.13$

2.12. Problem 12

Find the global max and min of $f(t) = te^{-t}$ for $t \geq 0$. (Hint: careful here, as the domain is neither closed nor finite)

2.12.1. Solution

$$f'(t) = e^{-t} - te^{-t}$$

$$0 = e^{-t} - te^{-t} \Rightarrow t = 1$$

$$f(1) = \frac{1}{e} \approx 0.37$$

Then for endpoints

$$f(0) = 0$$

Since I can't do $f(\infty)$, I can use L'Hopital's rule to show that

$$\lim_{t \rightarrow \infty} \frac{t}{e^t} = \lim_{t \rightarrow \infty} \frac{1}{e^t} = 0$$

so.. Global minimum at $x = 0$ with $f(0) = 0$ and $x = \infty$ with $f(\infty) = 0$

Global minimum at $x = 1$ with $f(1) = 0.37$

3. Lecture 3

3.1. Problem 1

Write the definition of $\lim_{x \rightarrow c} f(x) = L$

3.1.1. Solution

$\lim_{x \rightarrow c} f(x)$ is when we get $f(x)$ close enough to L so that

For any small $\varepsilon >$, there is $\delta > 0$ such that if

$$|x - c| < \delta$$

then

$$|f(x) - L| < \varepsilon$$

note that $x \neq c$

3.2. Problem 2

Write the definition of a function f continuous at $x = c$

3.2.1. Solution

f is continuous at point $x = c$ if

$$\lim_{x \rightarrow c} f(x) = f(c)$$

Note that, if f is continuous in $[a, b]$, then f is continuous on all points within $[a, b]$

3.3. Problem 3

Write the definition of the derivative of f at a point $x = a$

3.3.1. Solution

for a point a , then

$$f'(a) = \lim_{h \rightarrow 0} \frac{f(x + h) - f(x)}{h}$$

If this limit exists, f is differentiable at a .

3.4. Problem 4

Write the definition of the second derivative

3.4.1. Solution

Since $f''(x) = f'(f'(x))$

$$f''(a) = \lim_{h \rightarrow 0} \frac{f'(x + h) - f'(x)}{h}$$

3.5. Problem 5

Use the second derivative test to classify the critical points of $f(x) = x^3 - 3x + 4$

We know that $f'(x) = 3x^2 + 3$ and that $f'(x) = 0 \Rightarrow x = \pm 1$

Then

$$f''(x) = 6x$$

$$f''(1) = 6$$

$$f''(-1) = -6$$

$f''(1) > 0 \Rightarrow$ **Local minimum**

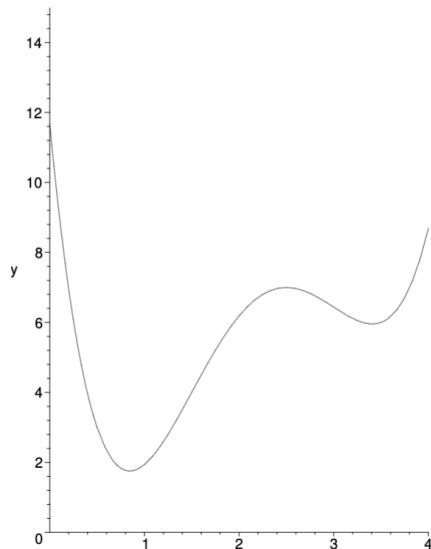
and $f''(-1) < 0 \Rightarrow$ **Local maximum**

3.5.1. Solution

3.6. Problem 6

Consider the function below:

- Identify the local minima and maxima.
- Identify the global minimum and maximum.



3.6.1. Solution

Local minima at $x \approx 0.8$ with $f(0.8) \approx 2$

Local maxima at $x \approx 2.5$ with $f(2.5) \approx 7$

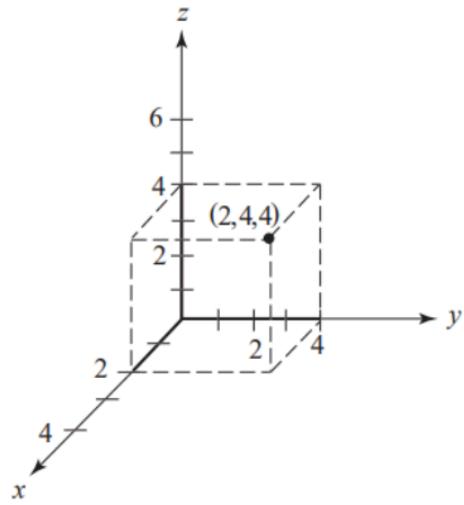
Local minima at $x \approx 3.5$ with $f(3.5) \approx 6$

Global minimum at $x \approx 0.8$ with $f(0.8) \approx 1.9$

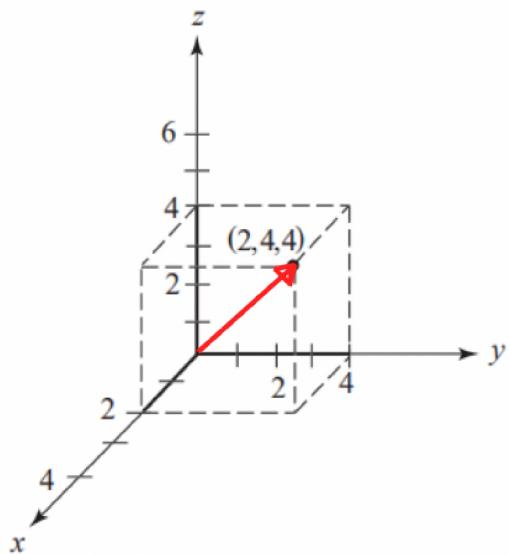
Global maximum at $x \approx 0$ with $f(0) \approx 10.8$

3.7. Problem 7

Draw the vector $(2, 4, 4)$ on the following graph and compute its length.



3.7.1. Solution



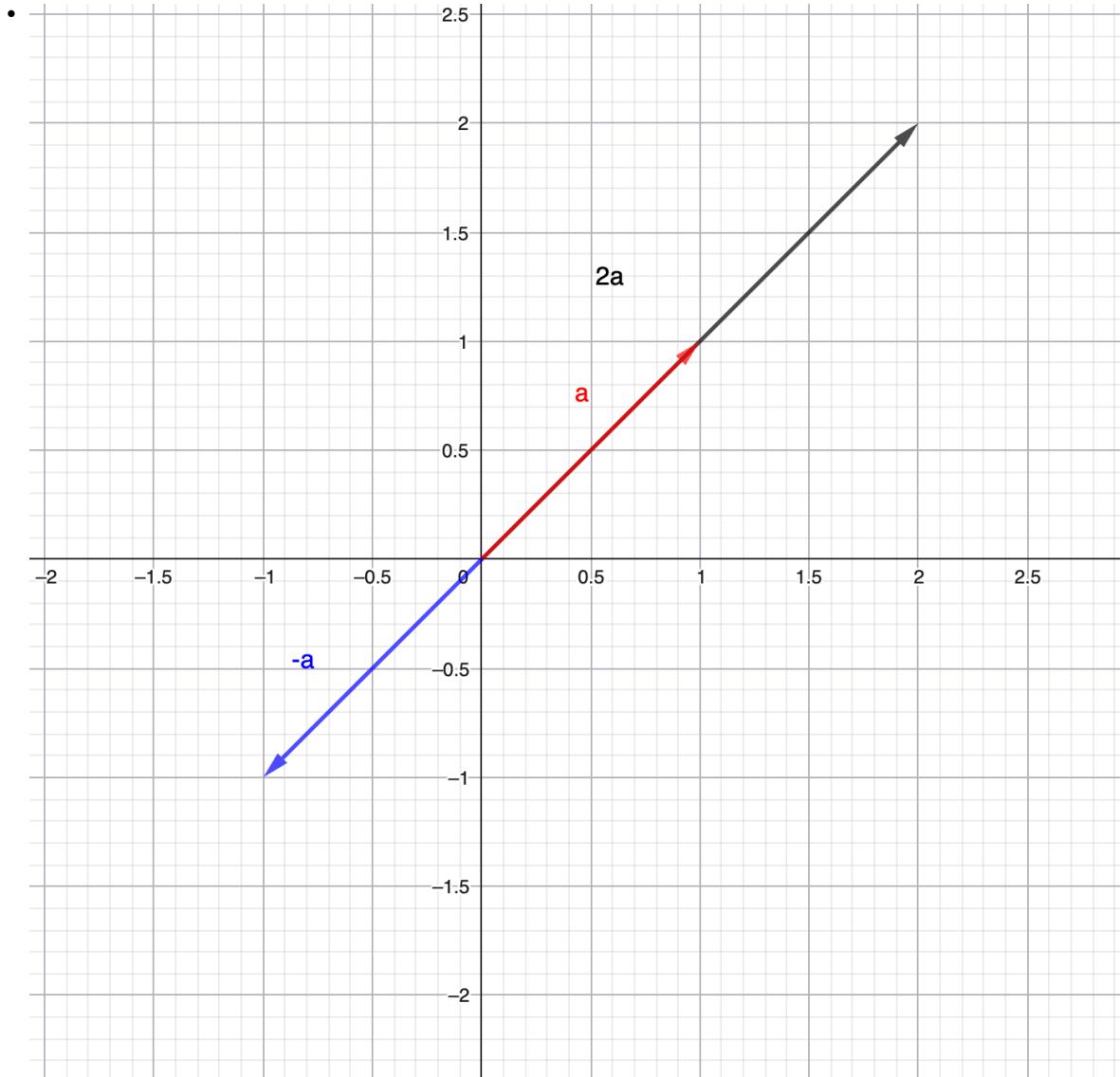
$$\|(2, 4, 4)\| = \sqrt{2^2 + 4^2 + 4^2} = \sqrt{68}$$

3.8. Problem 8

Let $a = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$.

- Draw a , $2a$, and $-a$.
- How can $-a$ be normalized to a unit vector?

3.8.1. Solution

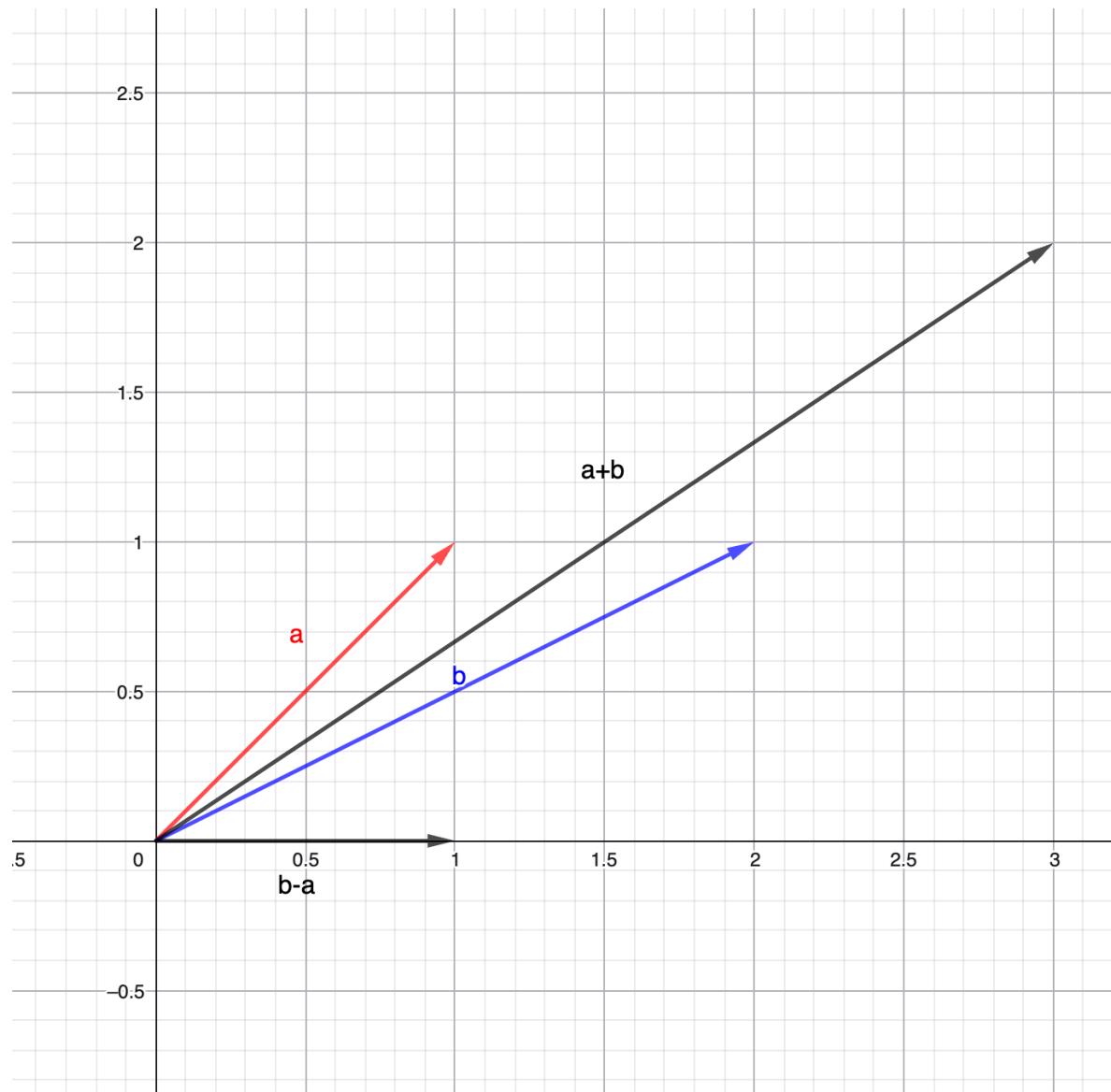


- Normalized to a unit vector $(-a)_u = \frac{-a}{\|-a\|} = \frac{-1, -1}{\sqrt{(-1)^2 + (-1)^2}} = \begin{pmatrix} -\frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \end{pmatrix}$

3.9. Problem 9

Draw $b - a$

3.9.1. Solution



3.10. Problem 10

Let

$$\mathbf{v} = (3, 4) \quad \mathbf{w} = (-4, 3)$$

- (1) Compute $\mathbf{v} \cdot \mathbf{w}$ ($\mathbf{v}^T \mathbf{w}$)
- (2) Use (1) to deduce that the vectors form a right angle
- Draw the two vectors on the plane to confirm (2)

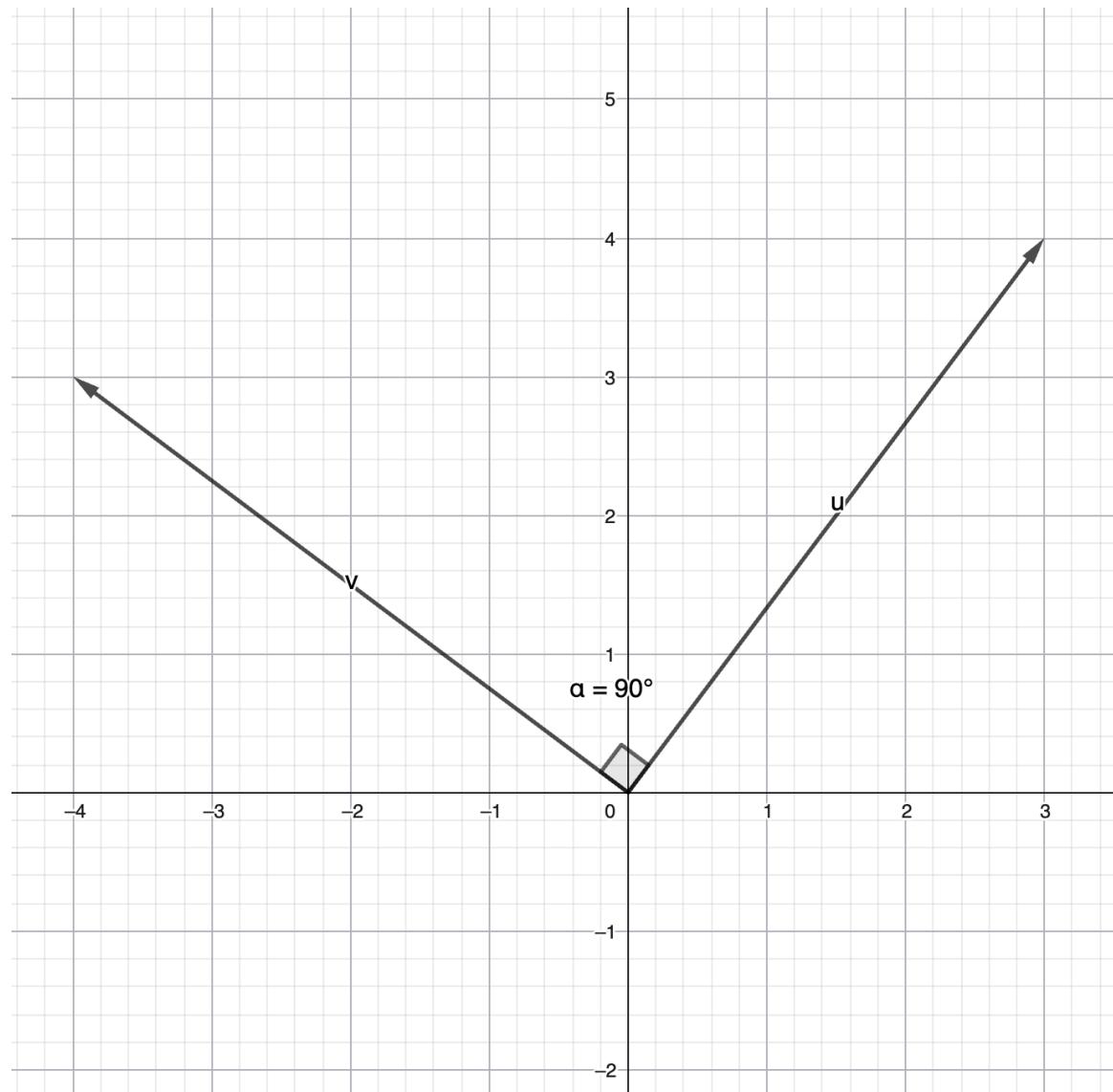
3.10.1. Solution

- $\mathbf{v} \cdot \mathbf{w} = 3 \cdot (-4) + 4 \cdot 3 = -12 + 12 = 0$
- When dot product = 0, angle is between them is 90

$$\cos(90^\circ) \|\mathbf{v}\| \|\mathbf{w}\| = 0 = \mathbf{v} \cdot \mathbf{w}$$

Since neither $\|\mathbf{v}\|$ or $\|\mathbf{w}\|$ is 0 $\cos(\theta) = 0$, so $\theta = 90^\circ$

-



-

3.11. Problem 11

Can you give the standard basis vectors in \mathbb{R}^n ?

3.11.1. Solution

for any vector a in \mathbb{R}^n

$$a = a_1 e_1 + a_2 e_2 + \dots + a_n e_n$$

Then the standard basis vectors are

$$e_1 = \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}, e_2 = \begin{pmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{pmatrix}, \dots, e_n = \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{pmatrix}$$

3.12. Problem 12

What are the domain and range for each of these functions?

- $f(x, y) = x^2 + y^2$
- $f(x, y) = (x^2 + y^2) \log(xy)$
- $f(x, y, z) = \log(z)x^2y^2$

3.12.1. Solution

- $f(x, y) = x^2 + y^2$
 - $D(f) = \mathbb{R}^2$
 - $R(f) = [0, \infty)$
- $f(x, y) = (x^2 + y^2) \log(xy)$
 - $D(f) = \{(x, y) \in \mathbb{R}^2 \mid xy > 0\}$
 - $R(f) = \mathbb{R}$
- $f(x, y, z) = \log(z)x^2y^2$
 - $D(f) = \{(x, y, z) \in \mathbb{R}^3 \mid z > 0\}$
 - $R(f) = \mathbb{R}$

4. Lecture 4

4.1. Problem 1

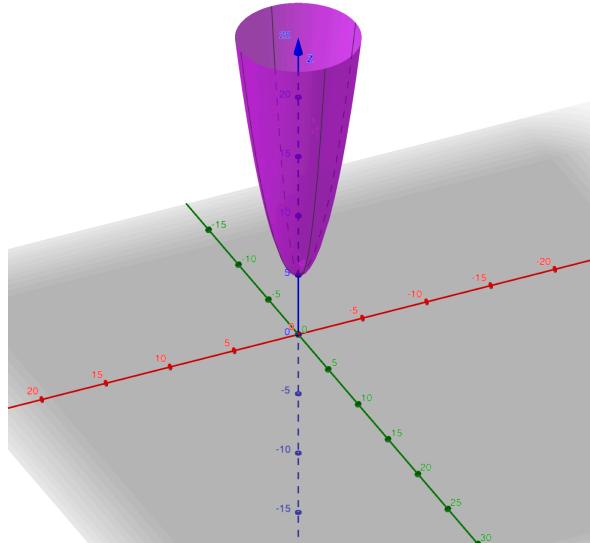
Can you describe in words the graphs of the following functions?

- $g(x, y) = x^2 + y^2 + 5$
- $h(x, y) = -x^2 - y^2$
- $q(x, z) = x^2 + (z - 1)^2$

4.1.1. Solution

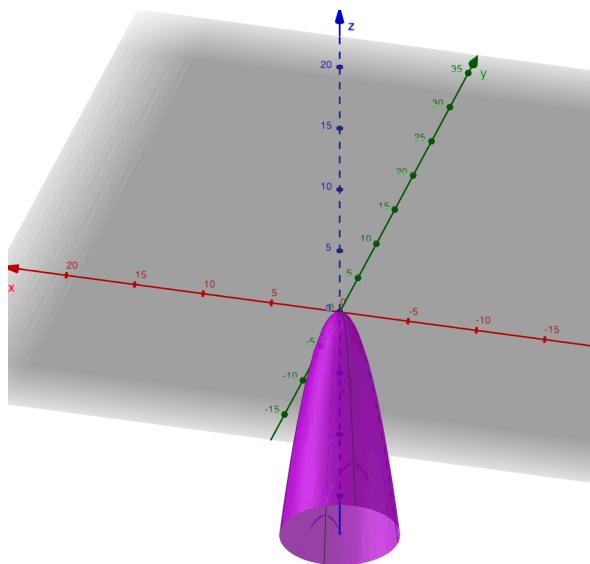
- $g(x, y) = x^2 + y^2 + 5$

upward circular paraboloid (bowl) that is shifted up by 5



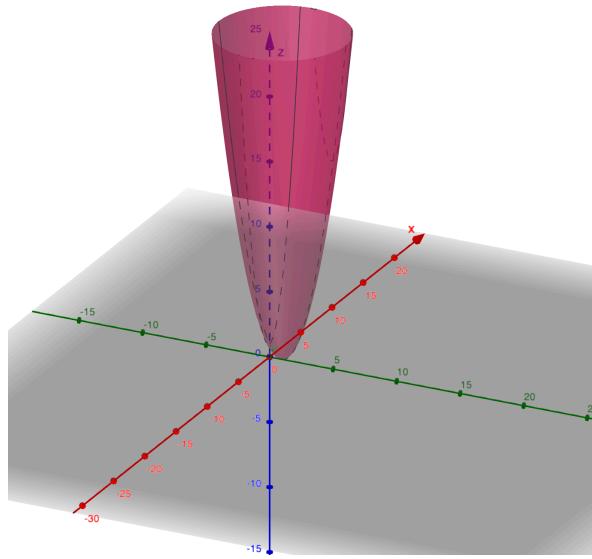
- $h(x, y) = -x^2 - y^2$

downward circular paraboloid (bowl)



- $q(x, z) = x^2 + (z - 1)^2$

upward circular paraboloid (bowl) that is shifted + 1 in the direction of z



4.2. Problem 2

Describe the cross-sections of the function $g(x, y) = x^2 - y^2$ with y fixed and then with x fixed. Use these cross-sections to describe the shape of the graph of g .

4.2.1. Solution

- with $x^2 - y^2$ and $y = c$ is an upwards parabola
- with $x^2 - y^2$ and $x = c$ is an downwards parabola
- together = saddle surface

4.3. Problem 3

Describe the level sets of the functions

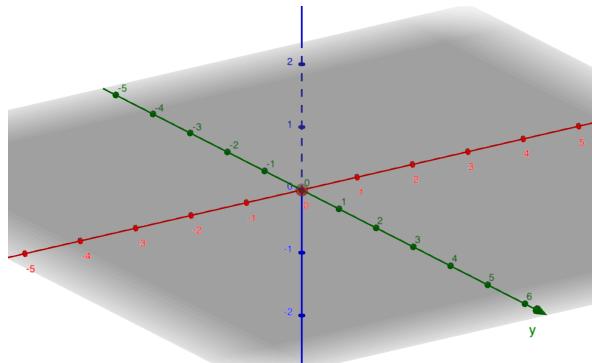
- $f(x, y, z) = x^2 + y^2 + z^2$
- $f(x, y, z) = x^2 + y^2 - z^2$

4.3.1. Solution

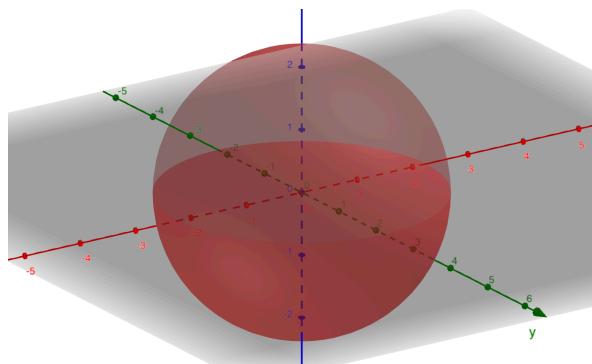
- $f(x, y, z) = x^2 + y^2 + z^2$

Level sets $x^2 + y^2 + z^2 = c$

For $c = 0$ a single point at $(0, 0, 0)$



For $c > 0$ a 3D-sphere with $r = \sqrt{c}$

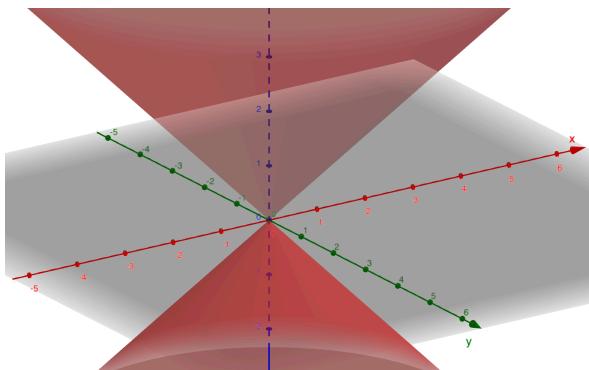


For $c < 0$ a single point at $(0, 0, 0)$

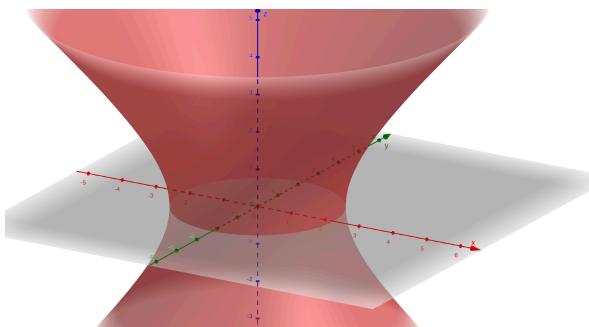
Undefined as $(-1)^2 = 1$

- $f(x, y, z) = x^2 + y^2 - z^2$

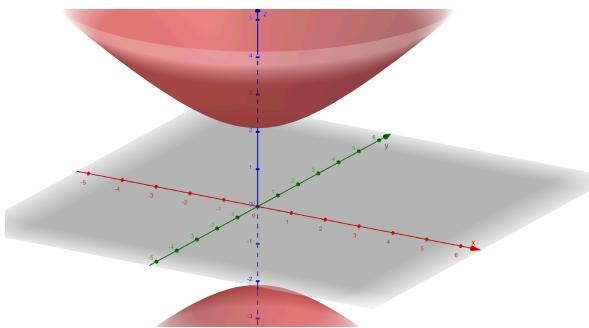
For $c = 0$ a double cone with center at $(0, 0, 0)$



For $c < 0$ a hyperboloid of one sheet



For $c > 0$ a hyperboloid of two sheets



4.4. Problem 4

Find the equation of the plane passing through the points $(1, 0, 1)$, $(1, -1, 3)$, and $(3, 0, -1)$.

4.4.1. Solution

The equation for the plane

$$a(x - x_0) + b(y - y_0) + c(z - z_0) = 0$$

with

point $P(x_0, y_0, z_0)$ and normal vector $N(a, b, c)$

i will use the tree points to make 2 vectors in the plane

$$v = (1, 0, 1) - (1, -1, 3) = \begin{pmatrix} 0 \\ 1 \\ -2 \end{pmatrix}$$

and

$$w = (3, 0, -1) - (1, -1, 3) = \begin{pmatrix} 2 \\ 1 \\ -4 \end{pmatrix}$$

Now by using cross product $N = v \times w$

$$N = v \times w = \begin{pmatrix} -2 \\ -4 \\ -2 \end{pmatrix}$$

with point $P(1, 0, 1)$ the plane becomes

$$-2(x - 1) - 4(y - 0) - 2(z - 1) = 0$$

$$-2x + 2 - 4y - 2z + 2 = 0$$

$$-2x - 4y - 2z + 4 = 0$$

4.5. Problem 5

What is the minimum number of points required to uniquely determine a plane?

4.5.1. Solution

3

4.6. Problem 6

In one-variable calculus, a limit exists at $x = a$ if the left-hand and right-hand limits match:

$$\lim_{x \rightarrow a^+} f(x) = \lim_{x \rightarrow a^-} f(x)$$

Does this make sense for multivariate functions?

4.6.1. Solution

Yes, but this must be true for all paths. (impossible task in practice)

So to show that a multivariate limit does not exist, you look for counterexamples:

$$\frac{2xy}{x^2 - y^2}$$

$$y = 0 \Rightarrow \lim_{x \rightarrow 0} \frac{2xy}{x^2 - y^2} = 0$$

$$y = x \Rightarrow \lim_{x \rightarrow 0} \frac{2x^2}{2x^2} = 1$$

Limit does not exist since $0 \neq 1$

4.7. Problem 7

Does the following limit exist?

$$\lim_{(x,y) \rightarrow (0,0)} \frac{xy}{x^2 + y^2}$$

4.7.1. Solution

$$y = 0 \Rightarrow \lim_{x \rightarrow 0} \frac{xy}{x^2 + y^2} = 0$$

$$y = x \Rightarrow \lim_{x \rightarrow 0} \frac{x^2}{2x^2} = \frac{1}{2}$$

DNE

4.8. Problem 8

Does the following limits exists?

- $\lim_{(x,y) \rightarrow (0,0)} e^{-x-y}$
- $\lim_{(x,y) \rightarrow (0,0)} x^2 + y^2$
- $\lim_{(x,y) \rightarrow (0,0)} \frac{x^2y}{x^2+y^2}$

4.8.1. Solution

- $\lim_{(x,y) \rightarrow (0,0)} e^{-x-y}$
 - $y = 0 \Rightarrow \lim_{x \rightarrow 0} e^{-x-y} = 0$
 - $y = x \Rightarrow \lim_{x \rightarrow 0} e^{-x-y} = \frac{1}{2}$
- $\lim_{(x,y) \rightarrow (0,0)} x^2 + y^2$
 - this is just 0

- $\lim_{(x,y) \rightarrow (0,0)} \frac{x^2y}{x^2+y^2}$

We want to prove that $\lim_{(x,y) \rightarrow (0,0)} \frac{x^2y}{x^2+y^2} = 0$

By definition

$$\forall \varepsilon > 0, \exists \delta > 0 \mid \underbrace{\left(\sqrt{x^2 + y^2} \right)}_{(x,y) \text{ to } (0,0)} < \delta \Rightarrow \left| \frac{x^2y}{x^2+y^2} + y^2 \right| < \varepsilon$$

Since

$$\frac{x^2|y|}{x^2+y^2} \leq \frac{x^2+y^2}{x^2+y^2}|y|$$

then

$$\frac{x^2|y|}{x^2+y^2} \leq |y| \leq \sqrt{x^2+y^2} \leq \delta$$

choose $\varepsilon = \delta$ then

$$\frac{x^2|y|}{x^2+y^2} \leq \varepsilon$$

So

$$\lim_{(x,y) \rightarrow (0,0)} \frac{x^2y}{x^2+y^2} = 0 \quad \square$$

4.9. Problem 9

Is the function continuous in the given region?

- $\frac{1}{x^2+y^2}$ on $-1 \leq x, y \leq 1$
- $\frac{1}{x^2+y^2}$ on $1 \leq x, y \leq 2$
- $\frac{y}{x^2+2}$ on $x^2 + y^2 \leq 1$

4.9.1. Solution

- $\frac{1}{x^2+y^2}$ on $-1 \leq x, y \leq 1$

at $x = y = 0$, $\frac{1}{x^2+y^2}$ is undefined

- $\frac{1}{x^2+y^2}$ on $1 \leq x, y \leq 2$

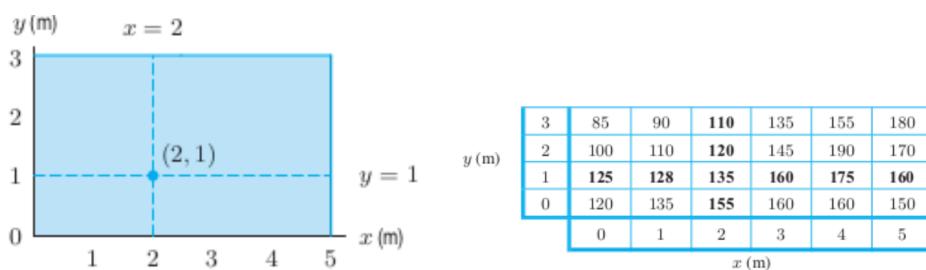
Since $1 \leq x$, $x^2 + y^2$ can never be 0, so yes it is continuous

- $\frac{y}{x^2+2}$ on $x^2 + y^2 \leq 1$

Because of x^2 , $x^2 + 2$ can not become 0, so yes it is continuous

4.10. Problem 10

Imagine an unevenly heated thin rectangular metal plate lying in the xy -plane. Temperature at (x, y) is $T(x, y)$



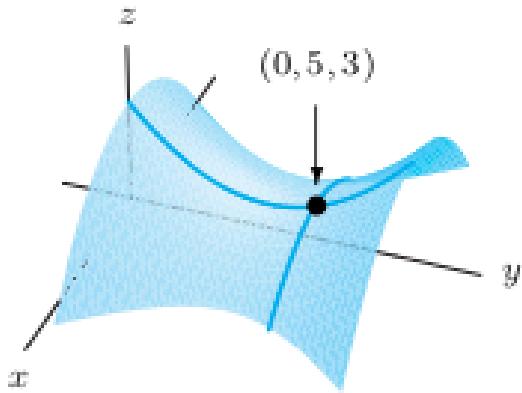
How does T vary near the point $(2, 1)$?

4.10.1. Solution

Its increasing towards $x = 3$ and decreasing towards $x = 1$

Also its increasing towards $y = 0$ and decreasing towards $y = 2$

4.11. Problem 11



- What is the sign of $f_x(0, 5)$?
- What is the sign of $f_y(0, 5)$?

4.11.1. Solution

I am assuming that the direction of the derivative is towards the x and y axis (which are the positive ends)

- What is the sign of $f_x(0, 5)$?
negative
- What is the sign of $f_y(0, 5)$?
positive

4.12. Problem 12

Let

$$f(x, y) = \frac{x^2}{y+1}$$

Find $f_{x(3,2)}$

4.12.1. Solution

$$f_{x(x,y)} = \frac{\partial}{\partial x} \frac{x^2}{y+1} = \frac{2x}{y+1}$$

$$f_{x(3,2)} = \frac{2 \cdot 3}{2-1} = \frac{6}{1} = 6$$

4.13. Problem 13

Find tangent plane to $f(x, y) = x^2 + y^2$ at $(3, 4)$

4.13.1. Solution

If f is differentiable, then

$$z = f(a, b) + f_{x(a,b)}(x - a) + f_{y(a,b)}(y - b)$$

Find the derivatives

$$f_{x(x,y)} = 2x \quad f_{y(x,y)} = 2y$$

Now plug it into the tangent equation

$$z = 3^2 + 4^2 + (2 \cdot 3)(x - 3) + (2 \cdot 4)(y - 4)$$

$$z = 25 + 6(x - 3) + 8(y - 4)$$

$$z = 25 + 6x - 18 + 8y - 32$$

$$z = 6x + 8y - 25$$

4.14. Problem 14

Let $f(x, y) = x^2 + y^2$ and call the tangent plane you computed at $(3, 4)$ $L(x, y)$. We define the error function

$$E(x, y) = f(x, y) - L(x, y)$$

The error near $(3, 4)$ is given by $E(3 + h, 4 + k)$ where h, k are small.

What is the distance between $(3 + h, 4 + k)$ and $(3, 4)$?

Compare $|E(3 + h, 4 + k)|$ with $h^2 + k^2$.

Observe that:

$$\frac{|E(x, y)|}{h^2 + k^2} \approx c$$

What can you say about the error near $(3, 4)$?

4.14.1. Solution

- What is the distance between $(3 + h, 4 + k)$ and $(3, 4)$?

$$\text{dist} = \sqrt{h^2 + k^2}$$

- Compare $|E(3 + h, 4 + k)|$ with $h^2 + k^2$.

$$E(3 + h, 4 + k) = f(3 + h, 4 + k) - L(3 + h, 4 + k)$$

$$25 + 6h + 8k + h^2 + k^2 - 25 + 6h + 8k = h^2 + k^2$$

So actually we see that

$$|E(3 + h, 4 + k)| = h^2 + k^2$$

Now

$$\frac{|E(x, y)|}{h^2 + k^2} = 1$$

- What can you say about the error near $(3, 4)$? The error is quadratic in the distance from $(3, 4)$

When $(h, k) \rightarrow (0, 0)$, $\sqrt{h^2 + k^2} \rightarrow 0$ faster than $h^2 + k^2$

$$\frac{h^2 + k^2}{\sqrt{h^2 + k^2}} = \sqrt{h^2 + k^2} \rightarrow 0$$

This means that the error goes to 0 faster than the distance itself

For the tangent, this means that even if you move a little bit away (small h, k), the value of the tangent plane is almost the same as the function itself.

5. Lecture 5

5.1. Problem 1

Compute partial derivatives by treating all other variables as constants

$$f(x, y, z) = x^2yz$$

5.1.1. Solution

Using

$$\frac{\partial f}{\partial x_i}(x_1, \dots, x_n) = \lim_{h \rightarrow 0} \frac{f(x_1, \dots, \cancel{x_i} + h, \dots, x_n) - f(x_1, \dots, \cancel{x_i}, \dots, x_n)}{h}$$

$$\frac{\partial f}{\partial x} = 2xyz \quad \frac{\partial f}{\partial y} = x^2z \quad \frac{\partial f}{\partial z} = x^2y$$

5.2. Problem 2

Compute the partial derivatives of

$$f(x_1, \dots, x_n) = \sum_{i=1}^n x_i^2$$

5.2.1. Solution

$$\frac{\partial}{\partial x_1} \sum_{i=1}^n x_i^2, \frac{\partial}{\partial x_2} \sum_{i=1}^n x_i^2, \dots, \frac{\partial}{\partial x_n} \sum_{i=1}^n x_i^2$$

$$2x_1, 2x_2, \dots, 2x_n$$

5.3. Problem 3

When $u = i$ or $u = j$, what is $f_u(a, b)$?

5.3.1. Solution

This means that either $u_1 = 1$ and $u_2 = 0$ or $u_1 = 0$ and $u_2 = 1$

$$u = 1i + 0j = i \quad \vee u = 0i + 1j = j$$

Because of this we only stepping either $a + h$ or $b + h$

This means that

$$f_u = \lim_{h \rightarrow 0} \frac{(a, b) = f(a + h, b) - f(a, b)}{h}$$

or

$$f_u = \lim_{h \rightarrow 0} \frac{(a, b) = f(a, b + h) - f(a, b)}{h}$$

This is exactly the same as taking the partial derivative with respect to the variable in that direction (partial derivatives) so

$$f_i(x, y) = f_x(x, y)$$

$$f_j(x, y) = f_y(x, y)$$

5.4. Problem 4

For $f_u(x, y)$ What happens when u is not a unit vector?

5.4.1. Solution

We take larger steps and therefore the $f_u(x, y)$ is scaled by some number

Let u not be a unit vector, then

$$f_u(x, y) = k \cdot f_{\hat{u}}(x, y) \quad \text{where } \hat{u} = \frac{u}{\|u\|}$$

Where $k = \|u\|$, when $u \neq 0$

To get the true rate of change per unit distance, you divide by $\|u\|$ (i.e., use a unit vector).

5.5. Problem 5

Calculate the directional derivative of $f(x, y) = x^2 + y^2$ at $(1, 0)$ in the direction of $i + j$.

5.5.1. Solution

$$u = i + j = \begin{pmatrix} 1 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\hat{u} = \frac{1, 1}{\|u\|} = \left(\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}} \right)$$

$$f_u(x, y) = \lim_{h \rightarrow 0} \frac{f\left(a + \frac{h}{\sqrt{2}}, b + \frac{h}{\sqrt{2}}\right) - f(a, b)}{h}$$

$$f_u(1, 0) = \lim_{h \rightarrow 0} \frac{f\left(1 + \frac{h}{\sqrt{2}}, \frac{h}{\sqrt{2}}\right) - f(1, 0)}{h}$$

$$= \lim_{h \rightarrow 0} \frac{\left(1 + \frac{h}{\sqrt{2}}\right)^2 + \left(\frac{h}{\sqrt{2}}\right)^2 - 1}{h} = \sqrt{2}$$

5.6. Problem 6

- Approximate $f(a_1 + hu_1, \dots, a_n + hu_n)$ with the first-order approximation at (hu_1, \dots, hu_n)
- What happens when you simplify the limit in the previous definition?

5.6.1. Solution

- Approximate $f(a_1 + hu_1, \dots, a_n + hu_n)$ with the first-order approximation at (hu_1, \dots, hu_n)

For $x = (x_1, \dots, x_n)$ near $a = (a_1, \dots, a_n)$

$$f(x) \approx L(x) = f(a) + \sum_{x=1}^n \frac{\partial f}{\partial x_i}(a)(x_i - a_i)$$

For $x = (a_1 + hu_1, \dots, a_n + hu_n)$ near $h = (hu_1, \dots, hu_n)$

$$f(x) \approx L(x) = f(h) + \sum_{x=1}^n \frac{\partial f}{\partial x_i}(h)a_i$$

or

$$\begin{aligned} f(a_1 + hu_1, \dots, a_n + hu_n) &\approx L(a_1 + hu_1, \dots, a_n + hu_n) = \\ &f(hu_1, \dots, hu_n) + \sum_{x=1}^n \frac{\partial f}{\partial x_i}(hu_1, \dots, hu_n)a_i \end{aligned}$$

- What happens when you simplify the limit in the previous definition?

For the previous definition (in the notes)

$$f_u(a) = \lim_{h \rightarrow 0} \frac{f(a_1 + hu_1, \dots, a_n + hu_n) - f(a_1, \dots, a_n)}{h}$$

$$f_u(a) \approx \lim_{h \rightarrow 0} \frac{f(h) + \sum_{x=1}^n \frac{\partial}{\partial x_i} f(h) a_i - f(a)}{h}$$

$$f_u(a) \approx \sum_{x=1}^n \frac{\partial}{\partial x_i} f(h) \frac{a_i}{h}$$

since $\frac{a_i}{h} = u_i$

$$f_u(a)a = \sum_{x=1}^n \frac{\partial}{\partial x_i} f(h) u_i = \nabla f(a) \cdot u$$

5.7. Problem 7

Use the preceding formula $(\nabla f(a) \cdot u)$ to calculate the directional derivative of $f(x, y) = x^2 + y^2$ at $(1, 0)$ in the direction of $i + j$.

5.7.1. Solution

Now that we know that $f_u(x, y) = \nabla f(a) \cdot u$

$$u = i + j = \begin{pmatrix} 1 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\hat{u} = \frac{1, 1}{\|u\|} = \left(\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}} \right)$$

$$f_{\hat{u}}(x, y) = \nabla f(x, y) \cdot u = \begin{pmatrix} 2x \\ 2y \end{pmatrix} \cdot \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} = \frac{2x}{\sqrt{2}} + \frac{2y}{\sqrt{2}}$$

$$f_{\hat{u}}(1, 0) = \begin{pmatrix} 2 \\ 0 \end{pmatrix} \cdot \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} = \frac{2}{\sqrt{2}} + \frac{0}{\sqrt{2}} = \frac{2}{\sqrt{2}} = \sqrt{2}$$

5.8. Problem 8

Find the gradient of $f(x, y) = x + e^y$ at $(1, 1)$. Use it to compute the directional derivative in the direction of $i + j$.

5.8.1. Solution

$$u = i + j = \begin{pmatrix} 1 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\hat{u} = \frac{1, 1}{\|u\|} = \left(\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}} \right)$$

$$f_{\hat{u}}(x, y) = \nabla f(x, y) \cdot u = \begin{pmatrix} 1 \\ e^y \end{pmatrix} \cdot \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} = \frac{1}{\sqrt{2}} + \frac{e^y}{\sqrt{2}}$$

$$f_{\hat{u}}(1, 1) = \frac{1}{\sqrt{2}} + \frac{e^1}{\sqrt{2}} = \frac{1+e}{\sqrt{2}}$$

6. Lecture 6

6.1. Problem 1

We computed the directional derivative by the inner product with the gradient vector

$$f_u(a) = \nabla f(a) \cdot u$$

Recall that the inner product measures the alignment of two vectors:

$$\nabla f(a) \cdot u = \|\nabla f(a)\| \cdot \underbrace{\|u\|}_1 \cdot \cos(\theta) = \|\nabla f(a)\| \cdot \cos(\theta)$$

Think, what does this tell us about the gradient vector?

6.1.1. Solution

Because of

$$f_u(a) = \|\nabla f(a)\| \cdot \cos(\theta)$$

As long as $\|\nabla f(a)\| \neq 0$

- When looking for the **maximum** increase. Assume that $\theta = 0$

Then $f_u(a)$ is maximized, when the direction u points along of $\nabla f(a)$ (i.e. when $\theta = 0$)

$$f_u(a) = \|\nabla f(a)\|$$

- We can also **minimize** by $\theta = 180$

Then $f_u(a)$ is minimized, when the direction u points opposite of $\nabla f(a)$ (i.e. when $\theta = 180$)

$$f_u(a) = -\|\nabla f(a)\|$$

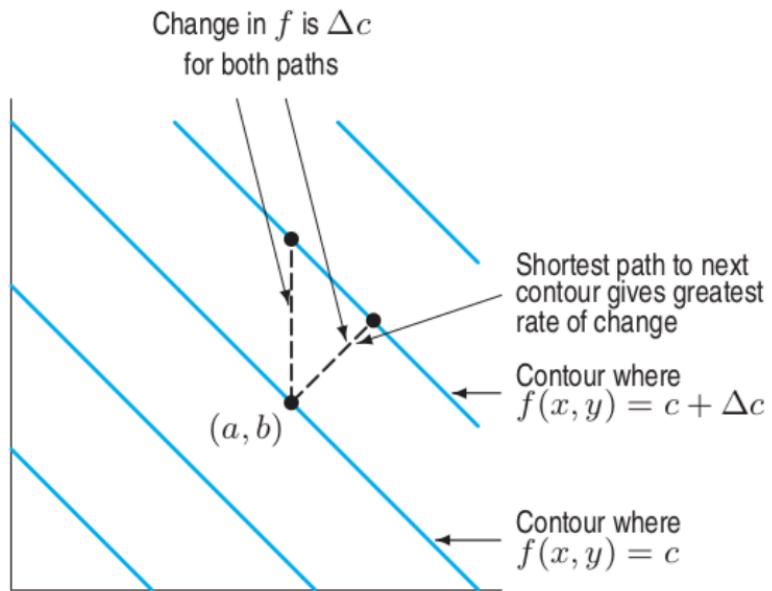
- What about **no change**?

Then, when the direction u is perpendicular (\perp) to $\nabla f(a)$ (i.e. when $\theta = 90$)

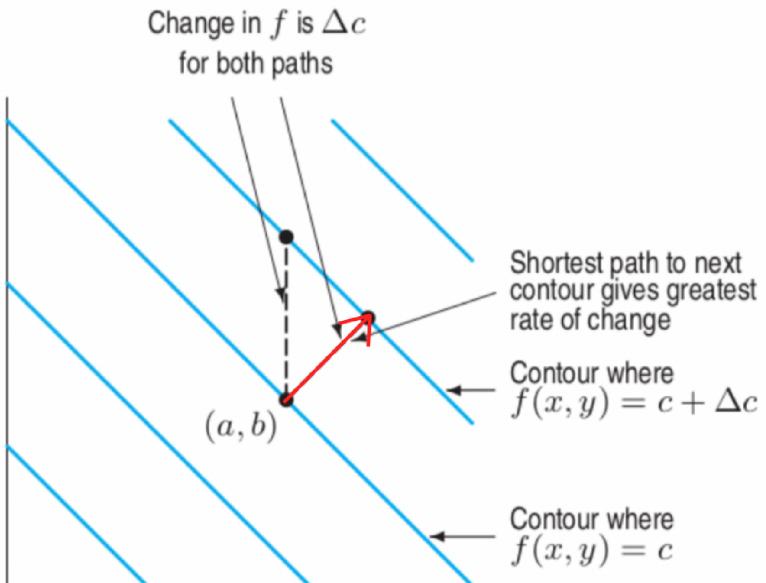
$$f_u(a) = 0$$

6.2. Problem 2

In the following picture, mark the gradient vector of f at (a, b) .



6.2.1. Solution



6.3. Problem 3

Let's consider a simple classification example where we need to classify whether a student passes an exam based on two features:

- x_1 = hours studied
- x_2 = hours slept

The goal is to make a binary classification such that

- $y = 1$ if the student passes (positive class).
- $y = 0$ if the student fails (negative class).

Suppose a data set $\{x_1^{(i)}, x_2^{(i)}, y^{(i)}\}$ with $i = 1, \dots, m$ is given.

The logistic regression model is defined by

$$f(x_1, x_2) = \frac{1}{1 + e^{-(\theta_1 x_1 + \theta_2 x_2 + b)}}$$

where θ_1 and θ_2 are parameters (weights) for the features. and b is some bias term.

The predicted outcome using the logistic model is

$$y^{(i)} = f(x_1^{(i)}, x_2^{(i)})$$

Think: What is the range of f ?

The amount of error we made is characterized by the following function. Let us define

$$L(\theta_1, \theta_2, b) = \sum_{i=1}^m [y^i \log(\hat{y}^i) + (1 - y^i) \log(1 - \hat{y}^i)]$$

What is the gradient vector?

6.3.1. Solution

- What is the range of f ?

The range of the general logistic function $\sigma(z) = \left(\frac{1}{1+e^{-z}}\right)$ is:

- As $z \rightarrow +\infty, \sigma(z) \rightarrow 0$
- As $z \rightarrow -\infty, \sigma(z) \rightarrow 1$

- What is the gradient vector?

$$\nabla f(\theta_1, \theta_2, b) = \left(\frac{\partial L}{\partial \theta_1}, \frac{\partial L}{\partial \theta_2}, \frac{\partial L}{\partial b} \right)$$

To simplify $L = \sum_{i=1}^m l^i$ where $l^i = [y^i \log(\hat{y}^i) + (1 - y^i) \log(1 - \hat{y}^i)]$

$$(a) \frac{\partial L}{\partial \theta_1} = \frac{1}{m} \sum_{i=1}^m (\hat{y}^{(i)} - y^{(i)}) x_1^{(i)}$$

So we need to find $\frac{\partial l}{\partial \theta_1}$

$$\begin{aligned} \frac{\partial l}{\partial \theta_1} &= - \left[\frac{\partial}{\partial \theta_1} y \log(\hat{y}) + \frac{\partial}{\partial \theta_1} (1 - y) \log(1 - \hat{y}) \right] \\ &= - \left[y \frac{1}{\hat{y}} \frac{\partial \hat{y}}{\partial \theta_1} + (1 - y) \frac{1}{1 - \hat{y}} \frac{\partial (1 - \hat{y})}{\partial \theta_1} \right] \quad (\text{applying chainrule}) \end{aligned}$$

$$\text{since } \frac{\partial (1 - \hat{y})}{\partial \theta_1} = \frac{\partial 1}{\partial \theta_1} - \frac{\partial \hat{y}}{\partial \theta_1} = 0 - \frac{\partial \hat{y}}{\partial \theta_1}$$

$$\begin{aligned} &= - \left[y \frac{1}{\hat{y}} \frac{\partial \hat{y}}{\partial \theta_1} + (1 - y) \frac{1}{1 - \hat{y}} \frac{\partial \hat{y}}{\partial \theta_1} \right] \\ &= - \left[y \frac{1}{\hat{y}} \frac{\partial \hat{y}}{\partial \theta_1} + \frac{1 - y}{1 - \hat{y}} \frac{\partial \hat{y}}{\partial \theta_1} \right] \end{aligned}$$

Then factor out $\frac{\partial \hat{y}}{\partial \theta_1}$

$$= - \left(y \frac{1}{\hat{y}} + \frac{1 - y}{1 - \hat{y}} \right) \cdot \frac{\partial \hat{y}}{\partial \theta_1}$$

This can be simplified by:

$$\begin{aligned} \frac{y}{\hat{y}} - \frac{1 - y}{1 - \hat{y}} &= \frac{y(1 - \hat{y})}{\hat{y}(1 - \hat{y})} - \frac{\hat{y}(1 - y)}{\hat{y}(1 - y)} = \frac{y(1 - \hat{y}) - (\hat{y}(1 - y))}{\hat{y}(1 - y)} \\ \frac{y - y\hat{y} - (\hat{y} - \hat{y}y)}{\hat{y}(1 - y)} &= \frac{y - y\hat{y} - \hat{y} + \hat{y}y}{\hat{y}(1 - y)} = \frac{y - \hat{y}}{\hat{y}(1 - y)} \end{aligned}$$

So now

$$\frac{\partial l}{\partial \theta_1} = - \frac{y - \hat{y}}{\hat{y}(1 - y)} \frac{\partial \hat{y}}{\partial \theta_1}.$$

Since $\sigma(x) = \frac{1}{1 + e^{-x}}$, $\sigma'(x) = \sigma(x)(1 - \sigma(x))$ and by chain-rule

Then for $f(z) = \frac{1}{1 + e^z}$

$$\frac{\partial \hat{y}}{\partial \theta_1} \Rightarrow \frac{\partial \hat{y}}{\partial z} \frac{\partial z}{\partial \theta_1} = \hat{y}(1 - \hat{y}) \cdot x_1$$

So now

$$\frac{\partial l}{\partial \theta_1} = - \frac{y - \hat{y}}{\hat{y}(1 - y)} \frac{\partial \hat{y}}{\partial \theta_1} = \frac{y - \hat{y}}{\hat{y}(1 - y)} \hat{y}(1 - \hat{y}) \cdot x_1 =$$

$$\frac{\partial l}{\partial \theta_1}(\hat{y} - y)x_1 \implies \frac{\partial L}{\partial \theta_1} = \frac{1}{m} \sum_{i=1}^m (\hat{y}^{(i)} - y^{(i)})x_1^{(i)}$$

$$(b) \frac{\partial L}{\partial \theta_2} = \frac{1}{m} \sum_{i=1}^m (\hat{y}^{(i)} - y^{(i)})x_2^{(i)}$$

Following the same procedure as (a) but differentiating w.r.t. θ_2 instead of θ_1

So.

$$\frac{\partial \hat{y}}{\partial \theta_2} \Rightarrow \frac{\partial \hat{y}}{\partial z} \frac{\partial z}{\partial \theta_2} = \hat{y}(1 - \hat{y}) \cdot x_2$$

So now

$$\frac{\partial l}{\partial \theta_2} = -\frac{y - \hat{y}}{\hat{y}(1 - \hat{y})} \frac{\partial \hat{y}}{\partial \theta_2} = \frac{y - \hat{y}}{\hat{y}(1 - \hat{y})} \hat{y}(1 - \hat{y}) \cdot x_2 =$$

$$\frac{\partial l}{\partial \theta_2}(\hat{y} - y)x_2 \implies \frac{\partial L}{\partial \theta_2} = \frac{1}{m} \sum_{i=1}^m (\hat{y}^{(i)} - y^{(i)})x_2^{(i)}$$

$$(c) \frac{\partial L}{\partial b} = \frac{1}{m} \sum_{i=1}^m (\hat{y}^{(i)} - y^{(i)})$$

Following the same procedure as (a) but differentiating w.r.t. b instead of θ_1

So.

$$\frac{\partial \hat{y}}{\partial b} \Rightarrow \frac{\partial \hat{y}}{\partial z} \frac{\partial z}{\partial b} = \hat{y}(1 - \hat{y})$$

So now

$$\frac{\partial l}{\partial b} = -\frac{y - \hat{y}}{\hat{y}(1 - \hat{y})} \frac{\partial \hat{y}}{\partial b} = \frac{y - \hat{y}}{\hat{y}(1 - \hat{y})} \hat{y}(1 - \hat{y}) =$$

$$\frac{\partial l}{\partial b}(\hat{y} - y)x_2 \implies \frac{\partial L}{\partial b} = \frac{1}{m} \sum_{i=1}^m (\hat{y}^{(i)} - y^{(i)})$$

$$\nabla f(\theta_1, \theta_2, b) = \left(\frac{1}{m} \sum_{i=1}^m (\hat{y}^{(i)} - y^{(i)})x_1^{(i)}, \frac{1}{m} \sum_{i=1}^m (\hat{y}^{(i)} - y^{(i)})x_2^{(i)}, \frac{1}{m} \sum_{i=1}^m (\hat{y}^{(i)} - y^{(i)}) \right)$$

$$\nabla f(\theta_1, \theta_2, b) = \frac{1}{m} \sum_{i=1}^m (\hat{y}^{(i)} - y^{(i)}) \left(x_1^{(i)}, x_2^{(i)}, 1 \right)$$

6.4. Problem 4

A function $f(x_1, \dots, x_n)$ has n first-order partial derivatives

$$\frac{\partial f}{\partial x_i}, \quad i = 1, \dots, n$$

How many second-order partial derivatives does it have?

6.4.1. Solution

Since

$$\frac{\partial^2 f}{\partial x_i^2}, \frac{\partial^2 f}{\partial x_i \partial x_j} \quad i, j = 1, \dots, n, \quad i \neq j$$

n^2 total mixed derivatives. So

$$n + n(n - 1) = n^2$$

6.5. Problem 5

Compute the second-order partial derivatives of

$$f(x_1, x_2) = x_1 x_2^2 + 3x_1^2 e^{x_2}$$

6.5.1. Solution

There should be $n^2 = 2^2 = 4$ possible second-order partial derivatives of $f(x_1, x_2)$

These are

$$\frac{\partial^2 f}{\partial x_1^2}, \quad \frac{\partial^2 f}{\partial x_2^2}, \quad \frac{\partial^2 f}{\partial x_1 \partial x_2}, \quad \frac{\partial^2 f}{\partial x_2 \partial x_1}$$

Now compute them all

$$\frac{\partial^2 f}{\partial x_1^2} = \frac{\partial}{\partial x_1} (x_2^2 + 6x_1 e^{x_2}) = 6e^{x_2}$$

$$\frac{\partial^2 f}{\partial x_2^2} = \frac{\partial}{\partial x_2} (2x_1 x_2 + 3x_1^2 e^{x_2}) = 2x_1 + 3x_1^2 e^{x_2}$$

$$\frac{\partial^2 f}{\partial x_1 \partial x_2} = \frac{\partial}{\partial x_1} (2x_1 x_2 + 3x_1^2 e^{x_2}) = 2x_2 + 6x_1 e^{x_2}$$

$$\frac{\partial^2 f}{\partial x_2 \partial x_1} = \frac{\partial}{\partial x_2} (x_2^2 + 6x_1 e^{x_2}) = 2x_2 + 6x_1 e^{x_2}$$

6.6. Problem 6

Find and analyze the critical points of

$$f(x, y) = x^2 - 2x + y^2 - 4y + 5$$

6.6.1. Solution

Then

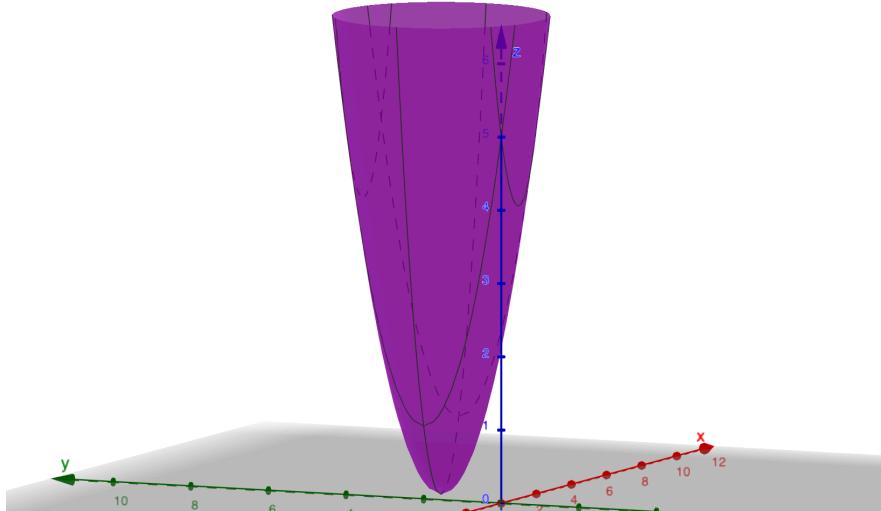
$$H = \begin{bmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial f}{\partial x \partial y} \\ \frac{\partial f}{\partial y \partial x} & \frac{\partial^2 f}{\partial y^2} \end{bmatrix} = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}$$

For a hessian $\det \begin{bmatrix} 2-\lambda & 0 \\ 0 & 2-\lambda \end{bmatrix} = 0$

So

$$(2-\lambda)(2-\lambda) - 0 \cdot 0 = 0 \Rightarrow \lambda = 2$$

So local minimum



As shown here, the critical point is also the global min

$$0 = \frac{\partial f}{\partial x} \Rightarrow x = 1$$

$$0 = \frac{\partial f}{\partial y} \Rightarrow y = 2$$

global min is at $x = 1, y = 2 \rightarrow f(1, 2) = 0$

6.7. Problem 7

Find and analyze any critical points of

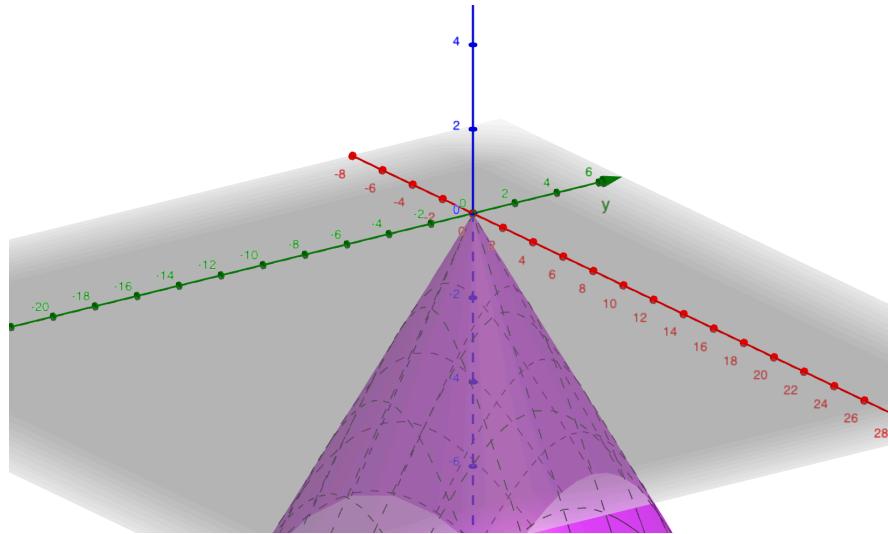
$$f(x, y) = -\sqrt{x^2 + y^2}$$

6.7.1. Solution

$$f_x(x, y) = -\frac{x}{\sqrt{x^2 + y^2}}, \quad f_y(x, y) = -\frac{y}{\sqrt{x^2 + y^2}}$$

$$f_x(0, 0) = \frac{0}{0} = \text{DNE}, \quad f_y(0, 0) = \frac{0}{0} = \text{DNE}$$

f is a cone though, where its global maximum is $f(0, 0) = 0$



6.8. Problem 8

Find and analyze any critical points of

$$f(x, y) = x^2 + y^2$$

6.8.1. Solution

Then

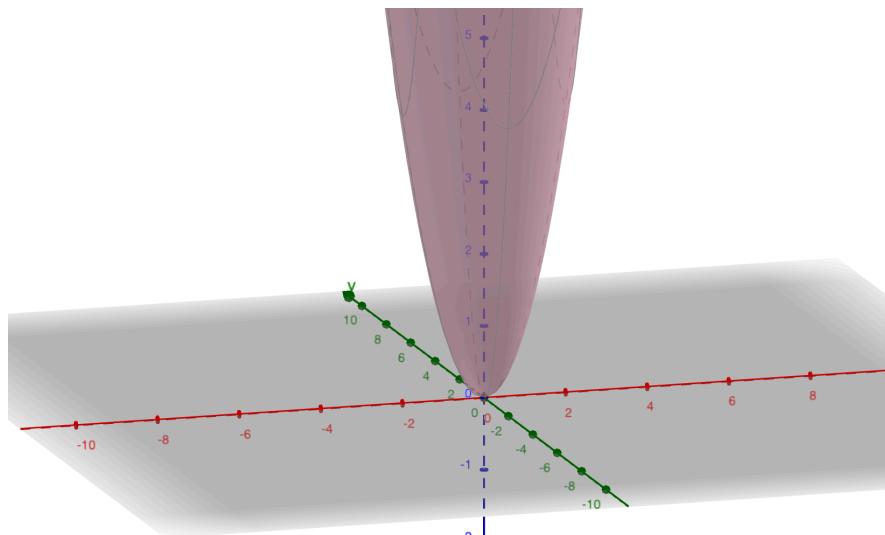
$$H = \begin{bmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial f}{\partial x \partial y} \\ \frac{\partial f}{\partial y \partial x} & \frac{\partial^2 f}{\partial y^2} \end{bmatrix} = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}$$

For a hessian $\det \begin{bmatrix} 2-\lambda & 0 \\ 0 & 2-\lambda \end{bmatrix} = 0$

So

$$(2-\lambda)(2-\lambda) - 0 \cdot 0 = 0 \Rightarrow \lambda = 2$$

So local minimum



The minimum must also be the global min

$$0 = \frac{\partial f}{\partial x} \Rightarrow x = 0$$

$$0 = \frac{\partial f}{\partial y} \Rightarrow y = 0$$

global min is at $0, 0 \rightarrow f(0, 0) = 0$

6.9. Problem 7

Classify the critical points of

$$f(x, y) = x^4 + y^4$$

6.9.1. Solution

Then

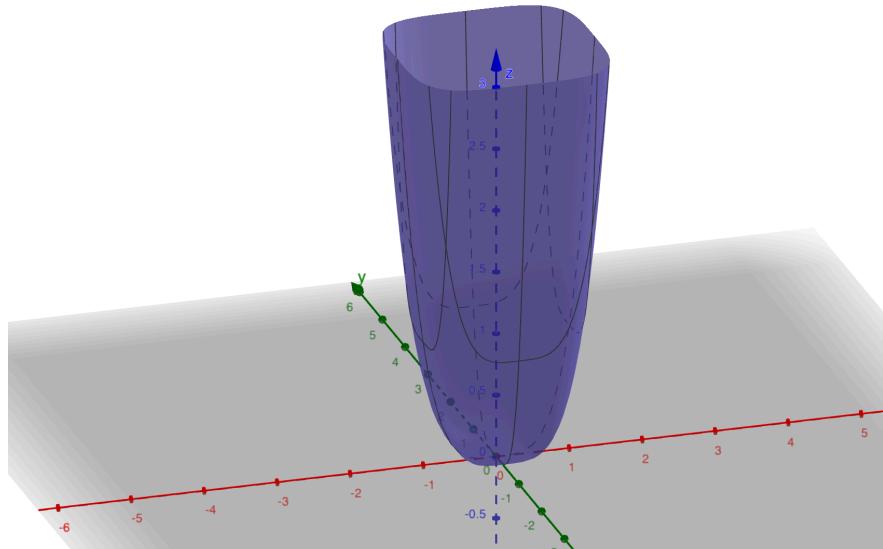
$$H = \begin{bmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial f}{\partial x \partial y} \\ \frac{\partial f}{\partial y \partial x} & \frac{\partial^2 f}{\partial y^2} \end{bmatrix} = \begin{bmatrix} 12x^2 & 0 \\ 0 & 12y^2 \end{bmatrix}$$

$$\text{For a hessian } \det \begin{pmatrix} 12x^2 - \lambda & 0 \\ 0 & 12y^2 - \lambda \end{pmatrix} = 0$$

So

$$(12x^2 - \lambda)(12y^2 - \lambda) = 0 \Rightarrow \lambda = 2$$

Because of $\lambda_1, \lambda_2 < 0$, this indicates local mimimum



The local minimum must also be the global min

$$0 = \frac{\partial f}{\partial x} \Rightarrow x = 0$$

$$0 = \frac{\partial f}{\partial y} \Rightarrow y = 0$$

gobal min is at $0, 0 \rightarrow f(0, 0) = 0$

6.10. Problem 8

Classify the critical points of

$$f(x, y) = -x^4 - y^4$$

6.10.1. Solution

Then

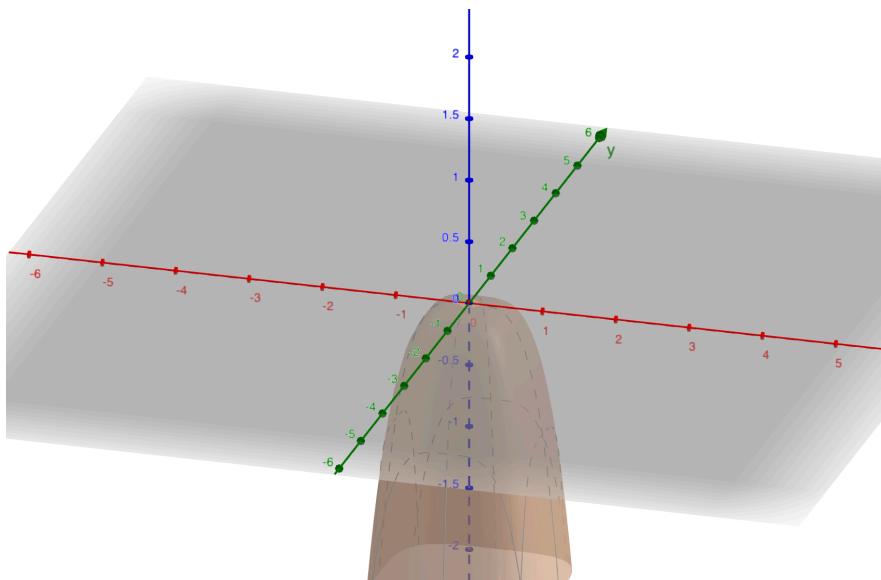
$$H = \begin{bmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial f}{\partial x \partial y} \\ \frac{\partial f}{\partial y \partial x} & \frac{\partial^2 f}{\partial y^2} \end{bmatrix} = \begin{bmatrix} -12x^2 & 0 \\ 0 & -12y^2 \end{bmatrix}$$

$$\text{For a hessian } \det \begin{pmatrix} -12x^2 - \lambda & 0 \\ 0 & -12y^2 - \lambda \end{pmatrix} = 0$$

So

$$(12x^2 - \lambda)(12y^2 - \lambda) = 0 \Rightarrow \lambda = -12 * x^2$$

Since $\lambda_1, \lambda_2 \leq 0$, I cannot directly conclude anything, only based on the eigenvalues from the hessian matrix. But since for $x, y \neq 0$, all eigenvalues are strictly negative, this is most likely a local maximum



The local max is clearly shown above. The local max must also be the global maxima

$$0 = \frac{\partial f}{\partial x} \Rightarrow x = 0$$

$$0 = \frac{\partial f}{\partial y} \Rightarrow y = 0$$

global min is at $0, 0 \rightarrow f(0, 0) = 0$

6.11. Problem 9

Classify the critical points of

$$f(x, y) = x^4 - y^4$$

6.11.1. Solution

Then

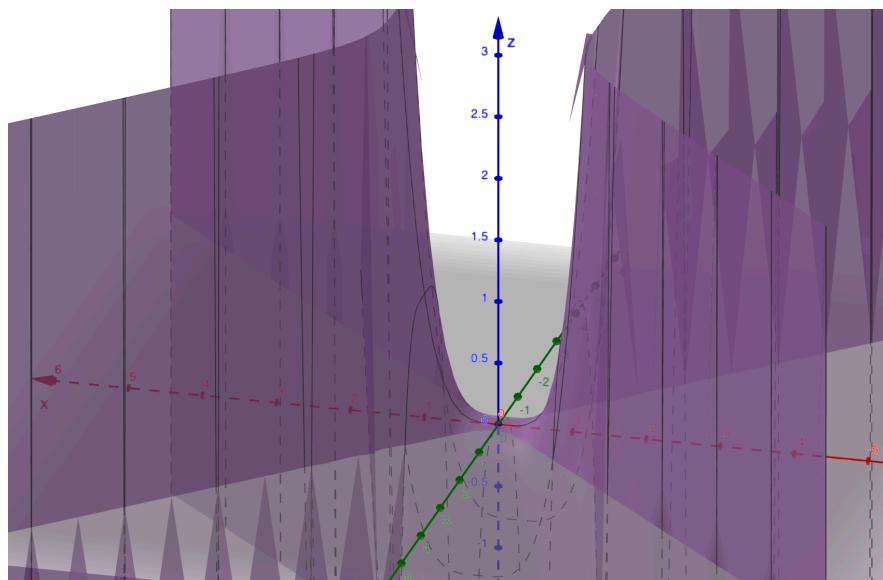
$$H = \begin{bmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial f}{\partial x \partial y} \\ \frac{\partial f}{\partial y \partial x} & \frac{\partial^2 f}{\partial y^2} \end{bmatrix} = \begin{bmatrix} 12x^2 & 0 \\ 0 & -12y^2 \end{bmatrix}$$

$$\text{For a hessian } \det \begin{pmatrix} 12x^2 - \lambda & 0 \\ 0 & -12y^2 - \lambda \end{pmatrix} = 0$$

So

$$(12x^2 - \lambda)(12y^2 - \lambda) = 0 \Rightarrow \lambda = -12x^2, 12y^2$$

Since $\lambda \leq 0 \geq \lambda$ and , I cannot directly conclude anything, only based on the eigenvalues from the hessian matrix. But since for $x, y \neq 0$, the eigenvalues have mixed signs, this is most likely a saddle point



The saddlepoint can be seen above.

$$0 = \frac{\partial f}{\partial x} \Rightarrow x = 0$$

$$0 = \frac{\partial f}{\partial y} \Rightarrow y = 0$$

The saddle point is at $0, 0 \rightarrow f(0, 0) = 0$

7. Lecture 7

7.1. Problem 1

Do all functions have global extrema? Can you think of a counterexample?

7.1.1. Solution

The global max is the the largest value $f(x)$ takes.

But if $f(x) \rightarrow +\infty$, then $f(x)$ does not have a global extrema

7.2. Problem 2

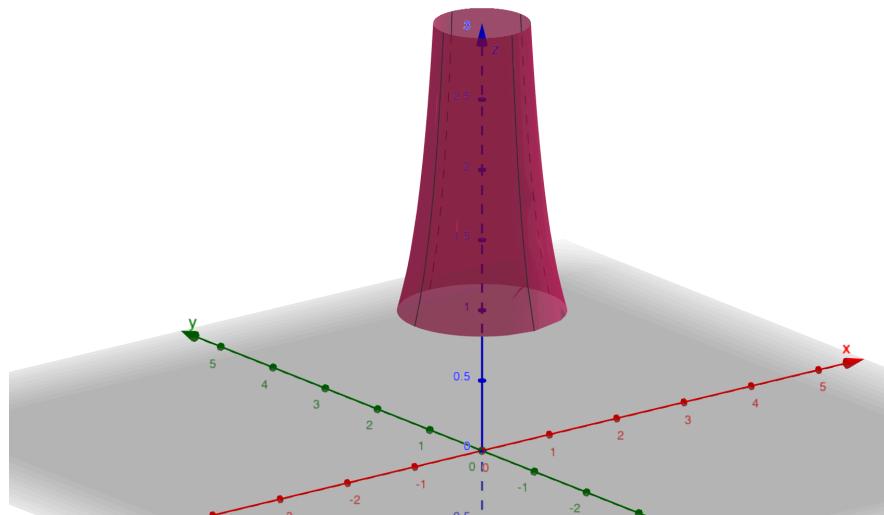
Does the function

$$f(x, y) = \frac{1}{x^2 + y^2}$$

have global maxima and minima on the region R given by $0 < x^2 + y^2 \leq 1$?

7.2.1. Solution

First inspect f



Since R is $(0, 1]$, R is not closed, therfore f does not have a global max

It does however has a global min at $\frac{1}{x^2+y^2} = 1$

7.3. Problem 3

Does the function

$$f(x, y) = x^2 y^2$$

have global maxima and minima in the xy -plane?

7.3.1. Solution

The range for f is $[0, \infty)$ as $|x|$ and $|y|$ grows arbitrarily large, and $f(x, y) \rightarrow \infty$

So global minima at $f(x, y) = 0$

And no global maxima

7.4. Problem 4

Suppose that $z = f(x, y) = x \sin(y)$, where $x = t^2$ and $y = 2t + 1$

Compute $f'(x, y)$ directly and using the chain rule.

7.4.1. Solution

$$\frac{\partial}{\partial t} f(x, y) = \frac{\partial f}{\partial x} \cdot \frac{\partial x}{\partial t} + \frac{\partial f}{\partial y} \cdot \frac{\partial y}{\partial t}$$

Then

$$\frac{\partial}{\partial t} f(x, y) = \sin(y) \cdot 2t + x \cos(y) \cdot 2$$

Then substitute x and y

$$\frac{\partial}{\partial t} f(x, y) = 2 \sin(2t + 1) \cdot t + 2t^2 \cos(2t + 1)$$

7.5. Problem 5

If f, g, h are differentiable and if $z = f(x, y)$, with $x = g(u, v)$ and $y = h(u, v)$

What is $\frac{\partial z}{\partial u}$ and $\frac{\partial z}{\partial v}$?

7.5.1. Solution

$$\frac{\partial z}{\partial u} = \frac{\partial z}{\partial x} \cdot \frac{\partial x}{\partial u} + \frac{\partial z}{\partial y} \cdot \frac{\partial y}{\partial u}$$

$$\frac{\partial z}{\partial v} = \frac{\partial z}{\partial x} \cdot \frac{\partial x}{\partial v} + \frac{\partial z}{\partial y} \cdot \frac{\partial y}{\partial v}$$

8. Lecture 8

8.1. Problem 1

Show that if f is differentiable with the local linearization

8.1.1. Solution

$$L(x) = f(a) - \sum_{i=1}^n m_i(x_i - a_i)$$

Then

$$m_i = \frac{\partial f}{\partial x_i}(a)$$

since

$$f(x) \approx L(x) = f(a) + \sum_{i=1}^n \frac{\partial f}{\partial x_i}(x_i - a_i)$$

8.2. Problem 2

Consider the function

$$f(x, y) = \sqrt{x^2 + y^2}$$

is f differentiable at the origin?

8.2.1. Solution

To check this

$$f_x(x, y) = \lim_{h \rightarrow 0} \frac{f(x + h, y) - f(x, y)}{h}$$

$$f_x(0, 0) = \lim_{h \rightarrow 0} \frac{f(h, 0) - f(0, 0)}{h} = \lim_{h \rightarrow 0} \frac{\sqrt{h^2}}{h} = \lim_{h \rightarrow 0} \frac{|h|}{h} = \text{DNE}$$

$$f_y(x, y) = \lim_{h \rightarrow 0} \frac{f(x, y + h) - f(x, y)}{h}$$

$$f_y(0, 0) = \lim_{h \rightarrow 0} \frac{f(0, h) - f(0, 0)}{h} = \lim_{h \rightarrow 0} \frac{\sqrt{h^2}}{h} = \lim_{h \rightarrow 0} \frac{|h|}{h} = \text{DNE}$$

f is **not** differentiable at the origin

8.3. Problem 3

Consider the function

$$f(x, y) = x^{\frac{1}{3}}y^{\frac{1}{3}}$$

Compute the partial derivatives at $(x, y) = (0, 0)$.

Is f differentiable at $(0, 0)$?

8.3.1. Solution

To check this

$$f_x(x, y) = \lim_{h \rightarrow 0} \frac{f(x+h, y) - f(x, y)}{h}$$

$$f_x(0, 0) = \lim_{h \rightarrow 0} \frac{f(h, 0) - f(0, 0)}{h} = \lim_{h \rightarrow 0} \frac{h^{\frac{1}{3}} \cdot 0^{\frac{1}{3}}}{h} = \lim_{h \rightarrow 0} \frac{0}{h} = 0$$

$$f_y(x, y) = \lim_{h \rightarrow 0} \frac{f(x, y+h) - f(x, y)}{h}$$

$$f_y(0, 0) = \lim_{h \rightarrow 0} \frac{f(0, h) - f(0, 0)}{h} = \lim_{h \rightarrow 0} \frac{0^{\frac{1}{3}} \cdot h^{\frac{1}{3}}}{h} = \lim_{h \rightarrow 0} \frac{0}{h} = 0$$

Note that to prove differentiability f must also be continuous on a small disk centered at the point a (local linearization)

For differentiability:

$$\lim_{h \rightarrow 0} \frac{E(x)}{\|h\|} = 0$$

Lets do that

$$\lim_{(h_1, h_2) \rightarrow (0, 0)} \frac{f(x) - L(x)}{\sqrt{h_1^2 + h_2^2}}$$

$$\lim_{(x, y) \rightarrow (a, b)} \frac{f(x) - L(x)}{\sqrt{h_1^2 + h_2^2}}$$

Since

$$L(0, 0) = f(0, 0) + f_x(0, 0)(x - 0) + f_y(0, 0)(y - 0) = 0 + 0x + 0y = 0$$

then

$$\lim_{(x, y) \rightarrow (0, 0)} \frac{x^{\frac{1}{3}}y^{\frac{1}{3}}}{\sqrt{(x)^2 + (y)^2}} = \text{DNE}$$

f is **not** differentiable at $(0, 0)$

8.4. Problem 4

Show that the function $f(x, y) = \ln(x^2 + y^2)$ is differentiable everywhere in its domain.

8.4.1. Solution

The domain of f is $(x, y) \in \mathbb{R}^2 \mid (x, y) \neq (0, 0)$

If the partial derivatives, f_x and f_y , of a function f exist and are continuous on a small disk centered at the point a , then f is differentiable at a .

Because of this, we want to show that f_x and f_y both exist and are continuous on the whole domain

$$f_x(x, y) = \frac{2x}{x^2 + y^2}, \quad f_y(x, y) = \frac{2y}{x^2 + y^2}$$

These are continuous on the whole domain, since $(x, y) \neq (0, 0)$

8.5. Problem 5

Use the definition of the definite integral to compute

$$\int_a^b c \, dx$$

8.5.1. Solution

The definition of the definite integral is:

$$\int_a^b f(x) \, dx = \lim_{n \rightarrow \infty} \sum_{k=1}^n f(x_k^*) \Delta x$$

Where $x_k = a + k \cdot \Delta x$, $\Delta x = \frac{b-a}{n}$ and $x_k^* \in [x_{k-1}, x_k]$

So then

$$\int_a^b c \, dx = \lim_{n \rightarrow \infty} \sum_{k=1}^n c \frac{b-a}{n} = \lim_{n \rightarrow \infty} n \cdot c \cdot \frac{b-a}{n} = c(b-a)$$

8.6. Problem 6

Use the definition of definite integral to simplify

$$\int_a^b cf(x) dx \quad \text{for a constant } c.$$

8.6.1. Solution

The definition of the definite integral is:

$$\int_a^b f(x) dx = \lim_{n \rightarrow \infty} \sum_{k=1}^n f(x_k^*) \Delta x$$

Where $x_k = a + k \cdot \Delta x$, $\Delta x = \frac{b-a}{n}$ and $x_k^* \in [x_{k-1}, x_k]$

$$\int_a^b cf(x) dx = \lim_{n \rightarrow \infty} \sum_{k=1}^n cf(x_k^*) \Delta x$$

$$\lim_{n \rightarrow \infty} c \cdot \sum_{k=1}^n f(x_k^*) \Delta x = c \cdot \lim_{n \rightarrow \infty} \sum_{k=1}^n f(x_k^*) \Delta x = c \cdot \int_a^b f(x) dx$$

8.7. Problem 7

Use the definition of definite integral to show that

$$\int_a^b f(x) + g(x) dx = \int_a^b f(x) dx + \int_a^b g(x) dx$$

8.7.1. Solution

$$\begin{aligned} \int_a^b f(x) + g(x) dx &= \lim_{n \rightarrow \infty} \sum_{k=1}^n f(x_k^*) + g(x_k^*) \Delta x \\ &= \lim_{n \rightarrow \infty} \sum_{k=1}^n f(x_k^*) \Delta x + \lim_{n \rightarrow \infty} \sum_{k=1}^n g(x_k^*) \Delta x \\ &= \int_a^b f(x) dx + \int_a^b g(x) dx \end{aligned}$$

8.8. Problem 8

Evaluate

$$\int_0^3 2x \, dx$$

as a limit of Riemann sums.

8.8.1. Solution

$$\begin{aligned} \int_0^3 2x \, dx &= \lim_{n \rightarrow \infty} \sum_{k=1}^n f(x_k^*) \Delta x \\ &= \lim_{n \rightarrow \infty} \sum_{k=1}^n 2x \cdot \frac{3}{n} \end{aligned}$$

Since $x = k\Delta x = \frac{3k}{n}$

$$\begin{aligned} &= \lim_{n \rightarrow \infty} \sum_{k=1}^n \frac{6k}{n} \cdot \frac{3}{n} \\ &= \lim_{n \rightarrow \infty} \sum_{k=1}^n \frac{18k}{n^2} \\ &= \lim_{n \rightarrow \infty} \frac{18}{n^2} \cdot \sum_{k=1}^n k \\ &= \lim_{n \rightarrow \infty} \frac{18}{n^2} \cdot n(n+1) \\ &= \lim_{n \rightarrow \infty} \frac{18(n+1)}{2n} \\ &= \lim_{n \rightarrow \infty} \frac{9(n+1)}{n} \\ &= \lim_{n \rightarrow \infty} 9 + \frac{1}{n} = 9 \end{aligned}$$

8.9. Problem 9

Compute

$$\int_0^3 2x \, dx$$

Using the fundamental theorem of calculus.

8.9.1. Solution

$$\int_a^b f(x) \, dx = F(b) - F(a)$$

$$\int_0^3 2x \, dx = F(3) - F(0)$$

Since

$$\int 2x \, dx = x^2$$

$$F(3) - F(0) = 9$$

8.10. Problem 10

Find

$$\frac{d}{dx} \left[\int_2^x \cos(t) \, dx \right]$$

8.10.1. Solution

Since

$$\frac{d}{dx} \left[\int_a^x g(t) \, dx \right] = g(x)$$

by second FTC

then

$$\frac{d}{dx} \left[\int_2^x \cos(t) \, dx \right] = \cos(x)$$

8.11. Problem 11

Let

$$g(x) = \int_1^x \sqrt{1+t^2} \, dx$$

- Find $g'(x)$
- Find $g(x^3)$
- Compute $\frac{d}{dx} g(x^3)$.

8.11.1. Solution

- Find $g'(x)$ Since

$$\frac{d}{dx} \left[\int_a^x g(t) \, dx \right] = g(x)$$

by second FTC

then

$$\frac{d}{dx} \left[\int_1^x \sqrt{1+t^2} \, dx \right] = \sqrt{1+x^2}$$

- Find $g(x^3)$

I want to express

$$g(x^3) = \int_1^{x^3} \sqrt{1+t^2} \, dx$$

- Compute $\frac{d}{dx}g(x^3)$.

Since

$$\frac{d}{dx} \left[\int_a^x g(t) \, dx \right] = g(x)$$

by second FTC

and

$$g(x^3) = \int_1^{x^3} \sqrt{1+t^2} \, dx$$

then

$$\frac{d}{dx}g(x^2) = \frac{d}{dx} \left[\int_1^{x^3} \sqrt{1+t^2} \, dx \right]$$

This is done by chainrule

$$\frac{d}{dt}f(x) = \frac{df}{dx} \cdot \frac{dx}{dt}$$

So

$$\begin{aligned} \frac{d}{dx} \left[\int_1^{x^3} \sqrt{1+t^2} \, dx \right] \\ \frac{d}{dx} \left[\int_1^{x^3} \sqrt{1+t^2} \, dx \right] = \sqrt{1+x^6} \cdot 3x^2 \end{aligned}$$

9. Lecture 9

9.1. Problem 1

Compute

$$\int_0^\infty e^{-5x} dx$$

9.1.1. Solution

Since

$$\int_a^\infty f(x) dx = \lim_{b \rightarrow \infty} \int_a^b f(x) dx$$

So

$$\int_0^\infty e^{-5x} dx = \lim_{b \rightarrow \infty} \int_0^b e^{-5x} dx$$

By first FTC

$$\lim_{b \rightarrow \infty} F(b) - F(0) = \lim_{b \rightarrow \infty} -\frac{e^{-5b}}{5} - \left(-\frac{e^{-5(0)}}{5} \right) = 0 - \left(-\frac{1}{5} \right) = \frac{1}{5}$$

9.2. Problem 2

Investigate the convergence of

$$\int_0^2 \frac{1}{(x-2)^2} dx.$$

9.2.1. Solution

By looking at the graph i can see that has assymtotic behvaior close to $x = 2$

This makes sense, because f is undefined at $x = 2$. Therfore

$$\lim_{b \rightarrow 2} \int_0^b \frac{1}{(x-2)^2} dx$$

Then using first FTC

$$\lim_{b \rightarrow 2} \int_0^b \frac{1}{(x-2)^2} dx = \lim_{b \rightarrow 2} F(b) - F(0)$$

Since $F(x) = -\frac{1}{x-2}$

$$\lim_{b \rightarrow 2} F(b) - F(0) = \lim_{b \rightarrow 2} \left(-\frac{1}{b-2} - \left(-\frac{1}{-2} \right) \right) = \lim_{b \rightarrow 2} \left(-\frac{1}{b-2} - \frac{1}{2} \right)$$

Since f diverges from 2^-

$$\lim_{b \rightarrow 2^-} \left(-\frac{1}{b-2} - \frac{1}{2} \right) = +\infty$$

9.3. Problem 3

Compute

$$\int_2^3 2x \sin(x^2) dx$$

Hint: Let $u = x^2$, then $du = 2x dx$. After substitution, the integral becomes

$$\int_{u(a)}^{u(b)} \sin(u) du = \int_{2^2}^{3^2} \sin(u) du$$

9.3.1. Solution

$$\int_3^9 \sin(u) du = F(9) - F(3) = \cos(9) - \cos(3) \approx 0.26$$

9.4. Problem 4

Evaluate

$$\int_0^1 x(x-1)^4 dx$$

9.4.1. Solution

Let $u = x$, then $du = x dx$. After substitution, the integral becomes

$$\int_{u(a)}^{u(b)} u^4 du = \int_{0-1}^{1-1} u^4 du$$

Then

$$\int_{-1}^0 u^4 du = F(0) - F(-1)$$

Since

$$F(x) = \frac{x^5}{5}$$

$$F(0) - F(-1) = \frac{0^5}{5} - \frac{(-1)^5}{5} = \frac{1}{5}$$

9.5. Problem 5

Evaluate

$$\int \sin^2(x) \, dx$$

9.5.1. Solution

$$\int \sin^2(x) \, dx = -\frac{\sin(x) \cos(x)}{2} + \frac{x}{2} + C$$

9.6. Problem 6

Evaluate

$$\int_0^1 x e^x \, dx$$

9.6.1. Solution

For definite integrals

$$\int_a^b f(x)g'(x) \, dx = (f(b)g(b) - f(a)g(a)) - \int_a^b f'(x)g(x) \, dx$$

For this.

$$\int_0^1 x e^x \, dx = (1 \cdot e^1 - 0 \cdot e^0) - \int_0^1 1 \cdot e^x \, dx$$

$$\int_0^1 x e^x \, dx = e - \int_0^1 e^x \, dx = e - (e^1 - e^0) = 1$$

9.7. Problem 7

Evaluate

$$\int_1^2 \ln(x) \, dx$$

9.7.1. Solution

Since $\int \ln(x) \, dx$ is not very intuitive

Let

$$\int_1^2 \ln(x) \, dx = \int_1^2 \ln(x) \cdot 1 \, dx$$

Now for definite integrals

$$\int_a^b f(x)g'(x) \, dx = (f(b)g(b) - f(a)g(a)) - \int_a^b f'(x)g(x) \, dx$$

For this,

$$\int_1^2 \ln(x) \cdot 1 \, dx = (\ln(2) \cdot 2 - \ln(0) \cdot 0) - \int_1^2 \frac{1}{x} \cdot x \, dx$$

Since

$$\int_1^2 \frac{1}{x} \cdot x \, dx = \int_1^2 1 \, dx = 0$$

$$\int_1^2 \ln(x) \cdot 1 \, dx = 2 \ln(2) \approx 1.39$$

9.8. Problem 8

Let M_{ij} and L_{ij} denote the max and min of f on the ij -th rectangle. If (u_{ij}, v_{ij}) is any point in the ij -th subrectangle:

$$\leq \sum_{i=1}^n \sum_{j=1}^m f(u_{ij}, v_{ij}) \Delta x \Delta y$$

- How does $\sum_{(i,j)} f(u_{ij}, v_{ij}) \Delta x \Delta y$ look geometrically?
- What happens as $n, m \rightarrow \infty$?

9.8.1. Solution

- How does $\sum_{(i,j)} f(u_{ij}, v_{ij}) \Delta x \Delta y$ look geometrically?

An area by f approximated by rectangles size $\Delta x \cdot \Delta y$

- What happens as $n, m \rightarrow \infty$?

As $n, m \rightarrow \infty$ each rectangle gets increasingly smaller, and the number of rectangles because larger. So large that the approximation becomes the area

9.9. Problem 9

If $g(x, y) = 1$ what is $\int_R g \, dA$

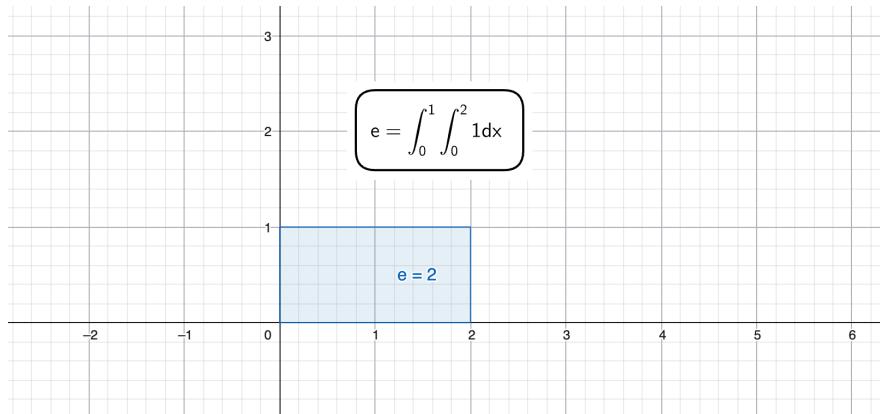
9.9.1. Solution

Since

$$\int_R 1 \, dA = \int_a^b \int_c^d 1 \, dy \, dx = (b - a) \cdot (c - d)$$

Then

$$\int_R g \, dA = \text{Areal of } R$$



9.10. Problem 10

How do we compute the average value of f over R ?

9.10.1. Solution

As for single variable intergration

$$f_{\text{avg}} = \frac{1}{b - a} \cdot \int_a^b f(x) \, dx \implies \frac{\text{Area}}{\text{Length of interval}}$$

Then for two variables

$$f_{\text{avg}} = \frac{1}{\iint_R 1 \, d} \cdot \iint_R f(x) \, dA \implies \frac{\text{Volume under surface } f(x, y)}{\text{Area of } R}$$

9.11. Problem 11

Let $f(x, y) = x^2y$, $R = [0, 1] \times [0, 1]$.

Compute $\int_R f \, dA$

$$\int_0^1 \int_0^1 x^2y \, dx \, dy$$

9.11.1. Solution

First

$$\int_0^1 x^2y \, dx = \frac{1^3 \cdot y}{3} = \frac{y}{3}$$

Then

$$\int_0^1 \frac{y}{3} \, dy = \frac{1^2}{6} = \frac{1}{6}$$

9.12. Problem 12

What if we switch the order of integration?

$$\int_0^1 \int_0^1 x^2y \, dy \, dx$$

9.12.1. Solution

First

$$\int_0^1 x^2y \, dy = \frac{x^2y^2}{2} = \frac{x^2}{2}$$

Then

$$\int_0^1 \frac{x^2}{2} \, dy = \frac{1^3}{6} = \frac{1}{6}$$

Same answer

9.13. Problem 13

A building is 8m wide and 16m long. It has a flat roof 12m high at one corner, and 10m high at each adjacent corner.

Find the volume of the building.

9.13.1. Solution

I assume that the highest corner of the roof is on point $P(0, 0, 12)$

Based on the height of each corner i can know that the surface of the roof, has vector $a = (8, 0, -2)$ and $b = (0, 16, -2)$

i can the find $a(x - x_0) + b(y - y_0) + c(z - z_0) = 0$ with a normal vector N .

Now by using cross product $N = v \times w$

$$N = v \times w = \begin{pmatrix} 32 \\ 16 \\ 128 \end{pmatrix}$$

with point $P(0, 0, 12)$ the plane becomes

$$32(x - 0) + 16(y - 0) + 128(z - 12) = 0$$

$$32x + 16y + 128z - 1536 = 0$$

$$z = -\frac{x}{4} - \frac{y}{8} + 12$$

Then i can

$$\int_0^8 \int_0^{16} -\frac{x}{4} - \frac{y}{8} + 12 \, dy \, dx$$

Since

$$\int -\frac{x}{4} - \frac{y}{8} + 12 \, dy = -\frac{1}{4}xy - \frac{1}{16}y^2 + 12y$$

Then

$$F(16) - F(0) = -4x + 176$$

Now since

$$\int -2x^2 + 176x \, dx = -2x^2 + 176x$$

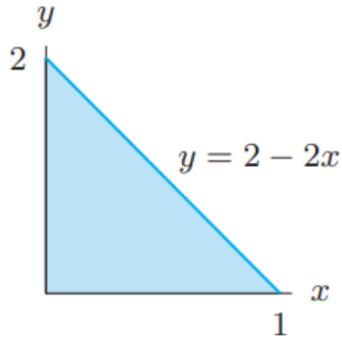
Then

$$F(8) - F(0) = 1280$$

Volume of the building is **1280 m³**

9.14. Problem 14

The density at (x, y) of a triangular metal plate is $\delta(x, y)$. Express its mass as an iterated integral.



9.14.1. Solution

We wish to express

$$m = \iint_R \delta(x, y) \, dA$$

Where $R = \{(x, y) : 0 \leq x \leq 1, 0 \leq y \leq 2 - 2x\}$

Hence

$$m = \int_0^1 \int_0^{2-2x} \delta(x, y) \, dy \, dx$$

9.15. Problem 15

A city occupies a semicircular region of radius 3 km bordering the ocean. Find the average distance from points in the city to the ocean.

9.15.1. Solution

We can use polar coordinates where $0 \leq r \leq 3$ and $0 \leq \theta \leq \pi$

Since it is a semicircle of radius R , the area is $(\frac{1}{2})\pi R^2 = (\frac{1}{2})\pi(3^2) = (\frac{9}{2})\pi$.

We know that $f_{\text{avg}} = \frac{\text{Distance}}{\text{Area of R}}$

Hence

$$f_{\text{avg}} = \frac{\iint \text{distance } dA}{\text{Area of R}} = \frac{\int_0^\pi \int_0^R r^2 dr d\theta}{(\frac{1}{2})\pi R^2}$$

Since $\int_0^R r^2 dr = \frac{R^3}{3}$

$$f_{\text{avg}} = \frac{\int_0^\pi \frac{R^3}{3} d\theta}{(\frac{1}{2})\pi R^2}$$

Since $\int_0^\pi \frac{R^3}{3} d\theta = R^3 \frac{\pi}{3}$

Then

$$f_{\text{avg}} = \frac{R^3 \frac{\pi}{3}}{(\frac{1}{2})\pi R^2}$$

Now substitute R for 3.

$$f_{\text{avg}} = \frac{\frac{3^3 \pi}{3}}{\frac{3^2 \pi}{2}} = \frac{9\pi}{\frac{9}{2}\pi} = 2$$

9.16. Problem 16

Compute

$$\int_W (1 + xyz) dV$$

over the cube $0 \leq x, y, z \leq 4$.

9.16.1. Solution

We know that $W = \{(x, y, z) : 0 \leq x, y, z \leq 4\}$

This means that $W = [0, 4] \times [0, 4] \times [0, 4]$

And therefore

$$\int_W (1 + xyz) dV = \iiint_W (1 + xyz) dV = \int_0^4 \int_0^4 \int_0^4 (1 + xyz) dx dy dz$$

Since $\int (1 + xyz) dx = \frac{1}{2}x^2yz + x$

Then

$$F(4) - F(0) = 8yz + 4$$

And

$$\int_W (1 + xyz) dV = \int_0^4 \int_0^4 (8yz + 4) dy dz$$

Since $\int (8yz + 4) dy = 4y^2z + 4y$

Then

$$F(4) - F(0) = 64z + 16$$

And

$$\int_W (1 + xyz) dV = \int_0^4 64z + 16 dz$$

Since $\int (64z + 16) dz = 32z^2 + 16z$

Then

$$F(4) - F(0) = 576$$

And

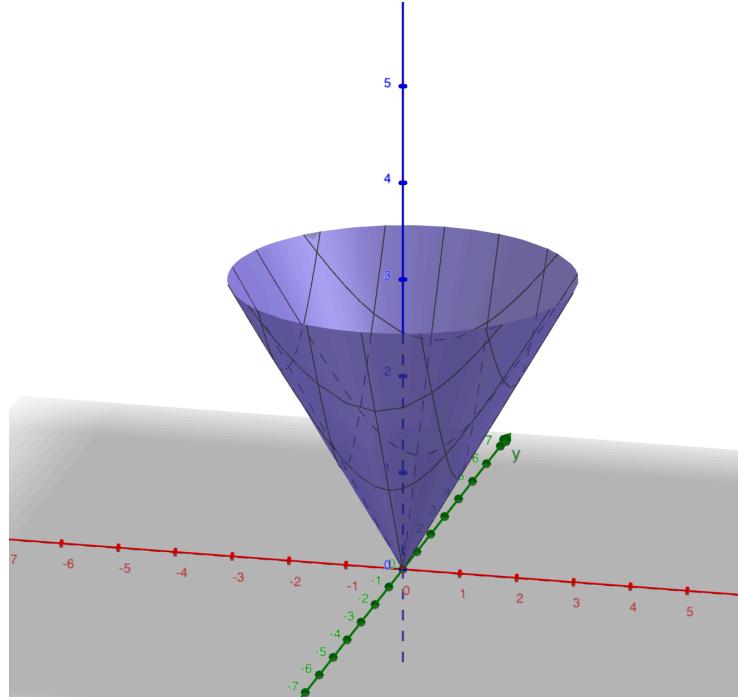
$$\int_W (1 + xyz) dV = \mathbf{576}$$

9.17. Problem 17

Set up an iterated integral for the mass of a solid cone bounded by $z = \sqrt{x^2 + y^2}$ and $z = 3$, with density $\delta(x, y, z) = z$.

9.17.1. Solution

The cone is given by $z = \sqrt{x^2 + y^2}$ and is cut off by the plane $z = 3$ meaning $z \leq 3$



$$z = \sqrt{x^2 + y^2}, \quad \text{where } z \leq 3$$

Then

$$m = \iiint_W \delta(x, y, z) dV$$

in this case this is:

$$\iiint_W z dV$$

Because the of the cone, polar coordinates are easier to work with

$$x = r \cos(\theta), \quad y = r \sin(\theta), \quad \underbrace{z = z}_{\text{cone is on } z}, \quad dV = r dz dr d\theta$$

In this instance θ is the whole circle around the z axis so $0 \leq \theta \leq 2\pi$

To find r we can use the definition of the circle at $z = 3$

Because of $3 = \sqrt{x^2 + y^2} \Rightarrow \underbrace{x^2 + y^2 = 9}_{\text{circle at } z=3}$ where $9 = r^2$, So $r = 3$

This means that $0 \leq r \leq 3$

To find z we look at the cones height from $z = 0$ to $z = 3$.

For any (r, θ) we know that $z = \sqrt{x^2 + y^2} = r$

This means that $\sqrt{x^2 + y^2} \leq z \leq 3 \implies r \leq z \leq 0$

Finally we can put it all together

$$\int_0^{2\pi} \int_0^3 \int_r^3 \delta(x, y, z) r \, dz \, dr \, d\theta = \int_0^{2\pi} \int_0^3 \int_r^3 \sqrt{x^2 + y^2} r \, dz \, dr \, d\theta$$

10. Lecture 10

No new problems

11. Lecture 11

11.1. Problem 1

Evaluate

$$\int_0^1 xe^{x^2} dx$$

(Recall: set $u = x^2$, $du = 2x dx$.)

11.1.1. Solution

When $u = x^2$ and $dx = 2x$

Then

$$\int_0^1 xe^{x^2} dx = \int_0^1 \frac{1}{2} \cdot e^u du$$

Now

$$\int_0^1 \frac{1}{2} \cdot e^u du = F(1) - F(0)$$

Since $\int \frac{1}{2} \cdot x^2 dx = \frac{x^3}{6}$

$$F(1) - F(0) = \frac{1^3}{6} - \frac{0^3}{6} = \frac{1}{6}$$

Making

$$\int_0^1 xe^{x^2} dx = \frac{1}{6}$$

11.2. Problem 2

Let $D_* = [0, 1] \times [0, 2\pi]$ with coordinates (r, θ) and

$$T(r, \theta) = (r \cos(\theta), r \sin(\theta))$$

What is $T(D_*)$?

11.2.1. Solution

D_* describe all points with distance to the center $(0, 0)$ of $0 \leq$ distance ≤ 1

As a transformation T this can be described as a disk with center $(0, 0)$

This means that $\sqrt{x^2 + y^2} < 1$

$$T(D_*) = \{(x, y) : \sqrt{x^2 + y^2} \leq 1\}$$

11.3. Problem 3

$$T(u, v) = \left(\frac{u+v}{2}, \frac{u-v}{2}\right) \text{ on } D_* = [-1, 1]^2.$$

Find $T(D_*)$

11.3.1. Solution

D_* describes all points within a 2×2 square with center in $(0, 0)$

The transformation $T(D_*)$ transforms it to a stilted square with a diagonal of 2

$$T(D_*) = \{(x, y) : \}$$

11.4. Problem 4

Use polar coordinates to compute

$$\int_{\infty}^{\infty} e^{-x^2} dx$$

Standard trick: square the integral and use polar coordinates to obtain $\sqrt{\pi}$

11.4.1. Solution

$$\text{By squaring } \int_{\infty}^{\infty} e^{-x^2} dx$$

I can fit this equation to use polar coordinates

$$\left(\int_{\infty}^{\infty} e^{-x^2} dx \right)^2 = \int_{\infty}^{\infty} \int_{\infty}^{\infty} e^{-x^2} e^{-y^2} dx dy, \quad \text{where } x = y$$

Now $x = r \cos(\theta)$ and $dx dy = r dr d\theta$

$$\int_0^{2\pi} \int_0^{\infty} r e^{-r^2(\cos(\theta)+\sin(\theta))^2} dr d\theta = \int_0^{2\pi} \int_0^{\infty} r e^{-r^2} dr d\theta$$

Then use u-substitution where $u = r^2$ and $du = 2r dr \Rightarrow \frac{1}{2} du = r dr$

$$\int_0^{2\pi} \int_0^{\infty} e^{-u} du d\theta$$

since $\int e^{-u} du = -e^{-u}$

$$F(\infty) - F(0) = -e^{-\infty} - (-e^0) = \frac{1}{2}(0 - (-1)) = \frac{1}{2}$$

Then

$$\int_0^{2\pi} \frac{1}{2} d\theta = \frac{1}{2} 2\pi = \pi$$

Then

$$\left(\int_{\infty}^{\infty} e^{-x^2} dx \right)^2 = \pi \Rightarrow \int_{\infty}^{\infty} e^{-x^2} dx = \sqrt{\pi}$$

11.5. Problem 5

Let $x = r \cos \theta, y = r \sin \theta$ and $z = z$. Let W_* consists of points in the form (r, θ, z) where $0 \leq r \leq 1, 0 \leq \theta \leq 2\pi, 0 \leq z \leq 1$.

Find the image set and compute its Jacobian.

11.5.1. Solution

This transformation

$$T(x, y, z) = (r \cos(\theta), r \sin(\theta), z)$$

Transforms $W_* = \{(r, \theta, z) : 0 \leq r \leq 1, 0 \leq \theta \leq 2\pi, 0 \leq z \leq 1\}$ (a cylinder, $r = 1, h = 1$)

To $V = \{(x, y, z) : -1 \leq x \leq 1, -1 \leq y \leq 1, 0 \leq z \leq 1\}$ (a cuboid, $w = 2, d = 2, h = 1$)

The Jacobian for 3D is:

$$J(r, \theta, z) = \begin{bmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} & \frac{\partial x}{\partial z} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} & \frac{\partial y}{\partial z} \\ \frac{\partial z}{\partial r} & \frac{\partial z}{\partial \theta} & \frac{\partial z}{\partial z} \end{bmatrix} = \begin{bmatrix} \cos(\theta) & \sin(\theta) & 0 \\ -r \sin(\theta) & r \cos(\theta) & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

11.6. Problem 6

Let $x = \rho \sin(\varphi) \cos(\theta)$, $y = \rho \sin(\varphi) \sin(\theta)$ and $z = \rho \cos(\varphi)$. Compute its Jacobian and use this to derive the change of variable spherical coordinate formula.

11.6.1. Solution

The Jacobian for 3D is:

$$J(\rho, \varphi, \theta) = \begin{bmatrix} \frac{\partial x}{\partial \rho} & \frac{\partial x}{\partial \varphi} & \frac{\partial x}{\partial \theta} \\ \frac{\partial y}{\partial \rho} & \frac{\partial y}{\partial \varphi} & \frac{\partial y}{\partial \theta} \\ \frac{\partial z}{\partial \rho} & \frac{\partial z}{\partial \varphi} & \frac{\partial z}{\partial \theta} \end{bmatrix} = \begin{bmatrix} \sin(\varphi) \cos(\theta) & \rho \cos(\varphi) \cos(\theta) & -\rho \sin(\varphi) \sin(\theta) \\ \sin(\varphi) \sin(\theta) & \rho \cos(\varphi) \sin(\theta) & -\rho \sin(\varphi) \cos(\theta) \\ \cos(\varphi) & -\rho \sin(\varphi) & 0 \end{bmatrix}$$

Now we can take the determinant

$$|J(\rho, \varphi, \theta)| = \rho^2 \sin(\varphi)$$

This means that any shape that is transformed by

$$T(x, y, z) = (\rho \sin(\varphi) \cos(\theta), \rho \sin(\varphi) \sin(\theta), \rho \cos(\varphi))$$

Is then also scaled by $\rho^2 \sin(\varphi)$

12. Lecture 12

Nothing new, besides Taylor series **[NOT CURRICULUM]**