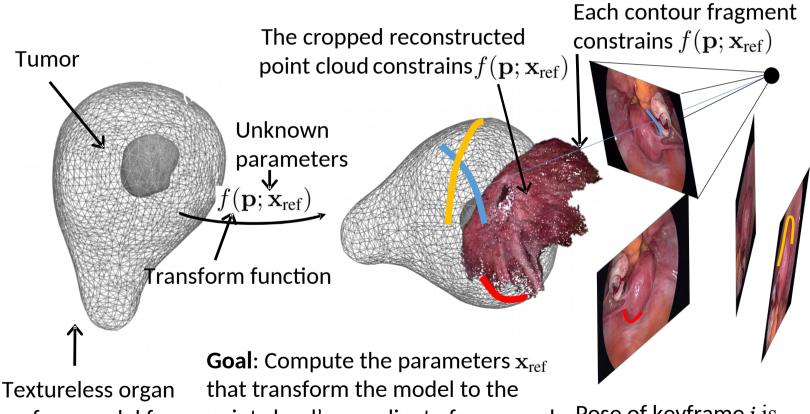








Keyframes with marked contour fragments



surface model from radiological data

point cloud's coordinate frame, and the reconstruction scale factor s

Pose of keyframe i is given by  $(\mathbf{R}_i, s \mathbf{t}_i)$