

# MST

```

PRIM( $G, w, r$ )
 $Q = \emptyset$ 
for each  $u \in G, V$ 
 $u.key = \infty$ 
 $u.\pi = NIL$ 
INSERT( $Q, u$ )
DECREASE-KEY( $Q, r, 0$ ) //  $r.key = 0$ 
while  $Q \neq \emptyset$ 
 $u = \text{EXTRACT-MIN}(Q)$ 
for each  $v \in G, Adj[u]$ 
if  $v \in Q$  and  $w(u, v) < v.key$ 
 $v.\pi = u$ 
DECREASE-KEY( $Q, v, w(u, v)$ )
    
```

attention, on calcule la distance par rapport aux nœuds déjà dans le graphe, pas à la source.

- Initialize  $Q$  and first for loop:  $O(V \lg V)$
- Decrease key of  $r$ :  $O(\lg V)$
- while loop:  $V$  EXTRACT-MIN calls  $\Rightarrow O(V \lg V)$   
 $\leq E$  DECREASE-KEY calls  $\Rightarrow O(E \lg V)$
- Total:  $O(E \lg V)$  (can be made  $O(E + V \lg V)$  with careful queue implementation)

```

KRUSKAL( $G, w$ )
 $A = \emptyset$ 
for each vertex  $v \in G, V$ 
MAKE-SET( $v$ )
sort the edges of  $G, E$  into nondecreasing order by weight  $w$ 
for each  $(u, v)$  taken from the sorted list
if FIND-SET( $u$ )  $\neq$  FIND-SET( $v$ )
 $A = A \cup \{(u, v)\}$ 
UNION( $u, v$ )
return  $A$ 
    
```

- Initialize  $A$ :  $O(1)$
- First for loop:  $V$  MAKE-SETS
- Sort  $E$ :  $O(E \lg E)$
- Second for loop:  $O(E)$  FIND-SETS and UNIONS
- Total time:  $O((V + E)\alpha(V)) + O(E \lg E) = O(E \lg E) = O(E \lg V)$   
 If edges already sorted time is  $O(E\alpha(V))$  which is almost linear

```

BFS( $V, E, s$ )
for each  $u \in V - \{s\}$ 
 $u.d = \infty$ 
 $s.d = 0$ 
 $Q = \emptyset$ 
ENQUEUE( $Q, s$ )
while  $Q \neq \emptyset$ 
 $u = \text{DEQUEUE}(Q)$ 
for each  $v \in G, Adj[u]$ 
if  $v.d == \infty$ 
 $v.d = u.d + 1$ 
ENQUEUE( $Q, v$ )
    
```

$O(V + E)$

```

DFS( $G$ )
for each  $u \in G, V$ 
 $u.color = \text{WHITE}$ 
 $time = 0$ 
for each  $u \in G, V$ 
if  $u.color == \text{WHITE}$ 
DFS-VISIT( $G, u$ )
    
```

```

DFS-VISIT( $G, u$ )
 $time = time + 1$ 
 $u.d = time$ 
 $u.color = \text{GRAY}$ 
for each  $v \in G, Adj[u]$ 
if  $v.color == \text{WHITE}$ 
DFS-VISIT( $v$ )
 $u.color = \text{BLACK}$ 
 $time = time + 1$ 
 $u.f = time$ 
    
```

parcours graphe

```

BELLMAN-FORD( $G, w, s$ )
INIT-SINGLE-SOURCE( $G, s$ )
for  $i = 1$  to  $|G, V| - 1$ 
for each edge  $(u, v) \in G, E$ 
RELAX( $u, v, w$ )
for each edge  $(u, v) \in G, E$ 
if  $v.d > u.d + w(u, v)$ 
return FALSE
return TRUE
    
```

- INIT-SINGLE-SOURCE updates  $\ell, \pi$  for each vertex in time  $\Theta(V)$
- Nested for loops runs RELAX  $V - 1$  times for each edge. Hence total time for these loops is  $\Theta(E \cdot V)$
- Final for loop runs once for each edge. Time is  $\Theta(E)$

Total time:  $\Theta(E \cdot V)$

Dijkstra :  
fonctionne  
seulement  
 $w > 0$

```

DIJKSTRA( $G, w, s$ )
INIT-SINGLE-SOURCE( $G, s$ )
 $S = \emptyset$ 
 $Q = G, V$  // i.e., insert all vertices into  $Q$ 
while  $Q \neq \emptyset$ 
 $u = \text{EXTRACT-MIN}(Q)$ 
 $S = S \cup \{u\}$ 
for each vertex  $v \in G, Adj[u]$ 
RELAX( $u, v, w$ )
    
```

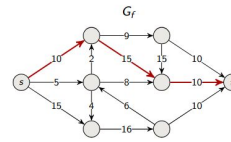
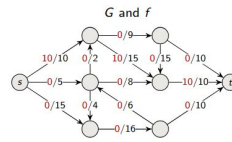
Running time Like Prim's dominated by operations on priority queue:

- If binary heap, each operation takes  $O(\lg V)$  time  $\Rightarrow O(E \lg V)$
- More careful implementation time is  $O(V \lg V + E)$

shortest path

FORD-FULKERSON-METHOD( $G, s, t$ ):

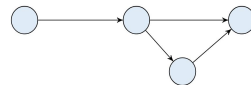
- Initialize flow  $f$  to 0
- while exists an augmenting path  $p$  in the residual network  $G_f$
- augment flow  $f$  along  $p$
- return  $f$



$O(V * E^2)$

calcul du  
max-flow  
ou min-cut  
(bottleneck)

1er DFS, obtenir les finishing times



2ème DFS sur  $G^A$ , obtenir les SCC (trier les vertices par ordre de finishing décroissants).

SCC (graphes dirigés)

run un DFS et changer le label à chaque fois qu'on passe dans la main loop

connected components

$$1/1 + 1/2 + 1/3 + 1/4 + 1/5 + \dots + 1/n = H_n = \ln n + O(1)$$

$n$ :th harmonic number

tree ( $u \rightarrow v$ )  $d[u] < d[v] < f[v] < f[u]$   
première découverte de  $v$  lors du DFS.

back edge ( $u \rightarrow v$ )  $d[v] < d[u] < f[u] < f[v]$   
 $v$  est gris — retour vers un ancêtre pas fini (peut former un cycle).

forward edge ( $u \rightarrow v$ )  $d[u] < d[v] < f[v] < f[u]$   
 $v$  est noir et descendant — déjà entièrement visité.

cross edge ( $u \rightarrow v$ )  $d[v] < f[v] < d[u] < f[u]$   
 $v$  est noir, ni ancêtre ni descendant — autre branche ou composante.

# Theorem (Master Theorem)

Let  $a \geq 1$  and  $b > 1$  be constants, let  $T(n)$  be defined on the nonnegative integers by the recurrence

$$T(n) = aT(n/b) + f(n).$$

Then,  $T(n)$  has the following asymptotic bounds

- ▶ If  $f(n) = O(n^{\log_b a - \epsilon})$  for some constant  $\epsilon > 0$ , then  $T(n) = \Theta(n^{\log_b a})$
- ▶ If  $f(n) = \Theta(n^{\log_b a})$ , then  $T(n) = \Theta(n^{\log_b a} \log n)$
- ▶ If  $f(n) = \Omega(n^{\log_b a + \epsilon})$  for some constant  $\epsilon > 0$ , and if  $a \cdot f(n/b) \leq c \cdot f(n)$  for some constant  $c < 1$  and all sufficiently large  $n$ , then  $T(n) = \Theta(f(n))$

$T(n) = T(n/5) + 2T(2n/5) + \Theta(n)$ . Educated guess  $O(n^a)$ .

$1 = (\%)^a + 2(\%)^a \Rightarrow a = 1$ , et comme on a  $f(n) = O(n^1)$  alors  $O(n \log n)$ .

## COUNTING-SORT( $A, B, n, k$ )

```
let C[0..k] be a new array
for i = 0 to k
    C[i] = 0
for j = 1 to n
    C[A[j]] = C[A[j]] + 1
for i = 1 to k
    C[i] = C[i] + C[i-1]
for j = n downto 1
    B[C[A[j]]] = A[j]
    C[A[j]] = C[A[j]] - 1
```

- ▶ First for-loop:  $\Theta(k)$
  - ▶ 2nd for-loop:  $\Theta(n)$
  - ▶ 3rd for-loop:  $\Theta(k)$
  - ▶ 4th for-loop:  $\Theta(n)$
  - ▶ Total:  $\Theta(n + k)$
- How big  $k$  is practical?
- ▶ 32-bit values? No
  - ▶ 16-bit values? Probably not
  - ▶ 8-bit values? Maybe depending on  $n$
  - ▶ 4-bit values? Probably unless  $n$  is very small

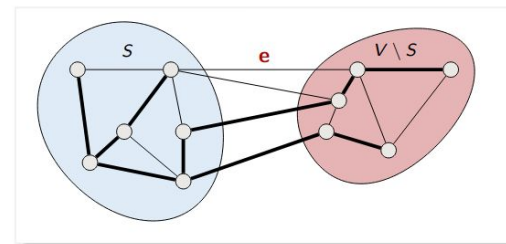
ture 25, 20.05.2025

PRESIDE-ORDER	→	Root	Left	Right
IN-ORDER	→	Left	Root	Right
POST-ORDER	→	Left	Right	Root

Consider a cut  $(S, V \setminus S)$  and let

- ▶  $T$  be a tree on  $S$  which is part of a MST
- ▶  $e$  be a crossing edge of minimum weight

Then there is MST of  $G$  containing  $e$  and  $T$



**Definition 2** Assume the same as above, then we also call  $r$  the competitive ratio if

$$ALG(I) \leq r \cdot OPT(I) + c$$

holds for all  $I$  and some constant  $c$  independent of the length of the sequence  $I$ . When  $c$  is 0,  $r$  is the strong competitive ratio.

$$T(n) = \begin{cases} \Theta(1) & \text{for } n < 50 \\ T(\frac{n}{4}) + T(\frac{3n}{4}) + O(\sqrt{n}) & \text{for } n \geq 50 \end{cases}$$

**2b (10 points)** Prove that  $T(n) = O(n)$ . You may simplify your calculations by assuming that  $n/4, 3n/4$  and  $\sqrt{n}$  always evaluate to integers.

In this problem you are asked to give a proof of  $T(n) = O(n)$ . Recall that you are allowed to refer to material covered in the lectures. Please answer inside the box on this and next page.

We will prove that  $T(n) \leq an - c\sqrt{n}$ , for some constants  $a$  and  $c$  (which we will choose). Also, there exists a constant  $b$  such that  $O(\sqrt{n}) \leq b\sqrt{n}$ . We prove our claim using strong induction. The base case is clear by the formula for  $n < 50$ . Now, suppose that for all  $k < n$ ,  $T(k) \leq ak - c\sqrt{k}$ . Now, we prove that  $T(n) \leq an - c\sqrt{n}$ . Note that

$$\begin{aligned} T(n) &= T(\frac{n}{4}) + T(\frac{3n}{4}) + O(\sqrt{n}) \\ &\leq \left(a\frac{n}{4} - c\sqrt{\frac{n}{4}}\right) + \left(a\frac{3n}{4} - c\sqrt{\frac{3n}{4}}\right) + b\sqrt{n} \\ &= an - c\sqrt{n} \left(\frac{1}{2} + \frac{\sqrt{3}}{2}\right) + b\sqrt{n}. \end{aligned}$$

Now, if we choose

$$c \geq \frac{b}{\frac{\sqrt{3}}{2} + \frac{1}{2}},$$

crazy complexity  $\rightarrow$  dp ?

```
// on veut partitionner le tableau en deux parties
// cette fonction réorganise le tableau de telle sorte à ce que les éléments
// inférieurs ou égaux au pivot soient à gauche et les éléments supérieurs soient à droite
func partition(array []int, low, high int) int {
    // on choisit le dernier élément comme pivot (arbitrairement, plus tard ce sera random!)
    pivot := array[high]

    // i représentera le dernier élément de la zone contenant des éléments ≤ pivot
    i := low - 1

    // on parcourt le tableau et on compare chaque élément avec le pivot
    for j := low; j < high; j++ {
        // l'élément courant est inférieur ou égal au pivot!
        if array[j] ≤ pivot {
            // on agrandit la zone contenant des éléments ≤ pivot
            // donc i pointe maintenant vers l'élément juste en dehors de la zone
            i++
            // on échange l'élément courant avec cet élément juste en dehors de la zone
            // donc i pointe maintenant correctement vers le dernier élément de la zone! (array[j])
            array[i], array[j] = array[j], array[i]
        }
    }

    array[i+1], array[high] = array[high], array[i+1] // on insert le pivot à sa place finale
    return i + 1 // la position du pivot
}

func quicksortRecursive(array []int, low, high int) [] {
    if low >= high {
        return
    }
    pivotIndex := betterPartitionRandomPivot(array, low, high)
    quicksortRecursive(array, low, pivotIndex-1)
    quicksortRecursive(array, pivotIndex+1, high)
}
```