## **ADVANCED** BAYESIAN MODELING



# EXAMPLE OF PRACTICAL MCMC:

RAT TUMOR DATA: MODEL 1

## Rat Tumor Example

```
n_j = total number of rats in control group of experiment j y_j = number in control group of experiment j that develop a tumor \theta_j = control group tumor probability in experiment j j = 1, \ldots, 71
```

Data values for n and y (N and y) in file rattumor.txt

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### Consider model specified in JAGS code file rattumor1.bug:

```
model {
  for (j in 1:length(y)) {
    y[j] ~ dbin(theta[j], N[j])
    theta[j] ~ dbeta(alpha, beta)
  alpha \sim dexp(0.001)
  beta \sim dexp(0.001)
```

(Same as analyzed earlier)

### This time, instead of using JAGS/rjags default options, we will

- use 4 chains
- initialize hyperparameters ( $\alpha$  and  $\beta$ ) to overdispersed combinations (different for each chain)
- run 1000 iterations for adaptation
- then run 1000 more iterations for burn-in
- ▶ finally run 2000 more iterations to check for convergence

Helpful: Determine crude preliminary values for parameters.

These will help determine what values could be considered "overdispersed."

Since the  $\theta$ s are probabilities, naive estimates are the empirical proportions

$$\hat{\theta}_j = \frac{y_j}{n_j}$$

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The  $\theta$ s have a  $Beta(\alpha, \beta)$  distribution under the prior. In particular (BDA3, Table A.1):

$$E(\theta \mid \alpha, \beta) = \frac{\alpha}{\alpha + \beta} \qquad var(\theta \mid \alpha, \beta) = \frac{\alpha\beta}{(\alpha + \beta)^2(\alpha + \beta + 1)}$$

Solving these for  $\alpha$  and  $\beta$  and then substituting the sample mean and variance of the  $\hat{\theta}_i$ s for  $E(\theta \mid \alpha, \beta)$  and  $var(\theta \mid \alpha, \beta)$  gives ...

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```
> d <- read.table("rattumor.txt", header=TRUE)</pre>
> thetahat <- d$v/d$N
> Etheta <- mean(thetahat)
> Vtheta <- var(thetahat)</pre>
> ( alphahat <- Etheta * (Etheta * (1 - Etheta) / Vtheta - 1) )</pre>
[1] 1.373948
> ( betahat <- alphahat * (1/Etheta - 1) )</pre>
[1] 8.573899
```

These values will help to initialize the chains.

Recall: Initial values should be overdispersed – extremely large or small.

Hyperparameters  $\alpha$  and  $\beta$  must be positive, so let's choose initial values about 100 times larger and smaller than we expect.

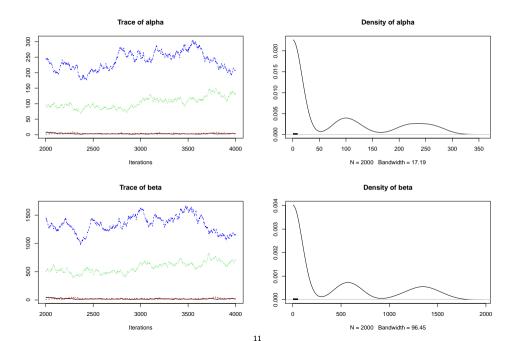
### For the 4 chains:

	Initial $\alpha$	Initial $eta$
Chain 1:	0.01	0.1
Chain 2:	100	0.1
Chain 3:	0.01	1000
Chain 4:	100	1000

Set up JAGS model in R with 4 chains initialized, and perform 1000 iterations of adaptation:

Perform 1000 iterations of burn-in, collect  $\alpha$  and  $\beta$  for 2000 more iterations, and plot results:

> plot(x1, smooth=FALSE)

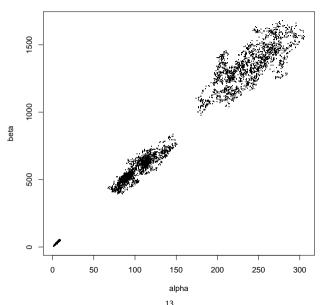


Chains are far from convergence, even after 4000 iterations.

Could run more iterations (try yourself), but don't expect much improvement.

For a Gibbs sampler, slow convergence might be due to high posterior correlations:

> plot(as.matrix(x1)[,c("alpha","beta")], pch=".", cex=2)



Results call into doubt earlier (default) analysis: There are regions of possibly high probability that were not sampled.

Fundamental problem: Priors were chosen close to flat for  $\alpha$  and  $\beta$ , but using actual flat priors would give an improper posterior.

Better to try a more well-behaved prior ...