Kneeling with and without kneepads during kneeling tasks

Simon Thwaites, Mark Rickman, Kelly Hall, Dominic Thewlis

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1 Proportion of FSR Activation

The sample proportions (\hat{p}) and confidence intervals (CIs) of FSR activation for all kneeling conditions in both sessions is presented in Table 1. If the proportion CIs overlap between session 1 and session 2, we can conclude that there is no statistically significant difference between the two proportions at the 95% confidence level. For bare kneeling, the proportion CIs overlapped between sessions for all kneeling tasks. For knee pad kneeling, the proportion CIs of sensor b did not overlap for upright kneeling and left and right reaching tasks (highlighted in grey in Table 1).

Table 1: Proportion (\hat{p}) and confidence intervals (CI) of force sensitive resistor (FSR) activation for all kneeling trials and conditions. Sn – session, e.g., a1 and a2 indicate session 1 and session 2 for FSR sensor a (see Figure 1).

		Upright		Backwards		Forward		Left		Right	
FSR	Sn	p̂ (CI)	Vis	p̂ (CI)	Vis	p̂ (CI)	Vis	p̂ (CI)	Vis	p̂ (CI)	Vis
		0.5 (0 - 1)		0.5 (0 - 1)	i	0.5 (0 - 1)	i	0.5 (0 - 1)	 	0.5 (0 - 1)	
Bare											
	a1	0.24 $(0.12 - 0.40)$	ļ i i	0.07 $(0.01 - 0.20)$	Ħ	0.17 $(0.07 - 0.32)$	j=	0.12 $(0.04 - 0.26)$	j∺	0.22 $(0.11 - 0.38)$	i - i
	a2	0.38 $(0.24 - 0.54)$	H	0.26 $(0.14 - 0.42)$	[H	0.22 $(0.11 - 0.38)$	j⊫i	0.21 $(0.10 - 0.37)$	je l	0.26 $(0.14 - 0.42)$	} ⊨ I
	b1	0.19 $(0.09 - 0.34)$	H	0.15 $(0.06 - 0.29)$	jel	0.17 $(0.07 - 0.32)$	j- l	0.15 $(0.06 - 0.29)$	j- l	0.32 $(0.18 - 0.48)$; H
	b2	0.24 $(0.12 - 0.40)$	H	0.29 $(0.16 - 0.45)$	ļĦ	0.24 $(0.12 - 0.40)$	₽	0.21 $(0.10 - 0.37)$	j⊭i	0.33 $(0.20 - 0.50)$	H
	c1	0.48 $(0.32 - 0.64)$	į H	0.49 $(0.33 - 0.65)$	H	0.51 $(0.35 - 0.67)$. H	0.49 $(0.33 - 0.65)$. H	0.76 $(0.60 - 0.88)$; н
	c2	0.55 $(0.39 - 0.70)$	H	0.52 $(0.36 - 0.68)$	H	0.56 $(0.40 - 0.72)$	H	0.52 $(0.36 - 0.68)$	H	0.55 $(0.39 - 0.70)$	H
	d1	0.19	H	0.22	H	0.22	je	0.17	ja	0.34	· H
	d2	(0.09 - 0.34) 0.41 $(0.26 - 0.57)$	H	(0.11 - 0.38) 0.41 $(0.26 - 0.57)$	ļн	(0.11 - 0.38) 0.27 $(0.14 - 0.43)$	ļн	(0.07 - 0.32) 0.26 $(0.14 - 0.42)$	[н	(0.20 - 0.51) 0.36 $(0.22 - 0.52)$	H
	e1	0.07	ļi	0.00	į.	0.00	į.	0.00	į.	0.00	
	e2	(0.01 - 0.20) 0.02 $(0.00 - 0.13)$	į.	(0.00 - 0.09) 0.02 (0.00 - 0.13)	<u></u>	(0.00 - 0.09) 0.00 $(0.00 - 0.09)$	į.	(0.00 - 0.09) 0.00 $(0.00 - 0.08)$	ė	(0.00 - 0.09) 0.00 $(0.00 - 0.08)$	ė
	f1	0.07	þ	0.00	į.	0.00	į.	0.00	į.	0.00	·
	f2	(0.01 - 0.20) 0.02 $(0.00 - 0.13)$	į.	(0.00 - 0.09) 0.02 (0.00 - 0.13)	ļi	(0.00 - 0.09) 0.00 $(0.00 - 0.09)$	į.	(0.00 - 0.09) 0.02 (0.00 - 0.13)	Ħ	(0.00 - 0.09) 0.00 $(0.00 - 0.08)$	ė
	g1	0.12	ja	0.24	[₩	0.20] H	0.15	ju	0.29	įн
	g2	(0.04 - 0.26) 0.02 $(0.00 - 0.13)$	į.	(0.12 - 0.40) 0.19 $(0.09 - 0.34)$	j⊨ı	(0.09 - 0.35) 0.10 $(0.03 - 0.23)$	Ħ	(0.06 - 0.29) 0.07 (0.01 - 0.20)	Ħ	(0.16 - 0.46) 0.31 $(0.18 - 0.47)$	∃ ⊢ l
	h1	0.17	ju	0.17	ju	0.12	ja	0.27	į -	0.22	<u></u> ⊷
	h2	(0.07 - 0.31) 0.19 $(0.09 - 0.34)$	j⊨i	(0.07 - 0.32) 0.17 $(0.07 - 0.31)$	ju	(0.04 - 0.26) 0.10 $(0.03 - 0.23)$	Ħ	(0.14 - 0.43) 0.21 $(0.10 - 0.37)$	j⊨i	(0.11 - 0.38) 0.26 $(0.14 - 0.42)$	i⊨
Knee F	Pade			(0.01 0.01)		(0.00 0.20)		(0.10 0.01)		(0.11 0.12)	
	a1	0.43 $(0.28 - 0.59)$	H	0.10 $(0.03 - 0.23)$	Ħ	0.57 $(0.41 - 0.72)$	<u>:</u> н	0.24 $(0.12 - 0.40)$	} ⊨ +	0.24 $(0.12 - 0.40)$	ļн
	a2	0.43 $(0.28 - 0.59)$	H	0.14 $(0.05 - 0.28)$	je l	0.31 $(0.18 - 0.47)$	H	0.17 $(0.07 - 0.31)$	H	0.31 $(0.18 - 0.47)$	H
	b1	0.33 $(0.20 - 0.50)$	ļн	0.26 $(0.14 - 0.42)$	}⊨i	0.43 $(0.28 - 0.59)$	į H	0.26 $(0.14 - 0.42)$	ŀ⊨	0.52 $(0.36 - 0.68)$	<u>:</u> H
	b2	0.69 $(0.53 - 0.82)$	H	0.57 $(0.41 - 0.72)$	<u> </u>	0.62 $(0.46 - 0.76)$; H	0.71 $(0.55 - 0.84)$; H	0.86 $(0.72 - 0.95)$. ₩
	с1	0.60 $(0.43 - 0.74)$	<u> </u>	0.50 $(0.34 - 0.66)$	H	0.52 $(0.36 - 0.68)$	- H	0.33 $(0.20 - 0.50)$; I-I	0.88 $(0.74 - 0.96)$	<u> </u>
	c2	0.55 $(0.39 - 0.70)$	H	0.69 $(0.53 - 0.82)$	<u> </u>	0.79 $(0.63 - 0.90)$; H	0.60 $(0.43 - 0.74)$; H	0.88 $(0.74 - 0.96)$	÷ •
	d1	0.10 $(0.03 - 0.23)$	Ħ	0.36 $(0.22 - 0.52)$	ļн	0.19 $(0.09 - 0.34)$	j⊨i	0.14 $(0.05 - 0.28)$	ju	0.64 $(0.48 - 0.78)$; н
	d2	0.05 $(0.01 - 0.16)$	H	0.36 $(0.22 - 0.52)$	HH	0.00 (0.00 - 0.08)		0.00 $(0.00 - 0.08)$		0.48 $(0.32 - 0.64)$; H

Table 1: Proportion (\hat{p}) and confidence intervals (CI) of force sensitive resistor (FSR) activation for all kneeling trials and conditions. Sn – session, e.g., a1 and a2 indicate session 1 and session 2 for FSR sensor a (see Figure 1). (continued)

		Upright		Backwards		Forward		Left		Right	
FSR	Sn	p̂ (CI)	Vis	p̂ (CI)	Vis	ρ̂ (CI)	Vis	ρ̂ (CI)	Vis	p̂ (CI)	Vis
	e1	0.00 $(0.00 - 0.08)$	ė	0.05 $(0.01 - 0.16)$	H	$0.00 \\ (0.00 - 0.08)$		$0.00 \\ (0.00 - 0.08)$		0.12 $(0.04 - 0.26)$	ļĦ
	e2	$0.02 \\ (0.00 - 0.13)$		0.02 $(0.00 - 0.13)$	H	$0.00 \\ (0.00 - 0.08)$	•	$0.05 \\ (0.01 - 0.16)$	Ħ	0.07 $(0.01 - 0.20)$	ļH
	f1	$0.00 \\ (0.00 - 0.08)$		0.02 $(0.00 - 0.13)$	H	$0.00 \\ (0.00 - 0.08)$		$0.00 \\ (0.00 - 0.08)$		$0.00 \\ (0.00 - 0.08)$	÷
	f2	0.07 $(0.01 - 0.20)$	H	$0.05 \\ (0.01 - 0.16)$	H	0.02 $(0.00 - 0.13)$	H	$0.00 \\ (0.00 - 0.08)$	į.	0.07 $(0.01 - 0.20)$	Ħ
	g1	0.17 $(0.07 - 0.31)$	ju	0.07 $(0.01 - 0.20)$	Ħ	$0.07 \ (0.01 - 0.20)$	Ħ	$0.07 \ (0.01 - 0.20)$	Ħ	0.26 $(0.14 - 0.42)$	H
	g2	0.07 $(0.01 - 0.20)$	H	0.02 $(0.00 - 0.13)$	į.	0.02 $(0.00 - 0.13)$	H	$0.00 \\ (0.00 - 0.08)$	į.	0.12 $(0.04 - 0.26)$	Ħ
	h1	$0.19 \ (0.09 - 0.34)$	j⊨	$0.07 \ (0.01 - 0.20)$	Ħ	$0.07 \ (0.01 - 0.20)$	je	$0.05 \ (0.01 - 0.16)$	Ħ	$0.07 \ (0.01 - 0.20)$	Ħ
	h2	$0.07 \\ (0.01 - 0.20)$	H	$0.02 \\ (0.00 - 0.13)$	H	$0.00 \\ (0.00 - 0.08)$	•	$0.00 \\ (0.00 - 0.08)$	ė	$0.00 \\ (0.00 - 0.08)$	
		0.5 (0 - 1)	 	0.5 (0 - 1)		0.5 (0 - 1)		0.5 (0 - 1)		0.5 (0 - 1)	<u> </u>