

Modified CNN version

Simon Smith's final project for CS 4710, modified from final project for CS 4700

Thanks to Dr. Ghassan Bati of Umm Al-Qura University in Saudi Arabia for the dataset. I only *barely* manually adjusted some of the images - changing the orientation of 2 or 3 horizonal Ajwa images to vertical so that they would match the rest of the dataset. https://www.qscience.com/content/journals/10.5339/jist.2023.12

Thanks to Dr. Chen for her help with this project last semester, and to Larry for his help this semester!

Setup Instructions

In your Google Drive, upload the provided folder date_data (attached in submission)

```
from torchvision import datasets, transforms import torch from torch.utils.data import DataLoader, random_split import matplotlib.pyplot as plt import torch.nn as nn import pickle

from google.colab import drive drive.mount('/content/drive', force_remount=True)

import os os.chdir("/content/drive/My Drive/date_data")

Mounted at /content/drive
```

Subsets, Transforms, Load data

Define subsets (train, validation, test) Perform transforms (resizing for all; data augmentation for train) Load data

from torchvision.datasets import ImageFolder

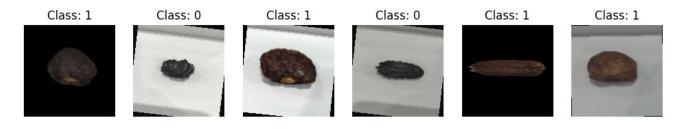
```
from torch.utils.data import random_split
from torchvision import transforms
# Step 1: Load without any transform initially
full_dataset = ImageFolder('./ajwa_medjool_database/') # ('./test_image/')
# Step 2: Split into subsets
train_size = int(0.65 * len(full_dataset))
valid_size = int(0.15 * len(full_dataset))
test_size = len(full_dataset) - train_size - valid_size
train_subset, valid_subset, test_subset = random_split(full_dataset, [train_size, valid_s
# Step 3: Define transforms
train_transform = transforms.Compose([
   transforms.Resize((128,128)),
   transforms.RandomHorizontalFlip(p=0.8),
   transforms.RandomRotation(20),
   transforms.ColorJitter(brightness=0.2, contrast=0.2, saturation=0.2),
   transforms.ToTensor(),
   transforms.Normalize(mean=[0.5]*3, std=[0.5]*3)
1)
test_transform = transforms.Compose([
    transforms.Resize((128,128)),
   transforms.ToTensor(),
   transforms.Normalize(mean=[0.5]*3, std=[0.5]*3)
])
# Step 4: Assign transforms by wrapping in Subset objects again
class TransformedDataset(torch.utils.data.Dataset):
    def init (self, subset, transform):
        self.subset = subset
        self.transform = transform
    def __getitem__(self, index):
        x, y = self.subset[index]
        return self.transform(x), y
    def __len__(self):
        return len(self.subset)
# Step 5: Wrap each subset
train_dataset = TransformedDataset(train_subset, train_transform)
valid_dataset = TransformedDataset(valid_subset, test_transform)
test_dataset = TransformedDataset(test_subset, test_transform)
# Step 6: load data
train_dat_load = DataLoader(train_dataset, batch_size=32, shuffle=True)
valid_dat_load = DataLoader(valid_dataset, batch_size=32, shuffle=False)
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```

Visualize data (optional)

Compare the augmented training data against non-augmented test data

```
# visualize augmented images in training dataset
images, labels = next(iter(train_dat_load))

fig, axes = plt.subplots(1, 6, figsize=(12,6))
for i in range(6):
   img = images[i] * 0.5 + 0.5 # unnormalize
   img = img.permute(1, 2, 0).clip(0,1)
   axes[i].imshow(img)
   axes[i].set_title(f"Class: {labels[i].item()}")
   axes[i].axis('off')
plt.show()
```



```
# show non-augmented images in test dataset
images, labels = next(iter(test_dat_load))

fig, axes = plt.subplots(1, 6, figsize=(12,6))
for i in range(6):
   img = images[i] * 0.5 + 0.5 # unnormalize
   img = img.permute(1, 2, 0).clip(0,1)
   axes[i].imshow(img)
   axes[i].set_title(f"Class: {labels[i].item()}")
   axes[i].axis('off')
plt.show()
```



New model with more layers

```
dummy_input = torch.ones((1,3,128,128))
# The CNN model, defined by blocks of layers below:
model = nn.Sequential()
# First block
model.add_module('conv1', nn.Conv2d(3, 32, kernel_size=5, padding=2))
model.add_module('relu1', nn.ReLU())
model.add_module('pool1', nn.MaxPool2d(2))
# Second block - THIS IS THE NEW LAYER
model.add module('conv2', nn.Conv2d(32, 64, kernel size=5, padding=2))
model.add_module('relu2', nn.ReLU())
model.add_module('pool2', nn.MaxPool2d(2))
# Third block
model.add module('conv3', nn.Conv2d(64, 128, kernel size=3, padding=1))
model.add_module('relu3', nn.ReLU())
model.add_module('pool3', nn.MaxPool2d(2))
# Generate "flattened_size" for fc1
output = model(dummy input)
print(f"output shape: {output.shape}")
flattened size = output.numel()
print(f"flattened size: {flattened_size}")
# Flatten layers, add FC layers
model.add_module('flatten', nn.Flatten())
model.add_module('fc1', nn.Linear(flattened_size, 1024))
model.add_module('relu_fc1', nn.ReLU())
model.add_module('dropout', nn.Dropout(0.5))
model.add_module('fc2', nn.Linear(1024, 2))
     output shape: torch.Size([1, 128, 16, 16])
     flattened size: 32768
#Loss and Optimizer
# Cross Entropy loss
loss fn = nn.CrossEntropyLoss()
# Adam optimizer
```

Train new model

```
def train(model, num_epochs, train_dl, valid_dl):
  loss_hist_train = [0] * num_epochs
  accuracy_hist_train = [0] * num_epochs
  loss_hist_valid = [0] * num_epochs
  accuracy_hist_valid = [0] * num_epochs
  for epoch in range(num_epochs):
   model.train()
    for x_batch, y_batch in train_dl:
      pred = model(x_batch)
      loss = loss_fn(pred, y_batch)
      loss.backward()
      optimizer.step()
      optimizer.zero_grad()
      loss_hist_train[epoch] += loss.item()*y_batch.size(0)
      is_correct = (
        torch.argmax(pred, dim=1) == y_batch
      ).float()
      accuracy_hist_train[epoch] += is_correct.sum()
    loss_hist_train[epoch] /= len(train_dl.dataset)
    accuracy_hist_train[epoch] /= len(train_dl.dataset)
   model.eval()
   with torch.no_grad():
      for x_batch, y_batch in valid_dl:
        pred = model(x_batch)
        loss = loss_fn(pred, y_batch)
        loss_hist_valid[epoch] += loss.item() * y_batch.size(0)
        is_correct = (
            torch.argmax(pred, dim=1) == y_batch
        ).float()
        accuracy_hist_valid[epoch] += is_correct.sum()
    loss_hist_valid[epoch] /= len(valid_dl.dataset)
    accuracy_hist_valid[epoch] /= len(valid_dl.dataset)
    print(f'Epoch {epoch+1} accuracy: '
```

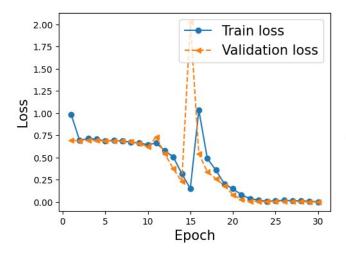
```
f'{accuracy_hist_train[epoch]:.4f} val _accuracy: '
         f'{accuracy_hist_valid[epoch]:.4f}')
  return loss_hist_train, loss_hist_valid, accuracy_hist_train, accuracy_hist_valid
# RESET num epochs TO 30 EPOCHS FOR REGULARITY BETWEEN TESTS
from time import time
torch.manual_seed(1)
num_epochs = 30
model start time = time()
hist = train(model, num_epochs, train_dat_load, valid_dat_load)
# Save as pickle, in case runtime disconnects
with open('./training_pickle/train_results_ML2_more_layers.pkl', 'wb') as f:
    pickle.dump((hist), f)
training_time = time() - model_start_time
print(f'Training time: {int(training_time / 60)} min, {int(training_time%60)} sec')
     Epoch 1 accuracy: 0.4846 val accuracy: 0.5000
     Epoch 2 accuracy: 0.5077 val _accuracy: 0.5333
     Epoch 3 accuracy: 0.4462 val _accuracy: 0.5000
     Epoch 4 accuracy: 0.4692 val _accuracy: 0.5000
     Epoch 5 accuracy: 0.5615 val _accuracy: 0.5667
     Epoch 6 accuracy: 0.4923 val _accuracy: 0.6000
     Epoch 7 accuracy: 0.5538 val _accuracy: 0.5000
     Epoch 8 accuracy: 0.5308 val _accuracy: 0.5000
     Epoch 9 accuracy: 0.5846 val _accuracy: 0.6000
     Epoch 10 accuracy: 0.6308 val accuracy: 0.9333
     Epoch 11 accuracy: 0.6462 val _accuracy: 0.4667
     Epoch 12 accuracy: 0.6769 val accuracy: 0.8667
     Epoch 13 accuracy: 0.8154 val _accuracy: 0.9667
     Epoch 14 accuracy: 0.9000 val accuracy: 0.9667
     Epoch 15 accuracy: 0.9769 val _accuracy: 0.5333
     Epoch 16 accuracy: 0.6769 val _accuracy: 0.6000
     Epoch 17 accuracy: 0.7308 val _accuracy: 0.9667
     Epoch 18 accuracy: 0.8615 val _accuracy: 0.9667
     Epoch 19 accuracy: 0.9769 val _accuracy: 0.9000
     Epoch 20 accuracy: 0.9538 val _accuracy: 1.0000
     Epoch 21 accuracy: 0.9846 val _accuracy: 1.0000
     Epoch 22 accuracy: 0.9923 val _accuracy: 1.0000
     Epoch 23 accuracy: 0.9923 val _accuracy: 1.0000
     Epoch 24 accuracy: 1.0000 val _accuracy: 1.0000
     Epoch 25 accuracy: 0.9923 val _accuracy: 1.0000
     Epoch 26 accuracy: 0.9923 val _accuracy: 1.0000
     Epoch 27 accuracy: 1.0000 val _accuracy: 1.0000
     Epoch 28 accuracy: 0.9923 val _accuracy: 1.0000
     Epoch 29 accuracy: 1.0000 val _accuracy: 1.0000
```

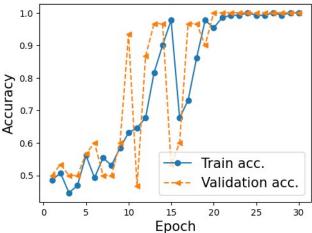
Epoch 30 accuracy: 1.0000 val _accuracy: 1.0000

Training time: 29 min, 2 sec

Visualise Learning Curves

```
# Load pickle
with open('./training_pickle/train_results_ML2_more_layers.pkl', 'rb') as f:
    hist = pickle.load(f)
import matplotlib.pyplot as plt
import numpy as np
x_arr = np.arange(len(hist[0])) + 1
fig = plt.figure(figsize=(12,4))
ax = fig.add_subplot(1,2,1)
ax.plot(x_arr, hist[0], '-o', label='Train loss')
ax.plot(x_arr, hist[1], '--<', label='Validation loss')</pre>
ax.legend(fontsize=15)
ax.set_xlabel('Epoch', size=15)
ax.set_ylabel('Loss', size=15)
ax = fig.add_subplot(1,2,2)
ax.plot(x_arr, hist[2], '-o', label='Train acc.')
ax.plot(x_arr, hist[3], '--<', label='Validation acc.')</pre>
ax.legend(fontsize=15)
ax.set_xlabel('Epoch', size=15)
ax.set_ylabel('Accuracy', size=15)
plt.show()
```





Evaluate Model on Test Data

```
for images, labels in test_dat_load:
  images = images / 225. #normalize
  pred = model(images) #predict
  print(pred.shape)
     torch.Size([32, 2])
     torch.Size([8, 2])
# check num correct:
all predicts = []
all labels = []
for images, labels in test dat load:
  pred = model(images)
  all_predicts.append(torch.argmax(pred, dim=1))
 all_labels.append(labels)
all predicts = torch.cat(all predicts)
all_labels = torch.cat(all_labels)
is_correct = (all_predicts == all_labels).float()
print(f'Test accuracy: {is_correct.mean():.4f}')
     Test accuracy: 1.0000
```

Visualisation of model predictions of test data

```
fit = plt.figure(figsize=(12,4))

for i in range(12):
    ax = fit.add_subplot(2,6,i+1)
    ax.set_xticks([]); ax.set_yticks([])

img = test_dataset[i][0]

pred = model(img.unsqueeze(0))
y_pred = torch.argmax(pred)

###
img_denorm = img * torch.tensor([0.5, 0.5, 0.5]).view(3,1,1) + torch.tensor([0.5, 0.5, ax.imshow(img_denorm.permute(1.2.0).clip(0.1))
```

