## Non-reversible Monte Carlo simulation of spin models

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### Outline

- Simple Mathematical Approach
- 2 Non-reversible Algorithm
- 3 Application Ising-Model
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### Definitions

Let  $\Omega = \{1, ..., n\}$  finite state space,

P transition matrix,  $P(x \rightarrow y) = P(x, y)$  and

 $\pi$  invariant distribution such that  $\pi P = \pi$ .

## Detailed Balance Equation

$$\pi(x)P(x,y) = \pi(y)P(y,x)$$
 for all  $x,y \in \Omega$ .

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### Convergence Theorem

Let P be the transition matrix of an irreducible and aperiodic Markov chain on finite state space  $\Omega$ . Then:

- (1) There exists a unique invariant distribution  $\pi$  (See [3], p. 14)
- (2) For all  $x, y \in \Omega$  and  $\delta > 0$ :

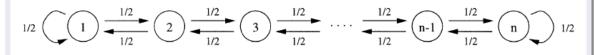
$$|P^t(x,y) - \pi(y)| \le (1-\delta)^t$$

(See extra material).

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#### Simple Random Walk

Nearest neighbor random walk with transition probabilities 1/2.

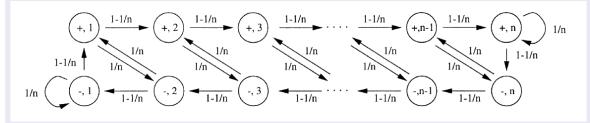


#### Invariant Distribution

$$\pi(x) = 1/n$$
 for all  $x \in \Omega$ .

### Directed Random Walk

Duplicate state space and introduce an extra label for direction.



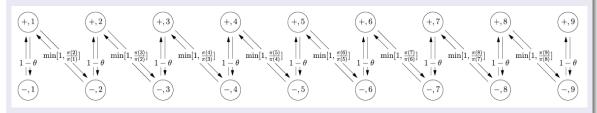
#### Invariant Distribution

 $\pi(\pm,x)=1/2n$  for all  $x\in\Omega$ , because P is double-stochastic.

 $\pi(x) = 1/n$  for all  $x \in \Omega$ , marginal distribution (See [2], Chapter 2).

# Non-reversible Algorithm

 $\theta$  is the probability to change direction.



**Step A** Metropolis update  $(\pm, x) \rightarrow (\mp, x \pm 1)$  with acceptance probability:

$$p_{acc} = \min \left[ 1, \frac{\pi(\mp, x \pm 1)}{\pi(\pm, x)} \right],$$

**Step B** Flip label to keep direction  $(\pm, x) \to (\mp, x)$  with fixed probability  $1 - \theta$ .

(See [1], Chapter 1)

# Non-reversible Algorithm

#### **Properties**

- No need to consider normalization like in Metropolis algorithm.
- ullet With heta we can control the probability to change direction.
- Convergences because the chain is irreducible and aperiodic.

#### Invariant Distribution

Both steps leave  $\pi$  invariant.

Step A follows the construction of a Metropolis algorithm.

Step B because  $\pi(+,x) = \pi(-,x)$ .

Easily derive (See [2], Chapter 5.1):

$$\pi(\pm, x) = \pi(x)/2$$
 for all  $x \in \Omega$ .

# Application Ising-Model

### Mean Field Ising Model over Magnetization

State space: 
$$\Omega = \{-1, 1\}^{N^d}$$

Spin: 
$$\sigma(v) = \{-1, 1\}$$
 for all  $v \in \Omega$ 

Magnetization: 
$$M = \sum_{v \in \Omega} \sigma(v)$$

Energy Level: 
$$\mathcal{H} = -\frac{J}{2N} \sum_{v,w} \sigma(v) \sigma(w) = -\frac{J}{2N} M^2$$

# Application Ising-Model

### Invariant Distribution (Gibbs distribution)

$$\pi(M) = \frac{N!}{(\frac{N+M}{2})!(\frac{N-M}{2})!} \exp\left(\frac{\beta JM^2}{2N}\right),$$

with inverse temperatur  $\beta$  and exchange matrix J (here J=1).

### Acceptance Probability

$$p_{acc} = \min \left[ 1, \frac{N \mp M}{N \pm M + 2} \exp \left( \frac{2\beta J}{N} (\pm M + 1) \right) \right]$$

(See [1], Chapter 2)

# Application Ising-Model

### Nearest Neighbor Ising Model over Energy Level

Energy Level:  $\mathcal{H} = -J \sum_{\langle v, w \rangle} \sigma(v) \sigma(w)$ , where  $\langle v, w \rangle$  are direct neighbors.

#### Acceptance Probability

In 2-D case a single spin flip can lead to energy changes  $\Delta \mathcal{H}=0$ ,  $\Delta \mathcal{H}=\pm 4$  and  $\Delta \mathcal{H}=\pm 8$ .

Use Fiber-Algorithm with acceptance probability (See [1], Chapter 3):

$$p_{acc} = \min \left[ 1 \, , \, rac{K_{\pm |\Delta \mathcal{H}|}}{K_{\mp |\Delta \mathcal{H}|}'} \exp^{-eta \Delta \mathcal{H}} 
ight]$$

where K is the number of possible moves before and K' after spin flip.

# Fiber-Algorithm

**Step A** Randomly select stepsize s from a given set.

**Step B** Metropolis update  $(\pm, x) \rightarrow (\mp, x \pm s)$  with acceptance probability:

$$p_{acc} = \min \left[ 1, \frac{\pi(\mp, x \pm s)}{\pi(\pm, x)} \right]$$

**Step C** Flip label to keep direction  $(\pm, x) \to (\mp, x)$  with fixed probability  $1 - \theta$ .

(See [2] Chapter 5.2 for general approach)

## Implementation

## Example (Non-reversible 1D-Ising-Model over M)

```
nonrevMFI1D(theta,plotRun,calcIndicators,samples)
>> nonrevMFI1D(0.001,1,0,10000)
```

## Example (Non-reversible 2D-Ising-Model over M)

```
nonrevMFI2DM(theta,plotRun,calcIndicators,samples)
>> nonrevMFI2DM(0.001,1,0,10000)
```

### Example (Non-reversible 2D-Ising-Model over E)

```
nonrevNNI2DE(theta,plotRun,calcIndicators,samples)
>> nonrevNNI2DE(0.001,1,0,10000)
```

#### References

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Material for this presentation: http://tinyurl.com/kzmthcq