

This excerpt from

Adaptation in Natural and Artificial Systems.

John H. Holland.

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Glossary of Important Symbols

(Page numbers indicate first important or defining occurrences in the text.)

English Symbols

A	a particular structure attainable by an adaptive plan; $A \in \mathcal{A}$ (5, 22)
\mathcal{A}	domain of action of an adaptive plan, the structures it can attain (5, 21)
$\mathcal{A}(t)$	the particular structure from \mathcal{A} being tried at time t (15, 22)
$\mathcal{A}_1(t)$	that part of the structure $\mathcal{A}(t)$ directly tested against the environment (23)
$\mathcal{B}(t)$	the population (set of structures) acted upon by the reproductive plan at time t (88, 91)
$\langle c_i \rangle$	controlling sequence for mutation rate (122)
$\langle C, J, V \rangle$	("initiation condition," "end signal," "predicted value") for behavioral atom (156)
d_i	dominance map for i th position of homologous pair of l -tuples (112)
E	a particular environment of a system undergoing adaptation (4, 25)
\mathcal{E}	possible environments (uncertainty) of adaptive system (4, 25)
I	the range of signals the adaptive system can receive from the environment (22)
$I(t)$	the particular signal received by the adaptive system from the environment at time t (22)
\mathcal{J}_M	first M positive integers (91)
k or k_i	number of attributes (alleles, etc.) associated with the (i)th detector (gene, etc.) (21, 72)
l	number of detectors (genes, etc.) used in the representation of structures in \mathcal{A} (66)

$l(\xi)$	length of schema ξ (102)
$P(\xi)$	number of positions on which schema ξ is defined (110)
$L(N)$	expected loss under an allocation of N trials (by plan τ) (77)
M	size of population (data base) $\mathcal{B}(t)$ acted upon by reproductive plan (73, 91)
$\mathcal{M}(t)$	memory, that part of the input history retained by the adaptive plan <i>in addition</i> to the part summarized in the tested structure $\mathcal{Q}_1(t)$, where $\mathcal{Q}(t) = (\mathcal{Q}_1(t), \mathcal{M}(t))$ (23)
$M_\xi(t)$	number of instances of schema ξ in the population $\mathcal{B}(t)$ (87, 98)
n	number of trials allocated to random variables other than the best in a set of random variables (77)
N	total number of trials allocated to a set of random variables (76)
$P(\xi, t)$	$= \text{def. } M_\xi(t)/M$, the proportion of ξ in $\mathcal{B}(t)$ (102, 127)
$P_{[\]}$	probability of operator [] being applied to an individual in $\mathcal{B}(t)$ (102 P_c (crossing-over), 108 P_I (inversion), 110 P_M (mutation))
\mathcal{P}	a <i>set</i> of probability distributions over \mathcal{Q} (24)
Q_ξ	limit on rate of reproduction in environmental niche associated with ξ , set by renewal rates of resources in that niche (166)
n'	number of schemata receiving n' or more trials (under a genetic plan) (129)
$\mathcal{R}_{[\]}$	reproductive plans of type [] (90 ff)
$\mathcal{R}_1(P_c, P_I, P_M, (c_i))$	special class of type \mathcal{R}_1 plans used in the study of robustness (121 ff)
t	time (20)
\mathcal{J}	a set of adaptive plans to be compared (25)
$U_{\tau, E}(T)$	the payoff accumulated by plan τ in environment E up to time T (26)
\mathcal{U}	a set of random variables used when payoff is to be assigned stochastically to elements of \mathcal{Q} (25)
V_i	set of attributes (range of values) for the i th detector, δ_i (66)

Greek Symbols

$\alpha(\xi, \Delta t)$	average excess (in genetics) of schema (coadapted set) ξ (137)
$\delta_i: \mathcal{Q} \rightarrow V_i$	detector, assigns attributes (values from V_i) to structures $A \in \mathcal{Q}$ (66; cf. 6, 44)

Δ	crossing-over “pressure” (101)
ϵ_{ξ}	fraction of instances of ξ in $\mathcal{R}(t)$ lost because of action of operators (125)
$\lambda(\xi)$	steady-state probability of occurrence of schema ξ under crossing-over (100)
Λ	= <i>df.</i> $\{0, 1, *, \cdot, \diamond, \nabla, \Delta, p, '\}$, symbols of the broadcast language (144)
$\mu_E: \mathcal{A} \rightarrow \text{Reals}$	payoff or performance of structure $A \in \mathcal{A}$ in environment E (4, 25)
μ_{ξ}	the expected payoff to schema ξ (under some given probability distribution P over \mathcal{A}) (69)
$\bar{\mu}_{\xi}$	the <i>observed</i> average performance (payoff) of a set of samples of ξ (69)
$\bar{\mu}(t)$	the observed average performance of the structures in $\mathcal{R}(t)$ (102)
$\bar{\mu}(T)$ or $\bar{\mu}(t)$	the average performance (payoff) of all trials of \mathcal{A} to time T , or the average performance of trials of \mathcal{A} at time-step t (69)
$\mu_{h,t}$	= <i>df.</i> $\mu_E(A_h(t))$ (94)
$\bar{\mu}_t$	= <i>df.</i> $\sum_h \mu_{h,t} / M$, average performance of population $\mathcal{R}(t)$ (94)
ξ	a schema (designating a subset of \mathcal{A}); $\xi \in \Xi$ (68)
$\xi_{(j)}(N)$	schema with the j th highest <i>observed</i> average after N trials (77)
Ξ	the set of schemata defined over \mathcal{A} (68)
$\rho: \mathcal{A}_1 \rightarrow \Omega$	assigns operator to structure for plans of type $\mathcal{R}_{1,1}$ (92)
$\tau: I \times \mathcal{A} \rightarrow \Omega$ or $\tau: I \times \mathcal{A} \rightarrow \mathcal{A}$	an adaptive plan (4, 21)
χ	a criterion for comparing plans in the set \mathcal{J} (26)
$\omega: \mathcal{A} \rightarrow \mathcal{A}$ or $\omega: \mathcal{A} \rightarrow \mathcal{P}$	an operator (for modifying structures), either deterministic or stochastic; $\omega \in \Omega$ (24)
$\omega: \mathcal{S}_M \times \mathcal{A}_1^M \rightarrow \mathcal{P}$	a particular operator (for plans of type $\mathcal{R}_{1,1}$) (92)
Ω	the set of operators (for modifying structures) employed by an adaptive plan (3, 24)

Miscellaneous Symbols

\square	a “don’t care” indicator used in the definition of schemata (68)
$[\]^{\dagger}$	set of all permutations of (elements of) $[\]$ (107)

\sim	ratio is 1 in the limit (78)
\approx	difference is negligible (under stated conditions) (78)
\equiv <small>df.</small>	defined to be equal (94)

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