System Model:

$$\underline{Y}_{\bar{i}} = \underline{S}_{i}^{\mathsf{T}} \underline{X}_{i} + \underline{N}_{i}$$

where Xi E R is the channel input vector

taking real value with dimension 9 at time shot ?

For example,
$$X_1 = \begin{bmatrix} 1 & 2 \\ 2 & 3 \\ 3 & 4 \\ 4 & 5 \\ 1 & 6 \\ 2 & 7 \end{bmatrix}$$
 here $M = 6$. $q = 2$.

Si is an one-hot vector with dimension M.

For example, $S_1 = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ here M = 6.

Ni ERIXA is the Gaussian distributed channel noise with mean zero and variance one

 $N_i \sim N(0, 1).$

It E RIX9 is the channel output.

 Pesign an autoenvoder & autodecoder for this channel model to minimize the bit error rate (BER)

the bit error rate (BER)

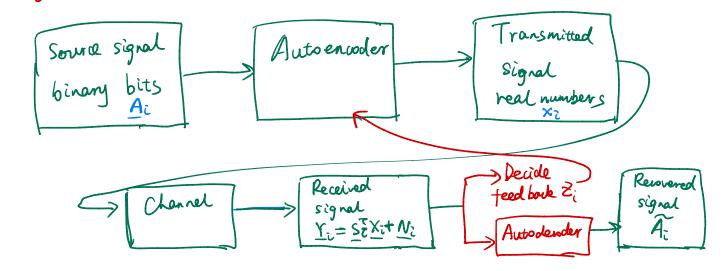
BER = # of bit errors

Total # of transmitted bits

for a given rate R.

For example, given $R = \frac{1}{3}$ \Rightarrow it takes \Rightarrow it tak

Objective:



Pesign autoencoder & autoclecoder, using python programming language.

Evaluate the performance of your design based on different Sets of 9, Q, B and plot the BER.