

Geospatial Data Management Final Project

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Scenario

Geospatial data points logging during my visit in Berlin
Using the phone app: GPSTLogger

<https://gpslogger.app/>

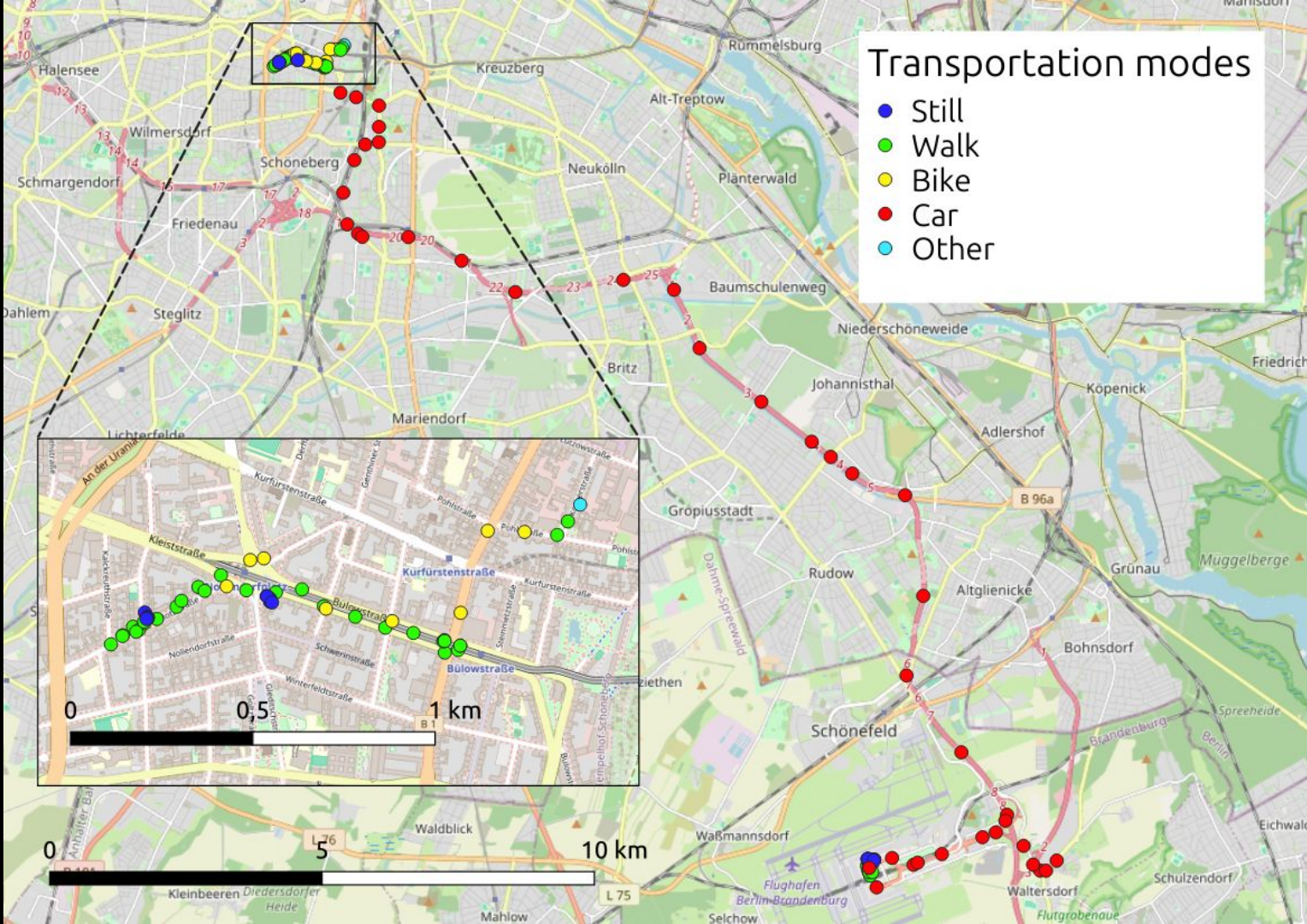
Data scheme

- Geometry with reference system: EPSG:4326 WGS 84
- Time: UTC + timezone
- Transportation mean: still, walk, bike, car

Interval of acquisition set to 1 minute

Transportation modes

- Still
- Walk
- Bike
- Car
- Other



Objective

To infer transportation means for each data point, and getting the lowest possible error

Measuring the error ratio:

$$\text{Error} = \text{number incorrect predictions} / \text{total points number}$$

Data preprocessing

Create a new table with selected attributes:

```
CREATE TABLE gps_20250520_processed AS  
  (SELECT ogc_fid AS id, wkb_geometry, time, mode, src,  
    LAG(wkb_geometry) OVER (ORDER BY time) AS prev_geom,  
    LAG(time) OVER (ORDER BY time) AS prev_time  
  FROM gps_20250520_original  
  ORDER BY time);
```

Using *prev_geom* and *prev_time* fields to compute the spatial and temporal distances between two consecutive points

And then get the speed between the current and the previous point

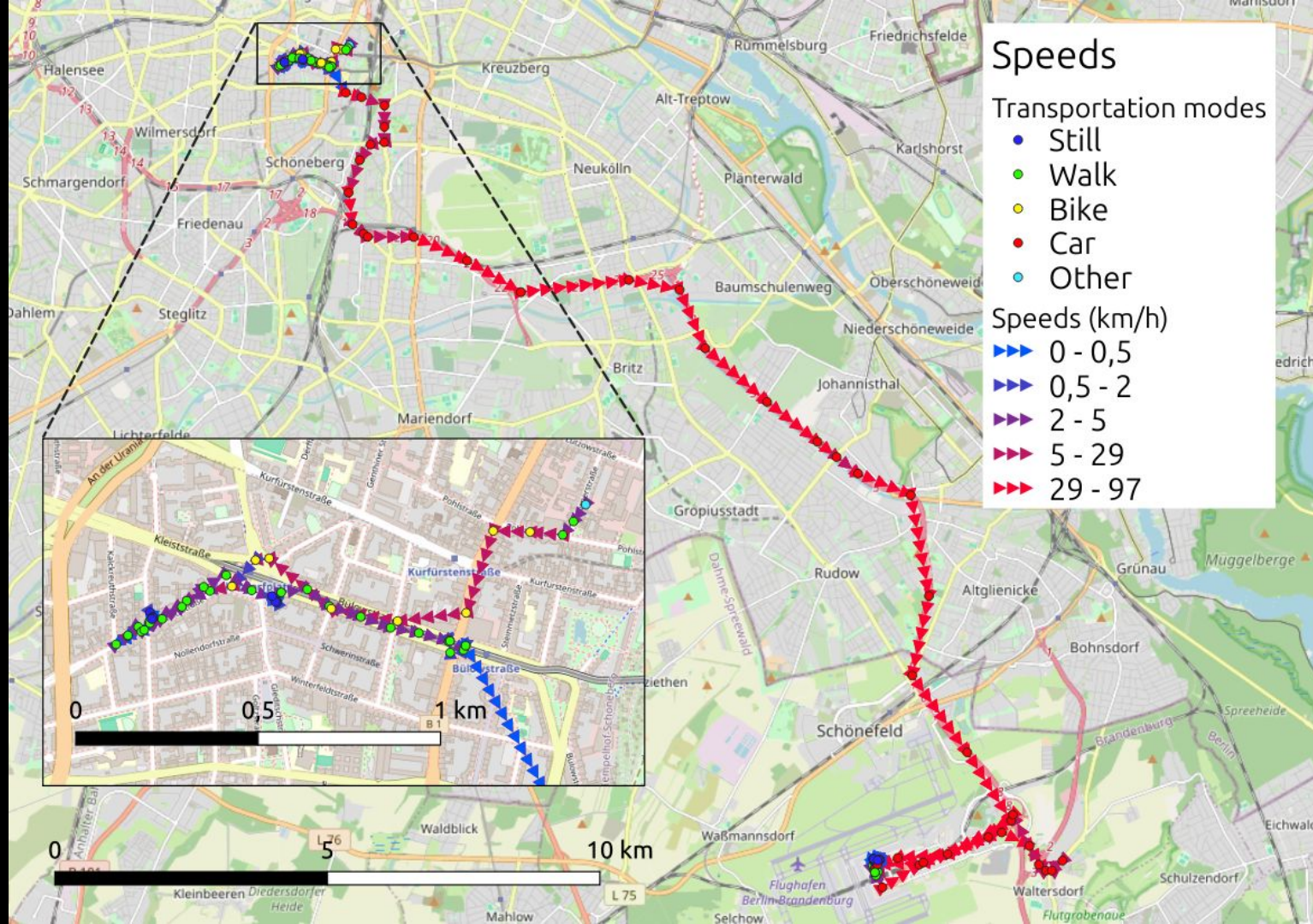
Speeds

Transportation modes

- Still
- Walk
- Bike
- Car
- Other

Speeds (km/h)

- ▶▶ 0 - 0,5
- ▶▶ 0,5 - 2
- ▶▶ 2 - 5
- ▶▶ 5 - 29
- ▶▶ 29 - 97

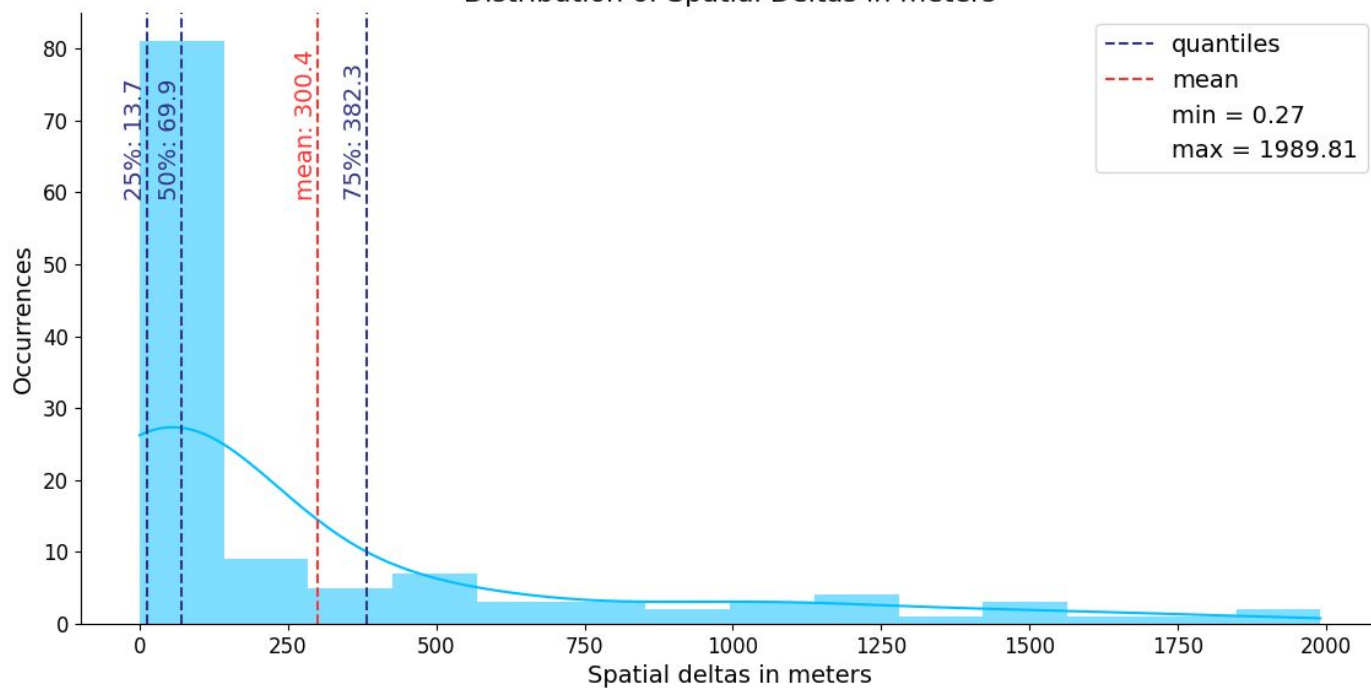


Statistics

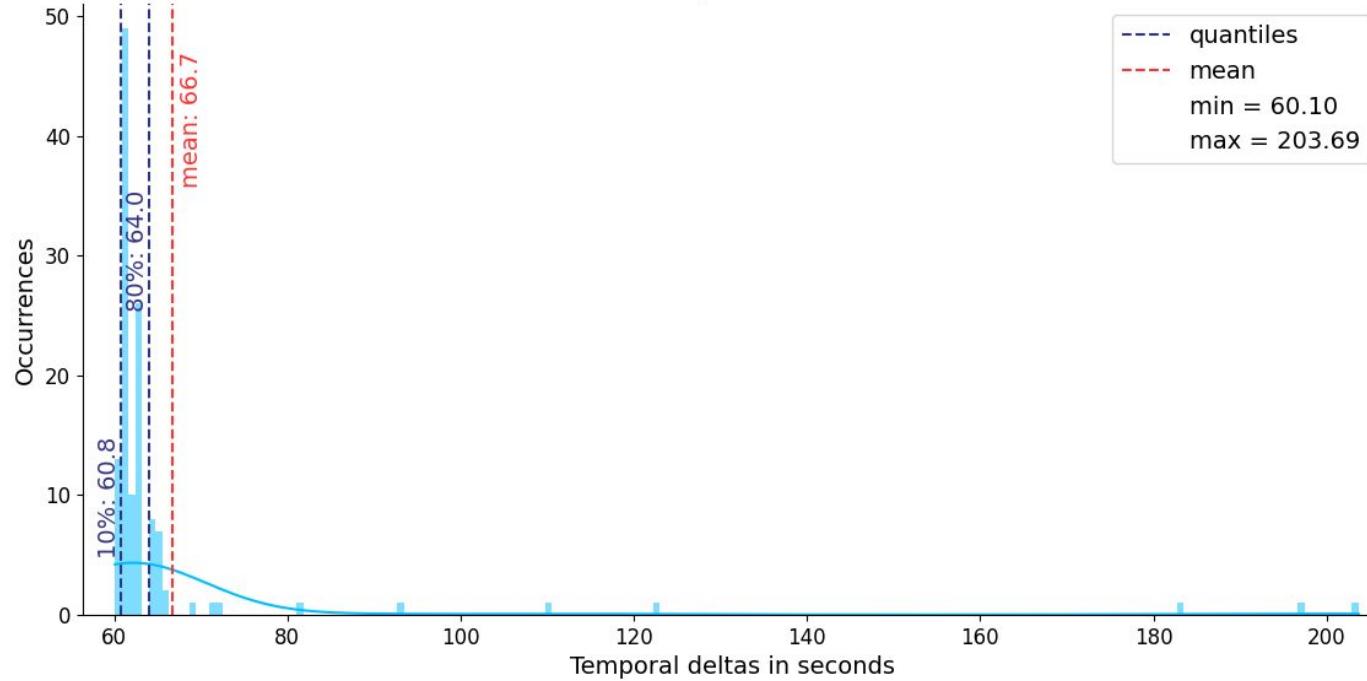
Base statistics

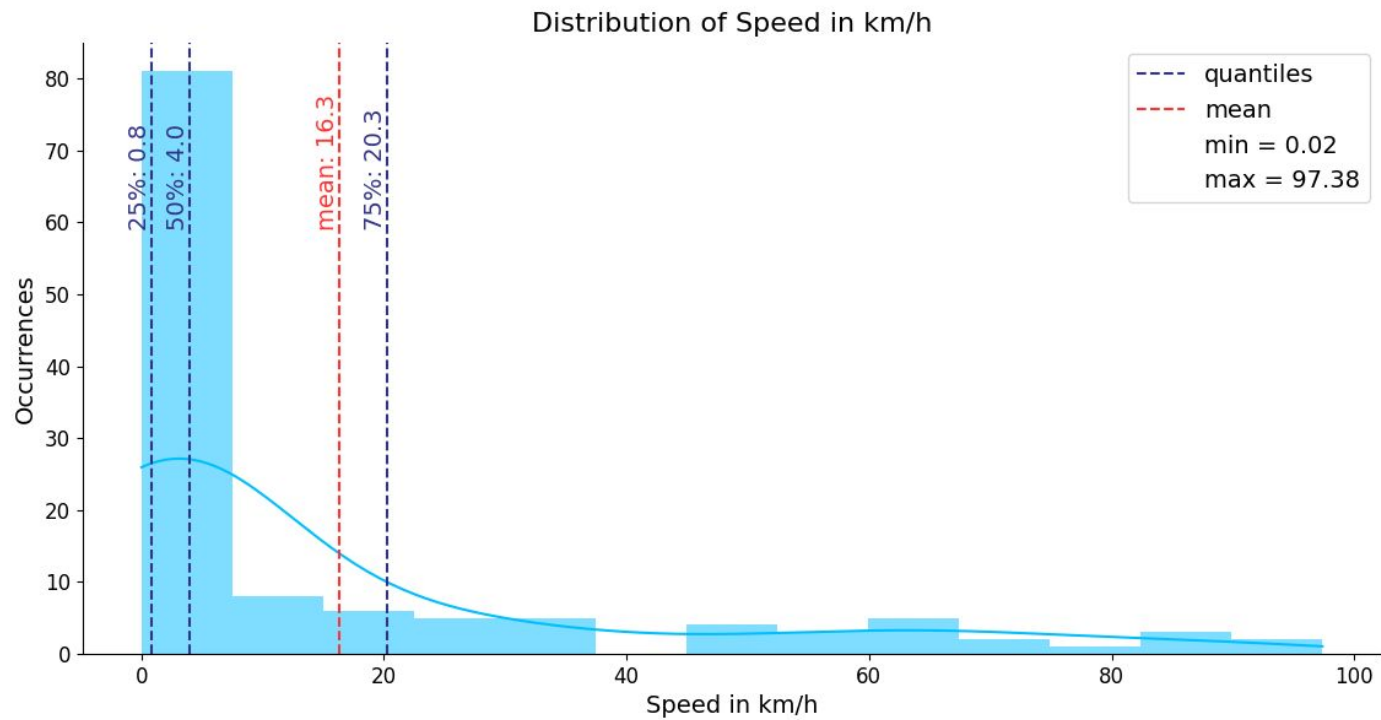
Metric	Value
Number of points	126
Total distance (m)	37551.58813949
Total duration (HH:mm:ss)	2:19:02.141

Distribution of Spatial Deltas in meters



Distribution of Temporal Deltas in seconds



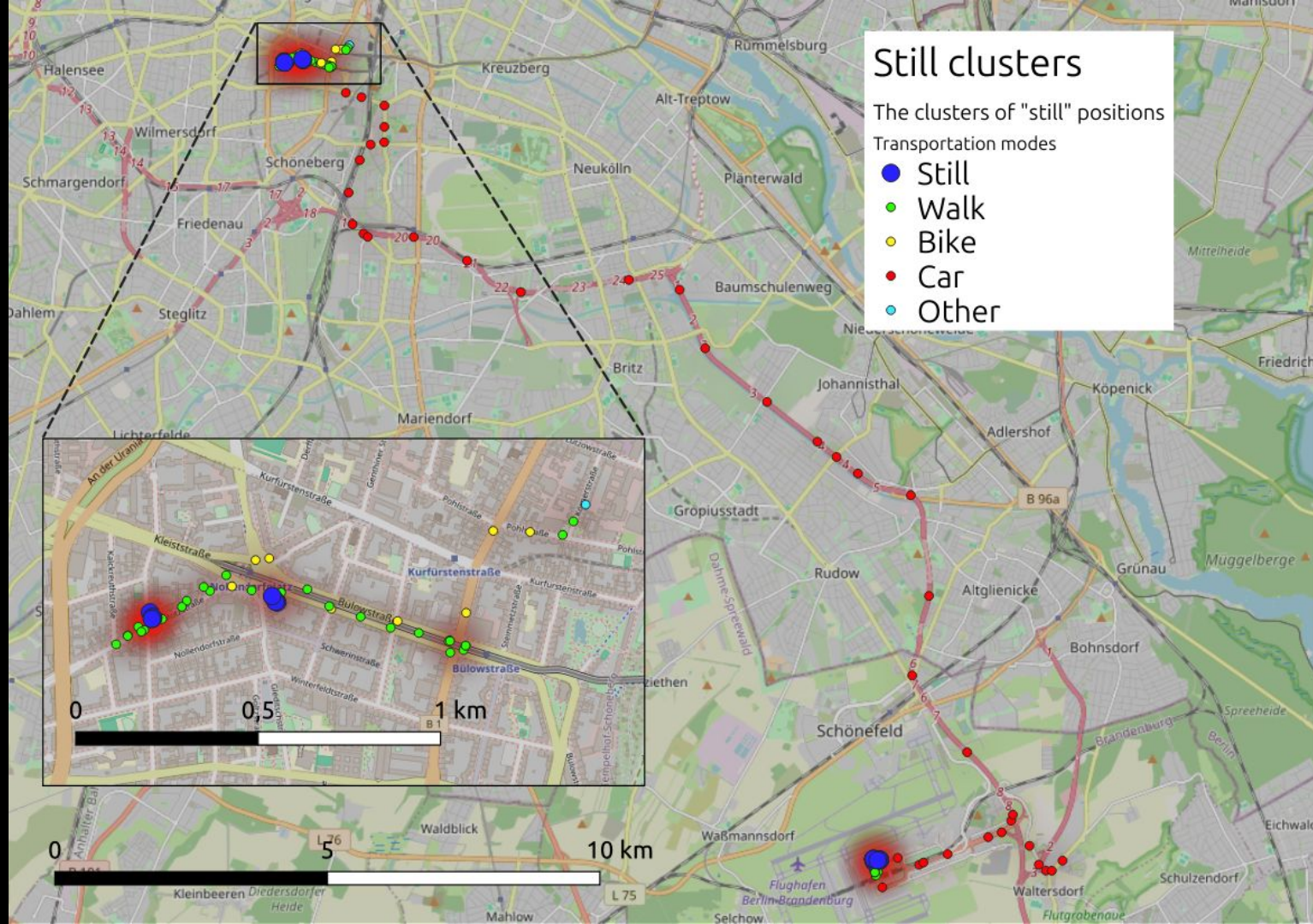


Still clusters

The clusters of "still" positions

Transportation modes

- Still
- Walk
- Bike
- Car
- Other



Solving approach

Python script to do a random search on range values:

```
thresholds = {  
    'still-walk': np.arange(0, 5, .01),  
    'walk-bike': np.arange(5, 10, .01),  
    'bike-car': np.arange(10, 20, .01)  
}
```

Updating the values on the data points table and comparing to the ground truth to find the minimal error ratio

https://github.com/simone-05/gdm_project/blob/main/random_search_with_csv.py

Results

Errors statistics

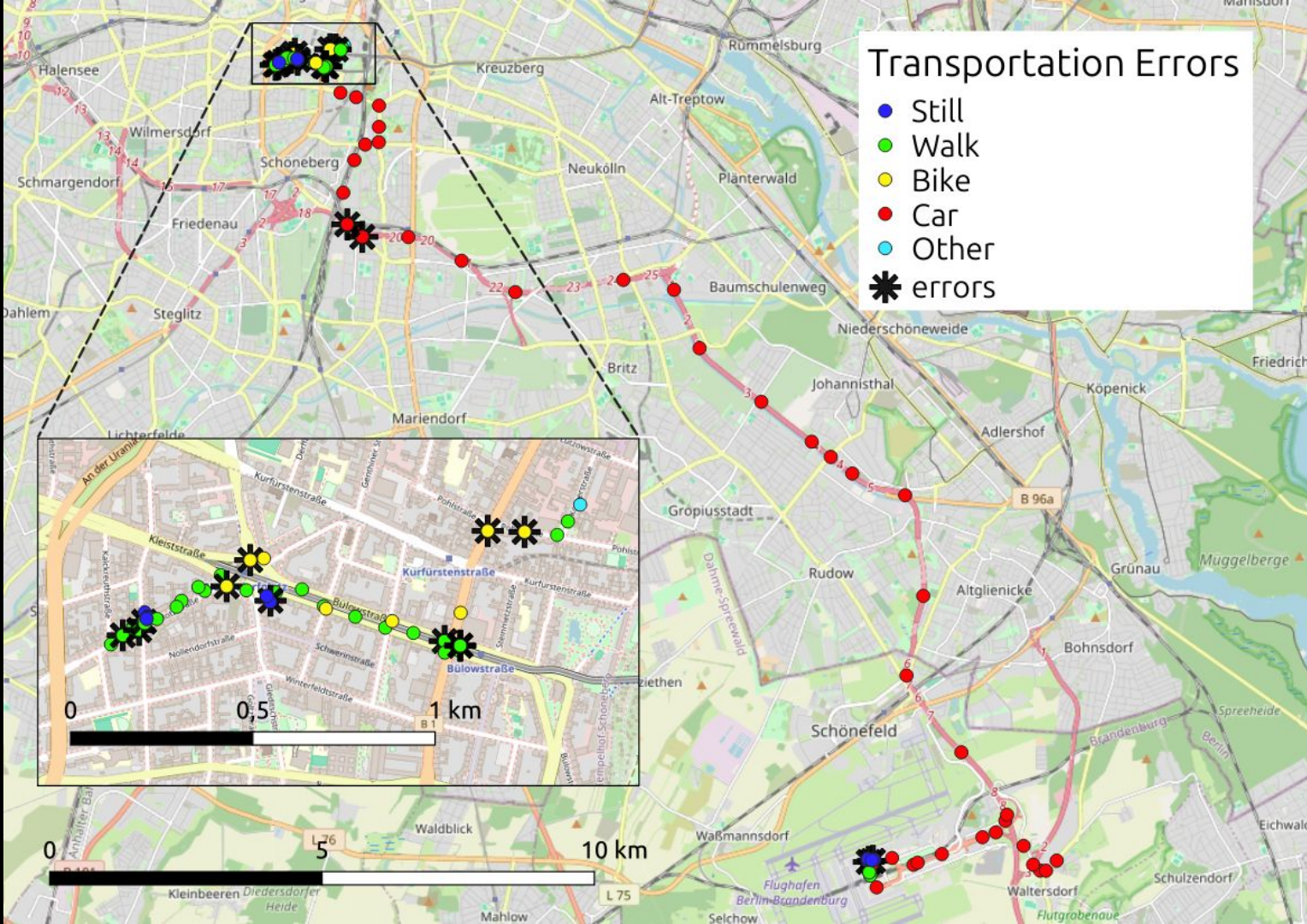
Metric	Value
Number of errors	15.0
Error ratio	0.12

Error stats details

Metric	Value
Correctly predicted car	39 out of 41
Correctly predicted still	36 out of 39
Correctly predicted walk	31 out of 37
Correctly predicted bike	4 out of 8
Missed walk, predicted as still	6
Missed bike, predicted as walk	4
Missed still, predicted as walk	3
Missed car, predicted as walk	1
Missed car, predicted as bike	1

Transportation Errors

- Still
- Walk
- Bike
- Car
- Other
- ✱ errors



End