

Notes on

Probability

from the lectures of
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Complements to Chapter 1

0.1 Probability construction

Operatively, there are two ways of furnishing a (measure of) probability on a measurable space (Ω, \mathcal{F}) : it may be claimed or inferred. In the first case, its law is given *a priori*, while in the second it is deduced *a posteriori*, from the knowledge of the probability values on some elementary events, that is.

The first is common in applications such as Bayesian Statistics, where you make an hypothesis on the distribution and then test it, while the second is also characteristic of measure theory. The key difference lies in the fact that we either have complete or minimal information about the probability.

In both cases some check are in order, as we need to ensure that the probability is *coherent*. Note that in the second case, we also need to ensure that the one generated is unique, the minimal information is *sufficient*, that is.

0.1.1 Discrete setting

Some results of this kind were produced already: we have dealt with the case of discrete partitions of the sample space Ω . We quote such theorems.

Theorem 0.1.1 (Existence and Uniqueness). *Let $\mathcal{E} = \{E_k\}_{k \in I}$ be a discrete partition of Ω and let the function $p : E_k \in \mathcal{E} \rightarrow p_k \in \mathbb{R}$ be such that*

$$\begin{cases} \sum_{k \in I} p_k = 1 \\ p_k \geq 0 \end{cases} \quad \text{for all } k \in I. \quad (1a)$$

$$p_k \geq 0 \quad \text{for all } k \in I. \quad (1b)$$

Then, there exist a unique probability \mathbb{P} on $\sigma(\mathcal{E})$ such that \mathbb{P} and p agree on \mathcal{E} . A function p with the properties (1a) and (1b) of is called a discrete probability density.

Morally, the discrete probability density on a partition describes a unique and consistent probability on the generated σ -algebra. Moreover, we have an explicit description of each event $E \in \sigma(\mathcal{E})$ and its probability $\mathbb{P}(E)$.

Lemma 0.1.2. *Let $\mathcal{E} = \{E_k\}_{k \in I}$ be a discrete partition of Ω . Then*

$$\sigma(\mathcal{E}) = \left\{ \bigcup_{k \in J} E_k \text{ for } J \subset I \right\}.$$

Now suppose that $p : E_k \in \mathcal{E} \rightarrow p_k \in \mathbb{R}$ is a discrete probability density. Then, if \mathbb{P} is the probability defined in Theorem 0.1.1,

$$\mathbb{P} \left(\bigcup_{k \in J} E_k \right) = \sum_{k \in J} p_k \quad \text{for all } J \subset I.$$

Remark 0.1.3. A special case worth mentioning is that of the atomic partition on a discrete Ω . Here, the σ -algebra generated is $\mathcal{P}(\Omega)$ and the discrete probability density is commonly referred to as $p(\{\omega\}) = p_\omega$. By the precedent results, p defines a unique agreeing probability \mathbb{P} such that

$$\mathbb{P}(E) = \sum_{\omega \in E} p_\omega \quad \text{for all } E \subset \Omega. \quad (2)$$

0.1.2 General setting

For more general settings the short message is that Theorem 0.1.1 holds, provided some conditions, while no explicit characterization like that of Lemma 0.1.2 is possible.

We present a powerful theorem of measure theory, that does just that. It will allow us to extend a *pre-probability*, a function with some coherence that is defined on a collection smaller than a σ -algebra, to a probability, in a unique fashion.

Definizione 0.1.4. Let \mathcal{A} be an algebra defined on Ω . Then, $\tilde{\mathbb{P}} : \mathcal{A} \rightarrow \mathbb{R}$ is a *pre-probability* if

1. $\tilde{\mathbb{P}}(\Omega) = 1$ (Normalization)
2. $\tilde{\mathbb{P}}(\bigcup_{i=1}^n A_i) = \sum_{i=1}^n \tilde{\mathbb{P}}(A_i)$ for $A_i \in \mathcal{A}$ (Additivity)
3. if $\bigcup_{i \in \mathbb{N}} A_i \in \mathcal{A}$, then $\tilde{\mathbb{P}}(\bigcup_{i \in \mathbb{N}} A_i) = \sum_{i \in \mathbb{N}} \tilde{\mathbb{P}}(A_i)$.

Remark 0.1.5. The latter is the condition that ensure coherence with respect to the probability, and can be read as a *need-based σ -additivity*.

Theorem 0.1.6 (Carathéodory's Theorem). *Let \mathcal{A} be an algebra defined on Ω , and suppose that $\tilde{\mathbb{P}} : \mathcal{A} \rightarrow \mathbb{R}$ is a pre-probability. Then, there exists a unique probability $\mathbb{P} : \sigma(\mathcal{A}) \rightarrow \mathbb{R}$ such that $\tilde{\mathbb{P}}$ and \mathbb{P} agree on \mathcal{A} .*

Remark 0.1.7. This version of the Carathéodory's Theorem is of theoretical interest and provides two results. First, it shows that **existence** of a consistent extension is guaranteed just by requiring the coherence of $\tilde{\mathbb{P}}$ with the conditions that define a probability: these are encoded in Definition 0.1.4. Moreover, the theorem quantifies the idea that if $\tilde{\mathbb{P}}$, the information provided about \mathbb{P} that is, is defined on a large enough collection, then its extension is **unique**. In particular, we require \mathbb{P} to be given on an algebra, a much smaller collection than a σ -algebra.

We can refine the result for practical purposes by exploiting the equivalence between σ -additivity and continuity¹.

Lemma 0.1.8 (Carathéodory's Theorem, continuity characterization). *Let \mathcal{A} be an algebra defined on Ω , and suppose that $\tilde{\mathbb{P}} : \mathcal{A} \rightarrow \mathbb{R}$ satisfies*

1. $\tilde{\mathbb{P}}(\Omega) = 1$,
2. $\tilde{\mathbb{P}}(\bigcup_{i=1}^n A_i) = \sum_{i=1}^n \tilde{\mathbb{P}}(A_i)$,
3. if $A_i \downarrow \emptyset$, then $\tilde{\mathbb{P}}(A_i) \downarrow 0$,

where $A_n \in \mathcal{A}$. Then, there exists a unique probability $\mathbb{P} : \sigma(\mathcal{A}) \rightarrow \mathbb{R}$ such that $\tilde{\mathbb{P}}$ and \mathbb{P} agree on \mathcal{A} .

Remark 0.1.9. The usefulness of this is that monotone continuity, that is showing a limit is 0, is generally much easier than working on countable unions to arbitrary sets. It is of theoretical interest that this only holds if we use an algebra: as we will see, if it wasn't for this characterization weaker conditions on the collection (namely, that it is a π -system instead of an algebra) could be used.

Another refinement is in order: the minimal information condition could be weaker. This is an application of the Monotone class theorem, and while we will not go into details, some more can be found [here](#).

Definizione 0.1.10 (π -system). A collection \mathcal{C} is said to be a π -system if stable under finite intersection. Explicitly, if $A_1, \dots, A_n \in \mathcal{C}$ then $\bigcap_{i=1}^n A_i \in \mathcal{C}$.

Remark 0.1.11. Operatively, it suffices to show that if $A, B \in \mathcal{C}$ then $A \cap B \in \mathcal{C}$ for finite intersection stability to hold, by inductive argument.

Lemma 0.1.12.

This theorem is not just about comparisons. It furnishes sharp² conditions for the uniqueness in Theorem 0.1.6: it requires the pre-probability to be defined just on a π -system containing Ω , something weaker than an algebra.

¹This result from measure theory is taken to be known and the details are out of the scope of these notes.

²Mathematical gibberish for "minimal"

Borel's σ -algebra

σ -algebra on Bernoulli Space

Bassetti Unbound

Exercise 1. Let Ω be a set and let $A \subset \Omega$ a subset from it. Then, show that $\{A, A^c, \emptyset, \Omega\}$ is a σ -algebra.

Notes. This is the easiest nontrivial σ -algebra. It models a bet: the event may either happen or not (or nor could happen, that is the same as all the outcomes being realized). (??)

Exercise 2. Let $\{\mathcal{F}_\alpha\}_{\alpha \in I}$ be a collection of σ -algebras. Is $\bigcap_{\alpha \in I} \mathcal{F}_\alpha$ a σ -algebra. What about $\bigcup_{\alpha \in I} \mathcal{F}_\alpha$?

Notes. This³ justifies minimality arguments on the function $\sigma(\cdot)$. Read this [masterpiece](#), this [essay](#) and this very general and technical [site](#).

Exercise 3. Prove the well-definiteness of $\sigma(\mathcal{E})$ as the minimal σ -algebra containing \mathcal{E} .

Notes (Sketch of proof). Let $\Sigma(\mathcal{E})$ be the collection of all the σ -algebras containing the collection \mathcal{E} of subsets of Ω . (Prove that) $\Sigma(\mathcal{E})$ is not empty, and the family intersects to $\bigcap_{S \in \Sigma} S = \sigma(\mathcal{E})$.

Exercise 4. Let E_1, E_2 be events of Ω . Think of a sample space and construct a measure of probability $\mathbb{P} : \mathcal{P}(\Omega) \rightarrow \mathbb{R}$ such that the two events are independent and $\mathbb{P}(E_1) = \mathbb{P}(E_2) = \frac{1}{2}$.

Notes. (??)

Exercise 5.

Notes.

³The answer is that the first is, in fact, a σ -algebra, while the second not so, as it does not contain crossed unions and intersections.