Last Class ...

Example: Mass-Spring-Damper, Real World System

$$\mathcal{R}(\mathbf{u}, au; \mathbf{r}) = \mathbf{0}$$
 $\mathbf{u} = egin{bmatrix} x + c\dot{x} + kx = 0 \\ \dot{x} \end{pmatrix} \quad au = egin{bmatrix} c \\ \dot{x} \end{pmatrix} \quad au = egin{bmatrix} c \\ \dot{x} \end{pmatrix} \quad \mathbf{r} = egin{bmatrix} m \\ \dot{x}(0) \\ \dot{x}(0) \end{pmatrix}$

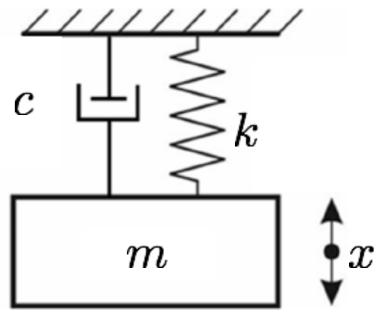
$$\tau = (\mathbf{u}, \mathbf{v}, \mathbf{s}, \theta)$$

$$k = \text{const}$$

$$c(T) = \exp\left(\frac{T_0}{T} - 1\right)$$

$$\dot{T} = c(T)\dot{x}^2 - \frac{T - T_0}{t_T}$$

$$\mathbf{v} = T$$
 $\mathbf{s} = egin{bmatrix} T_0 \ t_T \end{bmatrix}$ $\theta = k$





$$\mathbf{y} = x$$
 $\mathbf{q} = \max(\dot{x})$

Bayesian Machine Learning Approach to the Quantification of Uncertainties on Ab Initio Potential Energy Surfaces [2]