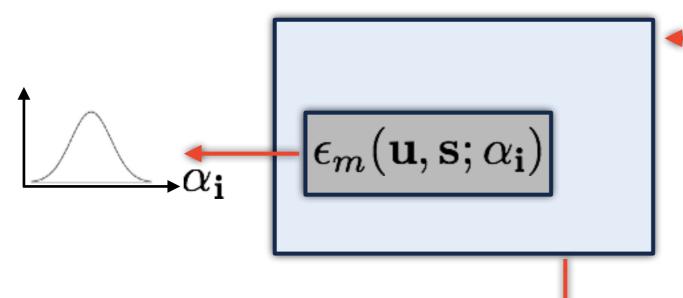
The 3-Steps Reliability Assessment

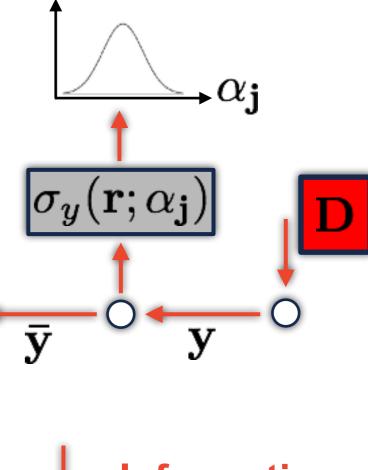
- Model <u>Calibration</u> (or <u>Inverse Problem</u>)
- Validation
- Predictive Assessment

The model is **informed by data**. Parameter values and their uncertainties are inferred from available observations by **solving an inverse problem**.



The use of probability to represent uncertainty naturally leads to the formulation of the calibration problem as Bayesian (**Bayesian Inference**):

Posterior
$$p(\theta, \alpha | \mathbf{D}, \mathcal{M}) = \frac{\mathcal{L}(\theta, \alpha; \mathbf{D}, \mathcal{M}) \mathbf{p}(\theta, \alpha | \mathcal{M})}{\int \mathcal{L}(\theta, \alpha; \mathbf{D}, \mathcal{M}) \mathbf{p}(\theta, \alpha | \mathcal{M}) \mathbf{d}\theta \mathbf{d}\alpha}$$



The 3-Steps Reliability Assessment

- Model <u>Calibration</u> (or <u>Inverse Problem</u>)
- Validation
- Predictive Assessment

