

D8 – PHÉNOMÈNES DE TRANSPORT

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Niveau : L2

Prérequis

- Mécanique Lagrangienne
- Problème à deux corps
- Mécanique du solide

Expériences

- ➥ Conservation de l'énergie et de la charge $v_z + gt$ durant la chute d'une réglette.

Table des matières

D²) Gén. de la conservation en mécanique

L3 - moment du système, eq E-L, pt à 2 corps, avec sollicit.

I Symétrie et Conservation

1) Symétrie du lagrangien

Soit $F(q, \dot{q}, t)$

$$L'(q_0, q_1, \dot{q}_1, t) = L(q_0, q_1, \dot{q}_1, t) + \frac{dF}{dt}$$

$$\frac{d}{dt} \left(\frac{\partial L'}{\partial \dot{q}_1} \right) - \frac{\partial L'}{\partial q_1} = \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}_1} \right) + \frac{d}{dt} \left(\frac{\partial dF}{\partial \dot{q}_1} \right) - \frac{\partial L}{\partial q_1} - \frac{\partial (dF)}{\partial q_1}$$

$$\text{Or } \frac{dF}{dt} = \frac{\partial F}{\partial t} + \frac{\partial F}{\partial q_i} \frac{dq_i}{dt} = \frac{\partial F}{\partial t} + \dot{q}_i \frac{\partial F}{\partial q_i}$$

$$\frac{d}{dt} \left(\frac{\partial L'}{\partial \dot{q}_1} \right) - \frac{\partial L'}{\partial q_1} = \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}_1} \right) - \frac{\partial dF}{\partial q_1} = 0$$

$$\Rightarrow \boxed{L' = L + \frac{dF}{dt}} \quad \text{deut aussi le système}$$

2) Théorème de Noether

Soit une transformation du second $q_i \rightarrow q'_i$

$$\text{avec } q'_i = q_i + \varepsilon g_i(q_i, t) = q_i + S q_i$$

$$q''_i = q'_i + \varepsilon \frac{\partial g_i}{\partial t} = q_i + S q_i$$

~~On démontre que $L(q'', \dot{q}'', t) = L(q', \dot{q}', t)$~~

Cette transformation deut une symétrie infinitésimale si et seulement si :

$$\boxed{L(q'_i, \dot{q}'_i, t) = L(q_i, \dot{q}_i, t) + \varepsilon \frac{dF(q_i, t)}{dt}}$$

$$\boxed{\text{ThM}} \quad L(q_i + \delta q_i, \dot{q}_i + \delta \dot{q}_i, t) - L(q_i, \dot{q}_i, t) = \varepsilon \frac{dF}{dt}$$

$$\sum_i \left(S_{q_i} \frac{\partial L}{\partial \dot{q}_i} + S_{\dot{q}_i} \frac{\partial L}{\partial q_i} \right) = \varepsilon \frac{dF}{dt}$$

$$\sum_i \left[S_{q_i} \left(\frac{\partial L}{\partial \dot{q}_i} - \frac{d}{dt} \frac{\partial L}{\partial \dot{q}_i} \right) + S_{\dot{q}_i} \frac{d}{dt} \frac{\partial L}{\partial q_i} + S_{q_i} \frac{\partial L}{\partial q_i} \right] = \varepsilon \frac{dF}{dt}$$

$$\underbrace{\sum_i \left(\frac{d}{dt} \left(S_{q_i} \frac{\partial L}{\partial \dot{q}_i} \right) \right)}_{= 0} = \varepsilon \frac{dF}{dt}$$

$$\underbrace{\left(\frac{d}{dt} \left(\sum_i S_{q_i} g_i(q_j, t) \frac{\partial L}{\partial \dot{q}_i} \right) - \varepsilon F \right) = 0}_{= 0}$$

$$\textcircled{Q} \quad Q = \sum_i \left(g_i(q_j, t) \frac{\partial L}{\partial \dot{q}_i} \right) - F(q_j, t) \cancel{=} 0$$

Q est une charge de Noether, c'est une constante du mouvement.

3) Conservation usuelles

$$\text{Cas particulier : } \frac{\partial L}{\partial q_K} = 0$$

$$\text{On a) la transfo } \sum g_K(q, t) = 1$$

$$\sum g_{K+0}(q, t) = 0$$

$$\delta q_K = \varepsilon \quad S_{q_K} = 0$$

$$S_{q_{K+0}} = 0 \quad S_{q_{j+0}} = 0$$

$$\rightarrow S_{q_i} \frac{\partial L}{\partial \dot{q}_i} + S_{\dot{q}_i} \frac{\partial L}{\partial q_i} = \varepsilon \frac{\partial L}{\partial q_K} = 0 \rightarrow \text{on obtient } F = 0$$

$$Q = \sum_i g_i(q_j, t) \frac{\partial L}{\partial \dot{q}_i} = \underbrace{\frac{\partial L}{\partial q_K}}_{= \text{const}} = \text{const}$$

Si q_r est une coord. spatiale \rightarrow conservation de l'impulsion

Si q_r est une coord angulaire \rightarrow conservation du moment cinétique

$$\mathcal{L} = \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\theta}^2) - V(r)$$

$$\frac{\partial \mathcal{L}}{\partial \dot{\theta}} = \frac{1}{2} m r^2 \dot{\theta} = \vec{r} \cdot \vec{p}$$

~~moment cinétique~~

$$\mathcal{L} = \frac{1}{2} m \vec{p}^2 = V$$

$$\frac{\partial \mathcal{L}}{\partial \vec{p}} = m \vec{v} = \vec{p}$$

Invariance dans le temps

$$\frac{\partial \mathcal{L}}{\partial t} = 0$$

$$\text{Alors } \frac{d\mathcal{L}}{dt} = \frac{\partial \mathcal{L}}{\partial t} + \dot{q}_i \frac{\partial \mathcal{L}}{\partial q_i} + \ddot{q}_i \frac{\partial \mathcal{L}}{\partial \dot{q}_i}$$

$$= 0 + \dot{q}_i \left(\frac{\partial \mathcal{L}}{\partial q_i} - \frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{q}_i} \right) + \dot{q}_i \frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{q}_i} + \ddot{q}_i \frac{\partial \mathcal{L}}{\partial \dot{q}_i}$$

$$\frac{d\mathcal{L}}{dt} = \frac{d}{dt} \left(\dot{q}_i \frac{\partial \mathcal{L}}{\partial \dot{q}_i} \right)$$

$$\frac{d}{dt} \left(\cancel{\dot{q}_i} \frac{\partial \mathcal{L}}{\partial \dot{q}_i} - \mathcal{L} \right) = 0$$

$$\rightarrow \boxed{H = \dot{q}_i \frac{\partial \mathcal{L}}{\partial \dot{q}_i} - \mathcal{L}} \text{ est constante}$$

$$(H = \dot{q}_i m \ddot{q}_i - \left(\frac{1}{2} m \dot{q}_i^2 - V(q) \right) = \frac{1}{2} m \dot{q}_i^2 + V(q))$$

Exemple gravitation

$$\ddot{z} = \frac{1}{2} m \dot{z}^2 - mg z$$

$$\ddot{z} = \varepsilon ; \quad S\ddot{z} = 0$$

$$L(\dot{z} + S\ddot{z}, z, S\dot{z}, t) = \frac{1}{2} m \dot{z}^2 - mg(z + S\dot{z})$$

$$1m \dot{z}^2 + mg\dot{z} = H$$

$$\dot{z} = z \left(\frac{H}{m} - gz \right)$$

$$z = \sqrt{\frac{H}{m} - gt^2}$$

$$\hookrightarrow S\ddot{z} = -mg S\dot{z} = -mg\varepsilon$$

$$F(z,t) \equiv -mgt$$

$$Q = \frac{\dot{z} \frac{\partial L}{\partial \dot{z}} - F}{S\dot{z}} = m \dot{z}^2 + mg t$$

$\dot{z} + gt = \text{const}$

$$\dot{z} = \text{const} - gt$$

$$z = z_0 + v_{z_0} t - \frac{1}{2} gt^2$$

$$H = \frac{1}{2} m \dot{z}^2 + mg z$$

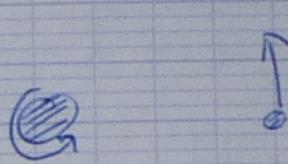
$$= \frac{1}{2} m (v_0 - gt)^2 + mg (z_0 + v_0 t - \frac{1}{2} gt^2)$$

$$= \frac{1}{2} m (v_0^2 + g^2 t^2 - 2v_0 gt) + mg (z_0 + v_0 t - \frac{1}{2} gt^2)$$

$$= \frac{1}{2} m v_0^2 + mg z_0$$

II Application : marées

Système Terre-Lune



$$E_C = \frac{1}{2} J_{\oplus} \omega_{\oplus}^2 + \frac{1}{2} J_{\odot} \omega_{\odot}^2 + \frac{1}{2} M_{\oplus} \left(\frac{M_{\odot}}{M_{\oplus} + M_{\odot}} D \right)^2 R^2$$

$$+ \frac{1}{2} M_{\odot} \left(\frac{M_{\oplus}}{M_{\oplus} + M_{\odot}} D \right)^2 R^2$$

Loi de Kepler

$$R = \sqrt{\frac{GM_{\oplus} + M_{\odot}}{D^3}}$$

$$\Rightarrow E_C = \frac{1}{2} J_{\oplus} \omega_{\oplus}^2 + \frac{1}{2} J_{\odot} \omega_{\odot}^2 + \frac{1}{2} \frac{M_{\odot} M_{\oplus}}{M_{\oplus} + M_{\odot}} D^2 \frac{GM_{\oplus} + M_{\odot}}{D^3}$$

$$E_C = \frac{1}{2} J_{\oplus} \omega_{\oplus}^2 + \frac{1}{2} J_{\odot} \omega_{\odot}^2 + \frac{1}{2} \frac{GM_{\oplus} M_{\odot}}{D}$$

$$L = E_C - E_P = \frac{1}{2} J_{\oplus} \omega_{\oplus}^2 + \frac{1}{2} J_{\odot} \omega_{\odot}^2 + \frac{3}{2} \frac{GM_{\oplus} M_{\odot}}{D}$$

$$\frac{\partial L}{\partial \theta} = 0 \Rightarrow \text{conservation du moment cinétique } L$$

$$\frac{\partial L}{\partial t} = 0 \Rightarrow \text{conservation de } H$$

$$H = \frac{1}{2} J_{\oplus} \omega_{\oplus}^2 + \frac{1}{2} J_{\odot} \omega_{\odot}^2 + \frac{1}{2} \frac{GM_{\oplus} M_{\odot}}{D}$$

$$L = J_{\oplus} \omega_{\oplus} + J_{\odot} \omega_{\odot} + \frac{M_{\oplus} M_{\odot}}{M_{\oplus} + M_{\odot}} D^2 R$$

$$L = J_{\oplus} \omega_{\oplus} + J_{\odot} \omega_{\odot} + M_{\oplus} M_{\odot} \sqrt{\frac{GD}{M_{\oplus} + M_{\odot}}}$$

On introduit les forces microscopiques

$$\mathcal{L}' = \mathcal{L} + \mathcal{L}_{\text{micro}}$$

$$\frac{d\mathcal{L}'}{dt} = 0 \quad (\text{les forces micro sont conservative})$$

→ Energie \mathcal{H} est conservée.

$$J = \gamma R^2 M$$

$$dU = 0 = T dS + dH$$

$$dH = -T dS \leq 0 \quad (\text{second principe})$$

$$J_{\oplus} = J_0 \frac{\gamma_0}{\gamma} \frac{R_0^2 M_0}{R^2 M_0}$$

$$\hookrightarrow \boxed{\frac{dH}{dt} \leq 0}$$

$$J_{\oplus} = J_0 \frac{\gamma_0}{\gamma} \frac{1}{1000}$$

$$H = \frac{1}{2} J_{\oplus} \omega_{\oplus}^2 + \frac{1}{2} J_{\oplus} \omega_{\oplus}^2 - \frac{1}{2} \frac{G m_{\oplus} m_{\odot}}{D} \quad \frac{dH}{dt} \leq 0$$

$$L = J_{\oplus} \omega_{\oplus}^2 + J_{\oplus} \omega_{\oplus}^2 + m_{\oplus} m_{\odot} \sqrt{\frac{G D}{m_{\oplus} m_{\odot}}} \quad \frac{dL}{dt} = 0$$

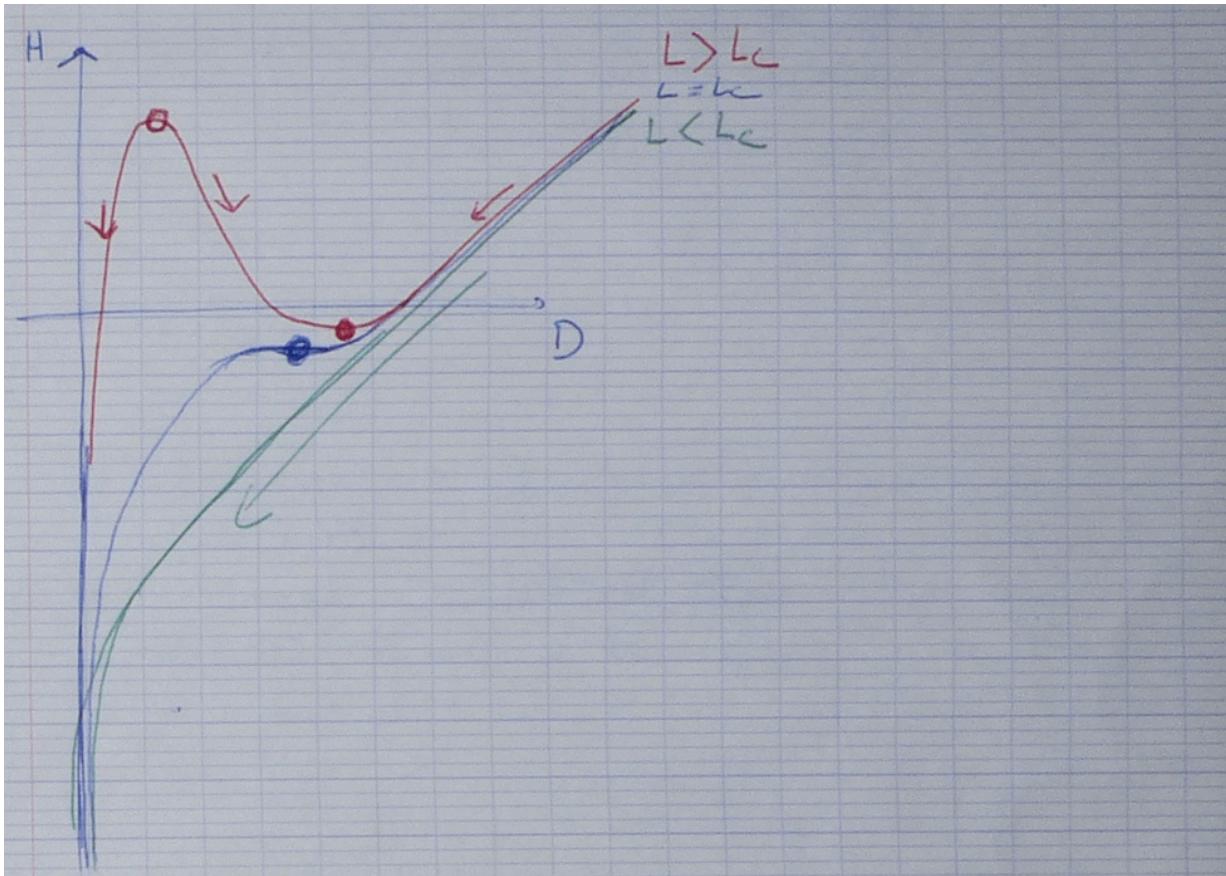
$$\omega_{\oplus} = \frac{L}{J_{\oplus}} - \frac{m_{\oplus} m_{\odot}}{J_{\oplus}} \sqrt{\frac{G D}{m_{\oplus} m_{\odot}}}$$

$$\rightarrow H = \frac{1}{2 J_{\oplus}} \left[L^2 + \frac{m_{\oplus}^2 m_{\odot}^2 G D}{m_{\oplus} + m_{\odot}} - 2 L m_{\oplus} m_{\odot} \sqrt{\frac{G D}{m_{\oplus} m_{\odot}}} \right] - \frac{1}{2} \frac{G m_{\oplus} m_{\odot}}{D}$$

$$\rightarrow \frac{dH}{dD} = \frac{m_{\oplus}^2 m_{\odot}^2 \cancel{L}}{2 J_{\oplus} (m_{\oplus} + m_{\odot})} - \frac{L m_{\oplus} m_{\odot}}{2 J_{\oplus}} \sqrt{\frac{G}{D(m_{\oplus} + m_{\odot})}} + \frac{G m_{\oplus} m_{\odot}}{2 D^2}$$

$$\frac{dH}{dD} = \frac{m_{\oplus} m_{\odot}}{L} \sqrt{\frac{G}{D(m_{\oplus} + m_{\odot})}} \left[\frac{m_{\oplus} m_{\odot}}{J_{\oplus}} \sqrt{\frac{G D}{D(m_{\oplus} + m_{\odot})}} - \frac{L}{J_{\oplus}} + \sqrt{\frac{G(m_{\oplus} + m_{\odot})}{D^3}} \right]$$

$$\boxed{\frac{dH}{dD} = \frac{m_{\oplus} m_{\odot}}{2} \sqrt{\frac{G}{D(m_{\oplus} + m_{\odot})}} (L - \omega_{\oplus})}$$

Application

$$\begin{aligned} n_c &= 0,0123 \text{ } n_{\oplus} & R_{\oplus} &= 0,3 \text{ } R_{\oplus}^L M_{\oplus} \\ R_{\oplus} &= 6378 \text{ km} & n_{\oplus} &= 5,975 \cdot 10^{-4} \text{ kg} \text{ ans}^{-1} \\ \bar{\omega}_{\oplus} &= 2301 \text{ rad/ans} & G &= 1,53 \cdot 10^3 \text{ } R_{\oplus}^3 n_{\oplus}^{-2} \text{ ans}^{-2} \\ \bar{D} &= 60,27 \text{ } R_{\oplus} & L &= 4403 \text{ } R_{\oplus}^2 \text{ ans}^{-1} \\ \cancel{2301 \cdot 5,975 \cdot 10^{-4}} & & \bar{n} &= 84,11 \text{ rad/ans} \end{aligned}$$

$$\frac{\bar{H}}{dD} = -68275 \text{ } n_{\oplus} R_{\oplus} \text{ ans}^{-2} = -2,61 \cdot 10^{22} \text{ J/m}$$

$$\frac{d\bar{D}}{dt} = 0,038 \text{ m/ans} \quad \frac{\bar{H}}{dt} = \frac{\bar{H}}{dD} \frac{dD}{dt} = -9,93 \cdot 10^{19} \text{ J/ans}$$

$$\boxed{\frac{d\bar{H}}{dt} = -3,15 \text{ TJ/s}}$$

Beaucoup ? Oui, mais non

$$\text{Activité humaine en 2020} = 18,5 \text{ TJ/s} \quad \text{USA} = 2,9 \text{ TW}$$

<u>Point d'équilibre</u> Point stable $D = 2,168 R_{\oplus}$	$\omega = 12329 \text{ rad/ans}$ $\hookrightarrow 1^{\circ} 62,2 \text{ jour/ans} \rightarrow \text{jour de } 4h28$
$D = 87,2 R_{\oplus}$	$\omega = 50,94 \text{ rad/ans}$ $\hookrightarrow 7,1 \text{ jour/ans} \rightarrow \text{jour de } 53d 9h22$ $(12334h22)$
<u>On estime le position initial de la Lune à $3,8 R_{\oplus}$</u> $\rightarrow \omega = 5313 \text{ rad/ans} \rightarrow 844,6 \text{ jours lune par ans.}$ Point instable \hookrightarrow Une toute l'yr 20h23 $\omega_{\oplus} = 16,70 \text{ rad/ans} \rightarrow 1840,4 \text{ jours/ans}$ $\hookrightarrow \text{jour de } 4h46$	
$\omega - \omega_{\oplus} = 6257$ $\omega = 5313$ $\omega = 6257 + 5313$	