cs123 INTRODUCTION TO COMPUTER GRAPHICS









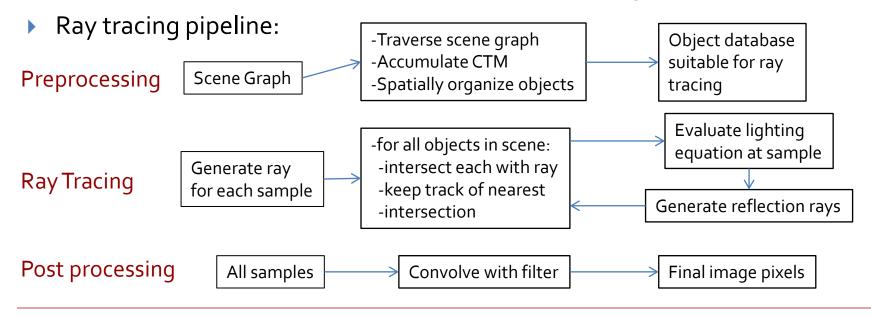


Polygon Rendering

Swapping the Loops

Review: Ray Tracing Pipeline

- Ray tracer produces visible samples of scene
- Samples are convolved with a filter to form pixel image



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Rendering Polygons

cs123

- Often need to render triangle meshes
- Ray tracing works well for implicitly defined surfaces
- Many existing models and modeling apps are based on polygon meshes can we render them by ray tracing the polygons?
 - ▶ Easy to do: ray-polygon intersection is a simple calculation
 - Very inefficient: It's common for an object, to have thousands of triangles, for a scene therefore hundreds of thousands or even millions of triangles – each needs to be considered in collision tests
- Traditional hardware pipeline is more efficient for many triangles:
 - Process the scene polygon by polygon, using "z-buffer" to determine visibility
 - Local illumination model
 - Use crude shading approximation to compute the color of most pixels

Traditional Fixed Function Pipeline (disappearing)

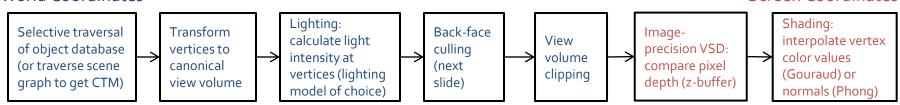
- Polygons (usually triangles) approximate the desired geometry
- One polygon at a time:
 - Each vertex is transformed into screen space, illumination model evaluated at each vertex. NO GLOBAL ILLUMINATION (except through ambient term hack)
 - One pixel of the polygon at a time:
 - Depth is compared against z-buffer; if the pixel is visible, color value is computed using either linear interpolation between vertex color values (Gouraud shading) or (better) a crude local lighting model for each pixel (e.g., Phong shading)

Geometry Processing

World Coordinates

Rendering/Pixel Processing

Screen Coordinates



Visible Surface Determination

Back face culling:

- We often don't need to render triangles "facing away" from us
- We know that the triangle's vertices are listed in a particular order (usually counter clockwise, by convention)
- If screen space vertex positions aren't in counter clockwise order, the camera is facing the back of the triangle and the triangle can be skipped

View volume clipping:

- If a triangle lies entirely outside of the view volume, it does not need to be rendered because it can't be seen
- Some special cases requiring polygon clipping: large triangles, triangles near edges of the view volume (i.e., triangles that intersect or overlap faces of the view volume.) Analogous to 2D case where we cannot trivially accept or reject using simple outcode tests comparing vertex coordinates against clip bounds
- Occlusion culling, triangles that are behind other opaque triangles don't need to be rendered

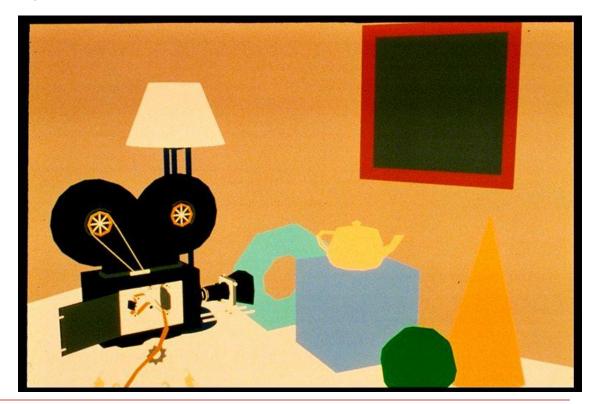
Programmable Shader Based Pipeline

- To allow the programmer to fine tune and optimize rendering, various stages of the pipeline are customizable
- You've played with shaders in lab
- Shaders are fast! Using shaders even all of the more advanced techniques mentioned in this lecture can be done in real time.
- Physical phenomena such as shadows (slides 18, 19) and light refraction can be emulated using shaders.

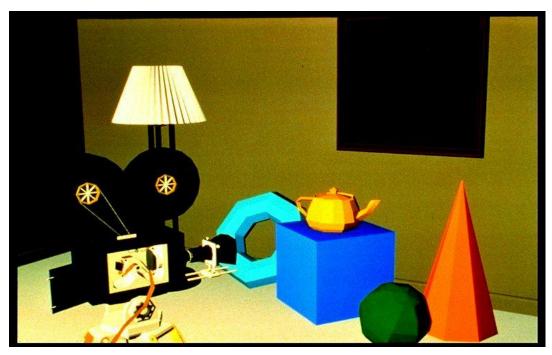


The image on the right is rendered with a custom shader. Note that only the right image has realistic shadows. A normal map is also used to add detail to the model.

Constant shading: no interpolation, pick a single representative intensity and propagate it over entire object. Loses almost all depth cues.

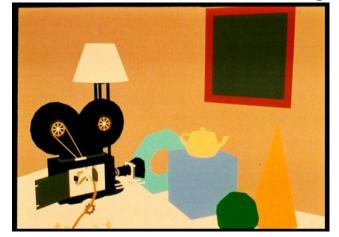


Pixar "Shutterbug" images from: www.siggraph.org/education/materials/HyperGraph /scanline/shade_models/shading.htm



Flat or Faceted Shading: constant intensity over each face



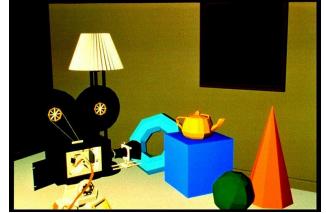


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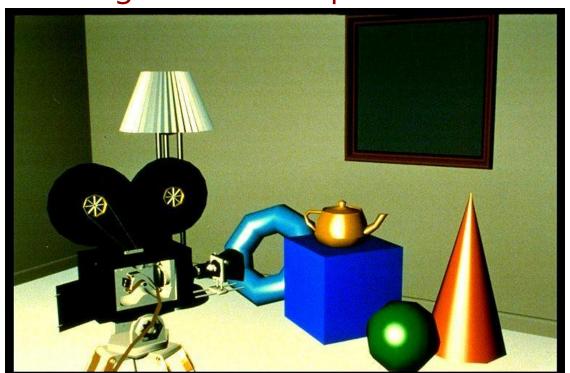


Gouraud Shading: Linear Interpolation of intensity across triangles to eliminate edge discontinuity

Flat Shading



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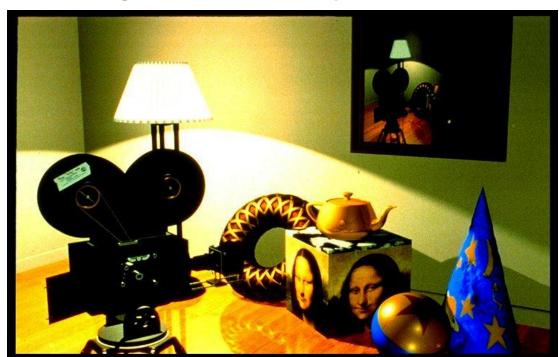


Phong Shading: Interpolation of vertex surface normals

Note: specular highlights but no shadows. Still a pure local illumination model

Gouraud Shading





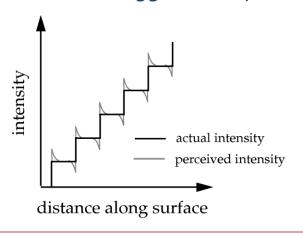
Global Illumination: Objects enhanced using shadow, texture, bump, and reflection mapping (see S20)

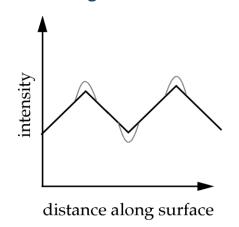
Phong Shading

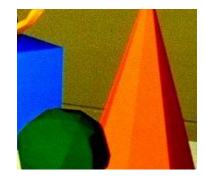


Shading Models (1/6: Faceted)

- Faceted Shading:
 - Single illumination value per polygon
 - With many polygons approximating a curved surface, this creates an undesirable faceted look.
 - Facets exaggerated by "Mach banding" effect



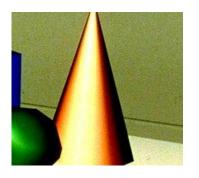


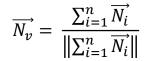


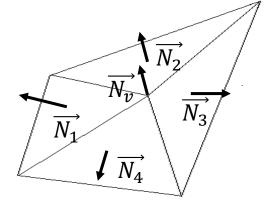
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Shading Models (2/6: Gouraud)

- Illumination intensity interpolation
 - Illumination values are computed at vertices, linearly interpolated across the pixels of the polygon
 - Eliminates intensity discontinuities at polygon edges; still have gradient discontinuities.
 - Mach banding is largely ameliorated, not eliminated
 - Must differentiate desired creases from tesselation artifacts (edges of cube vs. edges on tesselated sphere)
 - Step 1: Compute vertex normals by averaging surrounding polygon normals

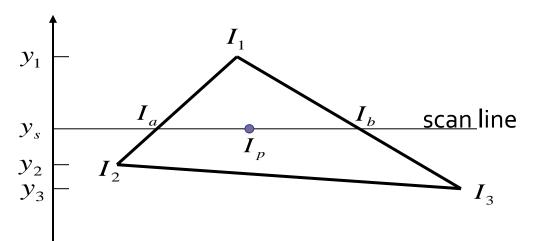






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- Step 2: Evaluate illumination at each vertex using lighting model (I_1, I_2, I_3)
- Step 3: Interpolate illumination along polygon edges (I_a, I_b)
- Step 4: Interpolate illumination along scan lines (I_p)



$$I_{a} = I_{1} \frac{y_{s} - y_{2}}{y_{1} - y_{2}} + I_{2} \frac{y_{1} - y_{s}}{y_{1} - y_{2}}$$
scan line
$$I_{b} = I_{1} \frac{y_{s} - y_{3}}{y_{1} - y_{3}} + I_{3} \frac{y_{1} - y_{s}}{y_{1} - y_{3}}$$

$$I_{p} = I_{a} \frac{x_{b} - x_{p}}{x_{b} - x_{a}} + I_{b} \frac{x_{p} - x_{a}}{x_{b} - x_{a}}$$

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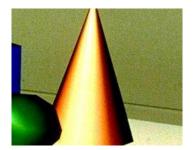
Shading Models (4/6: Gouraud cont.)

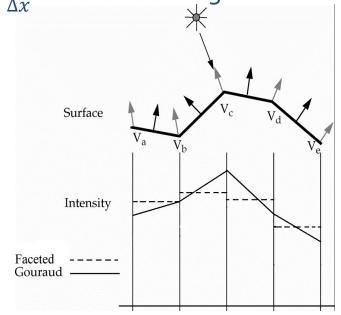
Takes advantage of scan line algorithm for efficiency

 $ightharpoonup rac{\Delta I}{\Delta y}$ is constant along polygon edge, $rac{\Delta I}{\Delta x}$ is constant along scan line

Gouraud vs. Faceted shading:







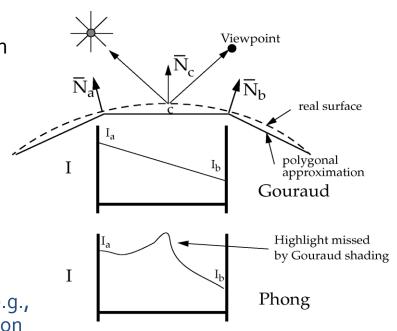
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Shading Models (5/6: Gouraud cont.)

- Gouraud shading can miss specular highlights because it interpolates vertex colors instead of calculating intensity directly at each point, or even interpolating vertex normals (Phong shading)
- N_a and N_b would cause no appreciable specular component, whereas N_c would. Interpolating between I_a and I_b misses the highlight that evaluating I at c would catch

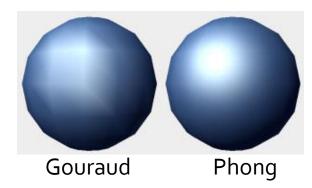
Phong shading:

- Interpolated normal comes close to the actual normal of the true curved surface at a given point
- Reduces temporal "jumping" affect of highlight, e.g., when rotating sphere during animation (example on next slide)

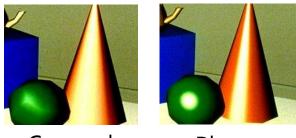


Shading Models (6/6: Phong Shading)

- Phong Model: normal vector interpolation
- Interpolate N rather than I
- Always captures specular highlights, but computationally expensive
 - At each pixel, N is recomputed and normalized (requires sq. root operation)
 - Then I is computed at each pixel (lighting model is more expensive than interpolation algorithms)
- This is now implemented in hardware, very fast
- Looks much better than Gouraud, but still no global effects



http://www.cgchannel.com/2010/11/cg-science-for-artists-part-2-the-real-time-rendering-pipeline/



Gouraud

Phong

http://en.wikipedia.org/wiki/Gourad_shading

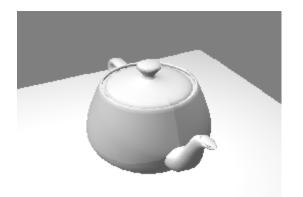
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Shadows (1/5) – Simplest Hack

- Render each object twice
 - First pass: render normally
 - Second pass: use transformations to compress object onto ground plane, render completely black
- Pros: Easy, can be convincing. Eye more sensitive to presence of shadow than shadow's exact shape
- Cons: Becomes complex computational geometry problem in anything but simplest case
 - Easy: projecting onto flat, infinite ground plane
 - How to implement for stairs? Rolling hills?



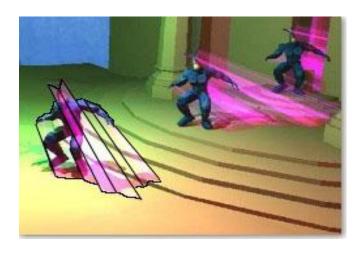


http://web.cs.wpi.edu/~matt/courses/cs563/t alks/shadow/shadow.html

Shadows (2/5) – More Advanced

For each light L
 For each point P in scene
 If P is in shadow cast by L
 Only use indirect lighting
 (ambient term for Phong lighting)
 Else
 Evaluate full lighting model
 (ambient, diffuse, specular for Phong)

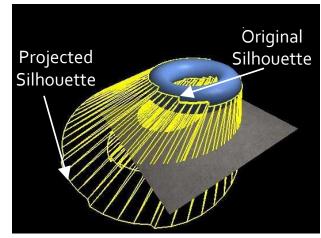
Next up: different methods for computing whether P is in shadow cast by L



Stencil shadow volumes implemented by former cs123 ta and recent Ph.D. Kevin Egan and former PhD student and book coauthor Prof. Morgan McGuire, on nVidia chip

Shadows (3/5) – Shadow Volumes

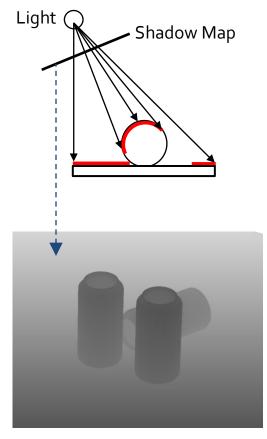
- For each light + object pair, compute mesh enclosing area where object occludes the light
 - Find silhouette: every edge shared by two triangles, such that one triangle faces light source and other faces away
 - ▶ On torus, where angle between N and L becomes > 90°
 - Project silhouette along light rays
 - Generate triangles bridging silhouette and projection
- A point P is in shadow from light L if
 - ▶ ∃ shadow volume *V* computed for *L* such that *P* is inside *V*
 - Can determine quickly using stencil buffer
 - Combined technique called 'Stencil Shadow Volumes'
 - More on Stencil Buffers, Stencil Shadow Volumes



Example shadow volume (yellow mesh)

Shadows (4/5) – Shadow Maps

- Render scene from point of view of light, saving depths instead of colors per pixel
 - Depth: world-space distance from light source to object under that pixel
 - Result: 2D image called a "shadow map"
- ▶ To determine if point *P* on object is in shadow
 - \blacktriangleright Compute distance d_P from P to light source
 - Look up min distance d_{min} in shadow map
 - Find pixel (depth value d_{min}) where line from P to L passes through shadow map
 - P in shadow if $d_P > d_{min}$



Visualization of Shadow Map

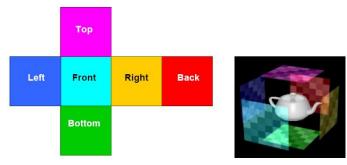
Shadows (5/5) – Shadow Map Tradeoffs

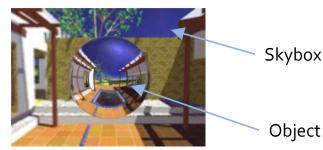
- Pro: Can extend to support soft shadows
 - Stencil shadow volumes only useful for hard-edged shadows
- Con: Naïve implementation has impressively bad aliasing problems
 - Many screen pixels covered by projection of one shadow map pixel
 - Doesn't make sense to filter shadow map (interpolating depth samples)
- Many workarounds for aliasing issues
 - <u>Percentage-Closer Filtering</u>: box blur by sampling shadow map in multiple places
 - <u>Cascaded Shadow Maps</u>: multiple shadow maps, denser resolution closer to viewer
 - Variance Shadow Maps: use statistical modeling instead of simple depth comparison



Environment Mapping (for Shiny Objects) (1/2)

- Approximate reflections by only reflecting skybox
 - ▶ Skybox a.k.a. environment map a.k.a. reflection map
- Environment map encloses 3D space
 - e.g. six faces of a cube surrounding scene
- ▶ To sample at point *P*
 - Compute direction vector E from P to eye
 - Reflect E about normal to obtain R
 - From center of environment map, move in direction of *R* until finding a sample
 - Treat P as being in the center of map; equivalently, treat environment map as being infinitely large





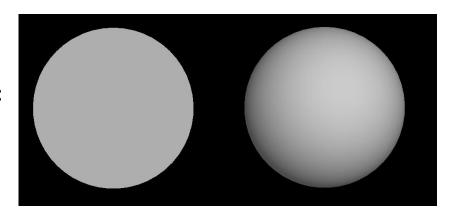
Environment Mapping (2/2)

- Non-trivial to reflect other objects in the scene
 - Achieved by rendering the entire scene, and storing results into faces of the environment map
 - Can do this offline for static geometry, but must generate at runtime for moving objects
 - Rendering environment map at runtime is expensive
- Not limited to six-sided textured skyboxes
 - e.g. can use a single 2D map 'unwrapped' from surface of a sphere. Choose sample points by calculating longitude and latitude
 - See "Texture Mapping of Sphere" in Texture Mapping lecture



Overview: Surface Detail

These spheres have same geometry:



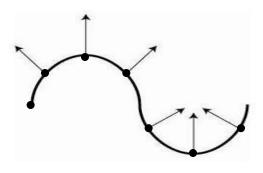
Observation

- What if we replaced the 3D sphere on the right with a 2D circle?
- ▶ The circle would have fewer triangles (thus renders faster)
- If we kept the sphere's normals, the circle would still look like a sphere!
- Works because human visual system infers shape from patterns of light and dark regions ("shape from shading"). Lightness at any point is determined by normal vector, not by actual geometry of model.

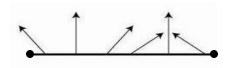
Idea: Surface Detail

- Start with a hi-poly model
- Decimate the mesh (remove triangles)
- Encode hi-poly normal information into texture
- Map texture onto lo-poly mesh
- Use fragment shader to look up normal for each pixel
- Use Phong shading to calculate pixel color
 - Replace N with value computed from texture

Next: how to encode normals in texture?



Original hi-poly model



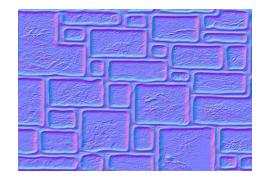
Lo-poly model with hi-poly model's normals preserved

Normal Mapping

- Easiest to render, hardest to produce
 - Usually need specialized modeling tools like Pixologic's ZBrush
- Idea: Fill a texture with normals
 - Fragment shader samples 2D color texture
 - Interprets R as N_X , G as N_Y , B as N_Z
 - ▶ Uses *N* to do light calculations
- Variants
 - Object-space: encodes normal itself
 - Tangent-space: encodes normal relative to object's original normal



Object-space normal map



Tangent-space normal map

Normal Mapping Example



Render showing simple underlying geometry

Normal map gives model finer detail

Normal mapping can completely alter the perceived geometry of a model

Normal Mapping Video

http://www.youtube.com/watch?v=RSmjxcAhkfE

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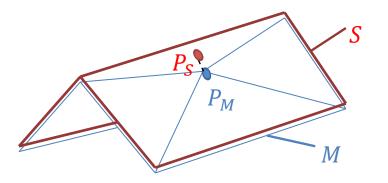
Aside: Creating Normal Maps

Automated

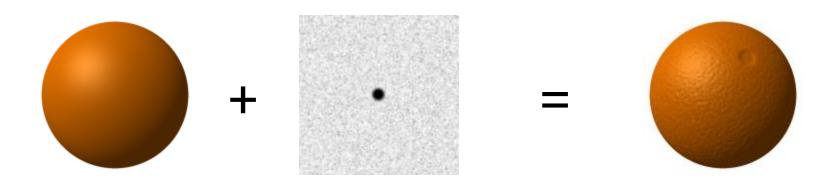
- Original mesh M simplified to mesh S
- Normal map texture coords assigned to S
- For each pixel in normal map
 - Find corresponding point on $S: P_S$
 - Find closest point on original mesh: P_M
 - Average nearby normals in M and save value in normal map

Manual

- Artist starts with S
- Uses specialized tools to draw directly onto normal map ('sculpting')



Bump Mapping: Example



Original object (plain sphere)

Bump map (height map)

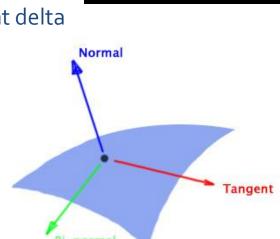
Sphere with bump-mapped normals

http://cse.csusb.edu/tong/courses/cs520/notes/texture.php

Height map

Bump Mapping

- Idea: instead of encoding normals themselves, encode relative heights
 - Black: minimum height delta, White: maximum height delta
 - Much easier to create than normal maps
- Use height deltas to perturb the normal
- To sample bump map
 - Collect several height samples from texture
 - Approximate gradient using height samples
 - Transform from tangent space to object space
 - Tangent space: XYZ system, where Z is aligned with the original normal



Tangent Space (using left-handed coordinate system)
http://jahovaos.com/groups/kb/wiki/19ed6/Relief_Mapping_Normal_Mapping.html

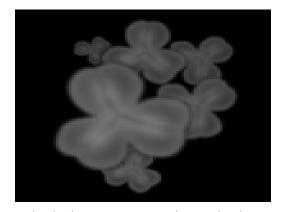
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Other Techniques: Displacement Mapping

- Move vertices along normals by looking up height deltas in a height map
- Doesn't provide extra detail like normal/bump mapping
- Useful for animating surfaces



http://www.creativemac.com/2004/02_feb/tutorials/koc4ddisplace040224.htm



The displacement map used to render the scene. The intensity value indicates the height at a given point.

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Other Techniques: Parallax Mapping

- Extension to normal mapping
- Distorts texture coordinates right before sampling, as a function of normal and eye vector
 - Example image on right: looking down at bricks from above
 - Texture coordinates stretched near top of brick, where you should be able to 'see' the top of the brick
 - Similarly, texture coordinates compressed near bottom of brick, where you shouldn't be able to 'see' the underside of the brick



Texture Mapped

Texture and Parallax Mapped

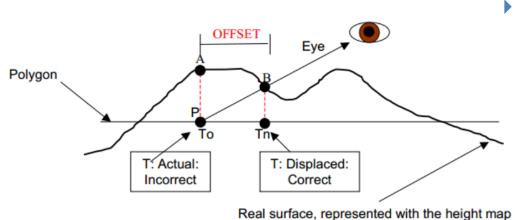
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Other Techniques: Parallax Mapping

- Actually rendering point P, with texture coords T_0
- Pretending to render B, with texture coords T_n
- Compute T_n by tracing the Eye ray a short distance, then drop the vertical component (Z component in tangent space). Add result to T_0 .

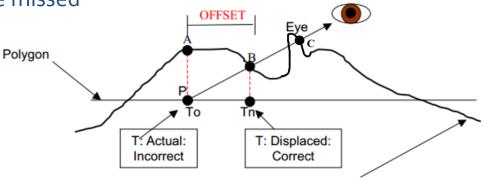


How far should we trace Eye ray? Approximate!

- $t = h \times s + b$
- h: height-map height at P
- s: arbitrarily chosen scale factor
- b: arbitrarily chosen bias
- Then $T_n = T_0 + (t \times Eye)_{xy}$

Other Techniques: Steep Parallax Mapping

- Extension on Parallax Mapping
 - Uses ray-marching to intersect ray with parts of heightmap parallax mapping might have missed



Real surface, represented with the height map

- Adds support for self-shadowing
- Invented by Brown PhD 'o6 Morgan McGuire and Max McGuire

Comparison



Texture Mapped

Creases between bricks look flat



Normal Mapped

Creases look progressively deeper



Parallax Mapped



Steep Parallax Mapped

Objects have self-shadowing

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