

XRootD Client Configuration & API Reference

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1 Introduction

This document describes the client (XrdCl) component of XRootD framework. In particular it focuses on configuration options of the client (configuration file, environment variables, parameters) and on how they interact with each other.

XrdCl is a multi-threaded C++ implementation of XRootD client based on an event-loop, and is provided by the libXrdCl library. The standard C++ API is documented here and is out of the scope of this document. The XrdCl implementation is fully asynchronous (all the synchronous calls have been implemented in terms of their asynchronous counterparts). All issued requests are queued and sequentially processed by a single-threaded $socket\ event$ -loop (however in order to increase performance it is possible to employ more than one event-loop). Also, all incoming responses are processed by the event-loop, however all the response handlers are executed in a thread-pool. The behavior of XrdCl: can be tuned using a configuration file, environment variables or XrdCl::DefaultEnv utility.

Low level connection handling is hidden from the user. Once a request is issued a connection between the client and the server will be established automatically, the connection will be kept alive for further reuse until TTL timeout elapses. By default XrdCl is multiplexing all request through a single physical connection, however it is possible to force the component to use multiple physical connections (up to 16) in order to increase the performance over WAN networks. It is also possible to force XrdCl to disconnect from a server (e.g. in order to reestablish the connection with a new credential). When the connection between client and server is being established the server may request the client to authenticate (if so, the server will send a list of acceptable authentication methods, e.g. krb5, qsi, etc.).

The **XrdCl** library is the base for following components: the command line interface (*xrdcp* and *xrdfs*), python bindings, SSI client and the Posix API.

In addition, this document, in the last section, describes the new declarative client API introduced in **version 4.9.0**.

2 Configuration File

This section describes the XRootD client configuration file. By default XRootD client will use the global config file: /ets/xrootd/client.conf. However, those settings migh be overwritten by the user specific config file: $\sim/.xrootd/client.conf$ and Environment Variables. For the complete list of configurable parameters please consult the Index of Environment Variables.

XRootD client supports protocol- and endpoint-level plug-ins. By convention a single config file is expected per plug-in, as they are discovered and configured by scanning configuration files. The plug-in manager will search for configuration files in:

• /etc/xrootd/client.plugins.d/,

- ~/.xrootd/client.plugins.d/,
- and at a location pointed to by: XRD_PLUGINCONFDIR

An XRootD client plug-in configuration file should a contain following key-value pairs:

- **url** followed by list of endpoints (by default root protocol is assumed) or protocols
- lib followed by a path to the library implementing given plug-in
- enable followed by true or false

For example the following config file defines a plug-in for *host.domain.edu* endpoint (root protocol is being assumed) and *http* protocol:

```
url = host.domain.edu; http://*
lib = /usr/lib64/libAwsomePlugIn.so
enabled = true
```

3 Command line tools (xrdcp/xrdfs)

3.1 xrdcp - copy files

xrdcp [options] source destination

DESCRIPTION

The **xrdcp** utility copies one or more files from one location to another. The data source and destination may be a local or remote file or directory. Additionally, the data source may also reside on multiple servers.

OPTIONS

-C | --cksum type [:value | print | source]

Obtains the checksum of type (i.e. adler32, crc32, or md5) from the source, computes the checksum at the destination, and verifies that they are the same. If a <u>value</u> is specified, it is used as the source checksum. When <u>print</u> is specified, the checksum at the destination is printed but is <u>not</u> verified.

```
-d | --debug \underline{lvl}
Debug level: 1 (low), 2 (medium), 3 (high).
```

-F | --coerce

Ignores locking semantics on the destination file. This option may lead to file corruption if not properly used.

-f | --force

Re-creates a file if it is already present.

-h | --help

Displays usage information.

-H | --license

Displays license terms and conditions.

-N | --nopbar

Does not display the progress bar.

-P | --posc

Requests POSC (persist-on-successful-close) processing to create a new file. Files are automatically deleted should they not be successfully closed.

-D | --proxy proxyaddr:proxyport [NOT YET IMPLEMENTED]

Use <u>proxyaddr:proxyport</u> as a SOCKS4 proxy. Only numerical addresses are supported.

-r | --recursive

Recursively copy all files starting at the given source directory.

--server

Runs as if in a server environment. Used only for server-side third party copy support.

-s | --silent

Neither produces summary information nor displays the progress bar.

-y | --sources <u>num</u>

Uses up to num sources to copy the file.

-S | --streams num

Uses <u>num</u> additional parallel streams to do the transfer. The maximum value is 15. The default is 0 (i.e., use only the main stream).

--tpc [delegate] first | only

Copies the file from remote server to remote server using third-party-copy protocol (i.e., data flows from server to server). The source and destination servers must support third party copies. Additional security restrictions may apply and may cause the copy to fail if they cannot be satisfied. Argument 'first' tries tpc and if it fails, does a normal copy; while 'only' fails the copy unless tpc succeeds. When 'delegate' is specified, the copy delegates the command issuer's credentials to the target server which uses those credentials to authenticate with the source server. Delegation is ignored if the target server is not configured to

use delegated credentials. Currently, only gsi credentials can be delegated.

-v | --verbose

Displays summary output.

$-V \mid --version$

Displays version information and immediately exits.

-z | **--zip** <u>file</u>

Copy given file from a ZIP archive (same as xrdcl.unzip opaque info).

-X | **--xrate** rate NOT YET IMPLEMENTED]

Limits the copy speed to the specified <u>rate</u>. The rate may be qualified with the letter \mathbf{k} , \mathbf{m} , or \mathbf{g} to indicate kilo, mega, or giga bytes, respectively. The option only applies when the source or destination is local.

-Z | --dynamic-src

File size may change during the copy.

-I \mid --infiles $\underline{\mathrm{fn}}$

Specifies the file that contains a list of input files.

-p | --path

Automatically create remote destination path.

--parallel n

Number of copy jobs to be run simultaneously.

--allow-http

Allow HTTP as source or destination protocol. Requires the XrdClHttp client plugin.

LEGACY OPTIONS

Legacy options are provided for backward compatability. These are now deprecated and should be avoided.

-adler

Equivalent to "-cksum adler32:source".

-DI pname numberval

Set the internal parameter pname with the numeric value numberval.

-DS pname stringval

Set the internal parameter pname with the string value stringval.

-md5

Equivalent to "-cksum md5:source".

-np

Equivalent to "-nopbar".

-OD cgi

Add cgi information <u>cgi</u> to any destination xrootd URL. You should specify the opaque information <u>directly</u> on the destination URL.

-OS cgi

Add cgi information cgi to any source xrootd URL.

-x

Equivalent to "-sources 12".

OPERANDS

<u>source</u>: a dash (i.e. -) indicating stanard in, a local file, a local directory name suffixed by /, or an xrootd URL in the form of:

xroot:// [user@] host [:port] /absolutepath

The absolute path can be a directory.

<u>destination</u>: a dash (i.e. -) indicating stanard out, a local file, a local directory name suffixed by /, or an xrootd URL in the form:

xroot:// [user@] host [:port] /absolutepath

The absolute path can be a directory.

3.2 xrdfs - xrootd file and directory meta-data utility

xrdfs [-no-cwd] host[:port] [command [args]]

DESCRIPTION

The **xrdfs** utility executes meta-data oriented operations (e.g., ls, mv, rm, etc.) on one or more xrootd servers. Command help is available by invoking xrdfs with no command line options or parameters and then typing "help" in response to the input prompt.

OPTIONS

-no-cwd

No CWD is being preset in interactive mode.

COMMANDS

```
chmod path <user><group><other>
Modify permissions of the path. Permission string example: rwxr-x-x
ls [\underline{-l}] [\underline{-u}] [\underline{-R}] [\underline{dirname}]
Get directory listing.
   -1 stat every entry and pring long listing
   <u>-u</u> print paths as URLs
   -R list subdirectories recursively
   -D show duplicate entries
locate [-n] [-r] [-d] <path>
Get the locations of the path.
   -r refresh, don't use cached locations
   -n make the server return the response immediately (it may be incomplete)
   <u>-d</u> do a recursive, deep locate in order to find data servers
   -m prefer host names to IP addresses
   <u>-i</u> ignore network dependencies (IPv6/IPv4)
mkdir [-p] [-m<user><group><other>] <dirname>
Creates a directory/tree of directories.
   -p create the entire directory tree recursively
   -m<user><group><other> permissions for newly created directories
\mathbf{mv} < \text{path} 1 > < \text{path} 2 >
Move path1 to path2 locally on the same server.
stat <path>
Get info about the file or directory.
   -q query optional flag query parameter that makes xrdfs return error code
   to the shell if the requested flag combination is not present; flags may be
   combined together using '|' or '&' Available flags: XBitSet, IsDir, Other,
   Offline, POSCPending, IsReadable, IsWriteable
```

statvfs <path>

Get info about a virtual file system.

query <code> <params>

Obtain server information. Query codes:

config <what> Server configuration; <what> is one of the following:

- bind_max the maximum number of parallel streams
- chksum the supported checksum
- pio_max maximum number of parallel I/O requests

- readv_ior_max maximum size of a readv element
- readv_iov_max maximum number of readv entries
- tpc support for third party copies
- wan_port the port to use for wan copies
- wan_window the wan_port window size
- window the tcp window size
- cms the status of the cmsd
- role the role in a cluster
- sitename the site name
- version the version of the server

checksumcancel <path> File checksum cancelation

checksum <path>File checksum

opaque <arg> Implementation dependent

opaquefile <arg> Implementation dependent

space <space> Logical space stats

<u>stats</u> < **what**> Server stats; < what> is a list of letters indicating information to be returned:

- \bullet a all statistics
- p protocol statistics
- b buffer usage statistics
- s scheduling statistics
- d device polling statistics
- u usage statistics
- i server identification
- z synchronized statistics
- ullet l connection statistics

<u>xattr</u> <**path**> Extended attributes

 $\mathbf{rm} < \! \mathrm{filename} \! >$

Remove a file.

rmdir <dirname>

Remove a directory.

$\mathbf{truncate} \leq \underline{\mathsf{filename}} \leq \mathsf{length} >$

Truncate a file.

prepare [-c] [-f] [-s] [-w] [-p priority] filenames

Prepare one or more files for access.

- -c co-locate staged files if possible
- -f refresh file access time even if the location is known
- -s stage the files to disk if they are not online
- -w whe files will be accessed for modification
- -p priority of the request, 0 (lowest) 3 (highest)

cat [-o localfile] file

Print contents of a file to stdout

-o print to the specified local file

tail [-c bytes] [-f] file

Output last part of files to stdout.

-c num_bytes out last num_bytes -f output appended data as file grows

spaceinfo path

Get space statistics for given path.

3.3 Return Codes

- 0 : success
- 50: generic error (e.g. config, internal, data, OS, command line option)
- \bullet **51**: socket related error
- 52 : postmaster related error
- 53 : XRootD related error
- **54** : redirection error
- 55 : query response was negative (this is not an error)

4 Environment Variables

This section describes XRootD client environment variables. The following list of environment variables applies to xrdcp, xrdfs any other application using the libXrdCl library, unless specified otherwise.

4.1 Categories

Limits/Performance:	
XRD_PARALLELEVTLOOP	
• XRD_REDIRECTLIMIT	
• XRD_SUBSTREAMSPERCHANNEL	
• XRD_WORKERTHREADS	
Logging:	
XRD_LOGLEVEL	
• XRD_LOGFILE	
• XRD_LOGMASK	
Metalinks:	
XRD_METALINKPROCESSING	
XRD_LOCALMETALINKFILE	
XRD_GLFNREDIRECTOR	
• XRD_MAXMETALINKWAIT	
Monitoring:	
XRD_APPNAME	
XRD_CLIENTMONITOR	
XRD_CLIENTMONITORPARAM	
Networking:	
XRD_NETWORKSTACK	
• XRD_PREFERIPV4	
Plug-in:	
XRD_PLUGIN	
XRD_PLUGINCONFDIR	
- Mai Book oon biit	

Recovery:	
	XRD_CONNECTIONRETRY
	XRD_OPENRECOVERY
	XRD_READRECOVERY
	XRD_WRITERECOVERY
	XRD_STREAMERRORWINDOW
TCP:	
101.	XRD_NODELAY
	XRD_TCPKEEPALIVE
	XRD_TCPKEEPALIVEINTERVAL VPD_TCPKEEPALIVEINTERVAL
	XRD_TCPKEEPALIVEPROBES
	XRD_TCPKEEPALIVETIME
Timeouts:	
	XRD_CONNECTIONWINDOW
	• XRD_REQUESTTIMEOUT
	• XRD_STREAMTIMEOUT
	XRD_DATASERVERTTL
	XRD_LOADBALANCERTTL
	• XRD_TIMEOUTRESOLUTION
XrCl::CopyProcess / xrdcp:	
Arcicopyrrocess / Ardep.	XRD_CPCHUNKSIZE
	XRD_CPINITTIMEOUT
	XRD_CFTRCTIMEOUT
	XRD_CPPARALLELCHUNKS
	XRD_XCPBLOCKSIZE
Others:	
	XRD_POLLERPREFERENCE
	XRD_RUNFORKHANDLER

4.2 Index of Environment Variables

4.2.1 XRD_APPNAME

Override the application name reported to the server.

Default: disabled

4.2.2 XRD_CLIENTMONITOR

Path to the client monitor library.

Default: disabled

4.2.3 XRD_CLIENTMONITORPARAM

Additional optional parameters that will be passed to the monitoring object on initialization.

Default: disabled

4.2.4 XRD_CONNECTIONWINDOW

A time window for the connection establishment. A connection failure is declared if the connection is not established within the time window. If a connection failure happens earlier then another connection attempt will only be made at the beginning of the next window.

Default: 120 (seconds)

4.2.5 XRD_CONNECTIONRETRY

Number of connection attempts that should be made (number of available connection windows) before declaring a permanent failure.

Default: 5

4.2.6 XRD_CPCHUNKSIZE

Size of a single data chunk handled by xrdcp / XrdCl::CopyProcess.

Default: 16KiB

4.2.7 XRD_CPINITTIMEOUT

Maximum time allowed for the copy process to initialize, ie. open the source and destination files.

Default: 600 (seconds)

4.2.8 XRD_CPPARALLELCHUNKS

Maximum number of asynchronous requests being processed by the xrdcp / XrdCl::CopyProcess command at any given time.

Default: 4

4.2.9 XRD_CPTPCTIMEOUT

Maximum time allowed for a third-party copy operation to finish.

Default: 1800 (seconds)

4.2.10 XRD_DATASERVERTTL

Time period after which an idle connection to a data server should be closed.

Default: 300 (seconds)

4.2.11 XRD_GLFNREDIRECTOR

The redirector will be used as a last resort if the GLFN tag is specified in a Metalink file.

Default: none

4.2.12 XRD_LOADBALANCERTTL

Time period after which an idle connection to a manager or a load balancer should be closed.

Default: 1200 (seconds)

4.2.13 XRD_LOCALMETALINKFILE

Enable/Disable local Metalink file processing (by convention the following URL schema has to be used: root://localfile//path/filename.meta4) The localfile semantic is now deprecated, use file://localhost/path/filename.meta4 instead!

Default: 0

4.2.14 XRD_LOGFILE

If set, the diagnostics will be printed to the specified file instead of stderr.

Default: disabled

4.2.15 XRD_LOGLEVEL

Determines the amount of diagnostics that should be printed. Valid values are: Dump, Debug, Info, Warning, and Error.

Default: disabled

4.2.16 XRD_LOGMASK

Determines which diagnostics topics should be printed at all levels. It's a "|" separated list of topics. The first element may be "All" in which case all the topics are enabled and the subsequent elements may turn them off, or "None" in which case all the topics are disabled and the subsequent flags may turn them on. If the topic name is prefixed with "^", then it means that the topic should

be disabled. If the topic name is not prefixed, then it means that the topic should be enabled.

The log mask may as well be handled for each diagnostic level separately by setting one or more of the following variables: XRD_LOGMASK_ERROR, XRD_LOGMASK_WARNING, XRD_LOGMASK_INFO, XRD_LOGMASK_DEBUG, and XRD_LOGMASK_DUMP.

Available topics: AppMsg, UtilityMsg, FileMsg, PollerMsg, PostMasterMsg, XRootDTransportMsg, TaskMgrMsg, XRootDMsg, FileSystemMsg, AsyncSock-Msg

Default: The default for each level is "All", except for the <u>Dump</u> level, where the default is "All| ^PollerMsg". This means that, at the <u>Dump</u> level, all the topics but "PollerMsg" are enabled.

4.2.17 XRD_MAXMETALINKWAIT

The maximum time in seconds a client can be stalled by the server if a Metalink redirector is available.

Default: 60 (seconds)

4.2.18 XRD_METALINKPROCESSING

Enable/Disable Metalink processing.

Default: 1

4.2.19 XRD_NETWORKSTACK

The network stack that the client should use to connect to the server. Possible values are:

- IPAuto automatically detect which IP stack to use
- **IPAll** use IPv6 stack (AF_INET6 sockets) and both IPv6 and IPv4 (mapped to IPv6) addresses
- \bullet IPv6 use only IPv6 stack and addresses
- IPv4 use only IPv4 stack (AF_INET sockets) and addresses
- $\bullet~ \mathbf{IPv4Mapped6}$ use $\mathbf{IPv6}$ stack and mapped $\mathbf{IPv4}$ addresses

Default: IPAuto

4.2.20 XRD_NODELAY

Disables the Nagle algorithm if set to 1 (default), enables it if set to 0.

Default: 1

4.2.21 XRD_OPENRECOVERY

Determines if open recovery should be enabled or disabled for mutable (truncate or create) opens.

Default: true

4.2.22 XRD_PARALLELEVTLOOP

The number of event loops.

Default: 1

4.2.23 XRD_PLUGIN

A default client plug-in to be used.

Default: none

4.2.24 XRD_PLUGINCONFDIR

A custom location containing client plug-in config files.

Default: none

4.2.25 XRD_POLLERPREFERENCE

A comma separated list of poller implementations in order of preference.

Default: built-in

4.2.26 XRD_PREFERIPV4

If set the client tries first IPv4 address (turned off by default).

Default: 0

4.2.27 XRD_READRECOVERY

Determines if read recovery should be enabled or disabled.

Default: true

4.2.28 XRD_REDIRECTLIMIT

Maximum number of allowed redirections.

Default: 16

4.2.29 XRD_REQUESTTIMEOUT

Default value for the time after which an error is declared if it was impossible to get a response to a request.

Default: 1800 (seconds)

4.2.30 XRD_RUNFORKHANDLER

Determines whether the fork handlers should be enabled, making the API fork safe.

Default: 0

4.2.31 XRD_STREAMERRORWINDOW

Time after which the permanent failure flags are cleared out and a new connection may be attempted if needed.

Default: 1800

4.2.32 XRD_STREAMTIMEOUT

Default value for the time after which a connection error is declared (and a recovery attempted) if there are unfulfilled requests and there is no socket activity or a registered wait timeout.

Default: 60 (seconds)

4.2.33 XRD_SUBSTREAMSPERCHANNEL

Number of streams per session.

Default: 1

4.2.34 XRD_TCPKEEPALIVE

Enable/Disable the TCP keep alive functionality.

Default: 0

4.2.35 XRD_TCPKEEPALIVEINTERVAL

Interval between subsequent keepalive probes (Linux only).

Default: 75

4.2.36 XRD_TCPKEEPALIVEPROBES

Number of unacknowledged probes before considering the connection dead (Linux only).

Default: 9

4.2.37 XRD_TCPKEEPALIVETIME

Time between last data packet sent and the first keepalive probe (Linux only).

Default: 7200

4.2.38 XRD_TIMEOUTRESOLUTION

Resolution for the timeout events. Ie. timeout events will be processed only every XRD_TIMEOUTRESOLUTION seconds.

Default: 15 (seconds)

4.2.39 XRD_WORKERTHREADS

Number of threads processing user callbacks.

Default: 3

4.2.40 XRD_WRITERECOVERY

Determines if write recovery should be enabled or disabled.

Default: true

4.2.41 XRD_XCPBLOCKSIZE

Maximu size of a data block assigned to a single source in case of an extreme copy transfer.

Default: 128MiB

4.3 Timeouts Explained

4.3.1 Connection Window and Connection Retry

The *ConnectionWindow* parameter is applied during client-server connection and controls two aspects of this process:

- First of all, it controls the length of time allowed to establish an XRootD connection (physical connection, XRootD hand-shake, and authentication if required). It is important to note that *Connection Window* is applied per physical address. This means that if a connection fails before the end of current *ConnectionWindow* and another physical address is available it will be tried immediately.
- Secondly (if there are no more available physical addresses), it defines the length of time that must elapse after a connection failure before the connection can be retried. More precisely, the client has to wait until the end of the current *ConnectionWindow* before attempting another connection. The number of retries that might be attempted is controlled by *ConnectionRetry* environment variable.

Let us illustrate all this with following example. Suppose XRootD client wants to connect to a server with three physical IP address (2x IPv6 and 1x IPv4). For the sake of argument let us suppose it will fail after 60s during the handshake procedure, while connecting to the 1^{st} IPv6 address. What will happen next? Since there are two more addresses available, the client will immediately proceed to the next one. Now let us suppose that the cumulative time spent

on establishing the physical connection and on carrying out the hand-shake exceeded 120s (nominal value of ConnectionWindow). In this case the second connection attempt will be timed out, and XRootD client will proceed to the 3^{rd} IP address. Again, let us suppose that similarly as in case of the 1^{st} IP address the connection failed after 60s. Since there are no more address to try, the client will have to wait until the end of the current ConnectionWindow (that is for another 60s) before the connection procedure can be restarted. Now how all this relates to the ConnectioRetry? The nominal value of ConnectioRetry is 5, which means we can retry the whole procedure four more times (Note: ConnectionRetry is not applied per single physical connection but rather to the whole connection procedure).

4.3.2 Stream Timeout

The *StreamTimeout* parameter is applied during every request/response exchange after the client and the server established a connection. It defines the maximum length of time that may elapse between the moment when the client has sent a request and the moment when the client has received a response for the request in question. If the time spent waiting for response from the server exceeds the *StreamTimeout* an error is declared (and the client will disconnect form the server).

There are two exceptions to the above stated rule:

- The server may force the client to reissue the request by sending *kXR*-wait response. In this case *StreamTimeout* does not apply to the original request anymore.
- The server may explicitly instruct the client to not apply the *StreamTime-out* to given request by sending *kXR_waitresp*.

4.3.3 Stream Error Window

The *StreamErrorWindow* controls the length of time that needs to elapse after a fatal error before the client may attempt to reconnect to the server. A fatal error is declared eg. if the host name cannot be resolved, a low level Posix system call fails (eg. *connect/fcntl/epool*), or client runs out of connection retries.

4.3.4 RequestTimeout

The *RequestTimeout* parameter is applied to a logical XRootD operation (eg. opening a file, listing directory, etc.) as a whole. It is the maximum length of time that may elapse from the moment an operation has been issued using XRootD client API until it has been resolved (no matter how many underlying requests it will trigger). If the *RequestTimeout* is exceeded an error is declared and the operation is resolved as failed.

Note: The value of this parameter might be overwritten directly by the user of XRootD client API by setting the timeout argument.

4.3.5 Time To Live

A Time To Live (TTL) timeout controls the lifetime of an idle physical connection. If for the given communication channel the time length elapsed from last exchange of request/response between the client and server exceeds the TTL timeout the given connection will be terminated. There are two types of TTL timeouts in XRootD client:

- DataServerTTL: a TTL timeout that is applied to Data Servers
- LoadBalancerTTL: a TTL timeout that is applied to Managers

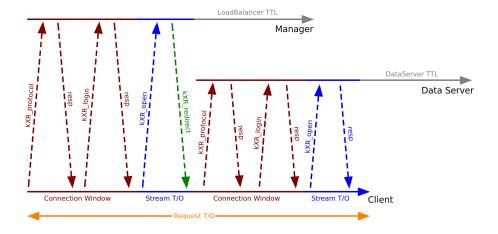
4.3.6 How does it all come together?

Let us now consider an example in order to illustrate how all those timeouts play along (for clarity please consult the diagram below). Suppose that an XrdCl::File::Open(...) operation is being called and that there is no open connection between the client and the server. The client will have to establish the XRootD connection first (subject to ConnectionWindow):

- open physical connection
- carry out hand-shake procedure (kXR_protocol, kXR_login, etc.)

Subsequently, the client will issue a kXR_open request (subject to $Stream_Timeout$). Let us suppose that the server will respond with a $kXR_redirect$ redirecting the client to a data server. In this case, the client will have to open another XRootD connection (again, subject to ConnectionWindow) and then send an open request (again, subject to StreamTimeout). Finally, once the server responds, the open operation will be resolved. The whole process described in the scenario above is subject to RequestTimeout.

Once the connections to the manager and data server become idle they will be subject to respective $TTL\ timeouts$.



4.3.7 xrdcp / XrdCl::CopyProcess Third-Party-Copy timeouts

The *CPInitTimeout* parameter is applied during initialization of a Third-Party-Copy (TPC) transfer. It defines the maximum length of time that may elapse until TPC transfer has been initialized (ie. *open* destination, *open* source, issue *sync*, for more details please consult the TPC Protocol Reference).

The *CPTPCTimeout* parameter defines the maximum length of time that may elapse between the moment when the actual transfer has been started and the moment when it is finished (ie. it is applied to the second *sync*, for more details please consult the TPC Protocol Reference).

5 Client Declarative API

This section describes XRootD client declarative API introduced in version 4.9.0. For the standard XrdCl::File and XrdCl::FileSystem API please consult our Doxygen documentation. Similarly as the standard XrdCl API, the declarative API allows to issue File and FileSystem operations, however its sole focus is on facilitating the asynchronous programing model and chaining of operations. Also, the new API has been designed to be more in line with modern C++ programming practices (see example below).

```
File f;
std::future<ChunkInfo> resp;

// open, read from and close the file
Pipeline p = Open(file, url, OpenFlags::Read)
Read(file, offset, size, buffer) >> resp
Close(file);

auto status = WaitFor(p);
```

5.1 Operation Utilities

There are several utilities for facilitating composition of operations:

- **Pipeline**: a class that can wrap any kind of operation (including compound operations).
- **Async**: a utility for asynchronous execution of pipelines.

Returns: std::future<XrdCl::XRootDStatus>

```
FileSystem fs(url);
std::future<XRootDStatus> status =
Async( Truncate(fs, path, size));
```

• WaitFor: a utility for synchronous execution of pipelines.

Returns: XrdCl::XRootDStatus.

```
FileSystem fs(url);
XRootDStatus status = WaitFor( Truncate(fs, path, size));
```

• XrdCl::Fwd: a forward is used to pass values between different operations in a pipeline. In particular it can be used to forward a value from an operation handler to a subsequent operation as an argument.

Consider following example of reading a whole file of unknown size:

```
2
3
      std::future<ChunkInfo> resp; // server response
6
      auto &&p = Open(file , url , OpenFlags :: Read) >>
                         [size, buff](XRootDStatus &status, StatInfo &info)
                               \begin{array}{ll} if \ (!\, status\,. IsOK \,()\,) & return\,; \\ size = info\,. \,GetSize \,()\,; \ // & forward \ size \ and \\ buff = new & char [\, info\,. \,GetSize \,()\,]\,; \ // & buffer \end{array}
12
13
                      Read(file,0,size,buff) >> resp
14
                      Close (file);
16
17
      auto status = WaitFor( p );
18
```

In lines 2-3 we declare forwardable *size* and *buffer* arguments. In the pipeline we first issue an open, which we handle with a lambda (open returns also stat information). Inside of the lambda (lines 11-12) we set the values of *size* and *buffer*. In the subsequent *Read* (line 14) operation we use the *size* and *buffer* although they values will be only set once we get the response for the preceding *Open*.

• XrdCl::Parallel: aggregates several operations (might be compound operations) for parallel execution; as an argument accepts variable number of operations or a container of operations (see example below).

```
auto &&o1 = Open(file1, url1, OpenFlags::Read);
auto &&o2 = Open(file2, url2, OpenFlags::Read);
auto &&o2 = Open(file2, url2, OpenFlags::Read);

// open 3 files in parallel
Pipeline p = Parallel(o1, o2, o3);

auto status = WaitFor( p );
```

5.2 Operation Handlers

The declarative API supports following handlers: XrdCl::ResponseHandler, functions, function objects, lambdas, std::future and $std::package_task$ (consult the list below for respective examples). Each operation defines its **response type** (see List of Operations) that should be used when constructing a respective handler for the operation.

• XrdCl::ResponseHandler – standard XRootD response handler. Operations can accept XrdCl::ResponseHandler both by reference and pointer.

```
2
    class ExampleHandler : public ResponseHandler
3
      public:
4
         void HandleResponse(
                XRootDStatus *status, // status of the operation
6
                                        // server response (type erased)
                AnyObject *response
           // handle the operation here
10
11
    };
12
13
14
    FileSystem fs(url);
16
17
    ExampleHandler hndl;
18
    auto status = WaitFor( Stat(fs,path) >> hndl );
19
20
```

- functions / function objects / lambdas the XRootD declarative API plays well with standard C++ callable elements. The callback signature has to match:
 - std::function<void(XRootDStatus&) for operations that define their response type as void.
 - std::function < void(XRootDStatus &, Response &)> where Response is defined as a response type for given operation.

```
void ExampleHandler (
           XRootDStatus &status, // status of the operation
3
                               // server response (explicit type)
4
5
6
        handle the operation here
8
9
10
    FileSystem fs(url);
12
    // could also be a lambda or function object !!!
13
    auto status = WaitFor( Stat(fs,path) >> ExampleHandler );
14
15
```

• std::future – the future's template parameter has to match the response type of given operation. In case of a failure the future will throw an instance of XrdCl::PipelineException that in turn will yield the XrdCl::XRo-otDStatus.

```
1
2
     File file;
    std::future<ChunkInfo> resp;
3
    Async( Read(off, size, buff) >> resp );
6
8
    // later on process the future
10
11
12
13
       // if everything went OK we will get the ChunkInfo,
14
       // otherwise it will throw
       ChunkInfo chunk = resp.get();
16
17
18
    catch( PipelineException &ex )
19
20
       // we will learn the reason for failing from
21
       // the status object
22
      XRootDStatus &status = ex.GetError();
23
24
25
26
```

• $std:packaged_task$ is a combination of a lambda and a std::future, e.g. it can be used to parse the response with a lambda into a desired type of std::future.

```
2
    using namespace std;
3
    packaged_task<uint64_t(XRootDStatus &st,StatInfo &info)> parse =
         [] (XRootDStatus &st, StatInfo &info)
             if (!st.IsOK) throw PipelineException(st);
7
             return info. GetSize();
           };
9
10
    FileSystem fs(url);
    future < uint 64_t > size = parse.get_future();
12
13
    Async( Stat(fs, path) >> parse);
14
15
    // later on use size the same way as
16
17
    // the future from previous example
18
```

5.3 Pipelining Semantics

Operations can be pipelined using operator. In order to illustrate the pipelining semantics we will consider following scenario: suppose one wants to read 1KB

form a files, however the prerequisite for reading is creating a lock file. Now let us consider following code:

```
File lock, file;
2
3
    FileSystem fs(url);
    std::future<ChunkInfo> resp; // server response
    auto &&p = Open(lock, "root://host//path/to/.lock", OpenFlags::New)
                Close (lock)
                Open(file, "root://host//path/to/file.txt", OpenFlags::Read)
                Read(file, 0, 1024, buff) >> resp
9
                Close (file);
               Rm(fs, "root://host//path/to/.lock");
12
    // we can already pass resp to an algorithm for processing
14
    // we wait for the pipeline to complete
    auto status = WaitFor( p );
16
```

In lines 6-7 the lock file is being created. Afterwards, in lines 8-10 the pipeline continues: it does an open, a read and a close on the actual file. Finally, in line 11 the lock file is being deleted. Note that if an operation on the pipeline fails subsequent operations in the pipeline wont be executed, however their handlers will be called with an error status of *errPipelineFailed* (in order to allow for a clean up if necessary). Using the pipelining API makes the source code more coherent and the control flow more explicit.

5.4 List of Operations

There are two types of operations: the *XrdCl::File* operations and *XrdCl::FileSystem* operations. Each operation has a well defined set of arguments, however any argument might be lifted to a *std::future* or a *XrdCl::Fwd.* It is possible (but not mandatory) to specify a handler for each operation using the streaming operator (*operator*>>). All Operations are non-copyable objects (*move* only).

5.4.1 File Operations

All arguments of any File Operation (except for the *XrdCl::File* object itself) are **liftable to** *XrdCl::Fwd* and *std::future*.

• Open – open remote / local file

```
{\bf Signature:}
```

```
Open( XrdCl::File &file, ...);Open( XrdCl::File *file, ...);
```

- <u>url</u> base **type**: std::string
- flags base **type**: *XrdCl::OpenFlags::Flags*
- <u>mode</u> base **type**: *XrdCl::Access::Mode*, **default**: *Access::None*

Operation status: XRootDStatus

Response:

- void
- $-\ \mathit{XrdCl}{::}\mathit{StatInfo}\ (\mathtt{not\ for\ XrdCl}{::}\mathit{ResponseHandler})$
- ullet Read read data from remote / local file

Signature:

- Read(XrdCl::File &file, ...);
- Read(XrdCl::File *file, ...);

Arguments (remaining):

- offset base **type**: uint64-t
- size base **type**: $uint32_t$
- − <u>buffer</u> − base **type**: void*

Operation status: XRootDStatus

 $\textbf{Response}: \textit{XrdCl}{::}\textit{ChunkInfo}$

 \bullet Close – close remote / local file

Signature:

- Close(XrdCl::File &file);
- Close(XrdCl::File *file);

Operation status: XRootDStatus

Response: void

• Stat – stat the remote / local file

```
{\bf Signature:}
```

```
- Stat( XrdCl::File &file, ...);
```

```
- force - base type: bool
```

Operation status: XRootDStatus

Response: XrdCl::StatInfo

• Write – write data to remote / local file

Signature:

```
- Write( XrdCl::File &file, ...);
```

Arguments (remaining):

```
- offset - base type: uint64-t
```

$$-$$
 size $-$ base **type**: $uint32_{-}t$

Operation status: XRootDStatus

Response: void

 $\bullet~\mathbf{Sync}$ – sync the remote / local file

Signature:

```
- Sync( XrdCl::File &file );
```

Operation status: XRootDStatus

Response: void

• Truncate – truncate the remote / local file Signature:

```
- Truncate( XrdCl::File &file, ...);
```

Arguments (remaining):

- size - base **type**: uint64-t

Operation status: XRootDStatus

Response: void

- VectorRead vector-read data from remote / local file Signature:
 - VectorRead(XrdCl::File &file, ...);
 - VectorRead(XrdCl::File *file, ...);

- $\underline{\mathrm{chunks}}$ base $\mathbf{type} : \mathit{XrdCl} :: \mathit{ChunkList}$
- − <u>buffer</u> − base **type**: void*

Operation status: XRootDStatus

 $\textbf{Response}: \textit{XrdCl}{::}\textit{ChunkList}$

- VectorWrite vector-write data to remote / local file Signature:
 - VectorWrite(XrdCl::File &file, ...);
 - VectorWrite(XrdCl::File *file, ...);

Arguments (remaining):

- chunks - base **type**: XrdCl::ChunkList

Operation status: XRootDStatus

Response: void

- WriteV writev data to remote / local file Signature:
 - Write V(XrdCl::File &file, ...);
 - WriteV(XrdCl::File *file, ...);

Arguments (remaining):

- offset base **type**: $uint64_-t$
- − <u>iov</u> − base **type**: struct iovec*
- <u>iovcnt</u> base **type**: int

Operation status: XRootDStatus

Response: void

• Fcntl – issue fcntl for remote / local file Signature:

```
- Fcntl( XrdCl::File &file, ...);
- Fcntl( XrdCl::File *file, ...);
```

Arguments (remaining):

- arg - base **type**: *XrdCl::Buffer*

Operation status: XRootDStatus

 $\textbf{Response}: \textit{XrdCl}{::}\textit{Buffer}$

 $\bullet~$ Visa – issue fcntl for remote / local file

Signature:

- $-\ \ Visa(\ XrdCl::File\ {\it \&file}\);$
- Visa(XrdCl::File *file);

Operation status: XRootDStatus

Response: XrdCl::Buffer

5.4.2 FileSystem Operations

All arguments of any FileSystem Operation (except for the XrdCl::FileSystem object itself) are liftable to XrdCl::Fwd and std::future.

• Locate – locate remote file

Signature:

- Locate(XrdCl::FileSystem &file, ...);
- Locate(XrdCl::FileSystem *file, ...);

Arguments (remaining):

- path base **type**: std::string
- flags base **type**: XrdCl::OpenFlags::Flags

Operation status: XRootDStatus

Response: LocationInfo

• **DeepLocate** – recursively locate remote file

```
{\bf Signature:}
```

```
DeepLocate(XrdCl::FileSystem &file, ...);
DeepLocate(XrdCl::FileSystem *file, ...);
```

- path base **type**: std::string
- flags base **type**: *XrdCl::OpenFlags::Flags*

Operation status: XRootDStatus

 $\textbf{Response}:\ \textit{LocationInfo}$

 \bullet Mv – move remote file

Signature:

- Mv(XrdCl::FileSystem & file, ...);
- Mv(XrdCl::FileSystem *file, ...);

Arguments (remaining):

- path1 base **type**: std::string
- path2 base **type**: std::string

Operation status: XRootDStatus

Response: void

• Query – query remote server

Signature:

- $\ \mathit{Query(\ XrdCl::FileSystem\ Efile,\ \dots)};$
- Query(XrdCl::FileSystem *file, ...);

Arguments (remaining):

- -queryCode -base $\mathbf{type} : \mathit{XrdCl} :: \mathit{QueryCode} :: \mathit{Code}$
- argument base **type**: XrdCl::Buffer

Operation status: XRootDStatus

Response: XrdCl::Buffer

• Truncate – truncate remote file

```
Signature:
    - Truncate( XrdCl::FileSystem &file, . . . );
    - Truncate( XrdCl::FileSystem *file, ...);
  Arguments (remaining):
    - path - base type: std::string
    - size - base type: uint64_-t
 Operation status: XRootDStatus
 Response: void
\bullet Rm – remove remote file
  Signature:
    - Rm(XrdCl::FileSystem &file, ...);
    - Rm(XrdCl::FileSystem *file, ...);
  Arguments (remaining):
    - path - base type: std::string
 Operation status: XRootDStatus
  Response: void
• MkDir – create remote directory
 Signature:
    - MkDir( XrdCl::FileSystem &file, . . . );
    - MkDir( XrdCl::FileSystem *file, ...);
  Arguments (remaining):
    - path - base type: std::string
  Operation status: XRootDStatus
 Response: void
• RmDir – remove remote directory
 Signature:
    - RmDir( XrdCl::FileSystem &file, . . . );
    - RmDir( XrdCl::FileSystem *file, ...);
  Arguments (remaining):
    - path - base type: std::string
  Operation status: XRootDStatus
 Response: void
```

```
Signature:
    - ChMod( XrdCl::FileSystem &file, ...);
    - ChMod( XrdCl::FileSystem *file, ...);
  Arguments (remaining):
    – path – base type: std::string
    - <u>mode</u> - base type: XrdCl::Access::Mode
 Operation status: XRootDStatus
 Response: void
• Ping – ping remote server
 Signature:
    - Ping( XrdCl::FileSystem &file );
    - Ping( XrdCl::FileSystem *file );
 Operation status: XRootDStatus
  Response: void
• Stat – stat remote directory or file
 Signature:
    - Stat( XrdCl::FileSystem &file, . . . );
    - Stat( XrdCl::FileSystem *file, ...);
  Arguments (remaining):
    - path - base type: std::string
  Operation status: XRootDStatus
 Response: XrdCl::StatInfo
• StatVFS – status information for a Virtual File System
  Signature:
    - StatVFS( XrdCl::FileSystem &file, . . . );
    - StatVFS( XrdCl::FileSystem *file, ...);
  Arguments (remaining):
    – path – base type: std::string
  Operation status: XRootDStatus
 Response: XrdCl::StatInfoVFS
```

• ChMod – change access mode on a remote directory or file

```
Signature:
    - Protocol( XrdCl::FileSystem &file );
    - Protocol( XrdCl::FileSystem *file );
  Operation status: XRootDStatus
  Response: XrdCl::ProtocolInfo
• DirList – list remote directory
  Signature:
    - DirList( XrdCl::FileSystem &file, . . . );
    - DirList( XrdCl::FileSystem *file, ...);
  Arguments (remaining):
    - path - base type: std::string
    - flags - base type: XrdCl::DirListFlags::Flags
  Operation status: XRootDStatus
  \mathbf{Response}: XrdCl::DirectoryList
• SendInfo – send info to remote server
  Signature:
    - SendInfo( XrdCl::FileSystem &file, . . . );
    - SendInfo( XrdCl::FileSystem *file, ...);
  Arguments (remaining):
    - info - base type: std::string
  Operation status: XRootDStatus
  Response: XrdCl::Buffer
• Prepare – prepare one or more files for access
 Signature:
    - Prepare( XrdCl::FileSystem &file, . . . );
    - Prepare(XrdCl::FileSystem *file, ...);
  Arguments (remaining):
    - fileList - base type: std::vector < std::string >
    - flags - base type: XrdCl::PrepareFlags::Flags
    - priority - base type: uint8_t
  Operation status: XRootDStatus
```

• Protocol – obtain server protocol information

Response: XrdCl::Buffer