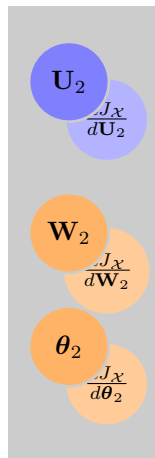
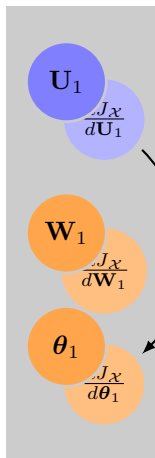


$$\mathbf{U}_1 = f_1(\mathbf{X}\mathbf{W}_1^T + \boldsymbol{\theta}_1) \quad \mathbf{U}_2 = f_2(\mathbf{U}_1\mathbf{W}_2^T + \boldsymbol{\theta}_2)$$

$$\begin{bmatrix} x_{0,0} & \dots & x_{0,m} \\ x_{1,0} & \dots & x_{1,m} \\ \vdots & & \vdots \\ x_{n,0} & \dots & x_{n,m} \end{bmatrix}$$



$$J_{\mathcal{X}}(\mathbf{y}, \hat{\mathbf{y}})$$

$$\frac{dJ_{\mathcal{X}}}{d\boldsymbol{\theta}_1} = \left( \mathbf{f}'_1 \odot \frac{dJ_{\mathcal{X}}}{d\mathbf{U}_1} \right)^T \mathbf{1}$$