

Project Proposal: Traffic Lights Controller

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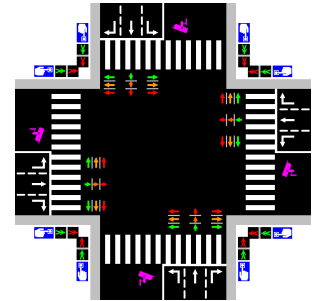
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1 Introduction

1.1 Basic idea of our project

The goal of our project is to design a controller for traffic lights at a crossing junction which have push button to allow pedestrian to notify that they are waiting to cross, and ultimately let them do so. There will be detectors on the road to check whether or not cars are waiting at the lights to assign some kind of priorities, while still taking into account the pedestrians.

Because we are a group of 6, we choose to work on a four-way instead of a simple junction. As we can see on the right, we have four crosswalks and two pairs of traffic lights to orchestrate. Ultimately, we should come up with a solution to avoid unwanted situation which are explained below. The pink cameras represent cars detectors.



To be noted that we do the project conjointly with the course of embedded system.

1.2 Why using model checking?

In such a system, lives are at stake. If the lights get mixed up, we could easily reach a state where pedestrians and cars cross the road at the same, or even in a situation where head-on collision could happen. With these information, it is easy to see why it is important to formally check our model to remove the chance of reaching problematic states.

Another interesting reason as of why our project could benefit from model checking it the real-time dimension. Indeed, a clogged junction increases the risk of accident (and also affects people's moods). Designing a controller to allow a fluid circulation can also make commuting safer.