

## TP1 : Reminder on Markov Chains - Stochastic gradient descent

### Exercice 1 : Box-Muller and Marsaglia-Bray algorithm

1. Let  $f : \mathbb{R}^2 \rightarrow \mathbb{R}$  integrable.

We note  $\phi : (r, \theta) \in \mathbb{R}_+^* \times ]0, 2\pi[ \mapsto (r \cos \theta, r \sin \theta) \in \mathbb{R}^2 - \{(0, x), x \geq 0\}$ , which is a diffeomorphism, we can apply the change of variable theorem with  $(x, y) = (r \cos \theta, r \sin \theta)$ . On a  $\det J_\phi = r$ .

$$\begin{aligned} \mathbb{E}[f(X, Y)] &= \mathbb{E}[f(\phi(R, \Theta))] \\ &= \frac{1}{2\pi} \int_{\mathbb{R}_+^* \times ]0, 2\pi[} f(r \cos \theta, r \sin \theta) r e^{-\frac{r^2}{2}} dr d\theta \\ &= \frac{1}{2\pi} \int_{\mathbb{R}^2 - \{(0, x), x \geq 0\}} f(x, y) e^{-(x^2+y^2)/2} dx dy \\ &= \frac{1}{2\pi} \int_{\mathbb{R}^2} f(x, y) e^{-(x^2+y^2)/2} dx dy \end{aligned}$$

We deduce the p.d.f of couple  $(X, Y)$  which is  $f_{X,Y}(x, y) = \frac{1}{2\pi} e^{-\frac{x^2+y^2}{2}} = \frac{1}{\sqrt{2\pi}} e^{-\frac{x^2}{2}} \frac{1}{\sqrt{2\pi}} e^{-\frac{y^2}{2}} = f_X(x) f_Y(y)$ . We showed that  $X, Y \sim \mathcal{N}(0, 1)$  and the independance of variables  $X$  and  $Y$ .

2. The previous question show that if we know how to generate a uniform variable  $\Theta$ , on  $[0, 2\pi]$ , and a Rayleigh variable  $R$ , which are independant, then we know how to simulate two independant variables of distribution  $\mathcal{N}(0, 1)$ .

The Python language allows us to generate a uniform distribution on  $[0, 1]$ , hence on  $[0, 2\pi]$ . Let's proof that we can simulate a Rayleigh variable by Inverse transform sampling.

Let  $R$  be a Rayleigh variable. We have

$$F_R(x) = \mathbb{P}(R \leq x) = \int_0^x r e^{-\frac{r^2}{2}} dr = \left[ -e^{-\frac{r^2}{2}} \right]_0^x = 1 - e^{-\frac{x^2}{2}}$$

This c.d.f is invertible of inverse  $F_R^{-1}(y) = \sqrt{-2 \ln(1 - y)}$ .

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#### Algorithm 1 Sampling independant gaussian variables

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Sample independent random variables  $U_1, U_2 \sim \mathcal{U}([0, 1])$ .

$\Theta \leftarrow 2\pi U_1$

$R \leftarrow \sqrt{-2 \ln(1 - U_2)}$

$X \leftarrow R \cos \Theta$

$Y \leftarrow R \sin \Theta$

**Output :**  $X, Y$

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3. (a) The while loop correspond to a rejection sampling. The target distribution is the uniform distribution on the unit disk (of p.d.f  $\frac{1}{\pi} \mathbb{1}_{D(0,1)}$ ), and the distribution that we know how to generate is the uniforme distribution on square  $[-1, 1]^2$  of p.d.f  $\frac{1}{4} \mathbb{1}_{[-1, 1]^2}$ . Hence, the random couple  $(V_1, V_2)$  follows a uniform distribution on the unit disk.

Let's proof that rigorously. For sake of clarity, we'll denote  $V_{i,1}, V_{i,2}$  the variables generated at the i-th step of the loop.

Let  $T = \inf \{i \in \mathbb{N}^*, V_{i,1}^2 + V_{i,2}^2 \leq 1\}$ .

We want to show that  $(V_{T,1}, V_{T,2})$  follows a uniform distribution on the unit disk.

Let  $f : [-1, 1]^2 \rightarrow \mathbb{R}$  a bounded and measurable function.

We have :

$$\begin{aligned}
\mathbb{E}[f(V_{T,1}, V_{T,2})] &= \mathbb{E} \left[ \sum_{k=1}^{\infty} f(V_{k,1}, V_{k,2}) \mathbb{1}_{(T=k)} \right] \\
&= \sum_{k=1}^{\infty} \mathbb{E}[f(V_{k,1}, V_{k,2}) \mathbb{1}_{(V_{k,1}^2 + V_{k,2}^2 \leq 1)} \prod_{i < k} \mathbb{1}_{(V_{i,1}^2 + V_{i,2}^2 > 1)}] \\
&= \sum_{k=1}^{\infty} \mathbb{E}[f(V_{k,1}, V_{k,2}) \mathbb{1}_{(V_{k,1}^2 + V_{k,2}^2 \leq 1)}] \left(1 - \frac{\pi}{4}\right)^{k-1} \text{ by independence} \\
&= \frac{4}{\pi} \frac{1}{4} \int_{[-1,1]^2} f(v_1, v_2) \mathbb{1}_{v_1^2 + v_2^2 \leq 1} dv_1 dv_2 \\
&= \frac{1}{\pi} \int_{D(0,1)} f(v_1, v_2) dv_1 dv_2
\end{aligned}$$

(b) Let  $f : [0, 1]^2 \rightarrow \mathbb{R}, g : [0, 1] \rightarrow \mathbb{R}$  bounded, measurable.

We show, by using the diffeomorphisme  $\phi : (v, \theta) \in ]0, 1[ \times ]0, 2\pi[ \mapsto (\sqrt{v} \sin \theta, \sqrt{v} \cos \theta) \in D(0, 1)$  of inverse  $\phi^{-1}(v_1, v_2) = \left(v_1^2 + v_2^2, 2 \arctan\left(\frac{v_2}{\sqrt{v_1^2 + v_2^2} + v_1}\right)\right)$  and such that  $|\det J(\phi)(v, \theta)| = 1/2$ , and by applying the change of variable theorem with  $(v_1, v_2) = (\sqrt{v} \cos \theta, \sqrt{v} \sin \theta)$ , that :

$$\begin{aligned}
\mathbb{E}[f(T_1, T_2)] &= \frac{1}{\pi} \int_{D(0,1)} f\left(\frac{v_1}{\sqrt{v_1^2 + v_2^2}}, \frac{v_2}{\sqrt{v_1^2 + v_2^2}}\right) dv_1 dv_2 \\
&= \frac{1}{\pi} \int_0^1 \int_0^{2\pi} f(\cos \theta, \sin \theta) |\det J(\phi)(v, \theta)| d\theta dv \\
&= \frac{1}{2\pi} \int_0^{2\pi} f(\cos \theta, \sin \theta) d\theta
\end{aligned}$$

et

$$\begin{aligned}
\mathbb{E}[g(V)] &= \frac{1}{\pi} \int_{D(0,1)} g(v_1^2 + v_2^2) dv_1 dv_2 \\
&= \frac{1}{\pi} \int_0^1 \int_0^{2\pi} g(v) |\det J(\phi)(v, \theta)| d\theta dv \\
&= \int_0^1 g(v) dv
\end{aligned}$$

Hence,  $V \sim \mathcal{U}([0, 1])$  and  $(T_1, T_2) \sim (\cos \Theta, \sin \Theta)$  where  $\Theta \sim \mathcal{U}([0, 2\pi])$ .

$$\begin{aligned}
\mathbb{E}[f(T_1, T_2)g(V)] &= \mathbb{E} \left[ f\left(\frac{V_1}{\sqrt{V_1^2 + V_2^2}}, \frac{V_2}{\sqrt{V_1^2 + V_2^2}}\right) g\left(\sqrt{V_1^2 + V_2^2}\right) \right] \\
&= \frac{1}{\pi} \int_{D(0,1)} f\left(\frac{v_1}{\sqrt{v_1^2 + v_2^2}}, \frac{v_2}{\sqrt{v_1^2 + v_2^2}}\right) g(v_1^2 + v_2^2) dv_1 dv_2 \\
&= \frac{1}{\pi} \int_{]0,1[ \times ]0,2\pi[} f(\cos \theta, \sin \theta) g(v) |\det J(\phi)(v, \theta)| dv d\theta \\
&= \frac{1}{2\pi} \int_0^{2\pi} f(\cos \theta, \sin \theta) d\theta \int_0^1 g(v) dv \\
&= \mathbb{E}[f(T_1, T_2)] \mathbb{E}[g(V)]
\end{aligned}$$

The couple  $(T_1, T_2)$  and the variable  $V$  are independant.

(c) Let's show that  $S$  follows a Rayleigh distribution.

Let  $s \geq 0$ .

$$\mathbb{P}(S \leq s) = \mathbb{P}(\sqrt{-2 \log V} \leq s) = \mathbb{P}(V \geq e^{-s^2/2}) = 1 - e^{-s^2/2}.$$

The c.d.f of  $S$  is the c.d.f of a Rayleigh distribution. According to question 1, the couple  $(X, Y) = (ST_1, ST_2)$  follows a multivariate gaussian distribution  $\mathcal{N}(0, I_2)$ .

(d) We are looking for  $\mathbb{E}[T]$  where  $T$  is the stopping time defined at question 3. (a)

The variable  $T$  follows a geometric distribution  $\mathcal{G}\left(\frac{\pi}{4}\right)$ , then we deduce that  $\mathbb{E}[T] = \frac{4}{\pi}$ .

## Exercice 2 : Invariant distribution

Let  $I = \left\{ \frac{1}{m}, m \in \mathbb{N}^* \right\}$ .

1. The definition of  $\mathcal{L}(X_{n+1}|X_n)$  is equivalent to define implicitly a sequence of independant random variable  $(Z_{n,m})_{n,m}$  of distribution  $\mathcal{B}\left(\frac{1}{m}\right)$  such that  $Z_{n,m}$  is independante of  $X_n$  and :

$$\begin{cases} X_{n+1} = \frac{1}{m+1} \text{ si } X_n = \frac{1}{m} \text{ et } Z_{n,m} = 1 \\ X_{n+1} \sim \mathcal{U}([0, 1]) \text{ sinon} \end{cases}$$

We have

$$\mathbb{P}[X_{n+1} \in A | X_n \notin I] = \int_{A \cap [0,1]} dt$$

and

$$\begin{aligned} \mathbb{P}\left[X_{n+1} \in A | X_n = \frac{1}{m}\right] &= \mathbb{P}[Z_{n,m} = 1] \mathbb{P}\left[X_{n+1} \in A | X_n = \frac{1}{m}, Z_{n,m} = 1\right] \\ &\quad + \mathbb{P}[Z_{n,m} = 0] \mathbb{P}\left[X_{n+1} \in A | X_n = \frac{1}{m}, Z_{n,m} = 0\right] \\ &= \frac{1}{m^2} \delta_{\frac{1}{m+1}}(A) + \left(1 - \frac{1}{m}\right)^2 \int_{A \cap [0,1]} dt \end{aligned}$$

We deduce the transition kernel of the Markov chain.

2. Let  $A \in \mathcal{B}([0, 1])$ .

We have :

$$P(x, A) = \mathbb{1}_{x \notin I} \pi(A) + \sum_{m=1}^{+\infty} \mathbb{1}_{x=1/m} \left( x^2 \pi(A) + (1 - x^2) \delta_{\frac{1}{m+1}}(A) \right)$$

.

Le right term is null almost everywhere with respect to the measure  $\pi(dx) = dx$ . We deduce that :

$$\int_0^1 P(x, A) dx = \int_0^1 \mathbb{1}_{x \notin I} \pi(A) dx = \pi(A) \int_0^1 \mathbb{1}_{x \notin I} dx = \pi(A)$$

The  $\pi$  is invariant with respect to the transition kernel  $P$ .

3. We have  $x \notin I$ , hence  $P(x, \cdot) = \pi(\cdot)$  :

$$Pf(x) = \int_0^1 f(y) P(x, dy) = \int_0^1 f(y) \pi(dy)$$

The function  $Pf$  si constant. We deduce that  $x \notin I, P^n f(x) = \int_0^1 f(y) \pi(dy)$  for all  $n \geq 1$ . Then  $\lim P^n f(x) = \int_0^1 f(y) \pi(dy)$ .

4. (a) We have  $P\left(x, \frac{1}{m+1}\right) = 1 - x^2$ . We show by induction the property  $P^n\left(x, \frac{1}{m+n}\right) = \prod_{k=0}^{n-1} \left(1 - \frac{1}{(m+k)^2}\right)$ .

Let's show the induction step :

$$\begin{aligned} P^{n+1}\left(x, \frac{1}{m+n+1}\right) &= \int_0^1 P\left(z, \frac{1}{m+n+1}\right) P^n(x, dz) \text{ according to Chapman-Kolmogorov equation} \\ &= P\left(\frac{1}{m+n}, \frac{1}{m+n+1}\right) P^n\left(\frac{1}{m}, \frac{1}{m+n}\right) \text{ car } P\left(z, \frac{1}{m+n+1}\right) = 0 \text{ if } z \neq \frac{1}{m+n} \\ &= \prod_{k=0}^n \left(1 - \frac{1}{(m+k)^2}\right) \text{ by induction hypothesis} \end{aligned}$$

(b) It's easy to show that for  $q \neq n-1$ ,  $P^n\left(x, \frac{1}{m+1+q}\right) = 0$

Then,

$$P^n(x, A) = \sum_{q \in \mathbb{N}} P^n\left(x, \frac{1}{m+1+q}\right) = P^n\left(x, \frac{1}{m+n}\right) = \prod_{k=0}^{n-1} \left(1 - \frac{1}{(m+k)^2}\right)$$

We obtain :

$$P^n\left(x, \frac{1}{m+n}\right) = \prod_{k=0}^{n-1} \frac{m+k-1}{m+k} \prod_{k=0}^{n-1} \frac{m+k+1}{m+k} = \frac{m-1}{m+n-1} \frac{m+n}{m}$$

$$\text{Then } \lim P^n(x, A) = \frac{m-1}{m} \neq 0 = \pi(A).$$

### Exercice 3 : Stochastic Gradient Learning in Neural Networks

1. We can notice that

$$R_n(w) = \frac{1}{n} \sum_{i=1}^n (y_i - w^T x_i)^2 = \mathbb{E}_{\mu_n} [(Y - w^T X)^2]$$

where  $\mu_n = \frac{1}{n} \sum_{i=1}^n \delta_{(x_i, y_i)}$  is the empirical measure of  $(X, Y)$ .

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#### Algorithm 2 Stochastic Gradient Descent for minimizing empirical risk

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**Input :** a sample  $(x_i, y_i)_{1 \leq i \leq n}$  of size  $n$   
 $w \leftarrow w_0$ , with random  $w_0$  e.g  $w_0 \sim \mathcal{N}(0, \sigma^2 I_2)$   
 $k \leftarrow 1$   
**while** not stopping criterion **do**  
    Sample  $(x^k, y^k) \sim \mu_n$   
     $w \leftarrow w - \gamma_k \nabla_w F(x^k, y^k, w)$   
     $k \leftarrow k + 1$   
**end while**  
**Output :**  $w$

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où  $F(x, y, w) = (y - w^T x)^2$  d'où  $\nabla_w F(x, y, w) = -2(y - w^T x)x$ , et  $\gamma_k = \gamma/\sqrt{k}$ .