# Report on Project 4: Driverless Car

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June 2, 2018

# 1 Overview

In this project, we use HMM to solve driverless car problems.

# 2 Problem 1

### 2.1 Problem 1a

According to the constraints given by the instruction,

$$\mathbb{P}(C_2 = 1 | D_2 = 0) = \frac{\mathbb{P}(C_2 = 1, D_2 = 0)}{\mathbb{P}(D_2 = 0)}$$
$$= \frac{\mathbb{P}(D_2 = 0 | C_2 = 1) \mathbb{P}(C_2 = 1)}{\mathbb{P}(D_2 = 0)}$$

And we have

$$\mathbb{P}(C_2 = 1) = \mathbb{P}(C_1 = 0)\mathbb{P}(C_2 = 1|C_1 = 0) + \mathbb{P}(C_1 = 1)\mathbb{P}(C_2 = 1|C_1 = 1)$$
$$= 0.5\epsilon + 0.5(1 - \epsilon)$$
$$= 0.5$$

So we have

$$\mathbb{P}(C_2 = 1 | D_2 = 0) = \frac{0.5\eta}{\mathbb{P}(D_2 = 0)}$$
$$\mathbb{P}(C_2 = 0 | D_2 = 0) = \frac{0.5(1 - \eta)}{\mathbb{P}(D_2 = 0)}$$

So the answer is

$$\mathbb{P}(C_2 = 1 | D_2 = 0) = \frac{0.5\eta}{0.5\eta + 0.5(1 - \eta)}$$
=  $\eta$ 

Notice that  $\mathbb{P}(D_2 = 0)$  is not 1 since  $\mathbb{P}(D_2)$  is related to  $\mathbb{P}(C_2)$ .

#### 2.2 Problem 1b

According to the HMM graph, the result could be written as

$$\begin{split} & \mathbb{P}(C_2 = 1 | D_2 = 0, D_3 = 1) \\ & \propto \mathbb{P}(C_2 = 1, D_2 = 0, D_3 = 1) \\ & = \{ \sum_{C_1 = \{0,1\}} \mathbb{P}(C_1) \mathbb{P}(C_2 = 1 | C_1) \} \cdot \mathbb{P}(D_2 = 0 | C_2 = 1) \cdot \{ \sum_{C_3 = \{0,1\}} \mathbb{P}(C_3 | C_2 = 1) \mathbb{P}(D_3 = 1 | C_3) \} \\ & = 0.5 \eta (\epsilon \eta + (1 - \epsilon)(1 - \eta)) \end{split}$$

Also,

$$\begin{split} & \mathbb{P}(C_2 = 0 | D_2 = 0, D_3 = 1) \\ & \propto \mathbb{P}(C_2 = 0, D_2 = 0, D_3 = 1) \\ & = \{ \sum_{C_1 = \{0,1\}} \mathbb{P}(C_1) \mathbb{P}(C_2 = 0 | C_1) \} \cdot \mathbb{P}(D_2 = 0 | C_2 = 0) \cdot \{ \sum_{C_3 = \{0,1\}} \mathbb{P}(C_3 | C_2 = 0) \mathbb{P}(D_3 = 1 | C_3) \} \\ & = 0.5(1 - \eta)((1 - \epsilon)\eta + \epsilon(1 - \eta)) \end{split}$$

After normalization, the result is

$$\mathbb{P}(C_2 = 1 | D_2 = 0, D_3 = 1) = \frac{\epsilon \eta^2 + \eta (1 - \epsilon)(1 - \eta)}{\epsilon \eta^2 + 2\eta (1 - \epsilon)(1 - \eta) + \epsilon (1 - \eta)^2}$$

#### 2.3 Problem 1c

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