Chapter 1

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1 Motivating example

- How to identify "Hey Siri" without machine learning?
- \bullet The (supervised) ML process is broadly as follows:

Pick a model and initialise parameters then repeat:

- Measure how good the model is against data
- Change params (to ideally improve the error)
- In ML we don't design the solution explicitly
- Deep models are deep in precisely the sense that they learn many layers of computation

2 The Key Components: Data, Models, and Algorithms

- Data what we can learn from
 - examples, targets and features
 - dimensionality fixed length Vs variable-length
 - garbage in, garbage out
- Model how to transform the data.
- Loss function quantifies the badness of our model.
 - minimize the loss to give the best parameters
 - training and testing error and overfitting
 - \mathbf{L}_1 , \mathbf{L}_2 and cross entropy
- **Algorithm** how to adjust the model's parameters to minimize the loss (gradient descent)

3 Models

Supervised

- regression real number target e.g. predicting house prices
- classification discrete number of targets e.g. predicting heart attacks $y \in \{0, 1\}$
- find f_{θ} such that $f_{\theta}(\mathbf{x}_i) = \hat{y}_i \sim y_i$ given data $\{\mathbf{x}_i, y_i\}_{i=1}^n$
- for classification we are (often) interested in $P(y|\mathbf{x})$
- tagging extending classification to multi-label classification (dog + cat, AWS, medical journal tagging)
- search and ranking ordered relevant subset retrieval
- recommender systems personalised recommendation subset retrieval
- sequence learning using sequential nature of input features
 - * tagging and parsing annotating a text sequence with attributes (e.g. named entities)
 - * automatic speech recognition from audio waves to text
 - * text to speech from text to audio waves
 - * machine translation

• Unsupervised

- **clustering** grouping "similar" samples
- **subspace estimation** dimensionality reduction
- representation learning representing in \mathbb{R}^n
- probabilistic graphical models defining causality
- generative adversarial networks (GANs) synthesize data

• Interacting with an Environment

- offline learning doesn't interact with environment
- intelligent agents are trained to make actions
- Reinforcement learning e.g. self driving car. The agent interacts with the environment via actions and observations over a period of time steps. The agent receives a reward after each action (defining this reward is a problem itself). The policy (i.e. what action to take in a certain scenario) is learnt balancing exploration and exploitation.

4 Exercises

1. Which parts of code that you are currently writing could be "learned", i.e., improved by learning and automatically determining design choices that are made in your code? Does your code include heuristic design choices?

A good starting place would be the syntax; a large set of labelled data, e.g. correct or incorrect syntax could be collected and used to train a classifier.

2. Which problems that you encounter have many examples for how to solve them, yet no specific way to automate them? These may be prime candidates for using deep learning.

answer

3. Viewing the development of artificial intelligence as a new industrial revolution, what is the relationship between algorithms and data? Is it similar to steam engines and coal (what is the fundamental difference)?

answer

4. Where else can you apply the end-to-end training approach? Physics? Engineering? Econometrics? answer

References

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