Labs
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#### **EPFL**

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# Problem Set 13, Dec 10, 2020 (Solutions to Matrix Factorization Theory Questions)

## Problem 3 (Which models will give the best performance):

Intuitively, the Movie Mean baseline should perform the best amongst all the baselines because it should be able to tell whether a movie is liked or disliked by the audience in general.

## **Problem 4 (Implement Stochastic Gradient Descent):**

NOTE: We use MSE instead of RMSE for updates.

1. Let  $E = X - WZ^{\top}$ . Then,  $e_{dn} = x_{dn} - (WZ^{\top})_{dn}$ .

Then, the entry corresponding to the  $i^{th}$  row of W,  $w_i$  in  $\nabla_{(W,Z)} f(W,Z)$  is given by  $\frac{1}{|\Omega|} \sum_{(i,n) \in \Omega} e_{in} z_n$ . Similarly, the entry corresponding to  $z_j$  in  $\nabla_{(W,Z)} f(W,Z)$  is given by  $\frac{1}{|\Omega|} \sum_{(d,j) \in \Omega} e_{dj} w_d$ .

- **2.** Given a single rating  $x_{dn}$ , G will be a sparse matrix. The entry corresponding to  $W_d$  will be  $\frac{1}{|\Omega|}e_{dn}z_n$  and that corresponding to  $Z_n$  will be  $\frac{1}{|\Omega|}e_{dn}w_d$ . Rest of the entries will be zero.
- 7. One can observe that only those entries of  $WZ^{\top}$  need to be updated whose row-index corresponds to an updated row of W or column-index corresponds to an updated row of W. Thus, in order to avoid the complete matrix computation after every step, we only need to recompute the dot product of only those row pairs of W and W in which at least one amongst the pair has been updated and update the corresponding entries of  $WZ^{\top}$ .

### **Problem 5 (Alternating Least Squares):**

The entry corresponding to  $w_i$  in  $\nabla_{(\boldsymbol{W})}L(\boldsymbol{W},\boldsymbol{Z})_{ij}$  is given by  $\sum_{(i,n)\in\Omega}e_{in}z_n$ . Setting it to zero and solving, we get  $\sum_{(i,n)\in\Omega}x_{in}z_n=\sum_{(i,n)\in\Omega}(w_i^{\top}z_n)z_n$ . Now, note that  $(w_i^{\top}z_n)z_n$  can be re-written as  $(z_nz_n^{\top})w_i$ . Using this in the previous equation, we get  $w_i=\sum_{(i,n)\in\Omega}(z_nz_n^{\top})^{-1}\sum_{(i,n)\in\Omega}x_{in}z_n$ .

Similarly, we obtain  $z_j = \sum_{(d,j) \in \Omega} (w_d w_d^\top)^{-1} \sum_{(i,n) \in \Omega} x_{dj} w_d$ .

In case of regularized ALS, the updates for  $w_i$  and  $z_j$  become  $\sum_{(i,n)\in\Omega}(z_nz_n^\top+\lambda \boldsymbol{I}_k)^{-1}\sum_{(i,n)\in\Omega}x_{in}z_n$  and  $\sum_{(d,j)\in\Omega}(w_dw_d^\top+\lambda \boldsymbol{I}_k)^{-1}\sum_{(i,n)\in\Omega}x_{dj}w_d$  respectively where k is the number of latent features.