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% Michael Bentivegna, Simon Yoon, Joya Debi
% ECE302 Stochastic Processes Project 5: MMSE FIR
clear;
clc;
close all;
% Summary of Project
% The goal is to design a filter to estimate a signal (target process) and
% achieve an MMSE estimate. Using Wiener filtering formulae, we derived
% theoretical valeus for correlations to be made applicable in the simulation
% of the MMSE estimation. We solve for the impulse response values via the
% linear equations of FIR filter length N. We solve for these normal
% equations for LMMSE.
% length of filter h
N = [4 6 10];
% sigma^2
sigsq = 0.5;
% M is number of samples, process len
M = 1000;
% random vectors
s = 2*randi(2, [M 1]) - 3;
d = sqrt(sigsq) * randn([M 1]);
% need to pad c so that convolution works at Rrr, Rsr[0] index
c = [0 \ 0 \ 1 \ .2 \ .4];
r = conv(s, c, 'same') + d;
for m = 1:length(N)
 % normal equations
    % Rrr autocorrelation
 R_r = zeros([N(m), 1]);
 R_{rr}(1:3) = [1.2 + sigsq .28 .4];
    % Rrr = xcorr(r);
    % Rsr
 R_sr = zeros([N(m), 1]);
 R_sr(1:3) = [1 .2 .4].';
    % Rsr = xcorr(s,r);
 R = R_r(abs((1:N(m)) - (1:N(m)).') + 1);
    Ra = Rrr(abs((1:N(m)) - (1:N(m)).') + 1);
 % solve for h
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% h = inv(R)*R_sr
 h = R \setminus R sr(1:N(m));
    % hA = Ra \setminus Rsr(1:N(m));
 % need to pad h so that it's correctly centered at middle
h = [zeros([N(m)-1 1]); h];
    hA = [zeros([N(m)-1 1]); hA];
 % calculate estimate with our filter
 s_hat = conv(r, h, 'same');
    % s_hatA = conv(r, hA , 'same');
 % calculate and print mse
mse = mean((s-s_hat).^2);
    % mseA = mean((s-s_hatA).^2);
 fprintf('Theoretical: N=%d: MSE=%f\n', N(m), mse);
    % fprintf('Via xcorr: N=%d: MSE=%f\n', N(m), mseA);
end
% The MSE is low, but not much better than random guessing at 0.5. Changing
% the sigma squared significantly changes performance, but N is too small
% for minute changes to be observed.
Theoretical: N=4: MSE=0.474677
Theoretical: N=6: MSE=0.476575
Theoretical: N=10: MSE=0.476370
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