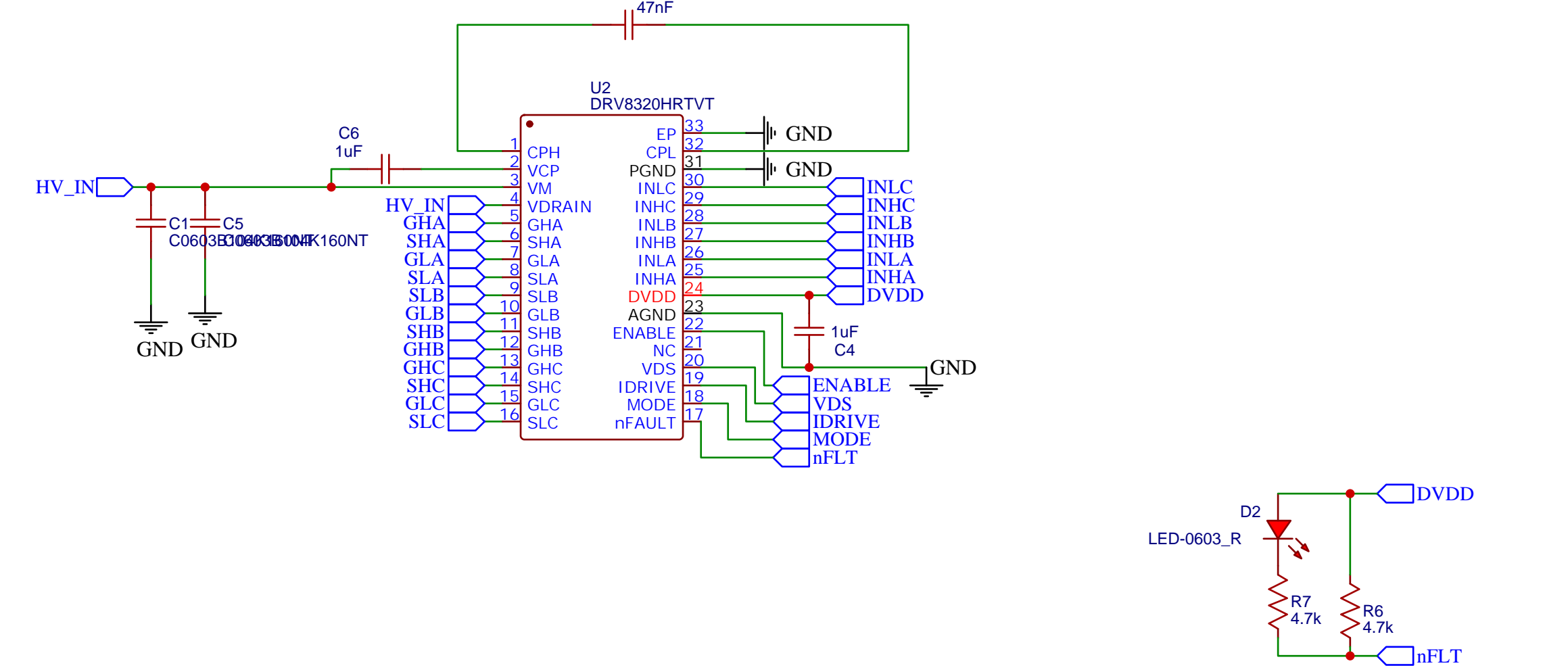
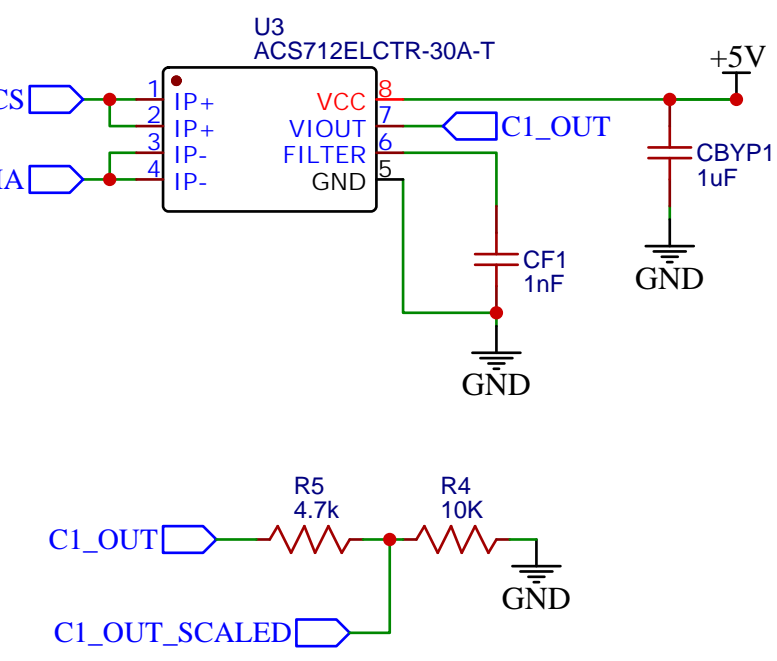
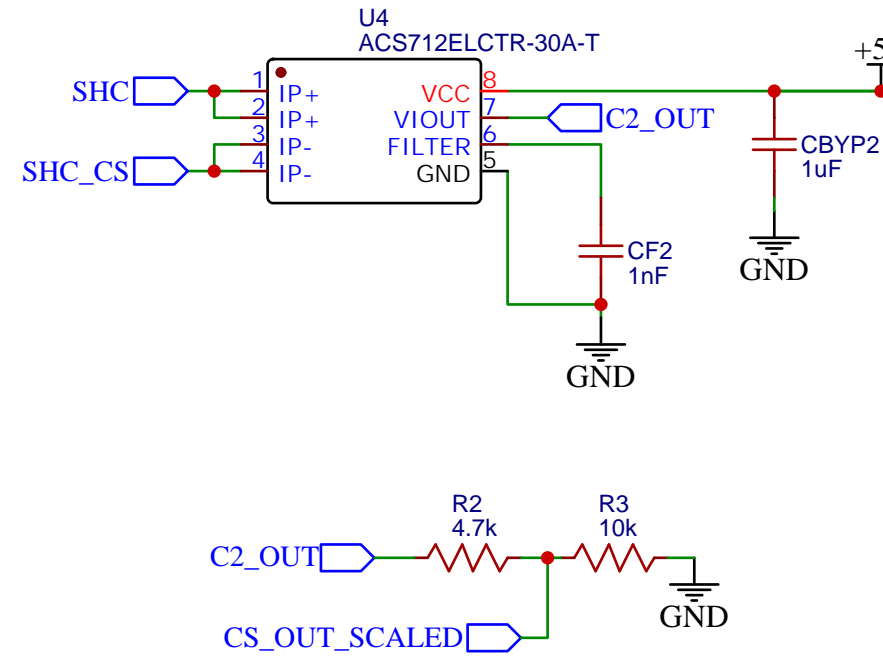


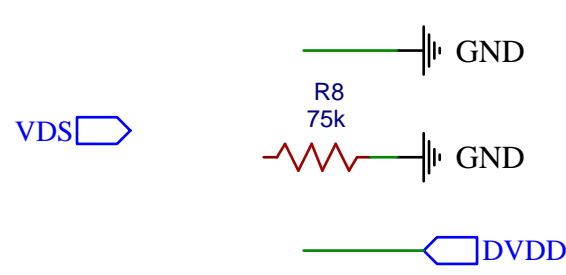
DRV8320H Gate driver circuit



ACS712 Current Sense Circuit

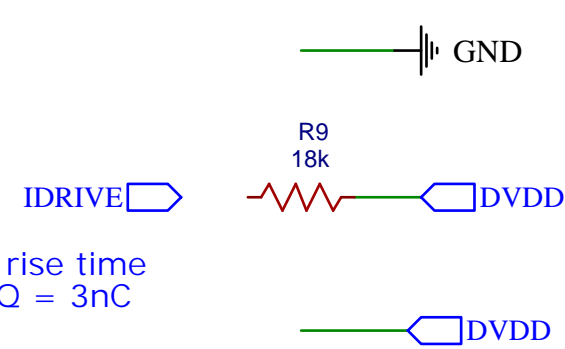


VDS config



VDS
voltage between SHx and SLx
limiting the voltage to limit the current
max current 50Amps (1_OCP= 4us impulse)
drain-source resistance 5mOhm
 $VDS = 50A \cdot 0.005Ohm = 0.25V$
configuration
VDS = Tied to AGND 0.06V
VDS = 18 k \pm 5% Tied to AGND 0.13V
VDS = 75 k \pm 5% Tied to AGND 0.26V
VDS = Hi-Z 0.6V (BEST)
VDS = 75 k \pm 5% Tied to DVDD 1.13VV
VDS = 18 k \pm 5% Tied to DVDD 1.88

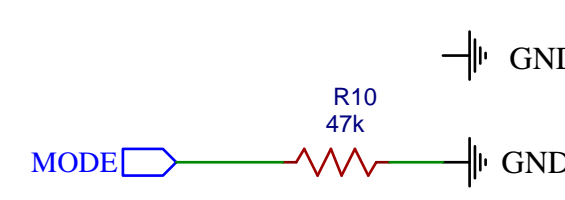
IDRIVE config



IDRIVE IDRIVE
 Setting the target gate current
 directly determining the mosfet rise time
 our mosfet gate-source charge $Q = 3nC$
 rise time = $Q/IDRIVE$ (pp 66)
 we want the rise time of 50ns
 $IDRIVE = Q/50ns = 0.06A$

configuration
IDRIVE = Tied to AGND 10mA
IDRIVE = 18 k \pm 5% tied to AGND 30mA
IDRIVE = 75 k \pm 5% tied to AGND 60mA
IDRIVE = Hi-Z 120mA
IDRIVE = 75 k \pm 5% tied to DVDD 260mA
IDRIVE = 18 k \pm 5% tied to DVDD 570mA
IDRIVE = Tied to DVDD 1000mA

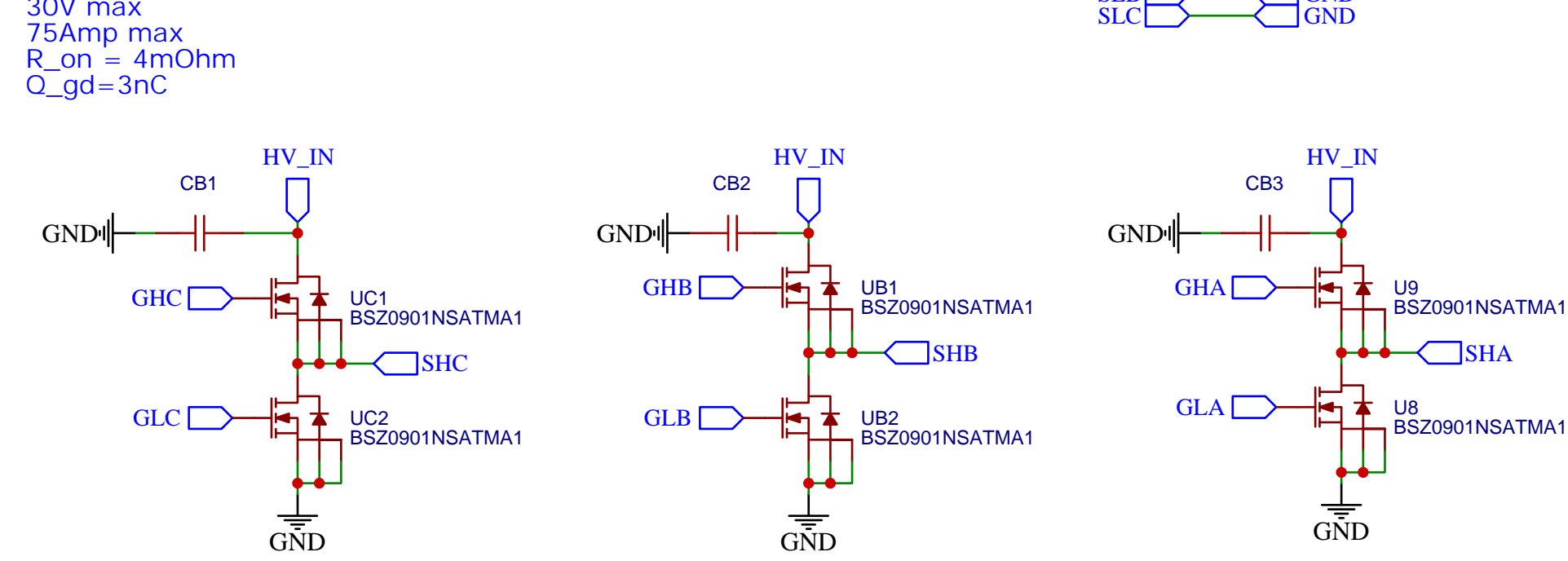
MODE config



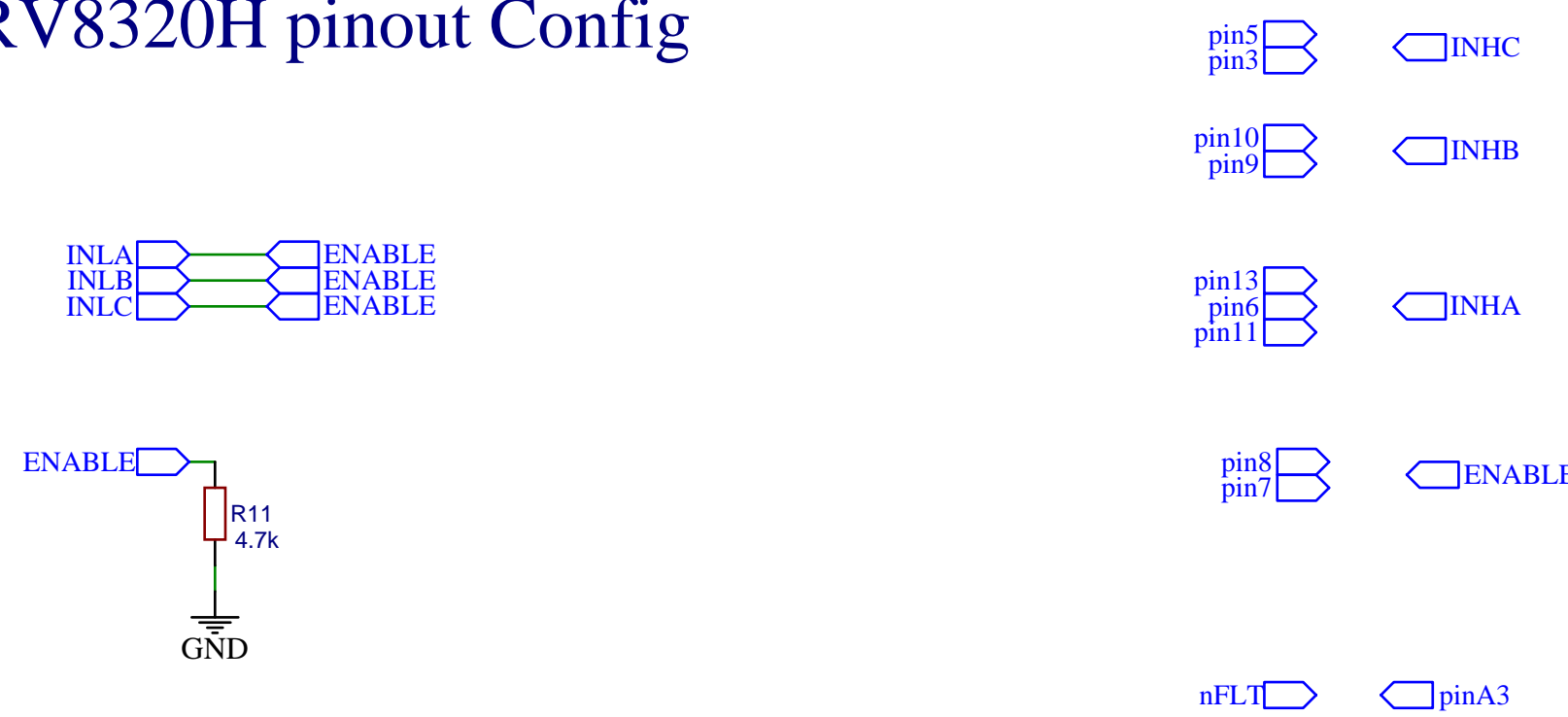
```
MODE
Setting the 3xPWM mode
Option for 6xPWM as well
pp 31

configuration
MODE - 00b = Tied to AGND 6xPWM
MODE - 01b= 47 k  $\pm$  5% tied to AGND 3xPWM
...
```

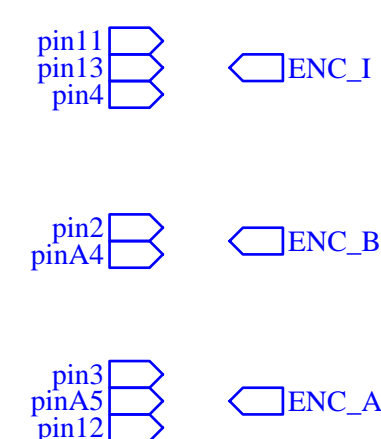
3x3mm MOSFETs (ex.BSZ0904NSI)



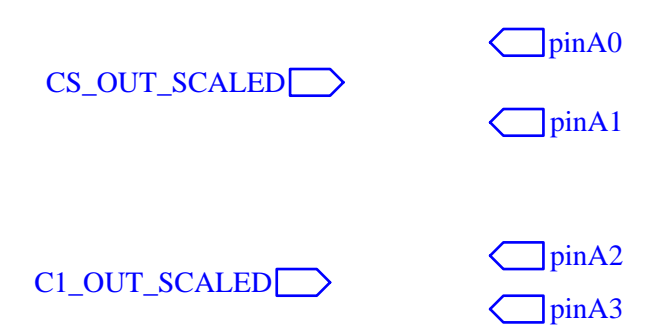
DRV8320H pinout Config



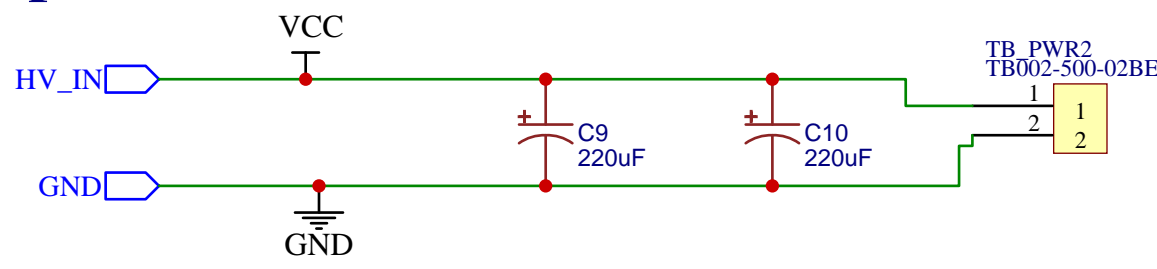
Encoder/Hall pinout config



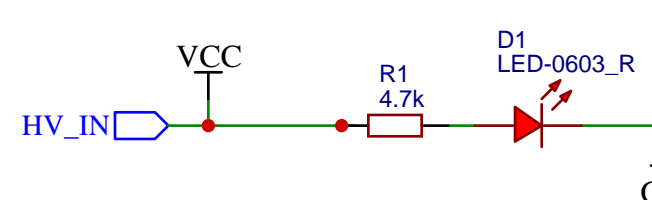
Current Sense Pin Config



Capacitors



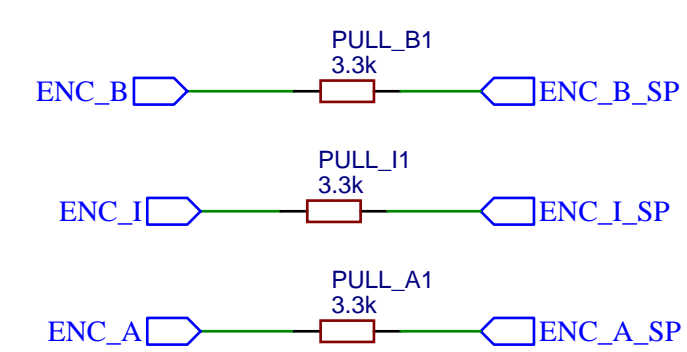
LED Circuit



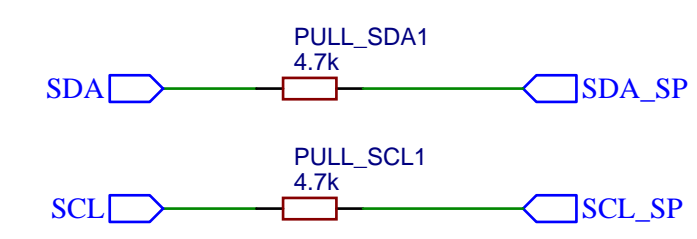
5/3.3V VDD selector



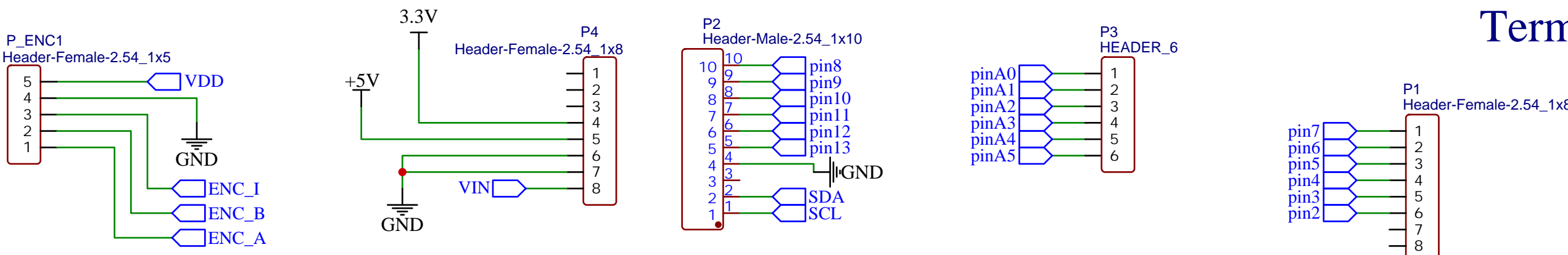
Enable/Disable Pullups Config



I2C



Arduino Header R3
Encoder/Hall Interface
Terminal blocks: Power + Motor



Motor output terminal

