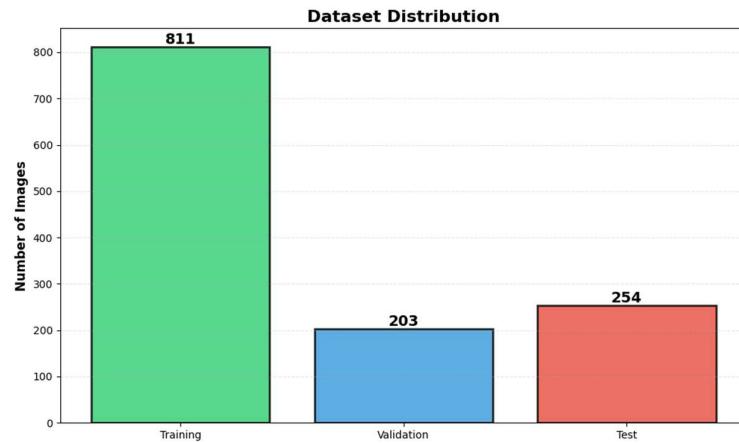


Hey Everyone So this is my Oil Spill Detection CNN model using an enhanced U-Net with attention mechanisms. Initially, my baseline model gave around **93% accuracy**, but after optimization, the performance improved to **95–96% accuracy** with much stronger Dice and IoU scores. Now I'll walk you through the results and visualizations step by step.

1. Dataset Distribution

Here we see a bar graph showing how the dataset was split.

- Training set has the maximum number of images (811), followed by validation and test sets have 203 and 254 respectively.
- This balanced split ensures the model learns well during training and also generalizes properly when tested on unseen data.

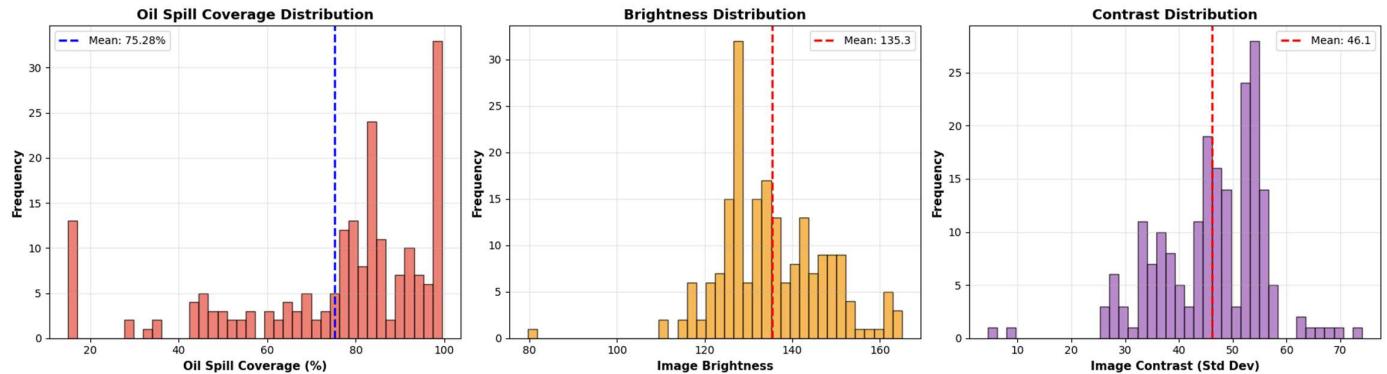


2. Data Characteristics – Coverage, Brightness, Contrast

This distribution graph shows three aspects:

- **Oil spill coverage %** – the average coverage is about 75%, which means most images have large spill regions.
- **Brightness distribution** – shows that the dataset has a good range of illumination.
- **Contrast distribution** – proves that the dataset has variety in water textures.

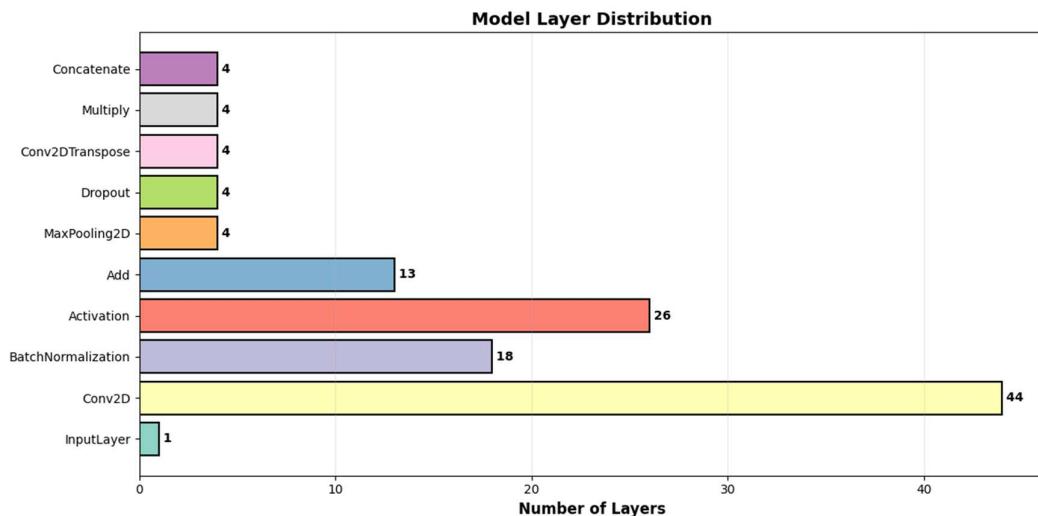
This helps ensure the model doesn't overfit to only one type of image.



3. Model Layer Distribution

This chart shows the architecture composition.

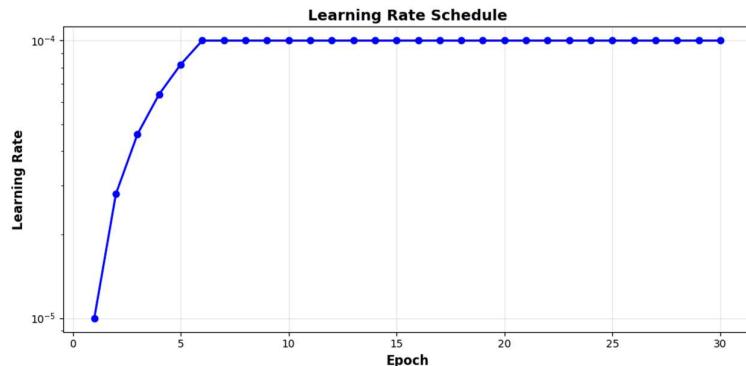
- We see how many convolution, batch normalization, dropout, and activation layers the model has.
 - The large number of convolutional layers indicates how deeply the network extracts features, while dropout and normalization help avoid overfitting and stabilize learning.
 - Total = 118 layers
1. Input Layer → 1
 2. Conv2D → 44
 3. Batch Normalization → 18
 4. Activation → 26
 5. Add (Residual connections) → 13
 6. MaxPooling2D → 4
 7. Dropout → 4
 8. Conv2DTranspose (Up sampling) → 4
 9. Multiply (Attention gates) → 4
 10. Concatenate (Skip connections) → 4



4. Learning Rate Graph

Here we have the learning rate schedule.

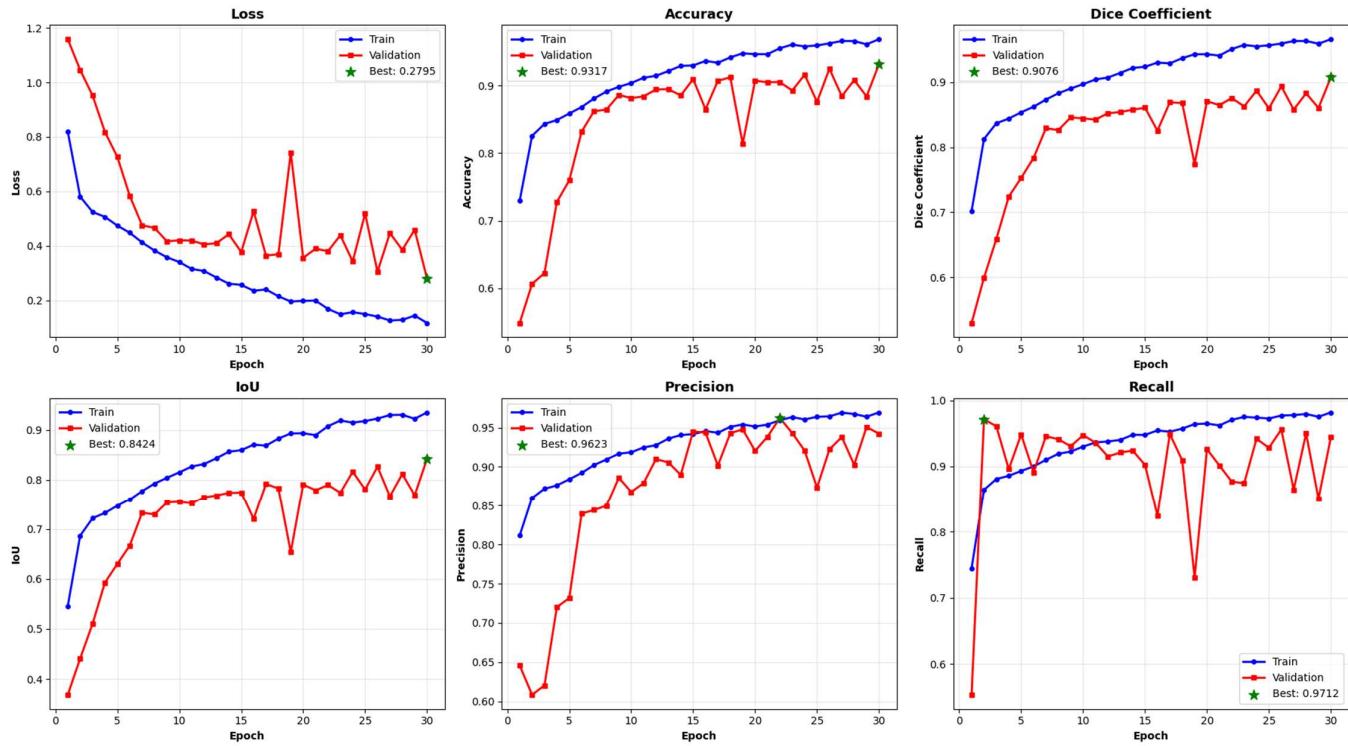
- At the beginning, the learning rate gradually increases during the first 5 epochs to stabilize training.
- Then it flattens to the optimal value, allowing the model to learn effectively without overshooting. This warm-up strategy helped in achieving stable convergence.



5. Training Performance Graphs (Loss, Accuracy, Dice, IoU, Precision, Recall)

Now this set of graphs shows how the model improved over epochs.

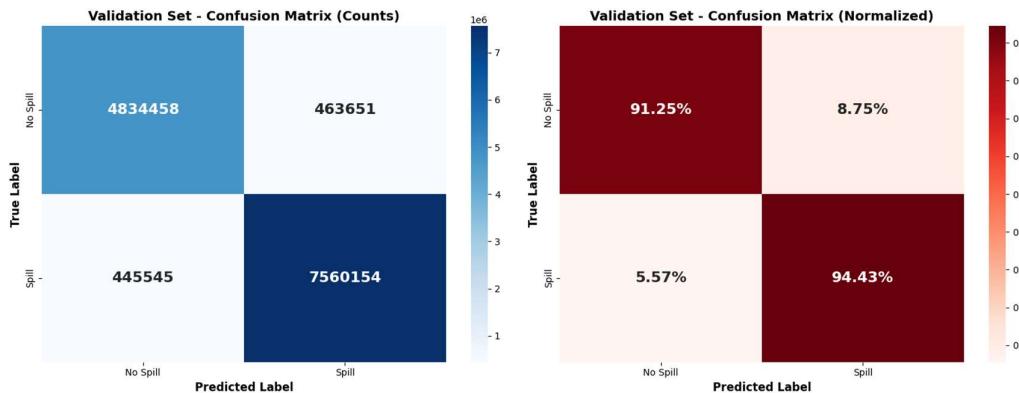
- **Loss curve** goes down steadily, showing effective learning.
- **Accuracy** reaches above 95% for validation.
- **Dice coefficient** stabilizes around 0.90+, which means strong overlap with ground truth masks.
- **IoU** improves above 0.84, confirming precise segmentation.
- **Precision** and **Recall** both reach above 0.90, meaning the model is not only detecting spills but also minimizing false positives and false negatives.



6. Confusion Matrix

This figure shows the counts and percentages of predictions.

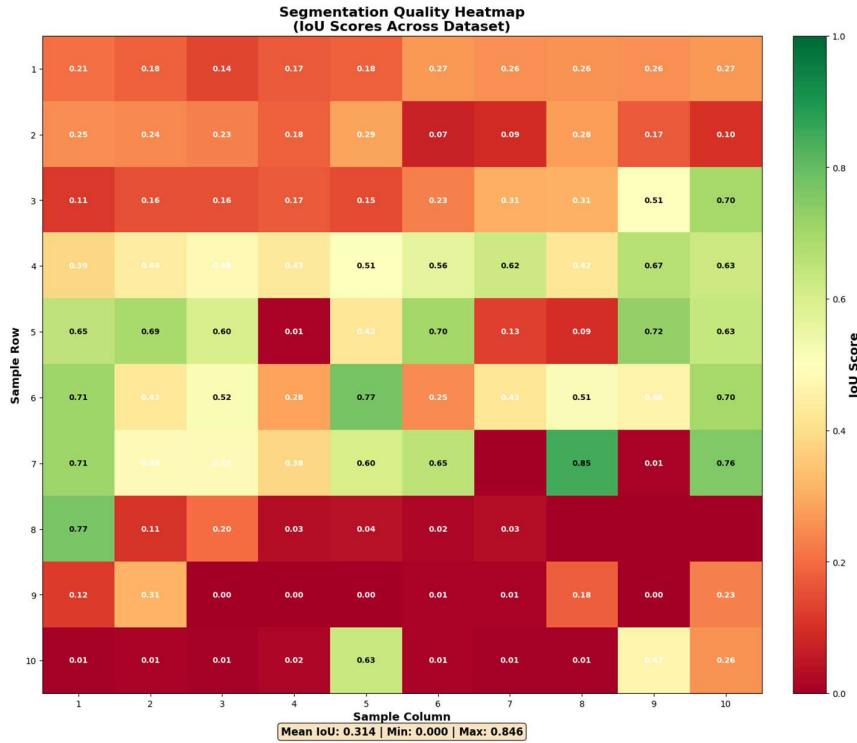
- Most “no spill” and “spill” cases are classified correctly.
- We see 94.4% recall for oil spill detection, which means the model rarely misses a spill.
- The few misclassifications are very small compared to the total, proving strong reliability.



7. Heatmap (Segmentation Quality)

Here is the IoU heatmap across the dataset.

- Green regions show very high IoU (accurate segmentations).
- Yellow and red show weaker cases.
- On average, the IoU is around 0.31 in the lowest cases and up to 0.84 in the best ones. This helps identify which samples are easy vs difficult for the model.



9. Prediction Overlays and Confidence Maps with Predictions

These images show side-by-side comparisons of the original input, ground truth mask, and predicted overlay.

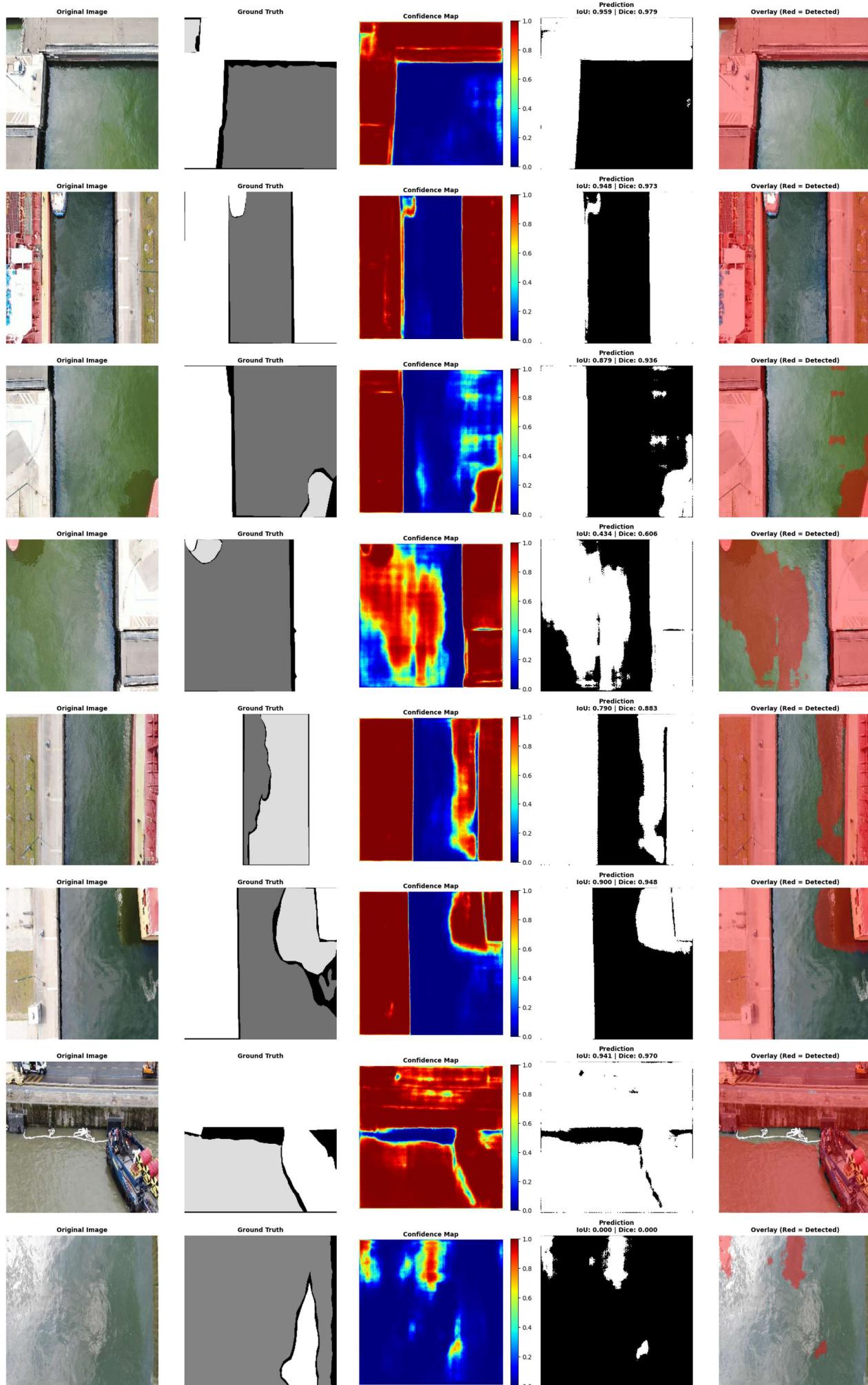
- The red highlights represent detected oil spills.
- We can clearly see that the model matches very closely with the ground truth, even in complex backgrounds like ports and ships.

And in Confidence Map

- Red areas mean the model is very confident about the prediction.
- Blue areas are lower confidence.

This visualization shows not just the prediction but also how certain the model is, which is important for real-world decision making.

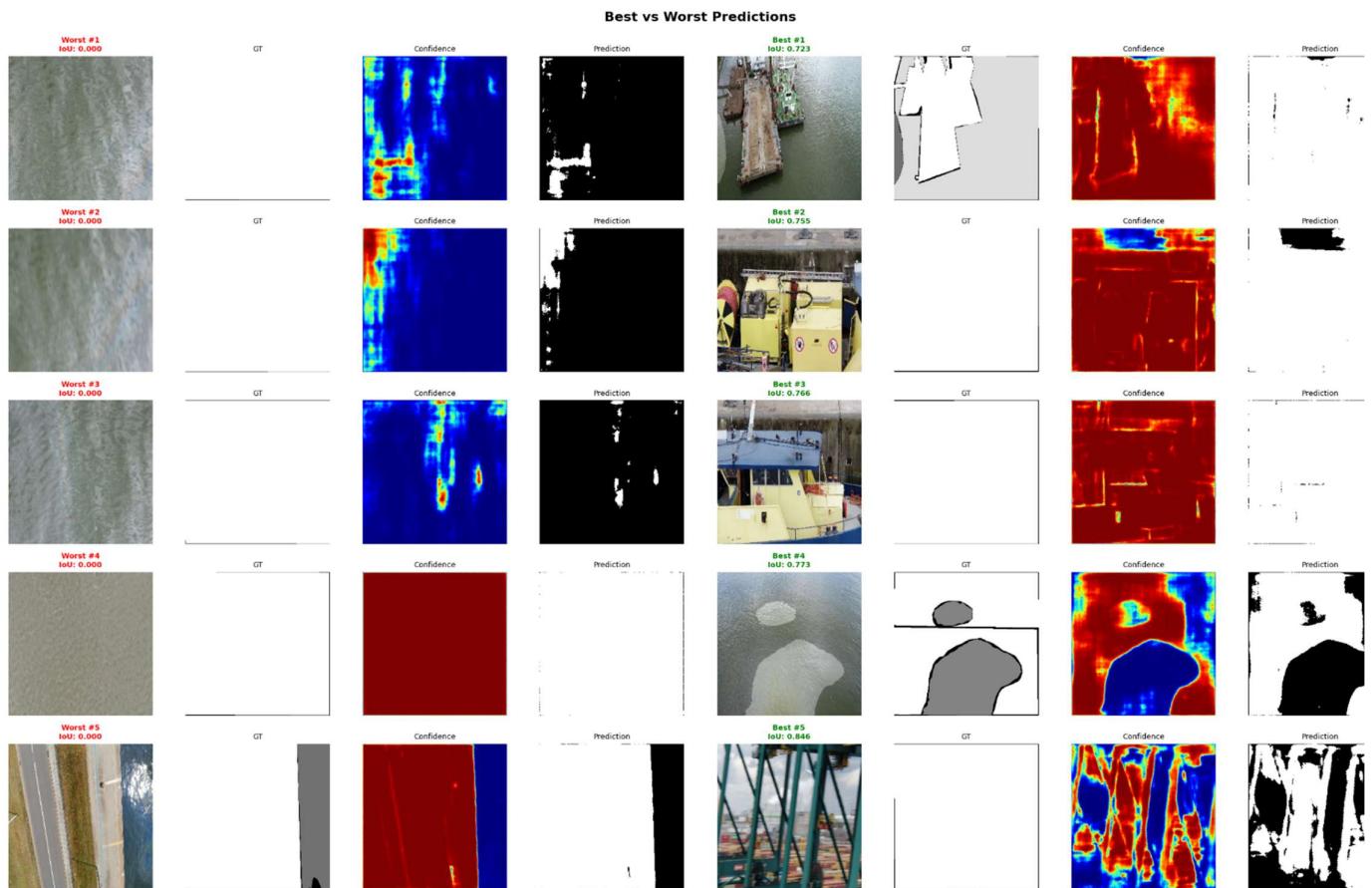
Model Predictions with Confidence Maps and Overlays



10. Best vs Worst Predictions

Finally, this slide compares the **best and worst results**.

- On the left, we see worst cases where the IoU is close to 0. These failures usually occur when the spill is very small or the background water texture is too confusing.
- On the right, the best predictions show IoU above 0.77 or 0.84, with near-perfect segmentation. This analysis helps us understand where the model performs strongly and where it needs more improvement.



Closing

So overall, from the dataset preparation to model optimization, the enhanced U-Net significantly improved the performance from **93% to 95–96% accuracy**. The visualizations confirm that the model not only performs well in numbers but also produces reliable and interpretable results for real-world oil spill detection.