ESP for V and W in the GIS and CIS algorithms, T=10 Triple State - SD State - SE SD-SE CIS 100 -**ESP** 1.00 10 -0.75 | signal - 0.1 - 0.00 | signal 0.1 0.50 0.25 0.1 -0.00 0.01 -100 0.01 100 0.01 0.01 V = noise