ESP for V and W in the GIS and CIS algorithms, T=1000 Triple State - SD State - SE SD-SE CIS 100 -**ESP** 1.00 10 -0.75 0.1 signal 100 0.1 -0.50 0.25 100 -10 -0.1 -0.00 0.01 -100 0.01 0.01 V = noise