

# SIMRAN MANN

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## EDUCATION

<b>Simon Fraser University</b> <i>Bachelor of Applied Science – Computing Science</i>	Sept 2022 – April 2027 GPA: 4.04/4.33
<b>Relevant courses:</b> Distributed Systems, Compilers, Computer Architecture, Operating Systems	

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## TECHNICAL SKILLS

**Programming Languages:** C/C++, Python, x86-64 Assembly, Bash, Java  
**Embedded Systems & Firmware:** STM32 MCUs, SPI, I2C, GPIO, DMA, DAC, ADC, Interrupts, RTOS  
**Software Tools:** Visual Studio Code, STM32Cube IDE, Git, Linux/Unix , Docker

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## PROJECTS

<b>Concurrent Data Structures Benchmarking</b> – Academic Project	October 2025
<ul style="list-style-type: none"><li>Implemented and benchmarked various concurrent data structures such as non-blocking Queues, Stacks and Sets with multi-producer/multi-consumer test suites.</li><li>Addressed ABA problems via version-tagged pointers and CAS, analyzed throughput, scalability, and contention bottlenecks.</li></ul>	
<b>C Language Compiler</b> – Academic Project	June - August 2025
<ul style="list-style-type: none"><li>Developed a compiler for a C-like language using Flex/Bison and LLVM IR, including SSA-form code generation and short-circuit evaluation</li><li>Gained practical experience with parsing, semantic analysis, and machine code generation pipelines</li><li>Built C runtime and Python scripts to automate testing, validating compilation and execution of code</li></ul>	
<b>Digital Embedded Clock</b> – Personal Project	April - May 2025
<ul style="list-style-type: none"><li>Developed a digital clock with real-time display, date/time adjustments, and alarm functionality on an embedded MCU</li><li>Implemented touchscreen functionality using interrupt-driven event handling to allow efficient data updates.</li></ul>	

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## EXPERIENCE

<b>SFU Robot Soccer – Firmware Developer</b>	May 2025 – Present
<ul style="list-style-type: none"><li>Designed and implemented the basestation firmware, enabling robots to receive and parse commands through UART from the software team and relay commands via LoRa to the motherboards for each robot</li><li>Contribute to motherboard firmware development and testing, ensuring real-time task scheduling and responses</li><li>Collaborate in a multidisciplinary team spanning firmware, software, and electronics to achieve robust match-ready performance</li></ul>	
<b>NETGEAR - Orbi Software Test Engineer</b>	Sep 2024 – April 2025
<ul style="list-style-type: none"><li>Developed a tool to parse UART serial output. Debugged, tested, and resolved issues with UART interfaces on devices.</li><li>Automated the main test plan, reducing test time from a full day to 2 hours.</li><li>Designed and maintained two automation testbeds used daily to verify device stability and performance</li><li>Automated a repetitive task involving rebooting or resetting a router or satellite, parsing raw console data to check that all interfaces were up, and calculating average boot-up time over multiple iterations.</li><li>Used Docker to transfer the automated tests onto all lab PCs without any setup issues.</li><li>Logged and tracked bugs using Jira, documented test reports and automated plans in Confluence.</li></ul>	