Image features exercise

Complete and hand in this completed worksheet (including its outputs and any supporting code outside of the worksheet) with your assignment submission. For more details see the <u>assignments page</u> (http://vision.stanford.edu/teaching/cs175/assignments.html) on the course website.

We have seen that we can achieve reasonable performance on an image classification task by training a linear classifier on the pixels of the input image. In this exercise we will show that we can improve our classification performance by training linear classifiers not on raw pixels but on features that are computed from the raw pixels.

All of your work for this exercise will be done in this notebook.

```
In [1]:
```

```
import random
import numpy as np
from cs175.data_utils import load_CIFAR10
import matplotlib.pyplot as plt

from __future__ import print_function

%matplotlib inline
plt.rcParams['figure.figsize'] = (10.0, 8.0) # set default size of plots
plt.rcParams['image.interpolation'] = 'nearest'
plt.rcParams['image.cmap'] = 'gray'

# for auto-reloading extenrnal modules
# see http://stackoverflow.com/questions/1907993/autoreload-of-modules-in-ipytho
n
%load_ext autoreload
%autoreload 2
```

Load data

Similar to previous exercises, we will load CIFAR-10 data from disk.

```
from cs175.features import color histogram hsv, hog feature
def get CIFAR10 data(num training=49000, num validation=1000, num test=1000):
    # Load the raw CIFAR-10 data
    cifar10 dir = 'cs175/datasets/cifar-10-batches-py'
    X train, y train, X test, y test = load CIFAR10(cifar10 dir)
    # Subsample the data
   mask = list(range(num_training, num training + num validation))
   X val = X train[mask]
   y_val = y_train[mask]
   mask = list(range(num training))
   X_train = X_train[mask]
   y train = y train[mask]
   mask = list(range(num test))
   X_test = X_test[mask]
   y_test = y_test[mask]
    return X train, y train, X val, y val, X test, y test
X train, y train, X val, y val, X test, y test = get CIFAR10 data()
```

Extract Features

For each image we will compute a Histogram of Oriented Gradients (HOG) as well as a color histogram using the hue channel in HSV color space. We form our final feature vector for each image by concatenating the HOG and color histogram feature vectors.

Roughly speaking, HOG should capture the texture of the image while ignoring color information, and the color histogram represents the color of the input image while ignoring texture. As a result, we expect that using both together ought to work better than using either alone. Verifying this assumption would be a good thing to try for the bonus section.

The hog_feature and color_histogram_hsv functions both operate on a single image and return a feature vector for that image. The extract_features function takes a set of images and a list of feature functions and evaluates each feature function on each image, storing the results in a matrix where each column is the concatenation of all feature vectors for a single image.

```
from cs175.features import *
num color bins = 10 # Number of bins in the color histogram
feature fns = [hog feature, lambda img: color histogram hsv(img, nbin=num color
bins)]
X_train_feats = extract_features(X_train, feature_fns, verbose=True)
X_val_feats = extract_features(X_val, feature_fns)
X test feats = extract features(X test, feature fns)
# Preprocessing: Subtract the mean feature
mean feat = np.mean(X train feats, axis=0, keepdims=True)
X train feats -= mean feat
X_val_feats -= mean_feat
X test feats -= mean feat
# Preprocessing: Divide by standard deviation. This ensures that each feature
# has roughly the same scale.
std feat = np.std(X train feats, axis=0, keepdims=True)
X_train_feats /= std_feat
X val feats /= std feat
X test feats /= std feat
# Preprocessing: Add a bias dimension
X train feats = np.hstack([X train_feats, np.ones((X_train_feats.shape[0], 1))])
X_val_feats = np.hstack([X_val_feats, np.ones((X_val_feats.shape[0], 1))])
X_test_feats = np.hstack([X_test_feats, np.ones((X_test_feats.shape[0], 1))])
```

```
Done extracting features for 1000 / 49000 images
Done extracting features for 2000 / 49000 images
Done extracting features for 3000 / 49000 images
Done extracting features for 4000 / 49000 images
Done extracting features for 5000 / 49000 images
Done extracting features for 6000 / 49000 images
Done extracting features for 7000 / 49000 images
Done extracting features for 8000 / 49000 images
Done extracting features for 9000 / 49000 images
Done extracting features for 10000 / 49000 images
Done extracting features for 11000 / 49000 images
Done extracting features for 12000 / 49000 images
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Done extracting features for 43000 / 49000 images
Done extracting features for 44000 / 49000 images
Done extracting features for 45000 / 49000 images
Done extracting features for 46000 / 49000 images
Done extracting features for 47000 / 49000 images
Done extracting features for 48000 / 49000 images
```

Train SVM on features

Using the multiclass SVM code developed earlier in the assignment, train SVMs on top of the features extracted above; this should achieve better results than training SVMs directly on top of raw pixels.

```
In [4]:
# Use the validation set to tune the learning rate and regularization strength
from cs175.classifiers.linear classifier import LinearSVM
learning rates = [1e-9, 1e-8, 1e-7]
regularization strengths = [5e4, 5e5, 5e6]
results = {}
best val = -1
best svm = None
# TODO:
# Use the validation set to set the learning rate and regularization strength. #
# This should be identical to the validation that you did for the SVM; save
                                                                 #
# the best trained classifer in best svm. You might also want to play
                                                                 #
# with different numbers of bins in the color histogram. If you are careful
                                                                 #
# you should be able to get accuracy of near 0.44 on the validation set.
                                                                 #
for lr in learning rates:
   for reg in regularization strengths:
      svm=LinearSVM()
      svm.train(X train feats, y train, learning rate=lr, reg=reg, num iters=8
00)
      y train pred = svm.predict(X train feats)
      y val pred=svm.predict(X val feats)
      accuracy train=np.mean(y train==y train pred)
      accuracy val=np.mean(y val==y val pred)
      results[(lr, reg)] = (accuracy train, accuracy val)
      if accuracy val > best val:
         best val = accuracy val
         best svm = svm
END OF YOUR CODE
# Print out results.
for lr, reg in sorted(results):
   train accuracy, val accuracy = results[(lr, reg)]
   print('lr %e reg %e train accuracy: %f val accuracy: %f' % (
             lr, reg, train accuracy, val accuracy))
print('best validation accuracy achieved during cross-validation: %f' % best val
```

```
lr 1.000000e-09 reg 5.000000e+04 train accuracy: 0.089122 val accura
cy: 0.089000
lr 1.000000e-09 reg 5.000000e+05 train accuracy: 0.098878 val accura
cy: 0.086000
lr 1.000000e-09 reg 5.000000e+06 train accuracy: 0.080653 val accura
cy: 0.066000
lr 1.000000e-08 reg 5.000000e+04 train accuracy: 0.102286 val accura
cy: 0.097000
lr 1.000000e-08 reg 5.000000e+05 train accuracy: 0.146102 val accura
cy: 0.158000
lr 1.000000e-08 reg 5.000000e+06 train accuracy: 0.417408 val accura
cy: 0.419000
lr 1.000000e-07 reg 5.000000e+04 train accuracy: 0.203388 val accura
cy: 0.202000
lr 1.000000e-07 reg 5.000000e+05 train accuracy: 0.411429 val accura
cy: 0.418000
lr 1.000000e-07 reg 5.000000e+06 train accuracy: 0.360224 val accura
cy: 0.348000
best validation accuracy achieved during cross-validation: 0.419000
```

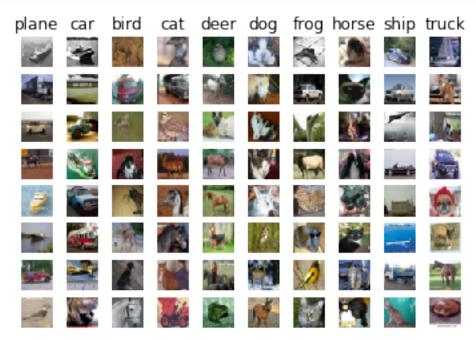
In [5]:

```
# Evaluate your trained SVM on the test set
y_test_pred = best_svm.predict(X_test_feats)
test_accuracy = np.mean(y_test == y_test_pred)
print(test_accuracy)
```

0.427

```
In [6]:
```

```
# An important way to gain intuition about how an algorithm works is to
# visualize the mistakes that it makes. In this visualization, we show examples
# of images that are misclassified by our current system. The first column
# shows images that our system labeled as "plane" but whose true label is
# something other than "plane".
examples_per_class = 8
classes = ['plane', 'car', 'bird', 'cat', 'deer', 'dog', 'frog', 'horse', 'ship'
, 'truck'l
for cls, cls name in enumerate(classes):
    idxs = np.where((y test != cls) & (y test pred == cls))[0]
    idxs = np.random.choice(idxs, examples per class, replace=False)
    for i, idx in enumerate(idxs):
        plt.subplot(examples per class, len(classes), i * len(classes) + cls + 1
)
        plt.imshow(X test[idx].astype('uint8'))
        plt.axis('off')
        if i == 0:
            plt.title(cls name)
plt.show()
```



Inline question 1:

Describe the misclassification results that you see. Do they make sense?

From the above classification we can see that HOG feature is not able to classify the images to correct classes as different images grouped together under a particular class have something in common with respect to each other for instance colors seem to be somewhat similar.

Neural Network on image features

Earlier in this assignment we saw that training a two-layer neural network on raw pixels achieved better classification performance than linear classifiers on raw pixels. In this notebook we have seen that linear classifiers on image features outperform linear classifiers on raw pixels.

For completeness, we should also try training a neural network on image features. This approach should outperform all previous approaches: you should easily be able to achieve over 55% classification accuracy on the test set; our best model achieves about 60% classification accuracy.

```
In [7]:
print(X_train_feats.shape)
(49000, 155)
In [8]:
from cs175.classifiers.neural_net import TwoLayerNet
input dim = X train feats.shape[1]
hidden dim = 500
num classes = 10
best net = None
# TODO: Train a two-layer neural network on image features. You may want to
                                                                   #
# cross-validate various parameters as in previous sections. Store your best
                                                                   #
# model in the best net variable.
                                                                   #
# get rid of this line for lr in learning rates:
best val = -1
results = {}
learning rates = [1e-2,1e-1,1]
regularization_strengths = [1e-4,1e-5]
for lr in learning rates:
   for reg in regularization strengths:
      net = TwoLayerNet(input dim, hidden dim, num classes)
      net.train(X train feats, y train, X val feats, y val,
                 num iters=3000, batch size=200,
                 learning rate=lr, learning rate decay=0.95,
                 reg=reg)
      y train pred = net.predict(X train feats)
```

```
acc_train = np.mean(y_train == y_train_pred)
       y val pred = net.predict(X val feats)
       acc_val = np.mean(y_val == y_val_pred)
       results[(lr, reg)] = (acc train, acc val)
       if best val < acc val:</pre>
          best val = acc val
          best net = net
# Print out results.
for lr, reg in sorted(results):
   train accuracy, val accuracy = results[(lr, reg)]
   print('lr %e reg %e train accuracy: %f val accuracy: %f' % (
              lr, reg, train accuracy, val accuracy))
print('best validation accuracy achieved during cross-validation: %f' % best val
END OF YOUR CODE
lr 1.000000e-02 reg 1.000000e-05 train accuracy: 0.260327 val accura
cy: 0.272000
lr 1.000000e-02 reg 1.000000e-04 train accuracy: 0.256694 val accura
cy: 0.272000
lr 1.000000e-01 reg 1.000000e-05 train accuracy: 0.588980 val accura
cy: 0.559000
lr 1.000000e-01 reg 1.000000e-04 train accuracy: 0.588857 val accura
cy: 0.564000
lr 1.000000e+00 reg 1.000000e-05 train accuracy: 0.864816 val accura
cy: 0.557000
lr 1.000000e+00 reg 1.000000e-04 train accuracy: 0.844449 val accura
cy: 0.573000
best validation accuracy achieved during cross-validation: 0.573000
In [9]:
# Run your neural net classifier on the test set. You should be able to
# get more than 55% accuracy.
test acc = (net.predict(X test feats) == y test).mean()
print(test acc)
```

Bonus: Design your own features!

You have seen that simple image features can improve classification performance. So far we have tried HOG and color histograms, but other types of features may be able to achieve even better classification performance.

For bonus points, design and implement a new type of feature and use it for image classification on CIFAR-10. Explain how your feature works and why you expect it to be useful for image classification. Implement it in this notebook, cross-validate any hyperparameters, and compare its performance to the HOG + Color histogram baseline.

Bonus: Do something extra!

Use the material and code we have presented in this assignment to do something interesting. Was there another question we should have asked? Did any cool ideas pop into your head as you were working on the assignment? This is your chance to show off!