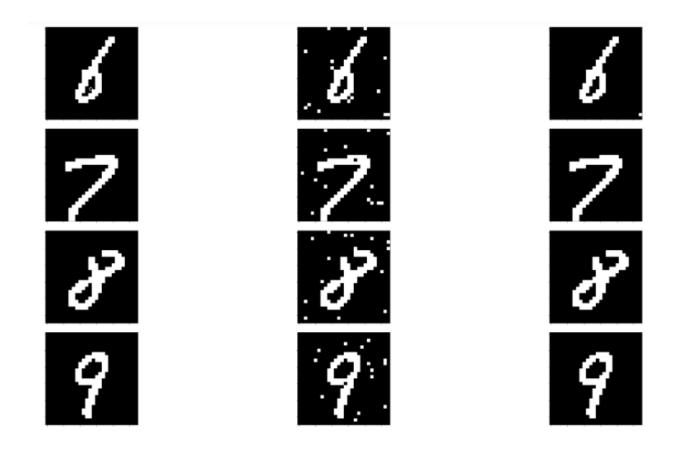
1. Average accuracy on the first 500 images: 99.48571%

```
#Report the fraction of all pixels that are correct in the 500 images.
print("The accuracy between true images and denoised image:",(np.sum(pic==denoised_images)/(784*500))*100,"%")
The accuracy between true images and denoised image: 99.4857142857143 %
```

2. One set of sample images for each digit -- For each digit you should put up a row of a (sample image, noised version, denoised version via MFI). This means should have a total of 30 images (10 rows, 3 columns).

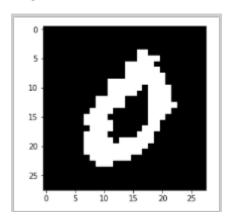
The Image is reconstructed with theta_ij(Hi_Hj)=0.2 and theta_ij(Hi_Xj)=0.2 I took the best reconstructed images.

True Image Noisy Image Reconstructed Image

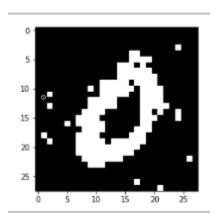


Best reconstruction (original, noisy, denoised):
 The Image is reconstructed with theta_ij(Hi_Hj)=0.2 and theta_ij(Hi_Xj)=0.2

Original iMAGE

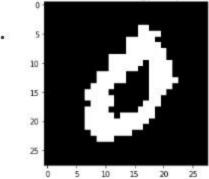


Noisy



Reconstructed

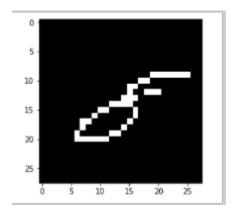
The most accurate reconstruction with theta_ij (Hi,Hj)=0.2 and theta_ij (Hi,Xj)=0.2



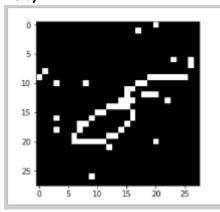
4. Worst reconstruction (original, noisy, denoised)

The Image is reconstructed with theta_ij(Hi_Hj)=0.2 and theta_ij(Hi_Xj)=0.2

Ortginal

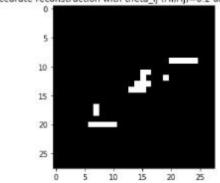


Noisy



Reconstructed

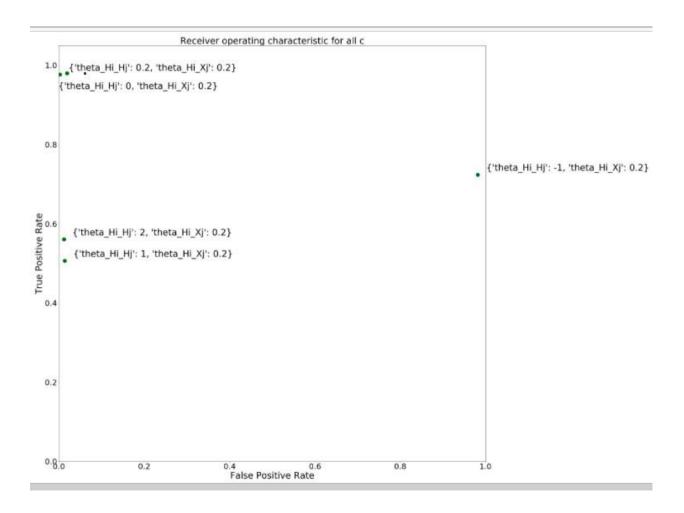
The least accurate reconstruction with theta_ij (Hi,Hj)=0.2 and theta_ij (Hi,Xj)=0.2



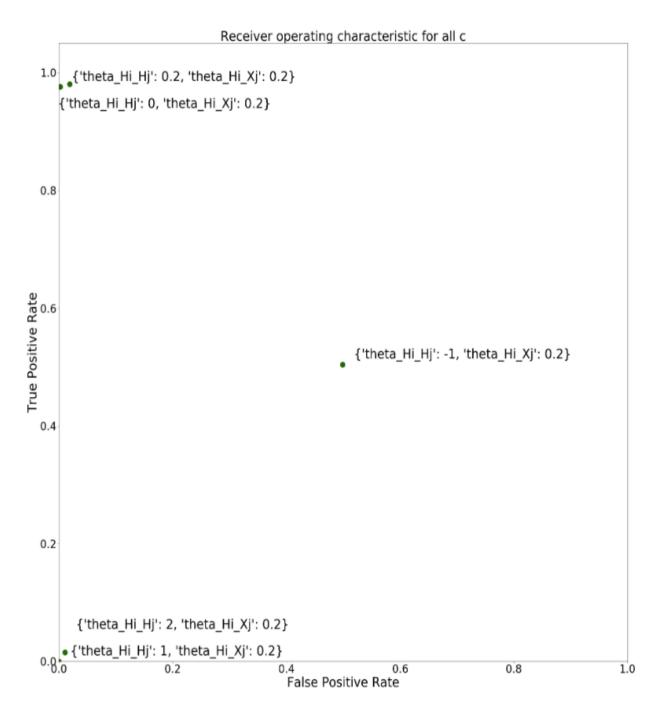
5. ROC curve:

Two Instances;

1. When I don't use updated value of pi (While updating pi for every pixel in a particular iteration)



2. When I use the updated value of pi ((While updating pi for every pixel in a particular iteration))



6. Code snippet:

Importing Libraries

```
In [1]: import os
import struct
import numpy as np
import pandas as pd
%matplotlib inline
import matplotlib.pyplot as plt
#import tensorflow as tf
import numpy as np
from sklearn.metrics import confusion_matrix
import matplotlib.gridspec as gridspec
```

Binarize the Data set

Adding random Noise to the data set

```
In [11]: #Create Noisy Data (Randomly)

X_train_noisy=np.copy(Train[:,1:785])#.values)
y_train_noisy=np.copy(Train[:,0])#.values)

In [12]: for i in range(0,X_train.shape[0]):
    bits_to_flip = np.random.choice(784,15,replace=False)
    for j in range(len(bits_to_flip)):
        X_train_noisy[i,bits_to_flip[j]] = (X_train_noisy[i,bits_to_flip[j]])*-1
```

Boltzamn Denoising Calculation (When I don't use the updated value of pi)

```
#Denoising the image
def boltzman(pic,theta_H,theta_X):
 pi_output=[[] for k in range(500)]
 min_error=0.1
 for i in range(len(pic)):
      pi=np.ones((28,28))*0.5
     pi_prev=np.ones((28,28))*0.5
      for 1 in range(30):
              for j in range(pic[i].shape[0]):
                  for k in range(pic[i].shape[0]):
                        z=0
                        if(j>0):
                            z=z+((theta_H)*((2*pi_prev[j-1,k])-1))
                        if(j<27):
                            z=z+((theta_H)*((2*pi_prev[j+1,k])-1))
                        if(k>0):
                            z=z+((theta_H)*((2*pi_prev[j,k-1])-1))
                        if(k<27):
                            z=z+((theta_H)*((2*pi_prev[j,k+1])-1))
                        z=z+(pic[i,j,k]*(theta_X))
                        pi[j,k]=(np.exp(z))/((np.exp(z)+np.exp(-z)))
             pi_prev=np.copy(pi)
      pi_output[i]=pi
 return pi_output
```

```
#Denoising the image
def boltzman(pic,theta_H,theta_X):
  pi_output=[[] for k in range(500)]
  min_error=0.1
  for i in range(len(pic)):
      pi=np.ones((28,28))*0.5
      pi_prev=np.ones((28,28))*0.5
      for 1 in range(50):
               for j in range(pic[i].shape[0]):
    for k in range(pic[i].shape[0]):
                          z=0
                          if(j>0):
                               z=z+((theta_H)*((2*pi[j-1,k])-1))
                           if(j<27):
                               z=z+((theta_H)*((2*pi[j+1,k])-1))
                           if(k>0):
                               z=z+((theta_H)*((2*pi[j,k-1])-1))
                           if(k<27):
                               z=z+((theta_H)*((2*pi[j,k+1])-1))
                           z=z+(pic[i,j,k]*(theta_X))
                           pi[j,k]=(np.exp(z))/((np.exp(z)+np.exp(-z)))
               pi_prev=np.copy(pi)
      pi_output[i]=pi
  return pi_output
```

Boltzman Output

```
#output->Boltzman
def result(pi_updated):

for i in range(500):
    for j in range(28):
        for k in range(28):
            if(pi_updated[i,j,k]>0.5):
            pi[i,j,k]=1

        else:
            pi_updated[i,j,k]=-1
    return pi
```

Creating the ROC Curves

```
#ROC Curve
# theta_ij (Hi,Hj)(Xi,Xj)[(-1,0.2),(0,0.2),(0.2,0.2),(1,0.2),(2,0.2)]
R P=[]
R F=[]
for theta in [(-1,0.2),(0,0.2),(0.2,0.2),(1,0.2),(2,0.2)]:
  tp=0
  fp=0
  labels=[]
  TPR=np.sum(pic==1)
  FPR=np.sum(pic==-1)
  pi=np.array(boltzman(pic noisy,theta[0],theta[1]))
  denoised_images=np.array(result(pi))
  for i in range(500):
    for j in range(28):
       for k in range(28):
          if(denoised_images[i,j,k]==1 and pic[i,j,k]==1):
              tp=tp+1
          elif(denoised_images[i,j,k]==1 and pic[i,j,k]==-1):
              fp=fp+1
 R P.append(tp/TPR)
  print("True Positive", tp)
  R F.append(fp/FPR)
  print("False Positive", fp)
```

```
plt.figure()
lw = 2
plt.rcParams['figure.figsize'] = [30,30]
types = {{"theta_Hi_Hj":-1, "theta_Hi_Xj":0.2},{"theta_Hi_Hj":0,"theta_Hi_Xj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.2},{"theta_Hi_Kj":0.
```