



IBM Developer
SKILLS NETWORK

Winning Space Race with Data Science

<Name>

<Date>



Outline

- Executive Summary
- Introduction
- Methodology
- Results
- Conclusion
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Executive Summary



SUMMARY OF
METHODOLOGIES



THE DATA WAS FIRST
COLLECTED THROUGH TWO
METHODS: API AND
WEBSCRAPING, BOTH VIA
PUBLIC SOURCES.



THEN THE DATA HAS BEEN
ANALYSED VIA METHODS SUCH
AS EDA, DATA WRANGLING
AND INTERACTIVE VISUAL
ANALYTICS TO GENERATE
INSIGHTS, AS WELL AS
MACHINE LEARNING.



THE PROCESS SHOWED DATA
CAN BE COLLECTED IN
DIFFERENT WAYS.



ALSO, NOT ALL MACHINE
LEARNING ALGORITHMS ARE
EQUALLY PERFORMANT, AS WE
FOUND OUT THAT DECISION
TREES WAS THE BEST
PERFORMER TO PREDICT IF A
ROCKET WOULD LAND
SUCCESSFULLY OR NOT.

Introduction

- Project background and context
- The objective of the work was to find ways to predict the successful landing or not of SpaceX rockets, using ML instead of rocket science. We also generated further insights regarding the context surrounding SpaceX landings, such as maps of best location for launches for instance.
- All of this would help assess costs encountered by SpaceX for launches, to see if SpaceY could compete.
- Problems you want to find answers
- In the notebooks, we tried to figure out what algorithm was the most performant to predict the outcome of the rocket's landing.

Section 1

Methodology

Methodology



Data collection methodology:

Data was collected through the SpaceX public API and through webscraping (https://en.wikipedia.org/wiki/List_of_Falcon_9_and_Falcon_Heavy_launches).



Perform data wrangling

After cleaning and analysis of the features, the data was labelled (successful or not).



Perform exploratory data analysis (EDA) using visualization and SQL



Perform interactive visual analytics using Folium and Plotly Dash



Perform predictive analysis using classification models

After the data wrangling, the data was split into test and train sets. Four machine learning algorithms were then applied and compared, using classification methods.

Data Collection

SpaceX API v4: <https://api.spacexdata.com/v4/rockets> It contains data on the launch of rockets. The data was retrieved using a get request.

Data was also collected by using webscraping of this wikipedia link: https://en.wikipedia.org/wiki/List_of_Falcon_9_and_Falcon_Heavy_launches.

Data Collection. - SpaceX API

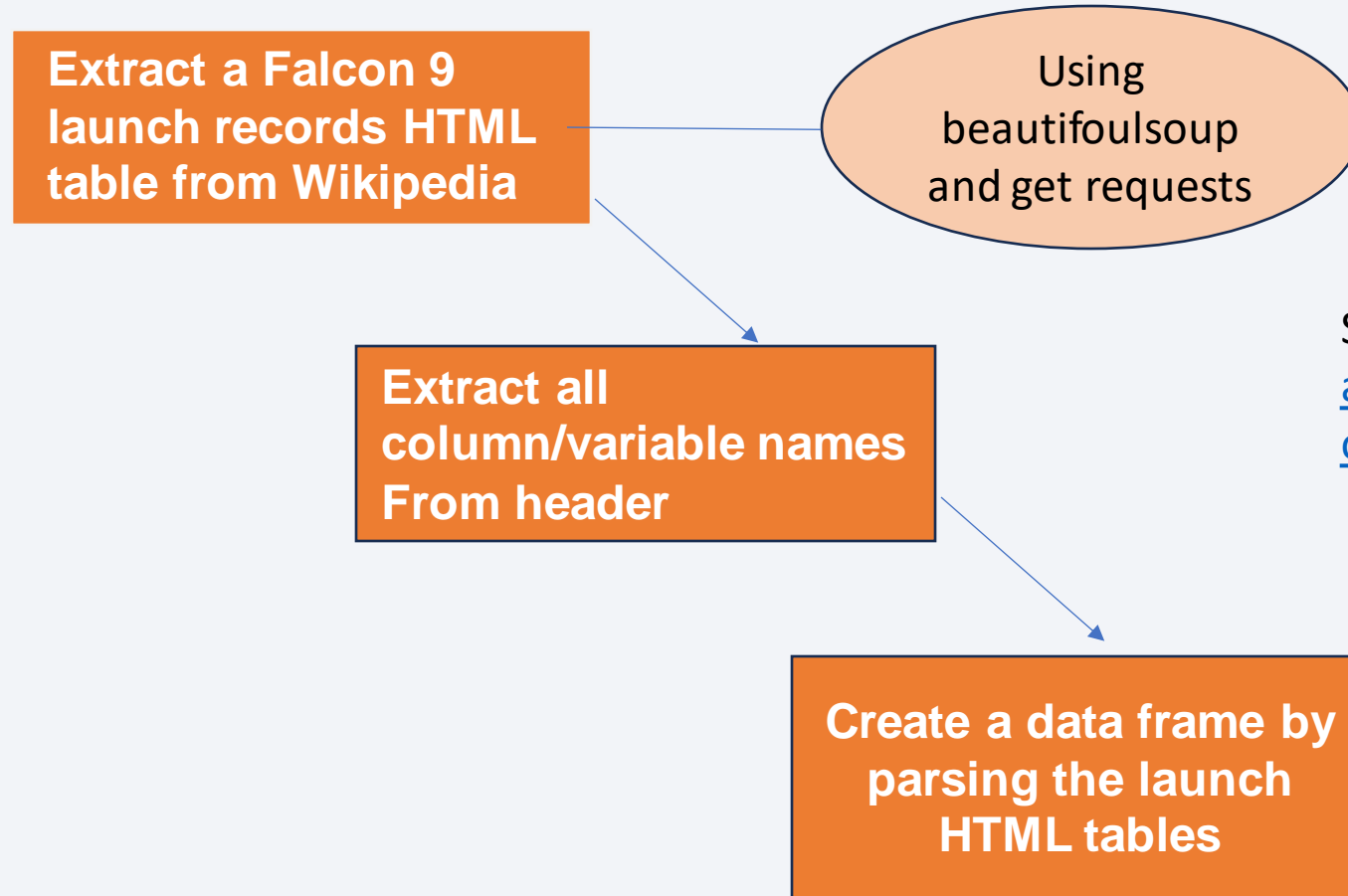
Source: [https://github.com/sinali/capstone_spaceX/blob/main/1 Data collection API.ipynb](https://github.com/sinali/capstone_spaceX/blob/main/1%20Data%20collection%20API.ipynb)

Data retrieved through
get request of the link

Filter the dataframe to
only include Falcon
9 launches

Data wrangling:
remove missing values

Data Collection - Wikipedia webscraping



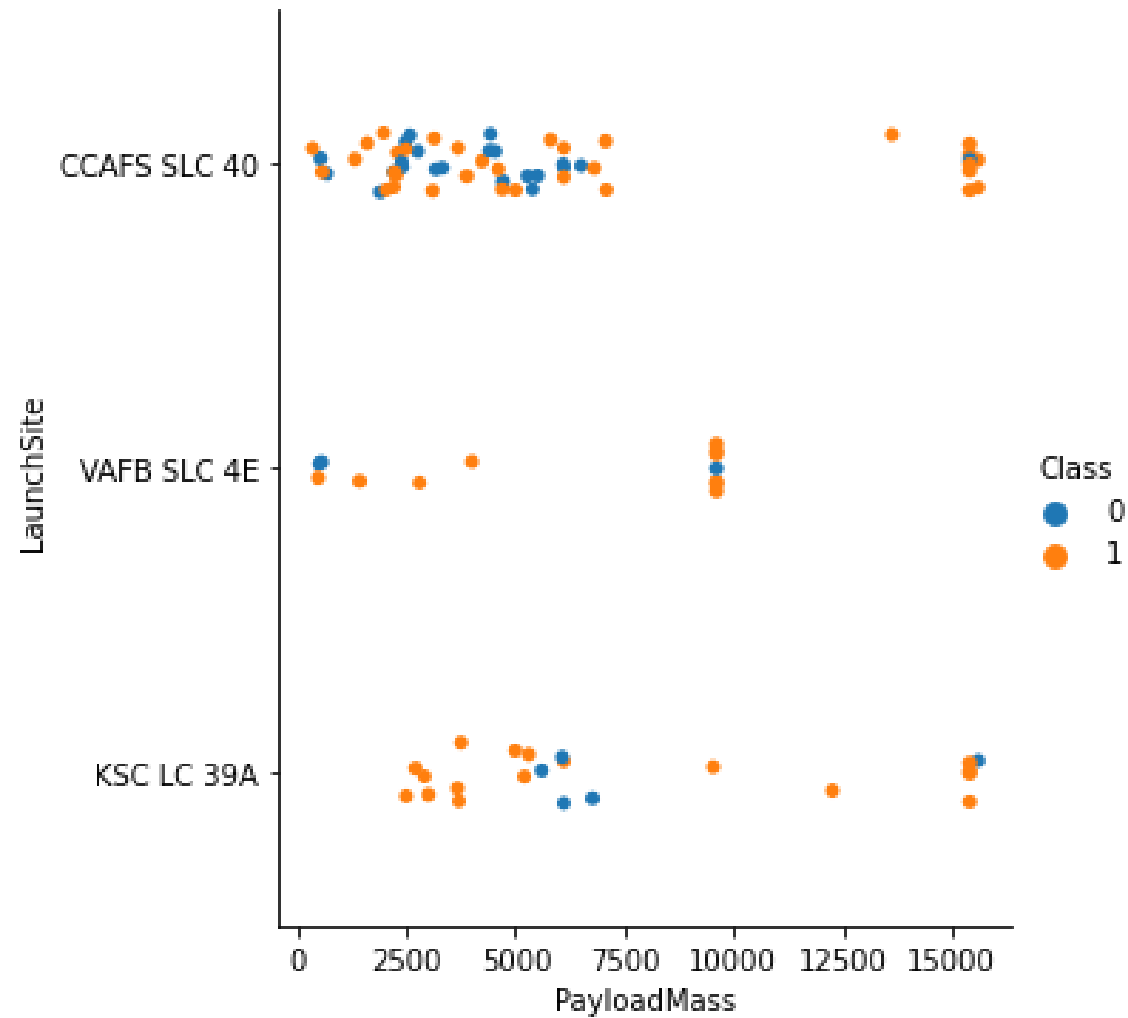
Source: https://github.com/sinali/capstone_spaceX/blob/main/1B_Data_Collection_Webscraping.ipynb

Data Wrangling

- Exploratory Data Analysis (EDA) to find some patterns in the data and determine what would be the label for training supervised models



- https://github.com/sina-ali/capstone_spaceX/blob/main/1C_Daya_Wrangling.ipynb



EDA with Data Visualization

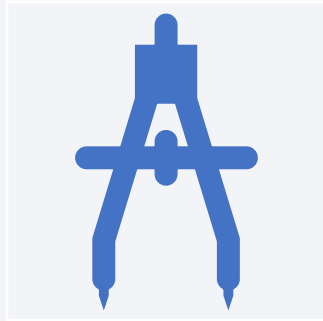
- The objective was to study the relationship between pairs of features, so barcharts and scatterplots were mainly used for this. For instance, this below is a scatterplot of the relationship between LaunchSite and PayloadMass.

- Source: https://github.com/sina-ali/capstone_spaceX/blob/main/2B_EDA_Visualisation_Lab.ipynb

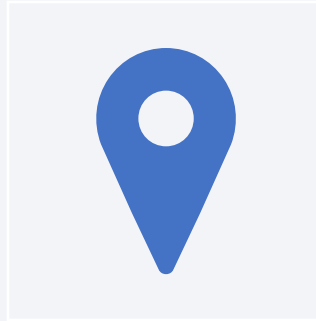
EDA with SQL

- Using bullet point format, summarize the SQL queries you performed
- Add the GitHub URL of your completed EDA with SQL notebook, as an external reference and peer-review purpose

Build an Interactive Map with Folium



On this Folium Interactive Map, markers show launch locations, circles show specific highlighted locations, lines show the distance between two coordinates, and finally, marker clusters show multiple markers at once, e.g. when multiple launch sites happen in one location.



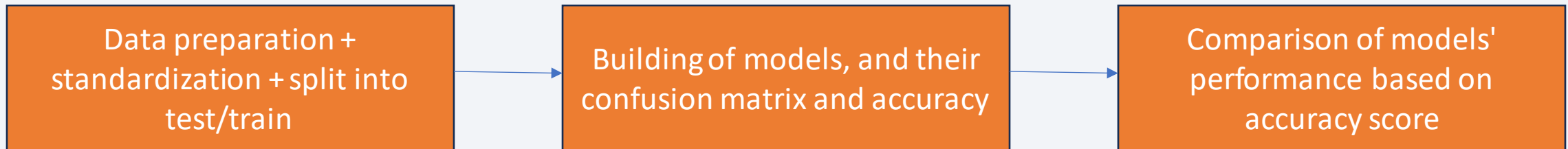
These objects give us explanations of events happening according to their geographical location and help make the map interactive.



Source: https://github.com/singali/capstone_spaceX/blob/main/3_Interactive_Visualisation_Folium.ipynb

Predictive Analysis (Classification)

- To classify our data, four ML models were built: logistic regression, SVM, decision tree, KNN. Their hyperparameters were then tuned with GridSearch to improve their individual accuracy score. In the end, their score were compared and decision trees was the best performer.



- https://github.com/sina-ali/capstone_spaceX/blob/main/4_Machine_Learning.ipynb

Results — EDA



Exploratory data analysis results:



The first launch of SpaceX was in 2015.



Almost all missions have successful outcomes: only two failures in 2015.

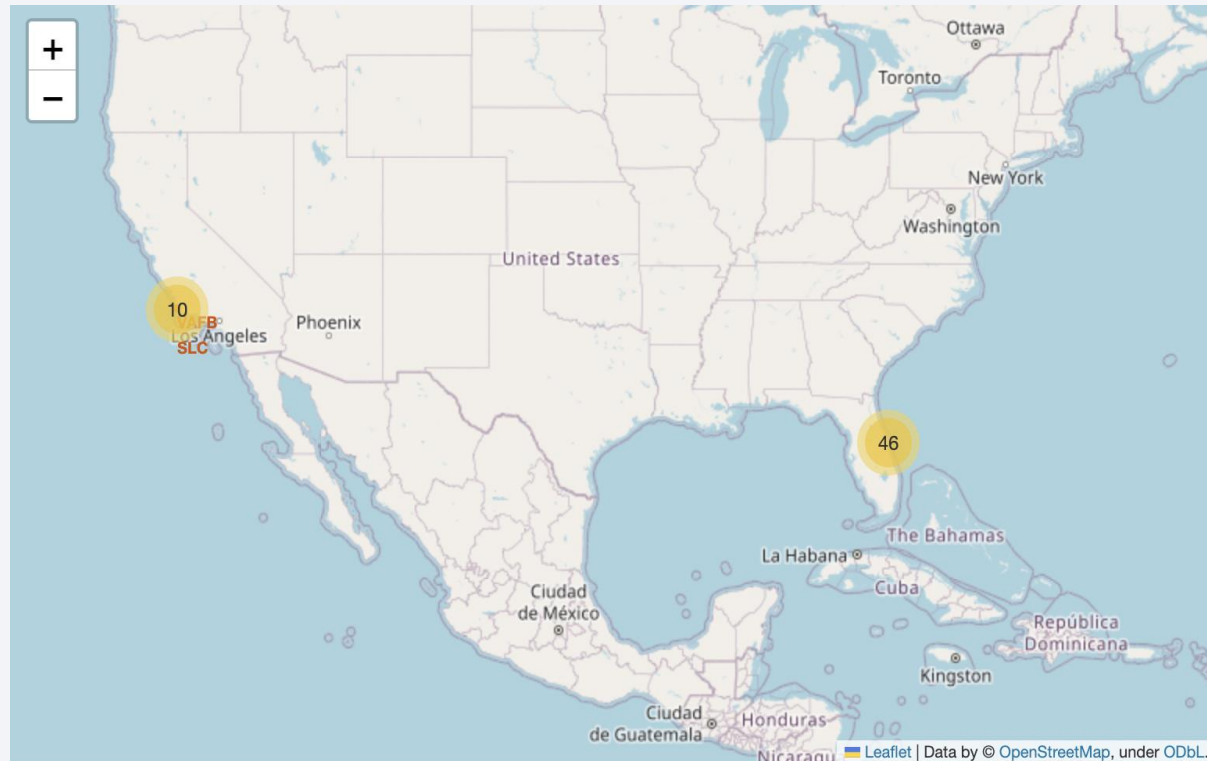


They are realized mainly near coastlines.

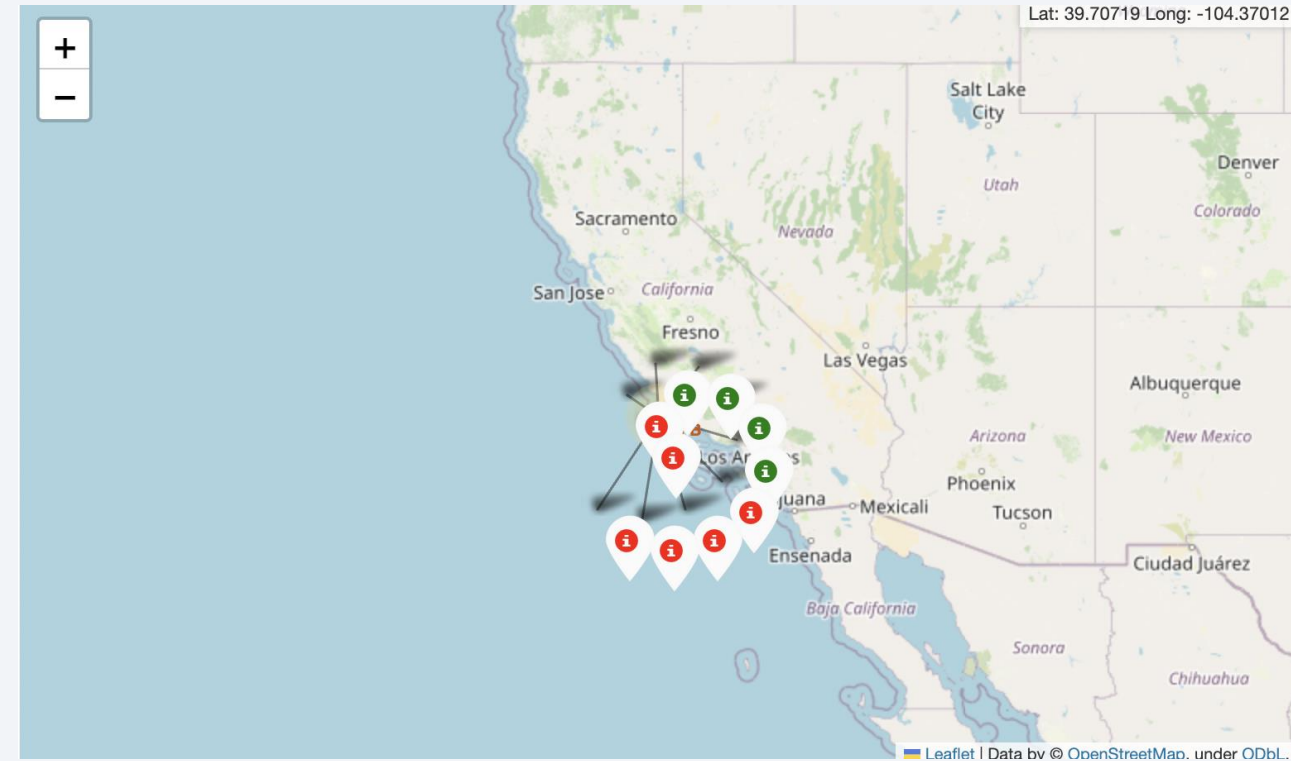


The average payload of f9 v1.1 is 2,298 kg.

Results – Interactive analytics



There are more launches on the East coast than the West coast (46 vs 10).



Multiples launches happen at the same location.

Results — Predictive analysis

- The classification applied on our data indicates that the best performer out of all four ML models was decision trees, with an accuracy score of 0.875.

```
Logistic Regression Accuracy: 0.8464285714285713  
SVM Accuracy: 0.8482142857142856  
Decision Tree Accuracy: 0.875  
KNN Accuracy: 0.8482142857142858  
Decision Tree is the best performing method.
```

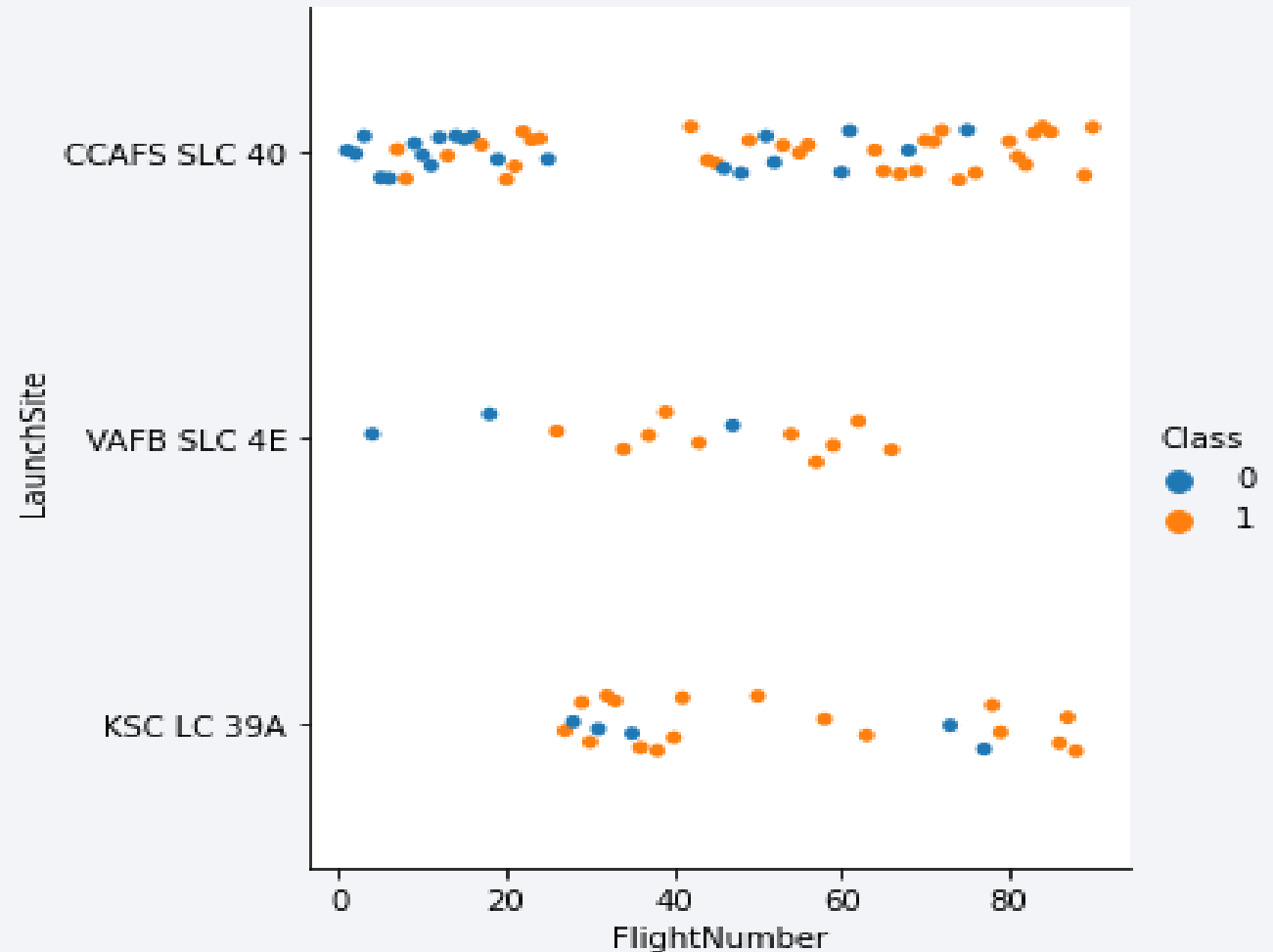

The background of the slide is an abstract composition. It features a dark blue field on the left side, which transitions into a complex pattern of diagonal streaks in shades of blue, red, and teal on the right. These streaks have a textured, almost woven appearance. Overlaid on this pattern is a faint, light blue grid that recedes into the distance, creating a sense of depth and perspective.

Section 2

Insights drawn from EDA

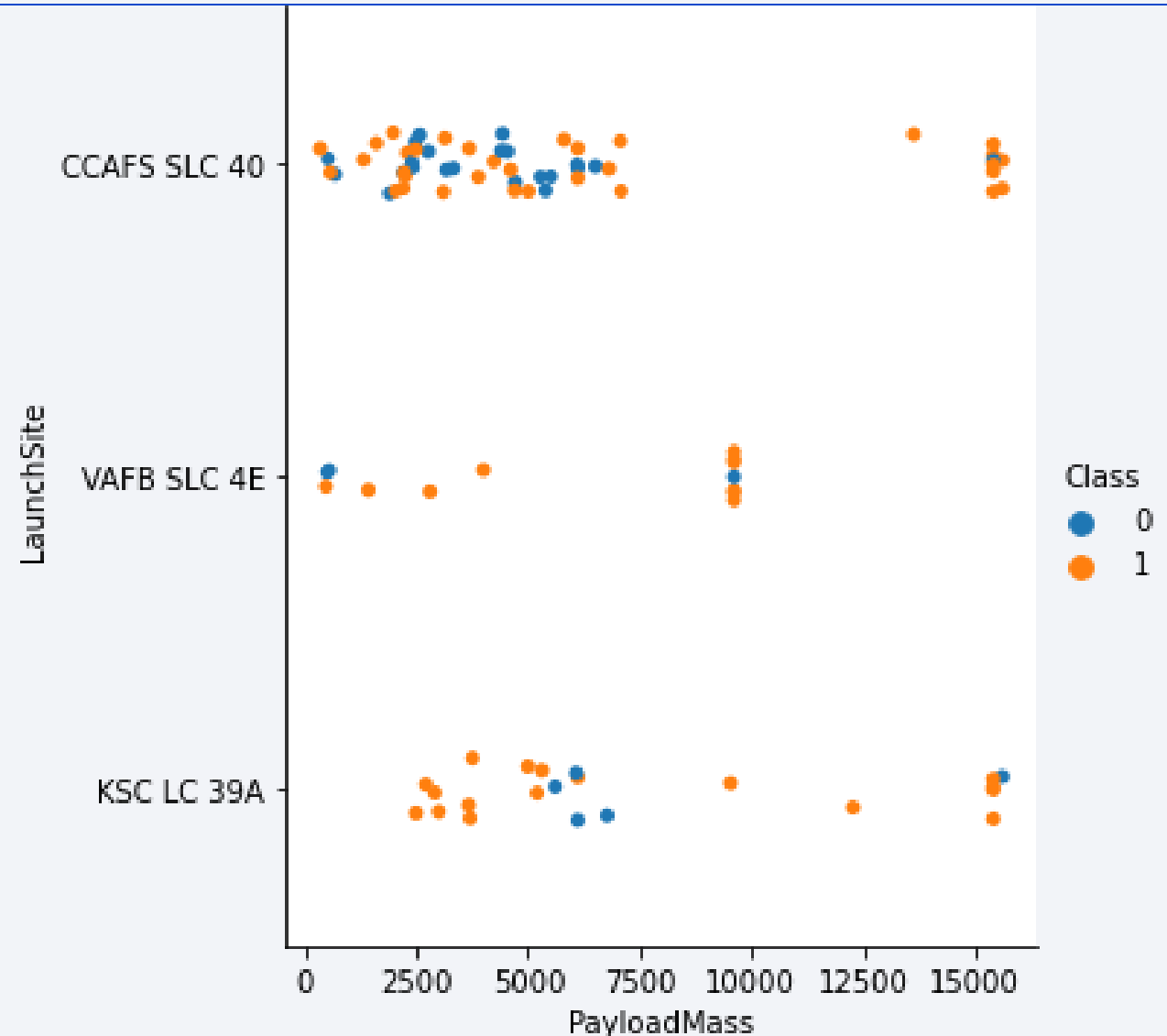
Flight Number vs. Launch Site

- This scatterplot shows that there is a correlation between FlightNumber and LaunchSite: the success rates increases with the number of launches made.



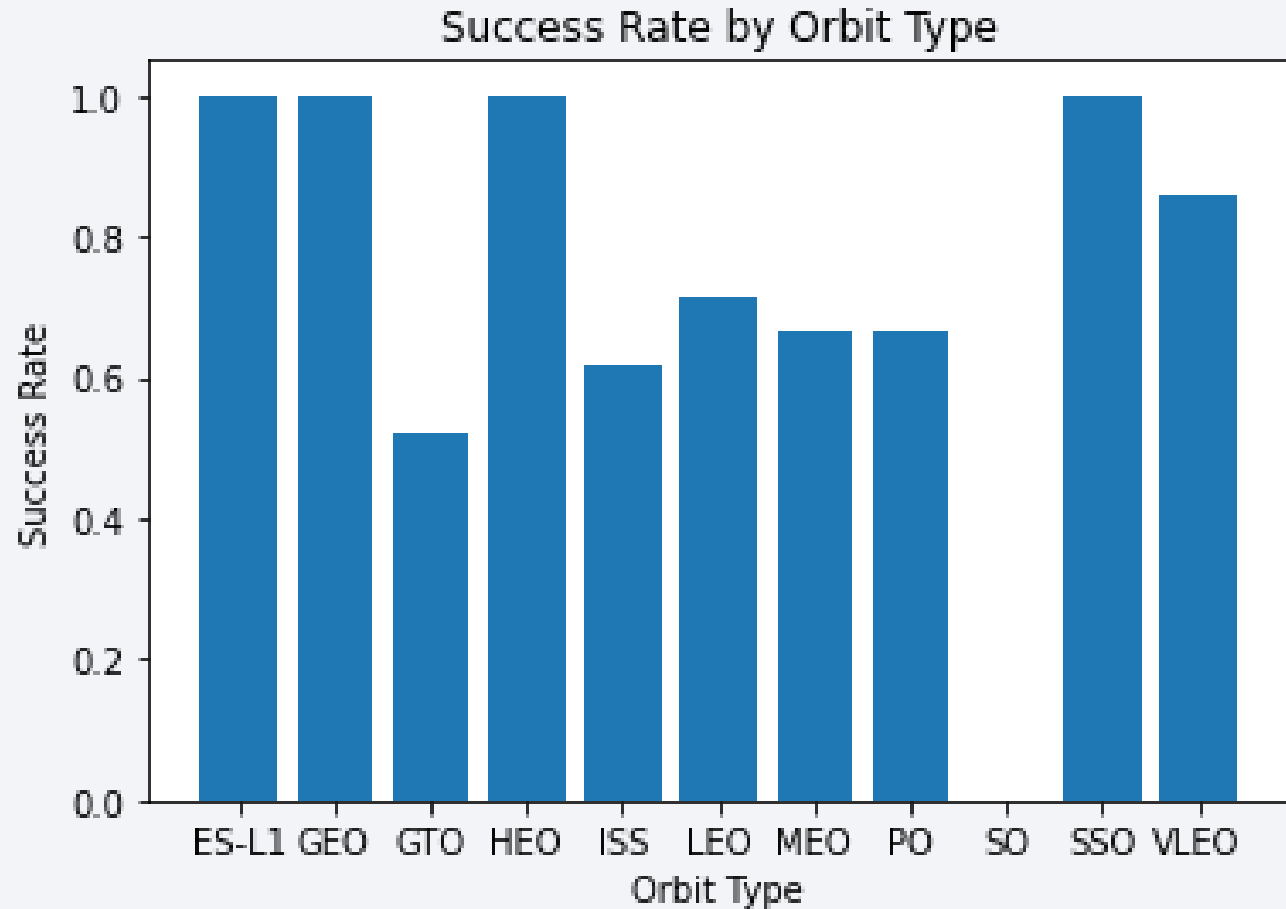
Payload vs. Launch Site

- It seems that the heavier the mass of the payload, the more success the launch will have in all three locations. It is a positive correlation.



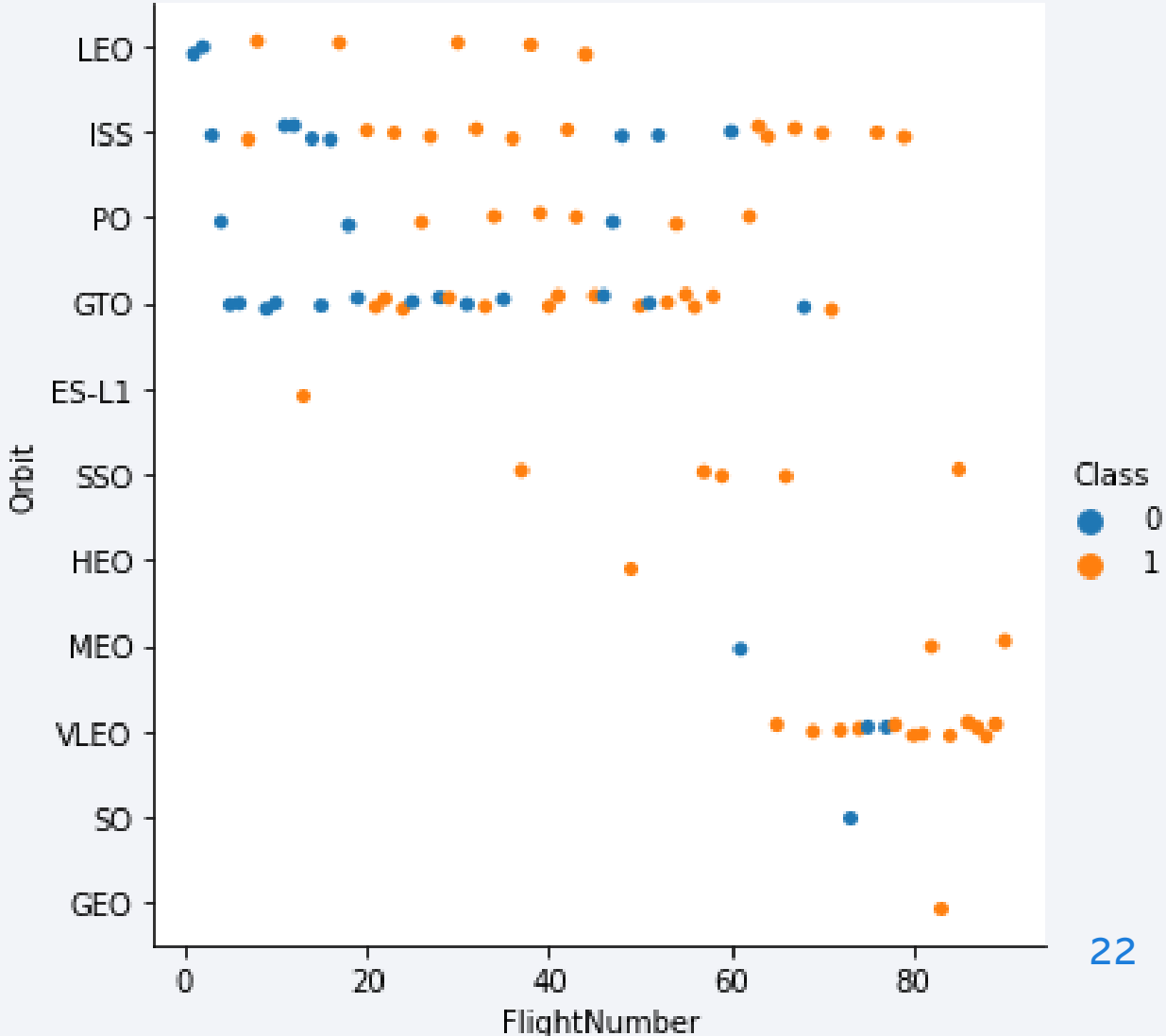
Success Rate vs. Orbit Type

- This barchart shows that the success rate will largely depend on the type of orbit, they're not equal: ES-L1, GEO, HEO, SSO and VLEO have the highest success rates.



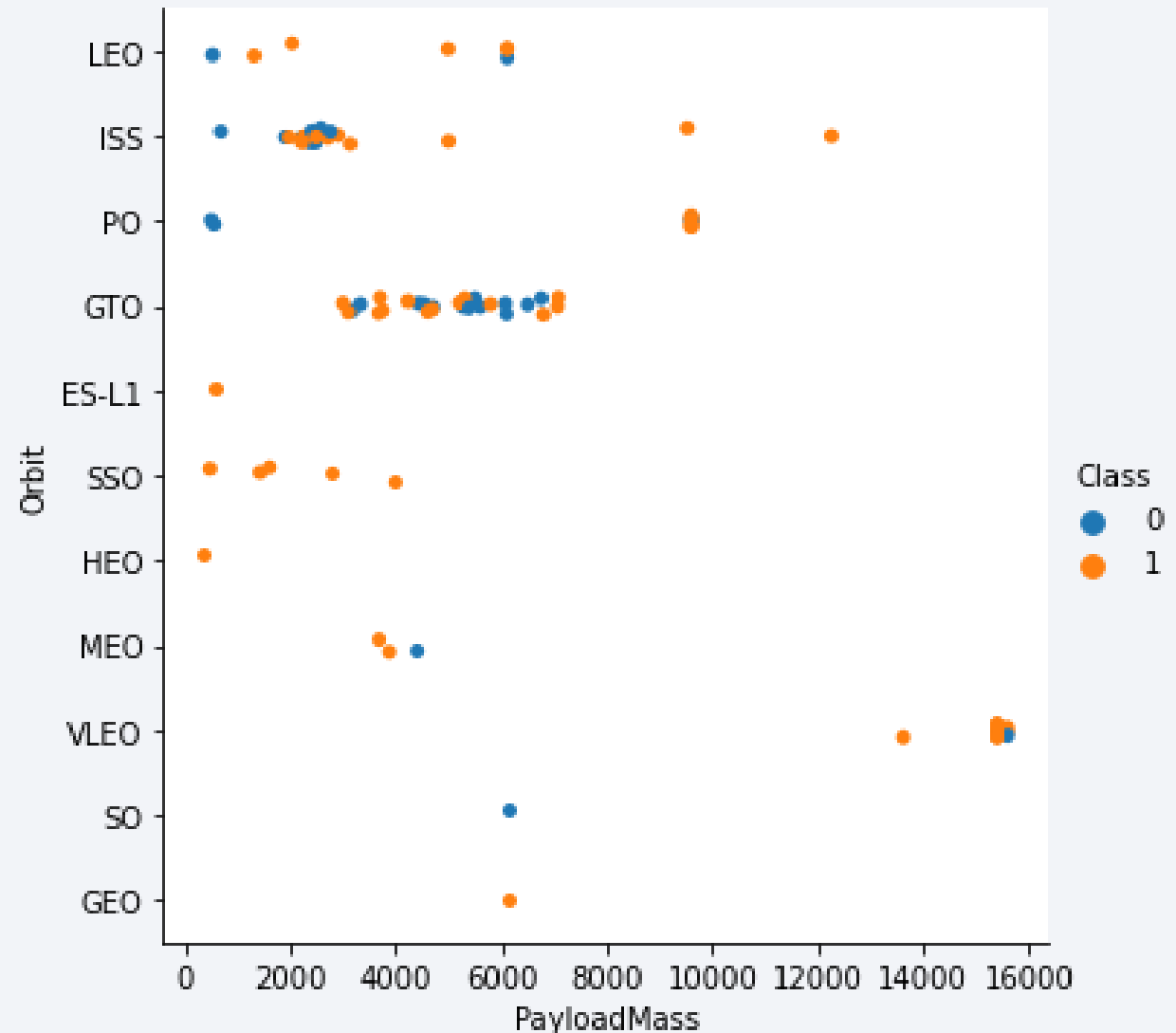
Flight Number vs. Orbit Type

- This scatterplot displays the fact that the more launches are made the more it will succeed and this, independently of the type of orbit.



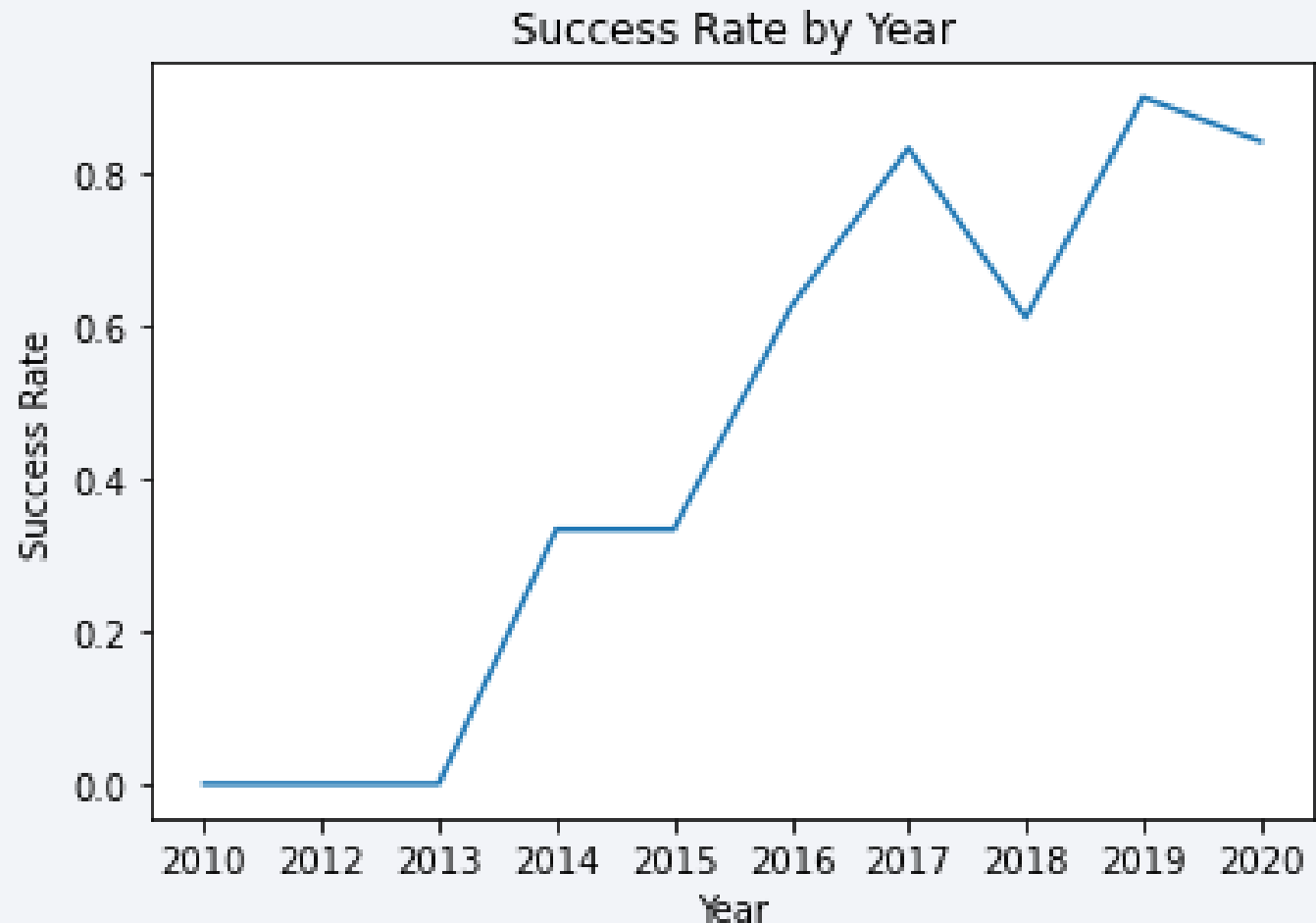
Payload vs. Orbit Type

- Once again, the heavier the payload the more chances of success the launch will have, except for GTO and MEO where the odds seem unaffected by the PayloadMass.
- For some orbits such as HEO, SO or GEO there are very few launches.



Launch Success Yearly Trend

- The success rate of the launches positively correlates with time: as the years go by, there is more success.
- There has been a dip in 2019.



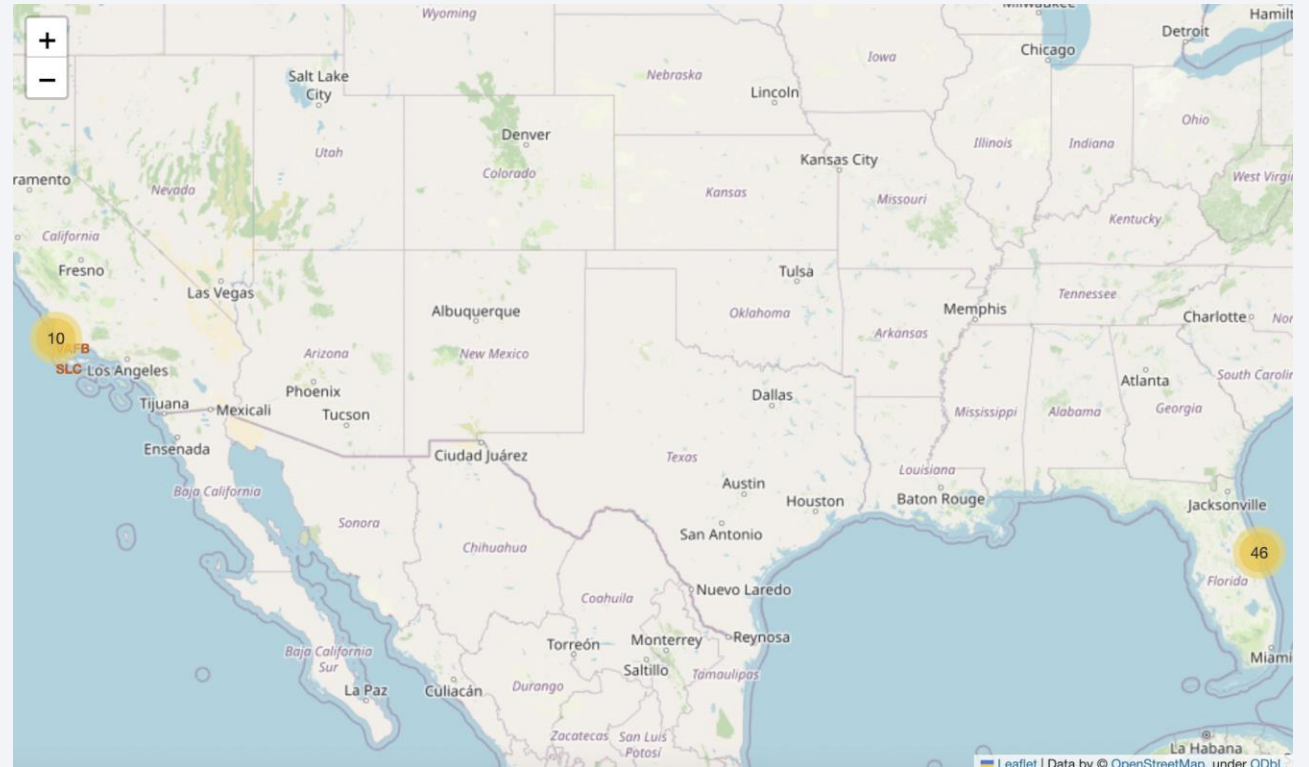
A satellite view of Earth from space, showing the curvature of the planet and city lights at night. The background is a deep blue gradient.

Section 3

Launch Sites Proximities Analysis

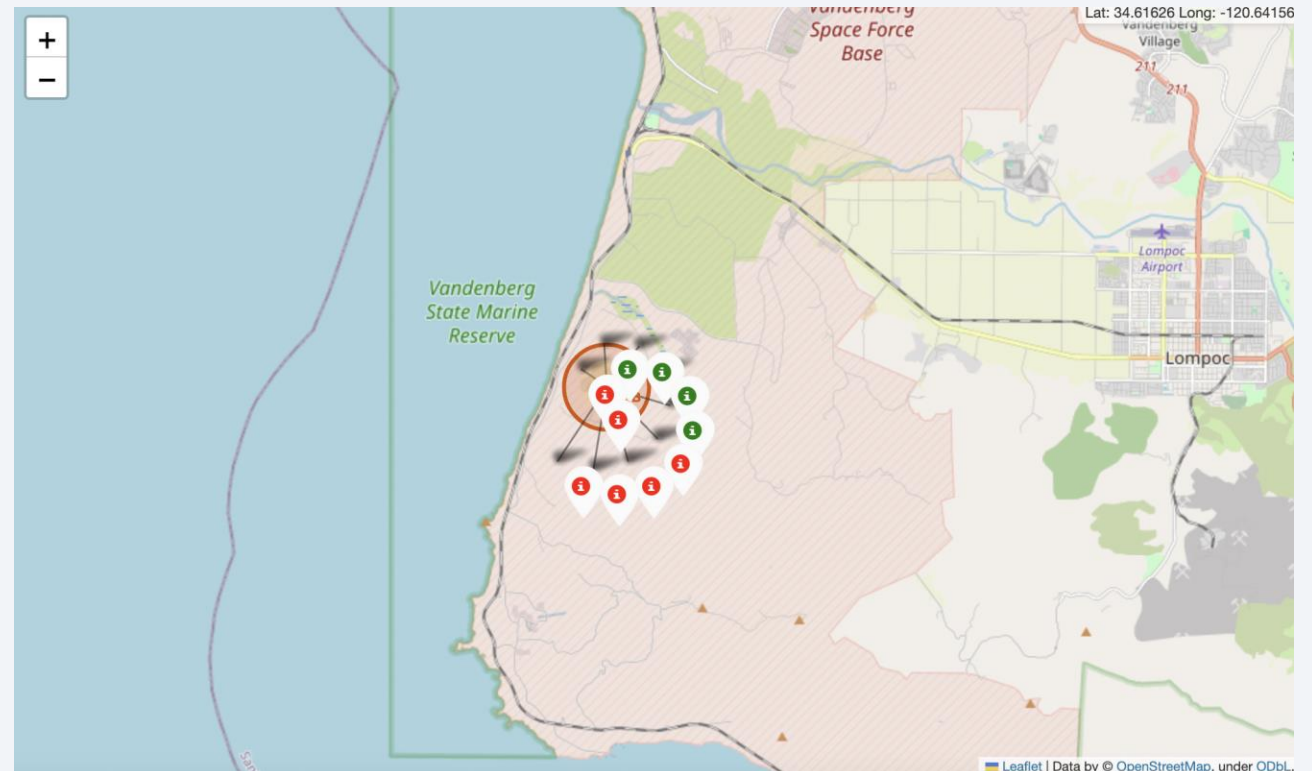
Map: Launch sites - markers

- This interactive map shows all of SpaceX's launch sites' locations.
- There are 10 locations on the west coast and 46 on the east coast of the United States, as shown by the markers.
- They're all near the sea, for safety.



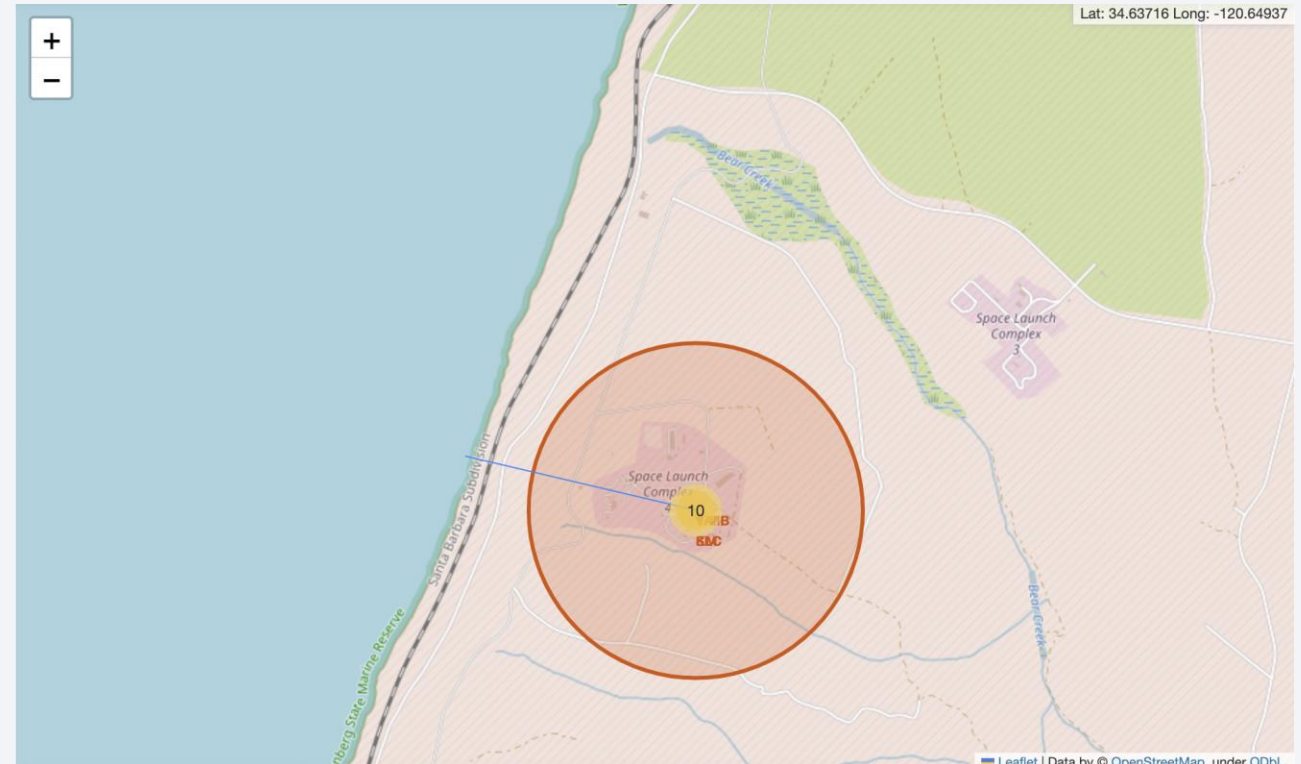
Map: Outcome of launches - labels

- The red and green labels on this map respectively represent the unsuccessful and successful launches sites.
- In this particular case, there were more failures than successes.



Map: Distance from other locations - lines

- Here, the point of the code was to generate a line that would display the distance between a launch site and a particular location, in this case its distance from the coastline.
- This is useful to visualize distances between coordinates.



Section 5

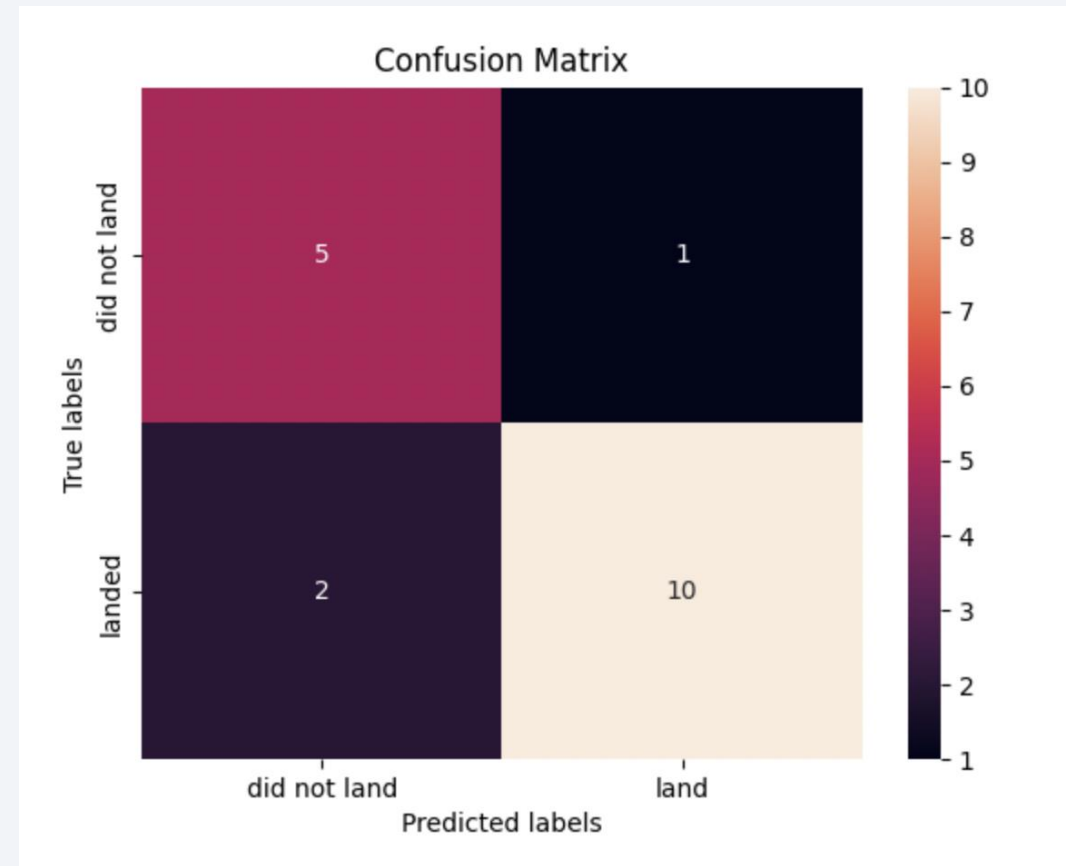
Predictive Analysis (Classification)

Classification Accuracy

- Visualize the built model accuracy for all built classification models, in a bar chart
- Find which model has the highest classification accuracy

Confusion Matrix

- This image represents the confusion matrix of the best performing model, decision trees.
- It has only one false positive and 2 false negatives, which are really low numbers.
- Moreover, there is a significant number of true positives and negatives.



Conclusions

- To choose an orbit, it is crucial to estimate what factors we deem to be the most essential, since the success rates of orbits varies based on different features.
- KSC LC 39A is the best location to launch from, except when the payload is too high.
- Maps are the most efficient way to visualize which factors make a launch location strategic, to then decide which ones to focus the strategy on.
- Decision trees is the trusted model of choice to predict the chances of success for futures launches.

Thank you!

