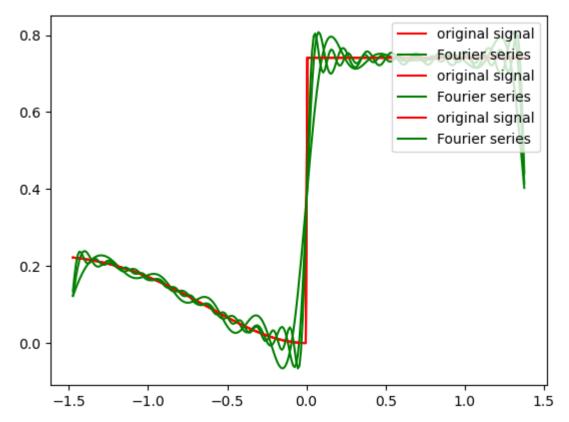
```
In [1]: import numpy as np
    import random
    import math
    import matplotlib.pyplot as plt
    from scipy.signal import sawtooth
    from scipy.signal import square
    from scipy.signal import sawtooth
    import matplotlib.pyplot as plt
    from pylab import rcParams
    import matplotlib.patches as patches
    import cv2
```

#### **Fourier series**

```
In [2]: def fseries(x, signal, K):
            Returns an approximation of a given signal with a Fourier series a
            of K coefficients.
            Parameters:
            x: independent variable (time)
             signal: function of x to be approximated
            K: number of harmonics to be used
            Returns:
            series: Fourier series of the signal
            a 0: coefficient with k=0
            a: array of coefficients for odd components (cosine)
            b: array of coefficients for even components (sine)
             0.00
             ## reconstructed signal
             #print(len(x))
            xr = np.zeros((len(x)))
             #print(xr)
             ## scaling factor
            c = (x[-1]-x[0])/len(x)
            a \theta = \text{np.dot(signal, np.ones(len(x)))} ## average of the signal over
            a \ 0 = c*a \ 0/np.pi
            ## Fourier coefficients arrays
            a = np.zeros(K)
            b = np.zeros(K)
            for k in range(1,K+1):
                 ## evaluates coefficients
                 a_k = c*np.dot(signal,np.cos(k*x))*1/np.pi
                 a[k-1]=a k
                 b k = c*np.dot(signal,np.sin(k*x))*1/np.pi
                 b[k-1]=b_k
                 ## computes series
                 xr = xr + a_k*np.cos(k*x) + b_k*np.sin(k*x)
                 series = 1/2*a 0+xr
             return series, a_0, a, b
```

```
In [3]: def best k(x, signal, K, tol):
            ## compute function norm keeping into account the scaling factor
            c = (x[-1]-x[0])/len(x) ##(b-a)/n
            norm = c*np.dot(signal, signal)
            for k in range(1,K+1):
                reconstructed_signal, a_0, a, b = fseries(x,signal, k)
                ## Parseval
                approx_norm = np.pi*(np.sum(a**2) + np.sum(b**2) + a_0**2/4)
                delta = np.abs(approx norm-norm)
                if (np.abs(delta) < tol):</pre>
                    break
            #print('the number of used harmonics is %d' % k)
            ## plots the signal and its approximation
            plt.plot(x, signal, 'r', label='original signal')
            plt.plot(x, reconstructed_signal, 'g', label='Fourier series')
            plt.legend(loc='upper right')
            return delta
```

```
In [5]: a = random.uniform(-2, -1)
        b = random.uniform(1, 2)
        p = random.uniform(0, 1)
        q = random.uniform(0, 1)
        r = random.uniform(0, 1)
        s = random.uniform(0, 1)
        t = np.arange(a, b, 0.01)
        signal = []
        for i in t:
            if a <= i <= 0:
                signal.append((p*np.exp(q*i))*np.sin(np.log(1+r*i**2)))
            elif 0 <= i <= b:
                signal.append(s)
        k array = [20, 40, 60]
        for k in k array:
            best_k(t, signal, k, 1/10)
```

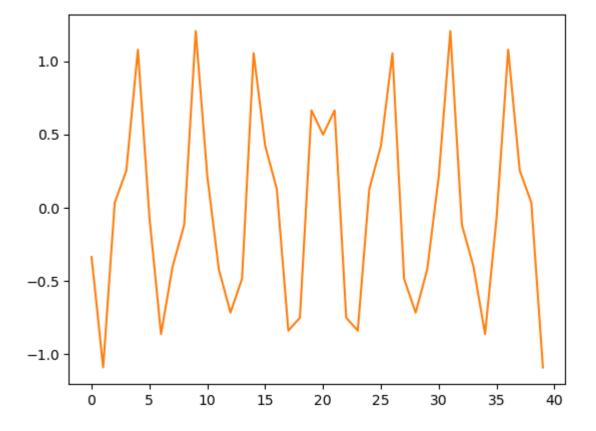


Comment: this plot concentrate that if k increases, the Gibbs phenomenon will decrease because much number of the combination sin and cos is near to real function. On the other hand, when n grows up, we have more overshoot and undershoot.

## **Fourier transform**

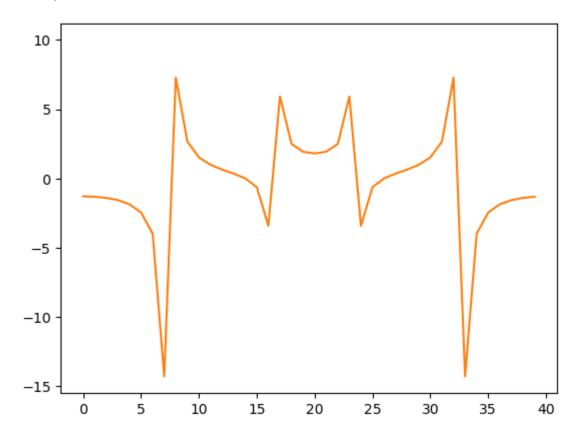
```
In [6]: alfa = random.uniform(-1, 1)
    beta = random.uniform(-1, 1)
    w0 = random.uniform(1, 5)
    w1 = random.uniform(10, 20)

    time = np.arange(-20, 20, 1)
    y = (alfa * np.cos(w0 * time)) + (beta * np.cos(w1 * time))
    plt.plot(0, 1, y)
```



```
In [7]: fft_y = np.fft.fft(y)
    plt.plot(0, 10, fft_y[:40])
```

/home/sina/anaconda3/lib/python3.9/site-packages/matplotlib/cbook/\_\_i
nit\_\_.py:1298: ComplexWarning: Casting complex values to real discard
s the imaginary part
 return np.asarray(x, float)



In terms of  $\delta$  functions, the presence of a peak at a particular frequency in the Fourier transform can be interpreted as the presence of a  $\delta$  function at that frequency in the signal. A peak in the Fourier transform indicates the presence of a frequency component in the input signal. The height or magnitude of the peak corresponds to the amplitude or strength of the frequency component.

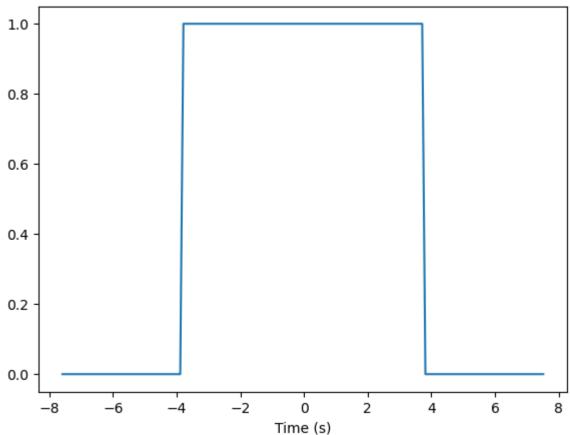
# ailising

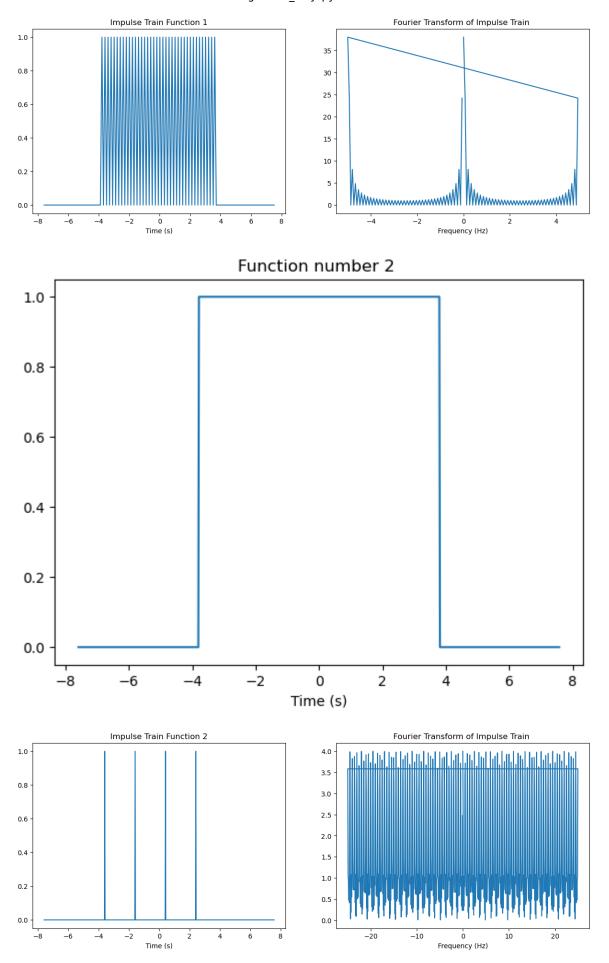
```
In [8]: def pT(t, T):
             p = np.zeros like(t)
             p[np.abs(t) \ll T] = 1
             return p
        fs1 = 10
        fs2 = 50
        T = np.random.uniform(1, 4)
        t1 = np.arange(-2*T, 2*T, 1/fs1)
        t2 = np.arange(-2*T, 2*T, 1/fs2)
        signal1 = pT(t1, T)
        signal2 = pT(t2, T)
        # Calculate train of impulses
        impulse train1 = []
        for count, t in enumerate(t1):
             if count % 2 == 0 and np.abs(t) <= T:
                 impulse_train1.append(1)
             else:
                 impulse_train1.append(0)
        impulse train2 = []
        for count, t in enumerate(t2):
             if count % 100 == 0 and np.abs(t) <= T:
                 impulse train2.append(1)
             else:
                 impulse train2.append(0)
        ft impulse train1 = np.fft.fft(impulse train1)
        ft impulse train2 = np.fft.fft(impulse train2)
        freq1 = np.fft.fftfreq(len(t1), 1/fs1)
        freq2 = np.fft.fftfreq(len(t2), 1/fs2)
        def temporal sampling rate(f, max value, decay percentage):
             """Calculate the temporal sampling rate for given decay percentage
             decay_value = max_value * (decay_percentage / 100)
             idx = np.argmin(np.abs(f - decay value))
             return idx
        \max \text{ value } 1 = \text{np.abs}(\text{ft impulse train1}).\max()
        \max \text{ value } 2 = \text{np.abs(ft impulse train2).max()}
        temporal_rate_1 = temporal_sampling_rate(np.abs(ft_impulse_train1), ma
        temporal rate 2 = temporal sampling rate(np.abs(ft impulse train2), md
        print("Temporal sampling rate for 10% decay:", t1[temporal_rate_1])
        print("Temporal sampling rate for 1% decay:", t2[temporal_rate_2])
        plt.figure(figsize=(15,5))
        plt.subplot(121)
        plt.title('Function number 1 ')
        plt.plot(t1, signal1)
        plt.xlabel('Time (s)')
```

```
plt.figure(figsize=(15,5))
plt.subplot(121)
plt.title('Impulse Train Function 1')
plt.plot(t1, impulse train1)
plt.xlabel('Time (s)')
plt.subplot(122)
plt.title('Fourier Transform of Impulse Train ')
plt.plot(freq1, np.abs(ft impulse train1))
plt.xlabel('Frequency (Hz)')
plt.figure(figsize=(15,5))
plt.subplot(121)
plt.title('Function number 2 ')
plt.plot(t2, signal2)
plt.xlabel('Time (s)')
plt.figure(figsize=(15,5))
plt.subplot(121)
plt.title('Impulse Train Function 2')
plt.plot(t2, impulse_train2)
plt.xlabel('Time (s)')
plt.subplot(122)
plt.title('Fourier Transform of Impulse Train ')
plt.plot(freq2, np.abs(ft impulse train2))
plt.xlabel('Frequency (Hz)')
plt.show()
```

Temporal sampling rate for 10% decay: 0.7132330586807729 Temporal sampling rate for 1% decay: 2.7732330586805816







High sampling rate means that we can have better representation of the signal. In first case (decay=10) we have high frequency. lower temporal sampling rate will result in a wider frequency spectrum with higher frequency components

#### LTI

```
In [9]: a = random.uniform(-2,-1)
b = random.uniform(0, 2)

p = random.uniform(0, 2)
q = random.uniform(0, 2)
r = random.uniform(0, 2)
T = random.uniform(0, 2)

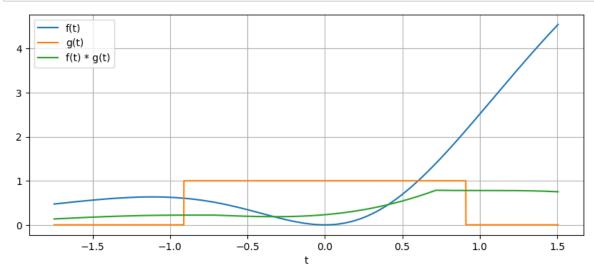
t = np.arange(a, b, 0.001)
```

```
In [10]: def f_t(t):
    return p * np.exp(q * t) * np.sin(np.log(1 + r * t**2))

def g_t(t):
    g_t_list = []
    for i in t:
        if abs(i) <= T:
            g_t_list.append(1)
        else:
            g_t_list.append(0)
    return g_t_list</pre>
```

```
In [11]: f_t = f_t(t)
g_t = g_t(t)
c = np.convolve(f_t, g_t, mode='same')
c_normalize = c / np.sum(f_t)
```

```
In [12]: plt.figure(figsize=(10, 4))
   plt.plot(t, f_t, label='f(t)')
   plt.plot(t, g_t, label='g(t)')
   plt.plot(t, c_normalize, label='f(t) * g(t)')
   plt.xlabel('t')
   plt.legend()
   plt.grid()
```

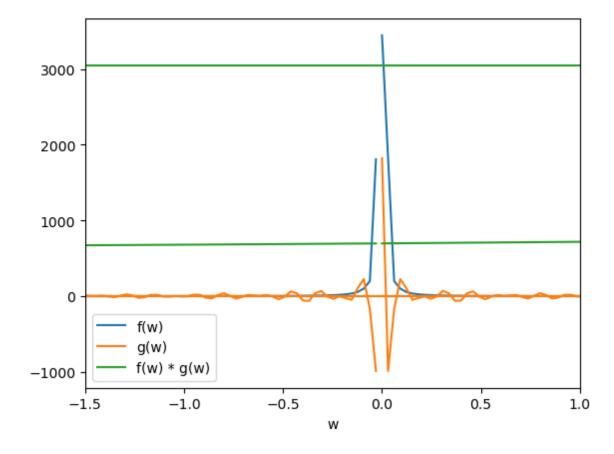


```
In [13]: freq = np.fft.fftfreq(len(t), 0.01)

f_t_fft = np.fft.fft(f_t)
g_t_fft = np.fft.fft(g_t)
c_fft = f_t_fft * g_t_fft
c = np.fft.ifft(c_fft).real

plt.plot(freq, f_t_fft, label='f(w)')
plt.plot(freq, g, label='f(w) * g(w)')
plt.plot(freq, c, label='f(w) * g(w)')
plt.xlabel('w')
plt.legend()
plt.xlim(-1.5, 1)
```

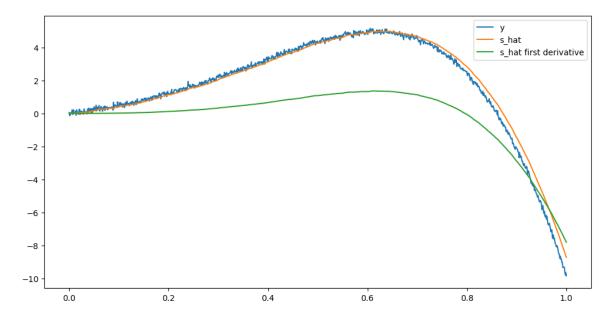
#### Out[13]: (-1.5, 1.0)



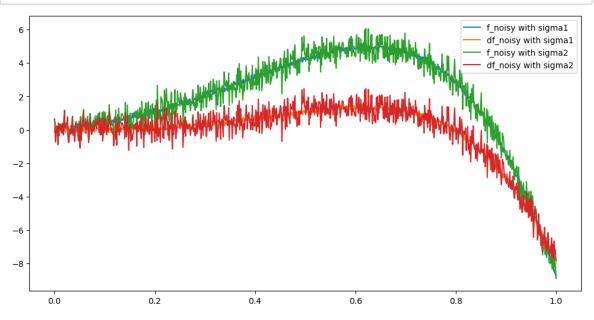
The convolution for two signal should be equal to convolution for fourier transform of f and g convolution

# Kalman filtering

```
In [14]: n = 1000
         T = np.linspace(0, 1, n)
         p = np.random.uniform(2, 4)
         q = np.random.uniform(2, 4)
         y = np.sin(p*T) * np.exp(q*T) + np.random.normal(0, 0.1, len(T))
         def kalman filter():
             n = 2
             m = 1
             phi = np.array([[1, T[1]-T[0]], [0, 1]])
             H = np.array([1, 0])[None, :]
             Q = np.array([[0.05, 0], [0, 0.05]])
             R = 10
             s = np.zeros((n, 1))
             P = np.zeros((n, n))
             s est = np.zeros((n, len(T)))
             for i in range(len(T)):
                 s pred = np.dot(phi, s)
                 P = np.dot(np.dot(phi, P), phi.T) + Q
                 K = np.dot(P, H.T) / (np.dot(np.dot(H, P), H.T) + R)
                 s = s pred + np.dot(K, y[i] - np.dot(H, s pred))
                 P = np.dot(np.eye(n) - np.dot(K, H), P)
                 s_{est}[:, i] = s[:, 0].flatten()
             return s est
         s est = kalman filter()
         f = s est[0, :]
         df = s_est[1, :]
         plt.figure(figsize=(12, 6))
         plt.plot(T, y, label="y")
         plt.plot(T, f, label="s_hat")
         plt.plot(T, df, label="s_hat first derivative")
         plt.legend()
         plt.show()
```



```
In [15]:
         sigmal = 0.1
         sigma2 = 0.5
         epsilon1 = np.random.normal(0, sigma1, n)
         epsilon2 = np.random.normal(0, sigma2, n)
         f_{noisy1} = f + epsilon1
         df noisy1 = df + epsilon1
         f noisy2 = f + epsilon2
         df noisy2 = df + epsilon2
         plt.figure(figsize=(12, 6))
         plt.plot(T, f_noisy1, label="f_noisy with sigma1")
         plt.plot(T, df_noisy1, label="df_noisy with sigma1")
         plt.plot(T, f_noisy2, label="f_noisy with sigma2")
         plt.plot(T, df noisy2, label="df noisy with sigma2")
         plt.legend()
         plt.show()
```



This code will generate two sets of plots for the two different values of the noise process covariance (sigma = 0.1 and sigma = 0.5), showing the estimates against the values for f and f' computed analytically.

#### wavelet

```
In [16]: def haar_wavelet_transform(img):
    n, m = img.shape

h0 = np.array([1/np.sqrt(2), 1/np.sqrt(2)])
    h1 = np.array([1/np.sqrt(2), -1/np.sqrt(2)])

new_array = np.zeros_like(img)
detail_array = np.zeros_like(img)

for i in range(n):
    for j in range(0, n, 2):
        two_pixels = img[i, j:j+2]
        new_array[i, j // 2] = np.dot(h0, two_pixels)
        detail_array[i, j // 2] = np.dot(h1, two_pixels)
return new_array, detail_array
```

```
In [17]: img_with_spesific_range_of_n_px = np.random.randint(24, 27, (16, 16))
    img_with_spesific_range_of_m_px = np.random.randint(201, 205, (16, 16))
    J32_spesific_px = np.concatenate((img_with_spesific_range_of_n_px, img
    random_image = np.random.randint(0, 255, (32, 32))
    I, detail_array1 = haar_wavelet_transform(random_image)
    sum_detailI = np.sum(np.abs(detail_array1) > 1/100) / (32 * 32)

Ir, detail_array2 = haar_wavelet_transform(J32_spesific_px)
    sum_detailIr = np.sum(np.abs(detail_array2) > 1/100) / (32 * 32)

print(sum_detailI, sum_detailIr)
```

0.4951171875 0.0234375

Sum detail is used as a measure of the level of detail in an image. If the fraction is high, the image contains a lot of detail information, while if the fraction is low, the image contains less detail information.

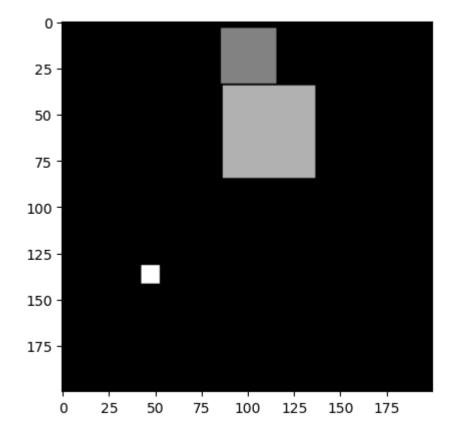
# **Image Proccessing**

```
In [20]: pixel_image = np.zeros((200, 200), dtype=np.uint8)

size = [10, 30, 50]
    for i in range(len(size)):
        x = np.random.randint(0, 140)
        y = np.random.randint(0, 140)
        brightness = np.random.randint(50, 256)
        pixel_image[y: y + size[i], x: x + size[i]] = brightness

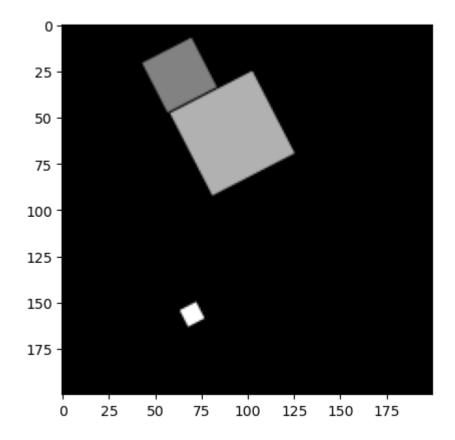
plt.imshow(pixel_image, cmap='gray')
```

Out[20]: <matplotlib.image.AxesImage at 0x7fe864bd32e0>



```
In [21]: random = np.random.uniform(10, 80)
M = cv2.getRotationMatrix2D((100,100), random, 1)
pixel_image_rotate = cv2.warpAffine(pixel_image, M, (200, 200))
plt.imshow(pixel_image_rotate, cmap='gray')
```

Out[21]: <matplotlib.image.AxesImage at 0x7fe864ade6a0>



### 2D DFT

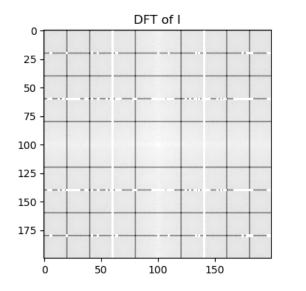
```
In [22]: I_dft = np.fft.fftshift(np.fft.fft2(pixel_image))
Ir_dft = np.fft.fftshift(np.fft.fft2(pixel_image_rotate))

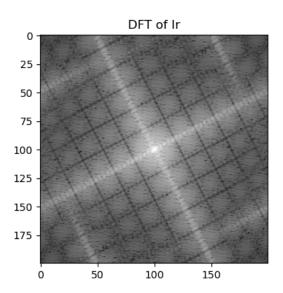
plt.figure(figsize=(10, 4))
plt.subplot(121)
plt.imshow(np.log(np.abs(I_dft)), cmap='gray')
plt.title('DFT of I')

plt.subplot(122)
plt.imshow(np.log(np.abs(Ir_dft)), cmap='gray')
plt.title('DFT of Ir')

/tmp/ipykernel_6002/1051944270.py:6: RuntimeWarning: divide by zero e ncountered in log
    plt.imshow(np.log(np.abs(I_dft)), cmap='gray')
```

#### Out[22]: Text(0.5, 1.0, 'DFT of Ir')

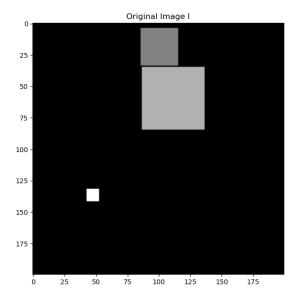


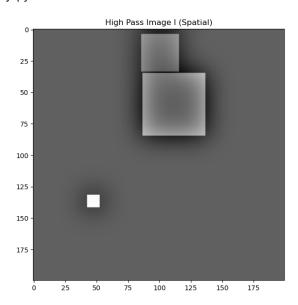


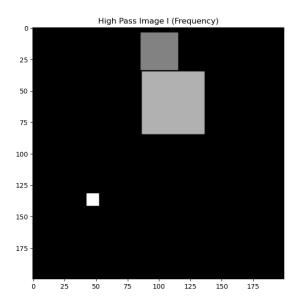
By visualizing the DFTs of the two images, we can observe their frequency content and analyze the differences between them. In the center we have zero frequency.

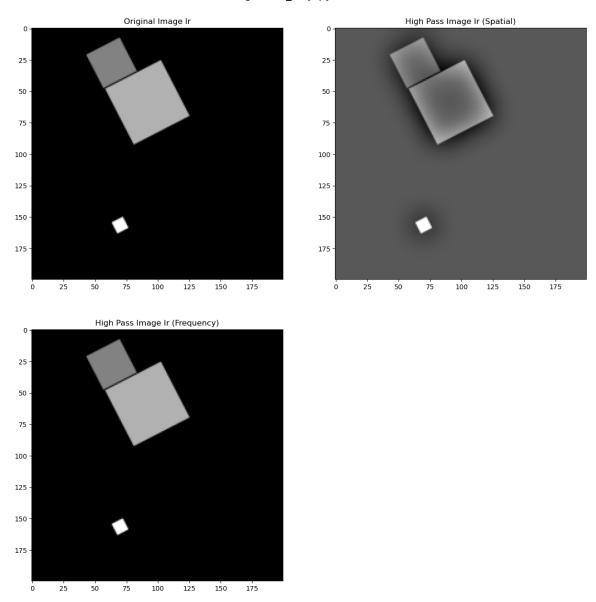
### **Image filtering**

```
In [23]: I = pixel image
         Ir = pixel image rotate
         I = I.astype(np.float32) / 255
         Ir = Ir.astype(np.float32) / 255
         kernel size = 51
         sigma = 10
         gaussian = cv2.getGaussianKernel(kernel size, sigma)
         gaussian = gaussian * gaussian.T
         # remove high freq
         I high pass = I - cv2.filter2D(I, -1, gaussian)
         Ir high pass = Ir - cv2.filter2D(Ir, -1, gaussian)
         I f = np.fft.fft2(I)
         Ir f = np.fft.fft2(Ir)
         gaussian f = np.fft.fft2(gaussian, (200, 200))
         I_high_pass_f = I_f - gaussian_f
         Ir_high_pass_f = Ir_f - gaussian_f
         I high pass f = np.fft.ifft2(I high pass f)
         Ir high pass f = np.fft.ifft2(Ir high pass f)
         plt.figure(figsize=(15, 15))
         plt.subplot(221)
         plt.imshow(I, cmap='gray')
         plt.title('Original Image I')
         plt.subplot(222)
         plt.imshow(I high pass, cmap='gray')
         plt.title('High Pass Image I (Spatial)')
         plt.subplot(223)
         plt.imshow(np.abs(I high pass f), cmap='gray')
         plt.title('High Pass Image I (Frequency)')
         plt.figure(figsize=(15, 15))
         plt.subplot(221)
         plt.imshow(Ir, cmap='gray')
         plt.title('Original Image Ir')
         plt.subplot(222)
         plt.imshow(Ir high pass, cmap='gray')
         plt.title('High Pass Image Ir (Spatial)')
         plt.subplot(223)
         plt.imshow(np.abs(Ir high pass f), cmap='gray')
         plt.title('High Pass Image Ir (Frequency)')
         plt.show()
```









when we do kernels like blur or gray filter, it's easier to convert. The rate is so important because it can convert important pixels to be lost.