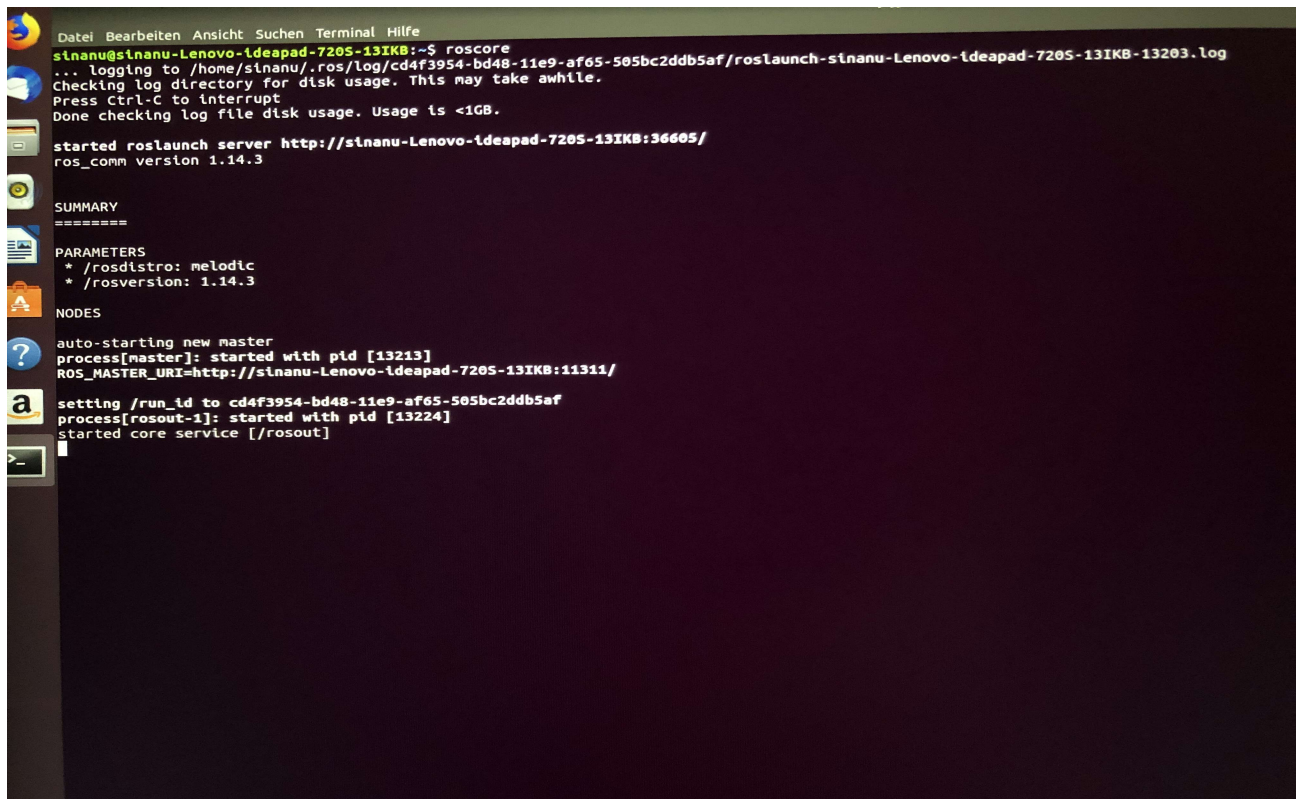


Bearbeitet von Gesche Grefe und Sinan Uyar (Gruppe: sg)

## Robotik Übung 1

### 1.1) roscore:

A terminal window on a Linux desktop. The terminal shows the command 'roscore' being executed. The output includes logging information, a summary of parameters (rostdistro: melodic, rosversion: 1.14.3), and a list of nodes (auto-starting new master, process[master], ROS\_MASTER\_URI, setting /run\_id, process[rosout-1], started core service [/rosout]).

```
sinanu@sinanu-Lenovo-Ideapad-720S-13IKB:~$ roscore
... logging to /home/sinanu/.ros/log/cd4f3954-bd48-11e9-af65-505bc2ddb5af/roslaunch-sinanu-Lenovo-Ideapad-720S-13IKB-13203.log
Checking log directory for disk usage. This may take awhile.
Press Ctrl-C to interrupt
Done checking log file disk usage. Usage is <1GB.

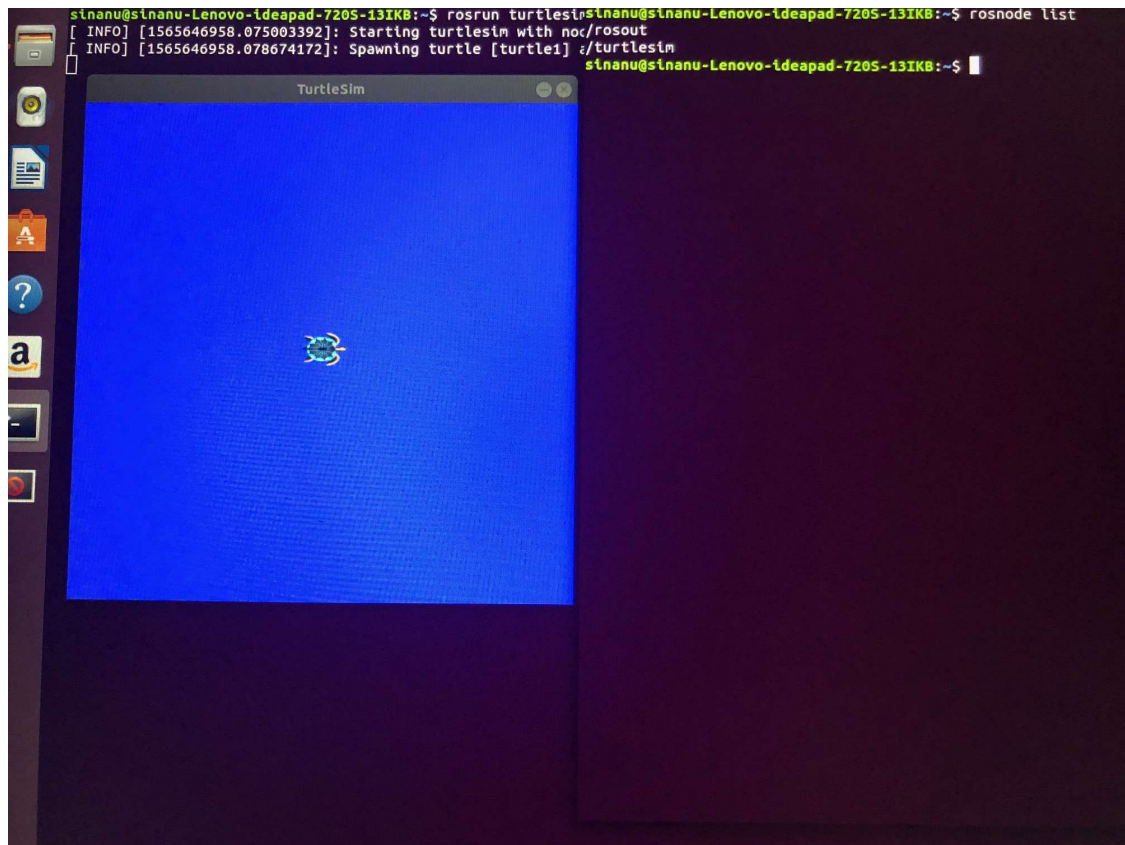
started roslaunch server http://sinanu-Lenovo-Ideapad-720S-13IKB:36605/
ros_comm version 1.14.3

SUMMARY
=====
PARAMETERS
* /rostdistro: melodic
* /rosversion: 1.14.3

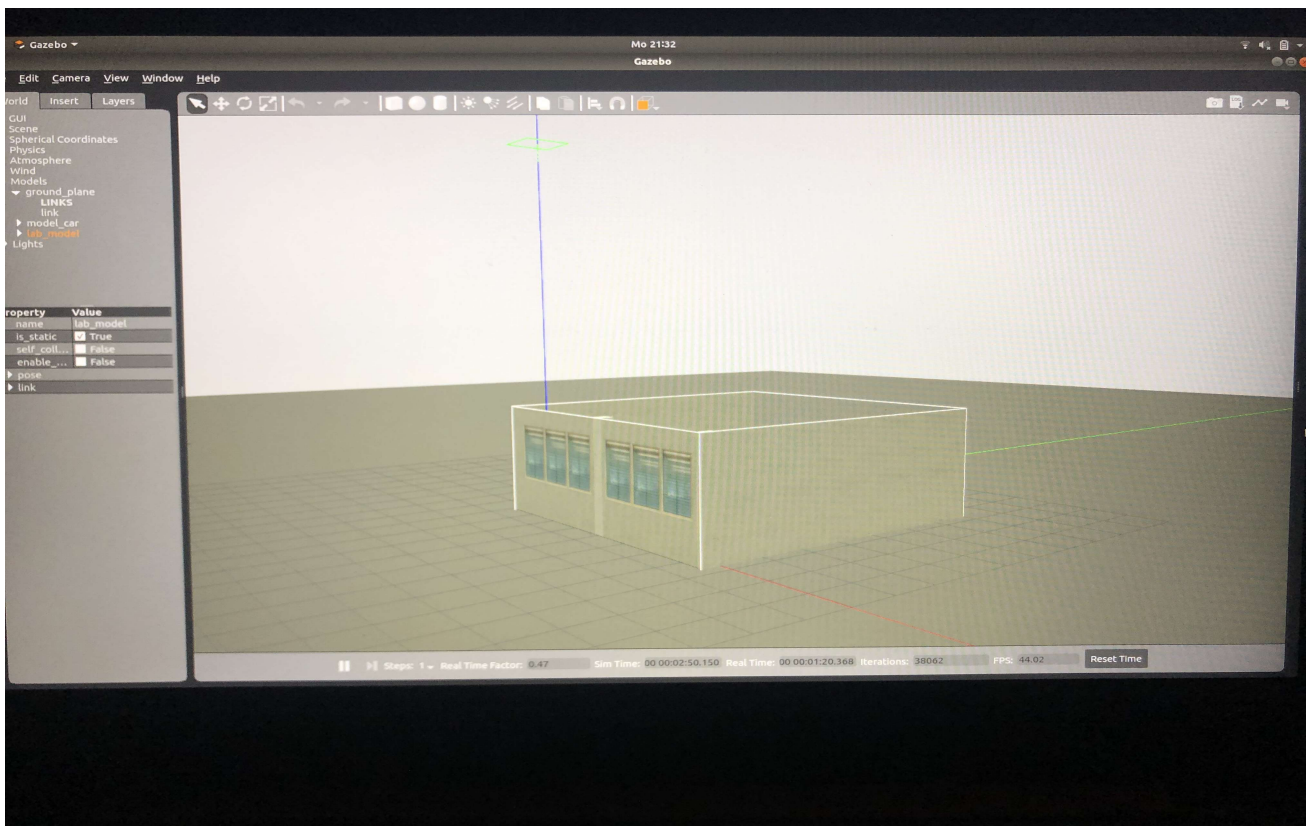
NODES
auto-starting new master
process[master]: started with pid [13213]
ROS_MASTER_URI=http://sinanu-Lenovo-Ideapad-720S-13IKB:11311/

setting /run_id to cd4f3954-bd48-11e9-af65-505bc2ddb5af
process[rosout-1]: started with pid [13224]
started core service [/rosout]
```

Und hier ist noch ein Foto für 1.1.5



1.2)



1.3)

Wir haben keine Vorkenntnisse von github, weswegen wir uns nicht hiermit sicher sind.  
Es sind zwei Ordner vorhanden, da wir einmal versehentlich den Gruppennamen großgeschrieben hatten, was gegen die naming conventions verstöß.

[https://github.com/sinan-uyar/robotik\\_ros\\_SG](https://github.com/sinan-uyar/robotik_ros_SG)