

```

#include <IRremote.h>
int RECV_PIN =11;
IRrecv irrecv(RECV_PIN);

void setup()
{
    ...
    IrReceiver.begin(RECV_PIN, ENABLE_LED_FEEDBACK);
    ...
}
void loop() {
    ...
    if (IrReceiver.decode())
    {
        int cmd = IrReceiver.decodedIRData.command;
        IrReceiver.resume(); //
        if (cmd == 0x10)
        {
        }
        ...
    }
    ...
}

```