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CONTEXT c_status

SETS

STATUS

CONSTANTS

PO

PA

CC

PC

UNDEFINED

BRAKE

AXIOMS

axm1: *partition*(STATUS, {PO}, {PA}, {CC}, {PC}, {UNDEFINED}, {BRAKE})

END

CONTEXT c_user_action

SETS

USER_ACTION

CONSTANTS

pa

pac

cc

pc

pcc

br

ccc

AXIOMS

axm1: $\text{partition}(\text{USER_ACTION}, \{pa\}, \{pac\}, \{cc\}, \{pc\}, \{pcc\}, \{br\}, \{ccc\})$

END

MACHINE M0**SEES** c_status**VARIABLES**

status

beforecc

engrun

INVARIANTS*inv1:* $status \subseteq STATUS$ *inv3:* $beforecc \subseteq \{PO, PA, UNDEFINED\}$ *inv4:* $engrun \in BOOL$ **EVENTS****Initialisation****begin***act1:* $status := \{PO\}$ *act2:* $beforecc := \{UNDEFINED\}$ *act3:* $engrun := FALSE$ **end****Event** PedalOnly $\langle \text{ordinary} \rangle \hat{=}$ **when***grd1:* $status = \{PA\} \vee status = \{PC\} \vee$
 $(status = \{CC\} \wedge beforecc = \{PO\})$ **then***act1:* $status := \{PO\}$ *act2:* $engrun := FALSE$ **end****Event** PedalAssist $\langle \text{ordinary} \rangle \hat{=}$ **when***grd1:* $status = \{PO\} \vee$
 $(status = \{CC\} \wedge beforecc = \{PA\})$ **then***act1:* $status := \{PA\}$ *act2:* $engrun := TRUE$ **end****Event** PedalOnly2CruiseControl $\langle \text{ordinary} \rangle \hat{=}$ **when***grd1:* $status = \{PO\}$ **then***act1:* $status := \{CC\}$ *act2:* $beforecc := \{PO\}$ *act3:* $engrun := TRUE$ **end****Event** PedalAssist2CruiseControl $\langle \text{ordinary} \rangle \hat{=}$ **when***grd1:* $status = \{PA\}$ **then***act1:* $status := \{CC\}$ *act2:* $beforecc := \{PA\}$ *act3:* $engrun := TRUE$ **end****Event** PedalCharge $\langle \text{ordinary} \rangle \hat{=}$ **when***grd1:* $status = \{PO\}$ **then***act1:* $status := \{PC\}$

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    act2: engrun := TRUE
  end
Event Brake ⟨ordinary⟩ ≐
  when
    grd1: status = {PO} ∨ status = {PA} ∨ status = {PC}
  then
    act1: status := {BRAKE}
    act2: engrun := FALSE
  end
Event BrakeCruiseControl2PedalOnly ⟨ordinary⟩ ≐
  when
    grd1: status = {CC} ∧ beforecc = {PO}
  then
    act1: status := {PO}
    act2: engrun := FALSE
  end
Event BrakeCruiseControl2PedalAssist ⟨ordinary⟩ ≐
  when
    grd1: status = {CC} ∧ beforecc = {PA}
  then
    act1: status := {PA}
    act2: engrun := TRUE
  end
END

```

MACHINE M1**REFINES** M0**SEES** c_status, c_user_action**VARIABLES**

status

beforecc

engrun

useraction

INVARIANTS**inv1:** $useraction \in STATUS \leftrightarrow USER_ACTION$ **EVENTS****Initialisation****begin****act1:** $status := \{PO\}$ **act2:** $beforecc := \{UNDEFINED\}$ **act3:** $engrun := FALSE$ **act4:** $useraction := \{\{PO \mapsto pc\}, \{PO \mapsto pa\}, \{PO \mapsto cc\}\}$ **end****Event** PedalAssist $\langle \text{ordinary} \rangle \hat{=}$ **refines** PedalAssist**when****grd1:** $status = \{PO\} \vee$ $(status = \{CC\} \wedge beforecc = \{PA\})$ $status \in \mathbb{P}(STATUS) \setminus \{\{PA\}, \{PC\}, \{BRAKE\}, \{UNDEFINED\}\}$ **then****act1:** $status := \{PA\}$ **act2:** $engrun := TRUE$ **act3:** $useraction := \{PO \mapsto pa, CC \mapsto ccc\}$ **end****Event** PedalOnly $\langle \text{ordinary} \rangle \hat{=}$ **refines** PedalOnly**when****grd1:** $status = \{PA\} \vee status = \{PC\} \vee$ $(status = \{CC\} \wedge beforecc = \{PO\})$ $status \in \mathbb{P}(STATUS) \setminus \{\{PO\}, \{BRAKE\}, \{UNDEFINED\}\}$ **then****act1:** $status := \{PO\}$ **act2:** $engrun := FALSE$ **act3:** $useraction := \{PA \mapsto pac, CC \mapsto ccc, PC \mapsto pcc\}$ **end****Event** PedalOnly2CruiseControl $\langle \text{ordinary} \rangle \hat{=}$ **refines** PedalOnly2CruiseControl**any**

s

where**grd1:** $s = PO$ **grd2:** $status \in \{\{PO\}\}$ **then****act1:** $status := \{CC\}$ **act2:** $beforecc := \{PO\}$ **act3:** $engrun := TRUE$ **act4:** $useraction(s) := cc$ **end****Event** PedalAssist2CruiseControl $\langle \text{ordinary} \rangle \hat{=}$

refines PedalAssist2CruiseControl

any

s

where

grd1: $s = PA$

grd2: $status \in \{\{PA\}\}$

then

act1: $status := \{CC\}$

act2: $beforecc := \{PA\}$

act3: $engrun := TRUE$

act4: $useraction(s) := cc$

end

Event PedalCharge $\langle ordinary \rangle \hat{=}$

refines PedalCharge

any

s

where

grd1: $s = PO$

grd2: $status \in \{\{PO\}\}$

then

act1: $status := \{PC\}$

act2: $engrun := TRUE$

act3: $useraction(s) := pc$

end

Event Brake $\langle ordinary \rangle \hat{=}$

refines Brake

any

s

where

grd1: $s \in STATUS \setminus \{CC, BRAKE, UNDEFINED\}$

grd2: $status = \{PO\} \vee status = \{PA\} \vee status = \{PC\}$
 $status \in \mathbb{P}(STATUS) \setminus \{\{CC\}, \{BRAKE\}, \{UNDEFINED\}\}$

then

act1: $status := \{BRAKE\}$

act2: $engrun := FALSE$

act3: $useraction(s) := br$

end

Event BrakeCruiseControl2PedalOnly $\langle ordinary \rangle \hat{=}$

refines BrakeCruiseControl2PedalOnly

any

s

where

grd1: $s = CC \wedge beforecc = \{PO\}$

grd2: $status \in \{\{CC\}\}$

then

act1: $status := \{PO\}$

act2: $engrun := FALSE$

act3: $useraction(s) := br$

end

Event BrakeCruiseControl2PedalAssist $\langle ordinary \rangle \hat{=}$

refines BrakeCruiseControl2PedalAssist

any

s

where

grd1: $s = CC \wedge beforecc = \{PA\}$

grd2: $status \in \{\{CC\}\}$

then

act1: $status := \{PA\}$

```
    act2: engrun := TRUE
    act3: useraction(s) := br
  end
END
```