

Establishment of Model

Technical term

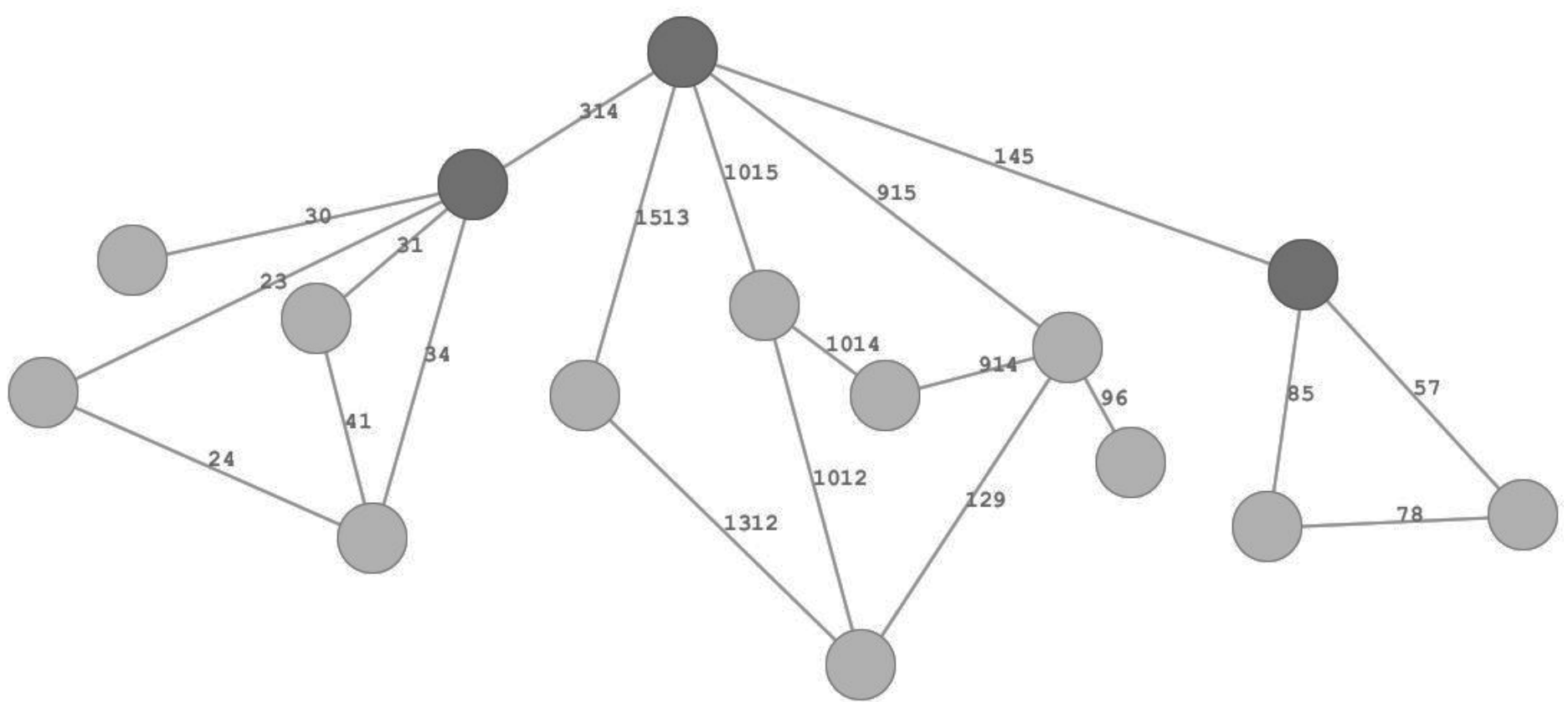
1. Graph is weighted undirected connected simple dynamic graph
2. Dynamic graph is graph which edges can be modified by using 2 operations
 - Add an edge from u to v with weight w
 - Delete an edge from u to v
3. Source node is a node which receives donations and has authority to distribute donations.
4. Expiration is state fulfilled demand of an object decrease to zero

Definition

1. Graph is 3-tuples $(V, E, \bar{I} = \langle \bar{I}_i \rangle)$ such that
 - V is set of vertices
 - E is set of edges
 - \bar{I} is vector of vector represent vehicles which travel to vertices, sorted by time during transportation process in ascending order
2. Vertex is 5-tuples (z, r, R, T, X) such that
 - $z \in \mathbb{R}_0^+$ is initial demand
 - $r \in \mathbb{R}^+$ is increasing demand rate
 - $R: \mathbb{R}_0^+ \rightarrow \mathbb{R}_0^+$ is function which $R(0) = 0$
 - $R: \mathbb{R}_0^+ \rightarrow \mathbb{R}_0^+$ is the vector represent time received donation
 - $X \in \mathbb{R}_0^+$ is total fulfilled demand
3. Vehicle is 3-tuples (s, l, b) such that
 - s is sink node index
 - $l \in \mathbb{R}_0^+$ is time during transportation process
 - $b \in \mathbb{R}_0^+$ is total utility value
4. Object is pair (B, d) such that
 - $B \in \mathbb{R}^+$ is utility value per piece
 - $d \in \mathbb{R}^+$ is time before expiration since object appear in the model

Description

In the model, disaster area is represented by m sub graphs denoted by G_i ; $\forall i \leq m$. These sub graphs called G_0 . It has been guaranteed that in case of different sub graphs, there exist only edges between source node. There exist n types of donation. For each day, there are inputs which determined by user represent incoming donations for every source node.



Demand Calculation

- General demand of node u at time t

Let $\phi_u(t): \mathbb{R}_0^+ \rightarrow \mathbb{R}_0^+$ such that

$$\phi_u(t) = r_u t + z_u$$

- Penalty demand of node u at time t

Let $\Phi_u(t): \mathbb{R}_0^+ \rightarrow \mathbb{R}_0^+$ such that

$$\Phi_u(t) = \sum_{i=1}^{|h|} \int_0^{h_i - h_{i-1}} R_u(T) dT + \int_0^{t - h_{|h|}} R_u(T) dT$$

- Total demand of node u at time t

Let $D_u(t): \mathbb{R}_0^+ \rightarrow \mathbb{R}_0^+$ such that

$$D_u(t) = \phi_u(t) + \Phi_u(t)$$

Objective

The objective of the model is to minimize $\lim_{t \rightarrow \infty} P(t)$ where

$$P(t) = \sum_{u \in V} \max^2(0, D_u(t) - X_u)$$