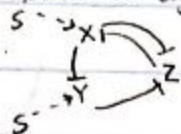


2. AC-DC: nonlinear dynamics



(a)  $\begin{pmatrix} \dot{X} \\ \dot{Z} \end{pmatrix} = \begin{pmatrix} \alpha_x + \beta_x s \\ \alpha_z \end{pmatrix} \frac{1}{1 + s + (\tilde{Z}/\tilde{Z}_x)^{n_{xz}}} - \tilde{\delta}_x \tilde{X}$

$\frac{\partial \tilde{Z}}{\partial t} = \frac{\alpha_z}{1 + (\tilde{X}/\tilde{X}_z)^{n_{xz}}} - \tilde{\delta}_z \tilde{Z}$

(b)  $\frac{\partial X}{\partial t} = \frac{\alpha_x + \beta_x s}{1 + s + (\tilde{Z}/\tilde{Z}_x)^{n_{xz}}} - X$

$\frac{\partial Z}{\partial t} = \frac{1}{1 + (\tilde{X}/\tilde{X}_z)^{n_{xz}}} - \delta_z Z$

Correction:  $t = \tilde{t} \tilde{\delta}_x$

$\frac{\partial \tilde{X}}{\partial \tilde{t}} = \frac{\partial [X \tilde{\alpha}_z / \tilde{\delta}_x]}{\partial [\tilde{t} / \tilde{\delta}_x]} = \frac{\alpha_x \tilde{\alpha}_z + \beta_x \tilde{\alpha}_z s}{1 + s + \left[ \left( \frac{\tilde{Z} \tilde{\alpha}_z}{\tilde{\delta}_x} \right) / \left( \frac{\tilde{Z} \tilde{\alpha}_z}{\tilde{\delta}_x} \right) \right]^{n_{xz}}} - \left( \tilde{\delta}_x \left( \frac{X \tilde{\alpha}_z}{\tilde{\delta}_x} \right) \right)$

$= \frac{\partial X}{\partial t} = \left[ \frac{\alpha_x + \beta_x s}{1 + s + \left[ \frac{\tilde{Z}}{\tilde{Z}_x} \right]^{n_{xz}}} - X \right] = \frac{\alpha_x + \beta_x s}{1 + s + \left[ \frac{\tilde{Z}}{\tilde{Z}_x} \right]^{n_{xz}}} - X$

$\frac{\partial \tilde{Z}}{\partial \tilde{t}} = \frac{\partial [Z \tilde{\alpha}_x / \tilde{\delta}_x]}{\partial [\tilde{t} / \tilde{\delta}_x]} = \frac{\alpha_z}{1 + \left[ \left( \frac{X \tilde{\alpha}_x}{\tilde{\delta}_x} \right) / \left( \frac{X \tilde{\alpha}_x}{\tilde{\delta}_x} \right) \right]^{n_{xz}}} - \tilde{\delta}_z \left[ \frac{Z \tilde{\alpha}_x}{\tilde{\delta}_x} \right]$

$= \frac{\partial Z}{\partial t} = \frac{1}{1 + \left[ \frac{X}{X_z} \right]^{n_{xz}}} - \delta_z Z$