

Artificial Neural Networks - Improving training and performance

Agenda

- The Challenges: Over fitting & local optima
- The Training
 - Epochs, Batch Size, Iterations
 - Gradient Descent (GD) Vs Stochastic GD (SGD) Vs Mini-Batch GD
 - SGD with momentum
 - Learning rates and adaptive learning rates
 - Weight Initialization
 - Batch Normalization
- Guarding against over-fitting
 - L1/L2 Regularization
 - Data Augmentation
 - Drop outs
- Neural Network Architectures

Epochs, Batch size, Iterations

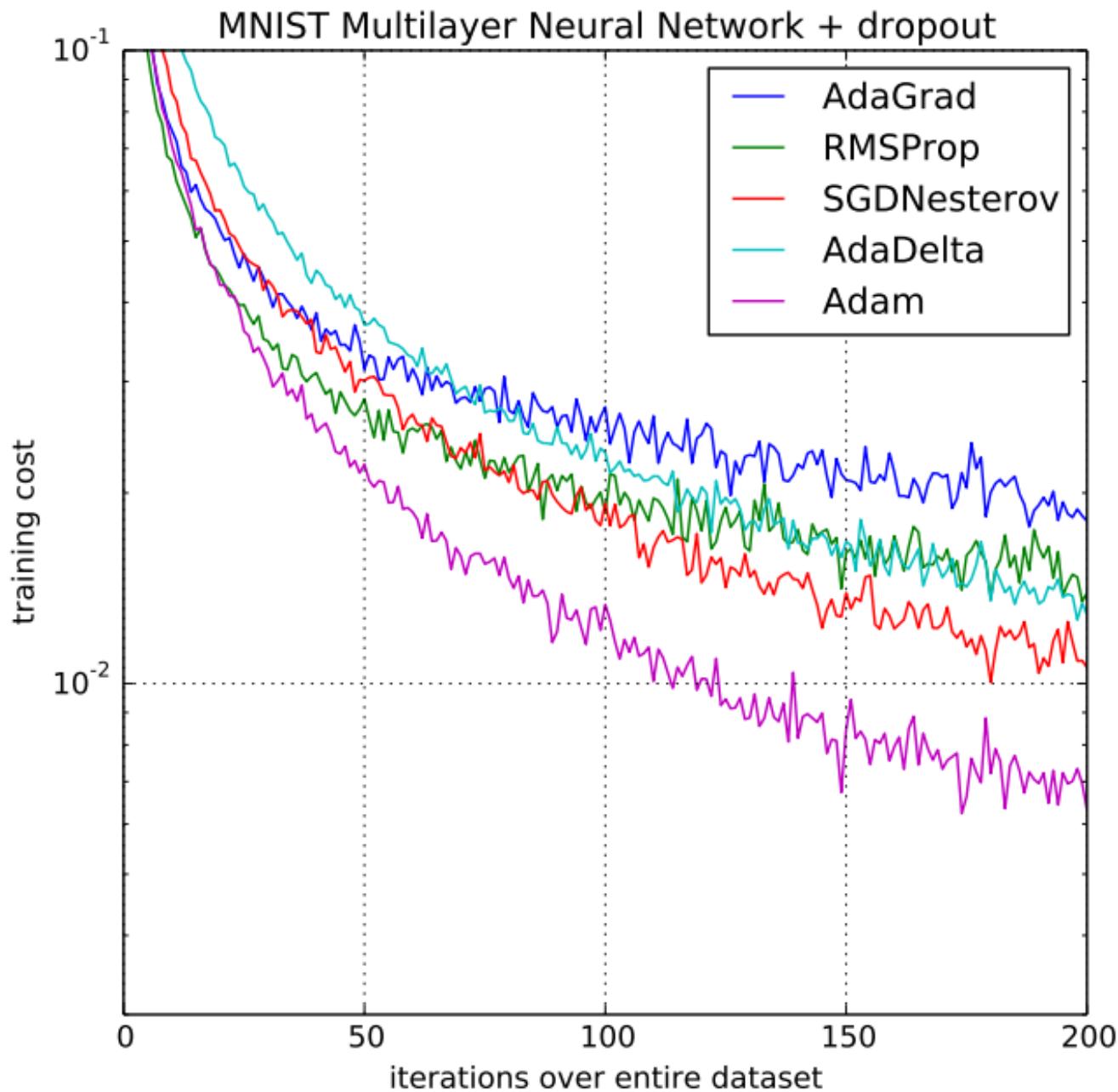
- When dataset is too large, passing all the data through a Neural net before we make weight updates is computationally expensive
- Instead we would create data batches with smaller batch size.
- After each batch is passed and weights updated, we will count it as one iteration.
- When an entire dataset is passed forward and backward (weights updated) through the neural network, we will count it as one epoch.
 - Too few epochs: under fitting, Too many: overfitting
 - Batch training: All of the training samples pass through the neural net, before weights are updated
 - Sequential training: Weights are updated after each training vector is passed through the neural net.

Gradient Descent and its Variants

- Gradient Descent
- Stochastic Gradient Descent
- Mini-Batch GD
- SGD with Momentum

Learning rate

- Choosing the Learning rate (η)
 - Too small, we will need too many iterations for convergence
 - Too large, we may skip the optimal solution
- Adaptive Learning Rate :
 - start with high learning rate and
 - gradually reduce the learning rate with each iteration.
 - Moreover, having different learning rates for different weight updates will help: Adagrad, RMS Prop



Weight Initialization Techniques

- Essential for efficient neural network training (esp. deep Neural Nets)
- Impacts:
 - gradient stability,
 - symmetry breaking,
 - reduced over fitting
 - and convergence speeds.
- Key Techniques:
 - Random Initialization: Small random numbers to break symmetry.
 - Xavier/Glorot Initialization: Scaled according to input and output size, for tanh/sigmoid activation.
 - He Initialization: Similar to Xavier but for ReLU activations.

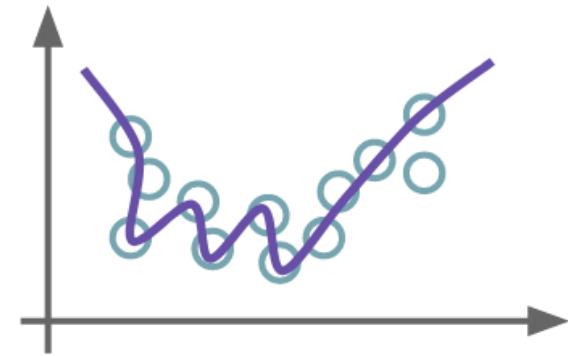
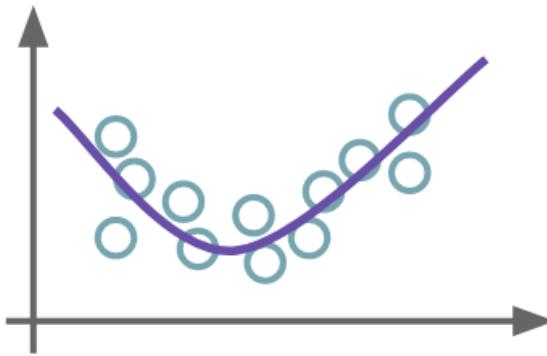
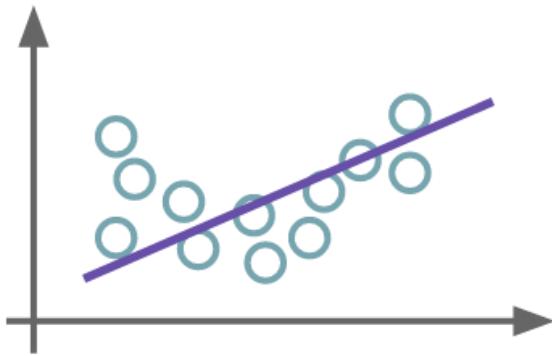
Batch Normalization

- Moving forward in neural nets, activations can become large or very small, and hence training can become unstable> weight initiations, input normalizations etc.
- What is Batch Normalization?
 - Batch.... Normalize
- Why does this work?
 - Covariate shifts> last layer > dist of inputs > keeps changing during training!
 - Regularization: each row when seen as a part of different batches, looks different in training. Disallows overfitting. Almost like data augmentation
- Normalization when testing or deploying?

Overfitting

- Neural Network Models are susceptible to overfitting
 - Large number of weights and biases
 - Excessive learning (Epochs) on training data
- Ways to avoid Overfitting
 - Increase sample size
 - Early stopping
 - Reduce Network Size
 - Regularization

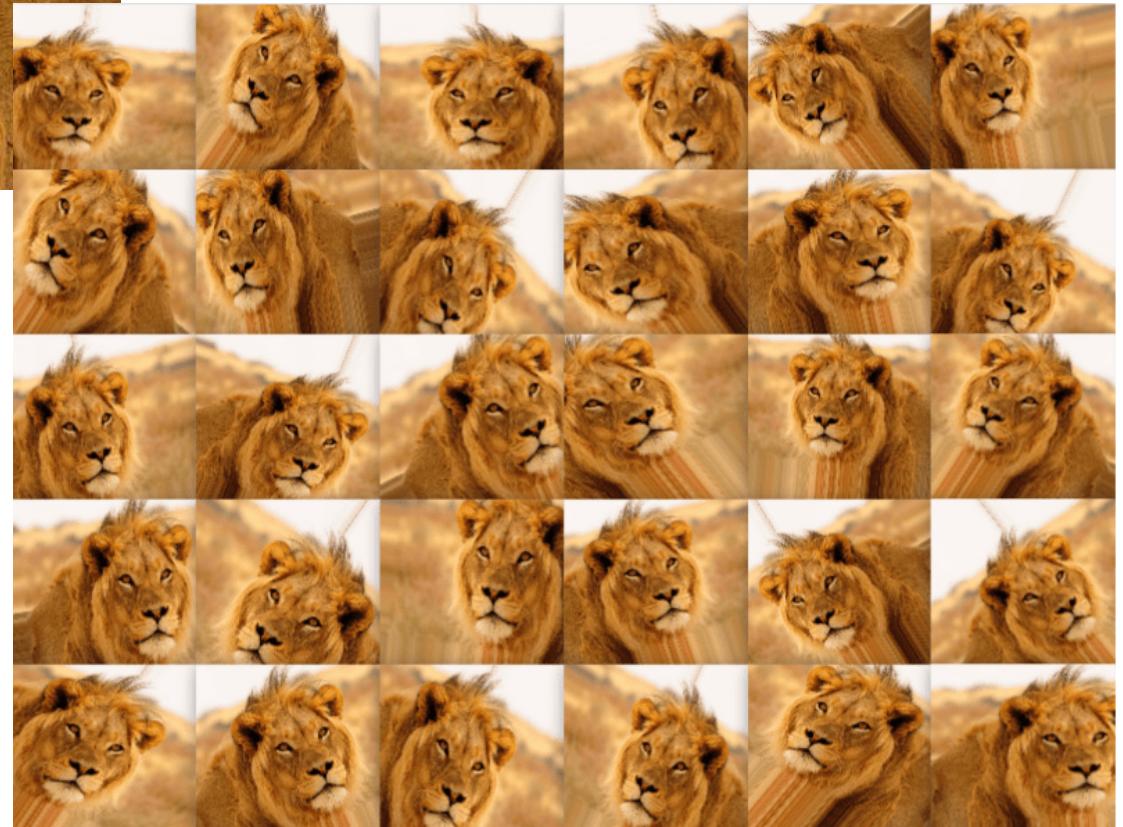
Under Vs Over-fitting



L1/L2 Regularization

- Regularization techniques are in general methods to avoid this overfitting problem.
- The idea behind regularization is that models that overfit the data are complex models that have for example too many parameters.
- Weight decay based regularization, penalizes the usual loss function by adding a complexity term that would give a bigger loss for more complex models.
- Types of Regularization
 - LASSO (L1)
 - Ridge (L2)
- Optimal value of λ , the decay rate or penalty coefficient, is determined through cross-validation

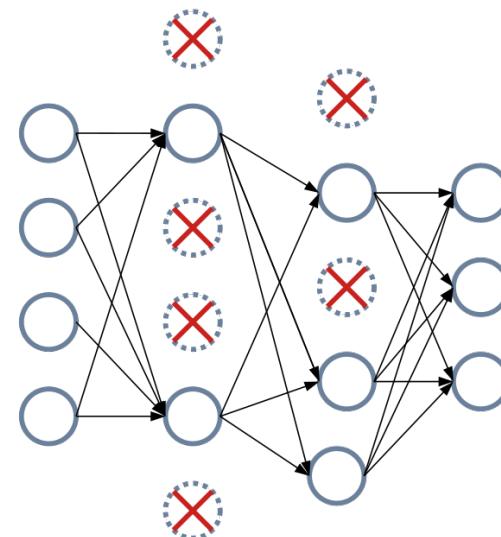
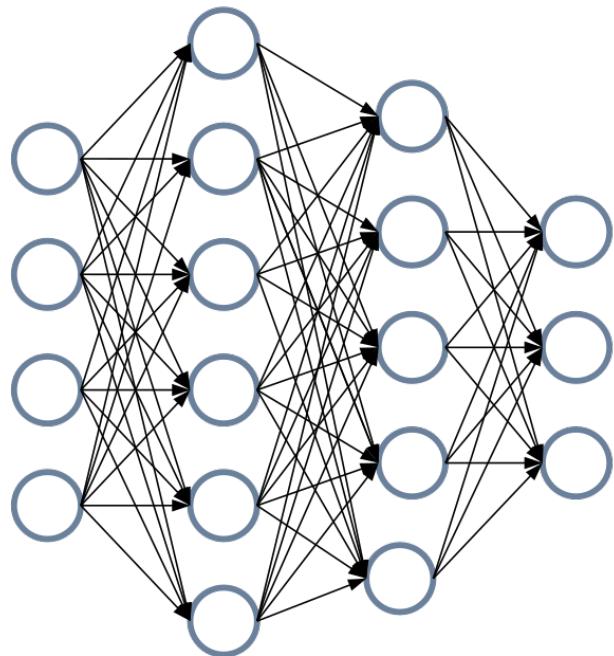
Data Augmentation



Dropout

- What is dropout? How is it implemented?
- Only in training
- Why does it work
 - Usual training: some nodes gain more predictive power than others
 - Forces redundancy and robustness
 - Training teams
 - Co-adapt > units change in a way to fix up mistakes induced in previous layers > overfitting to data (does not generalize) > Regularization
- Scaling weights appropriately after training.

Input layer Hidden layers Output layer



Types of NN

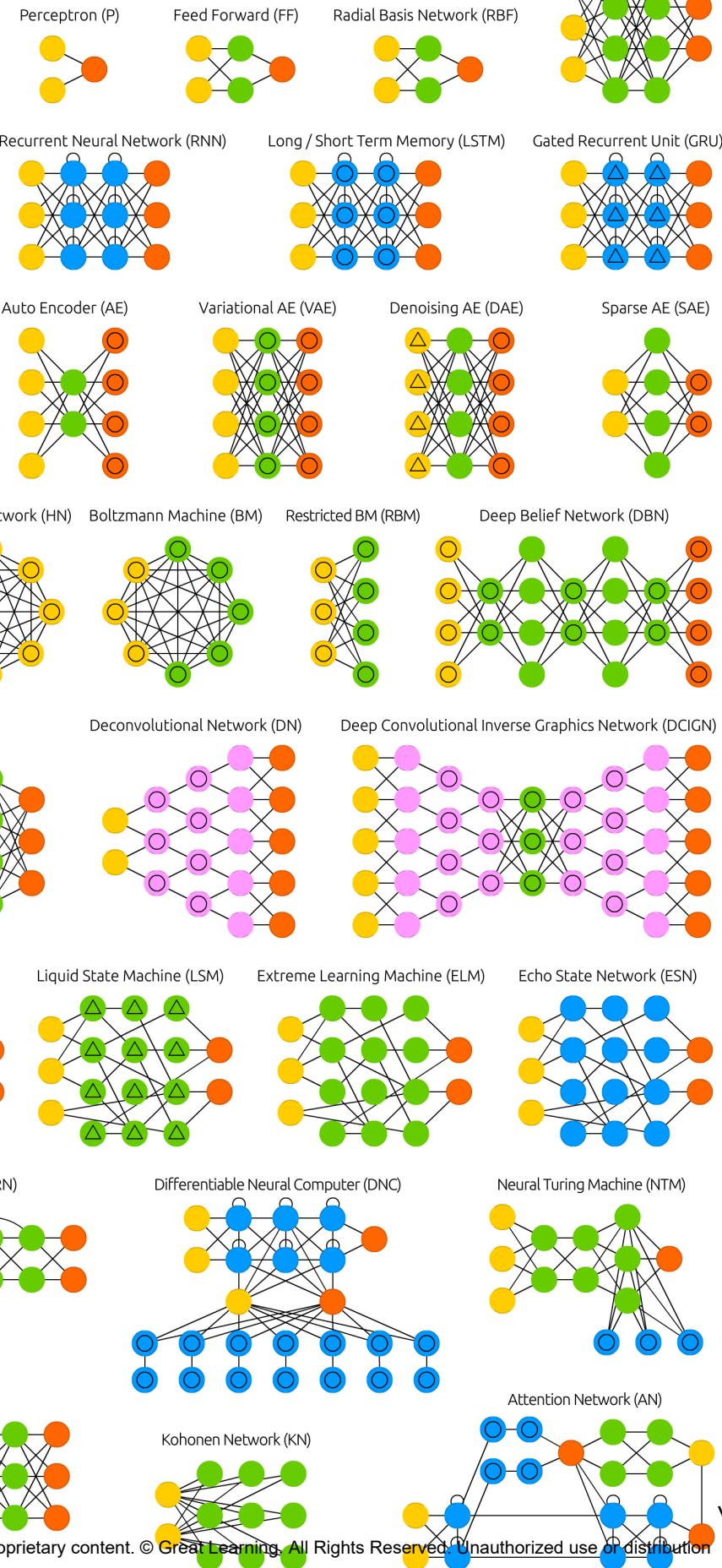
- Feed Forward
 - MLP
 - DNN
 - CNN
- RNN
- LSTM

A mostly complete chart of

Neural Networks

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- Input Cell
- Backfed Input Cell
- △ Noisy Input Cell
- Hidden Cell
- Probabilistic Hidden Cell
- △ Spiking Hidden Cell
- Capsule Cell
- Output Cell
- Match Input Output Cell
- Recurrent Cell
- Memory Cell
- △ Gated Memory Cell
- Kernel
- Convolution or Pool

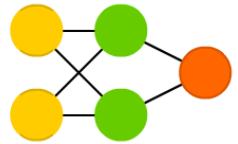


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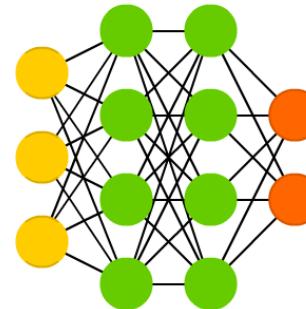
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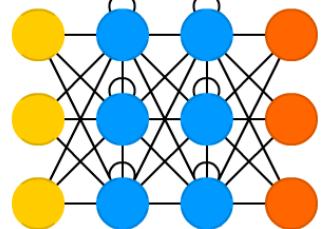
Feed Forward (FF)



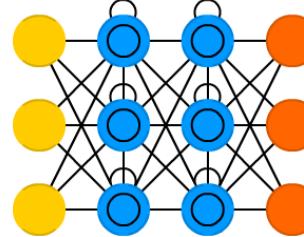
Deep Feed Forward (DFF)



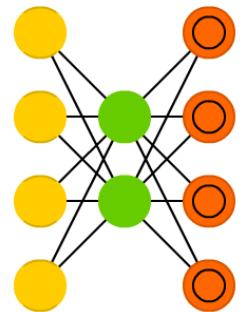
Recurrent Neural Network (RNN)



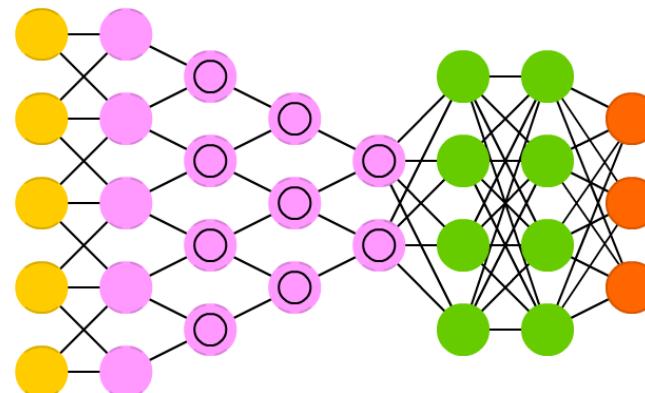
Long / Short Term Memory (LSTM)



Auto Encoder (AE)

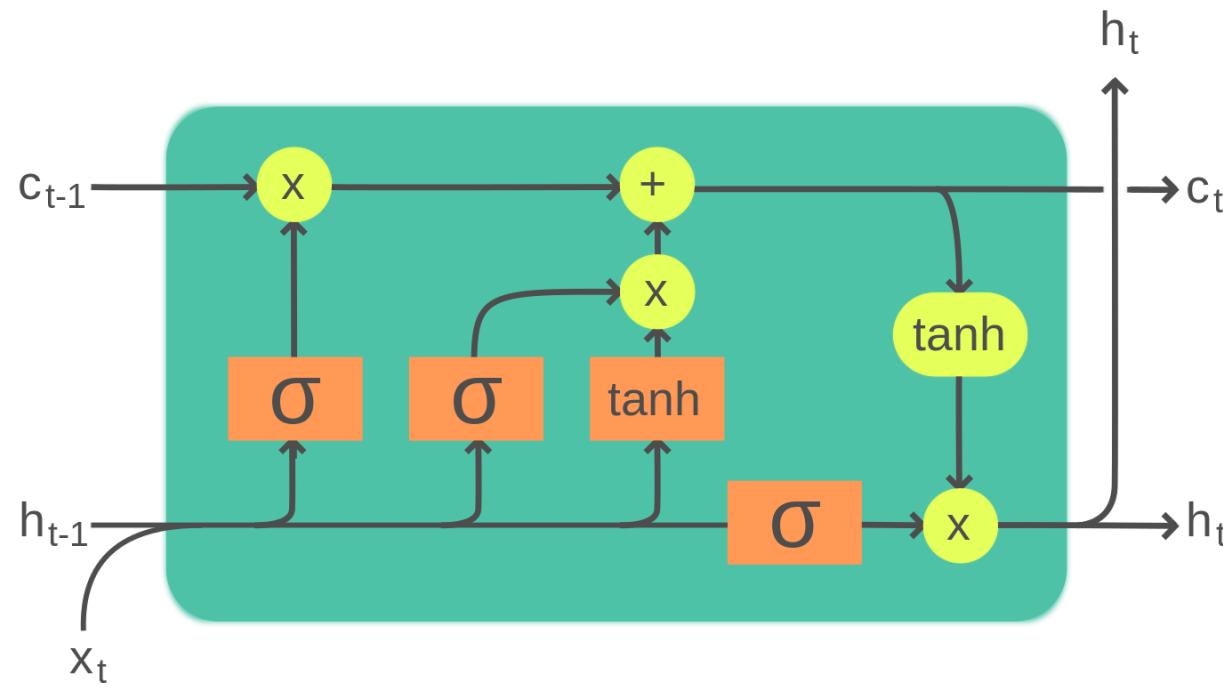


Deep Convolutional Network (DCN)



Text generation using an RNN

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Legend:

