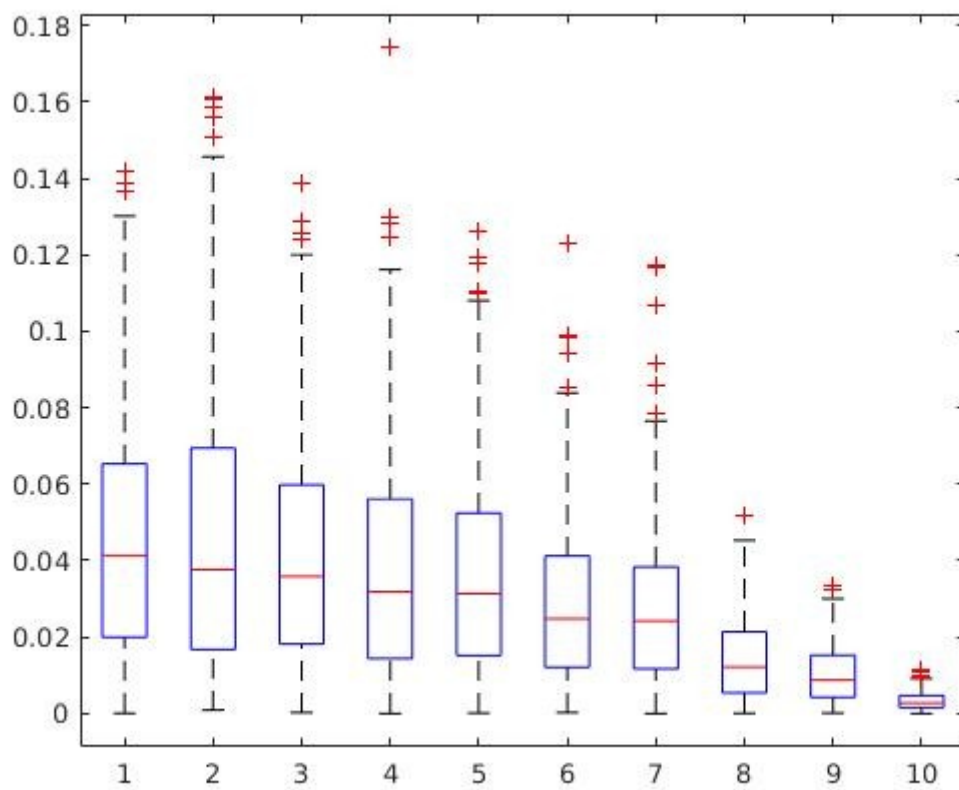


ASSIGNMENT-3

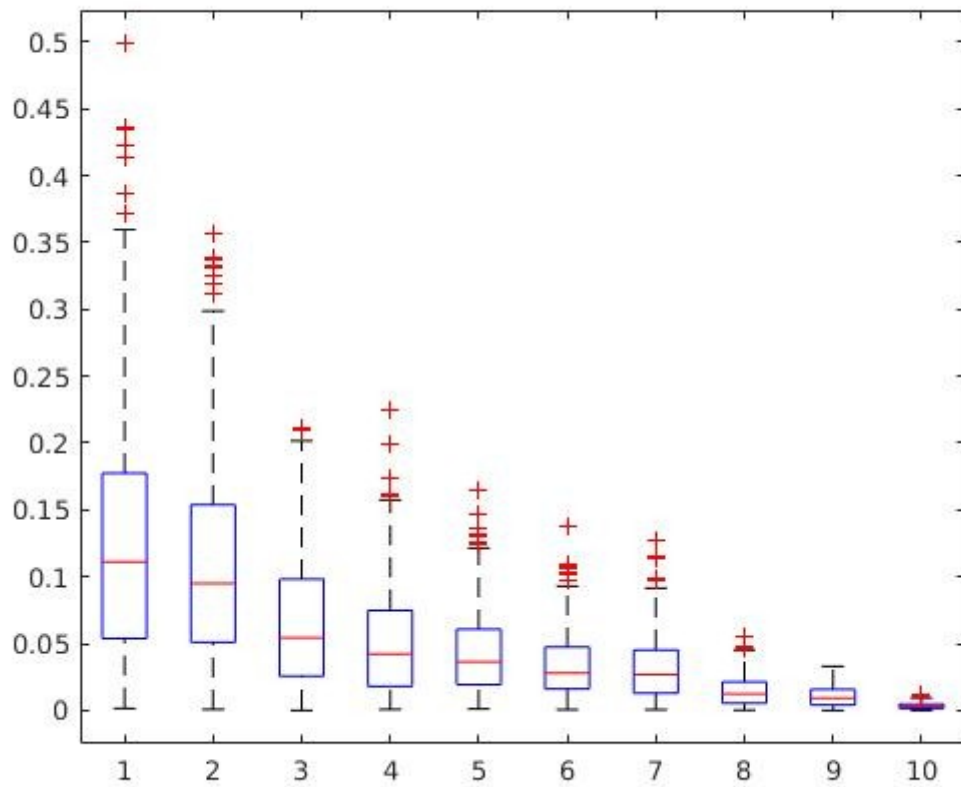
170050021 Abhijeet Singh Yadav

170050029 Devansh Garg

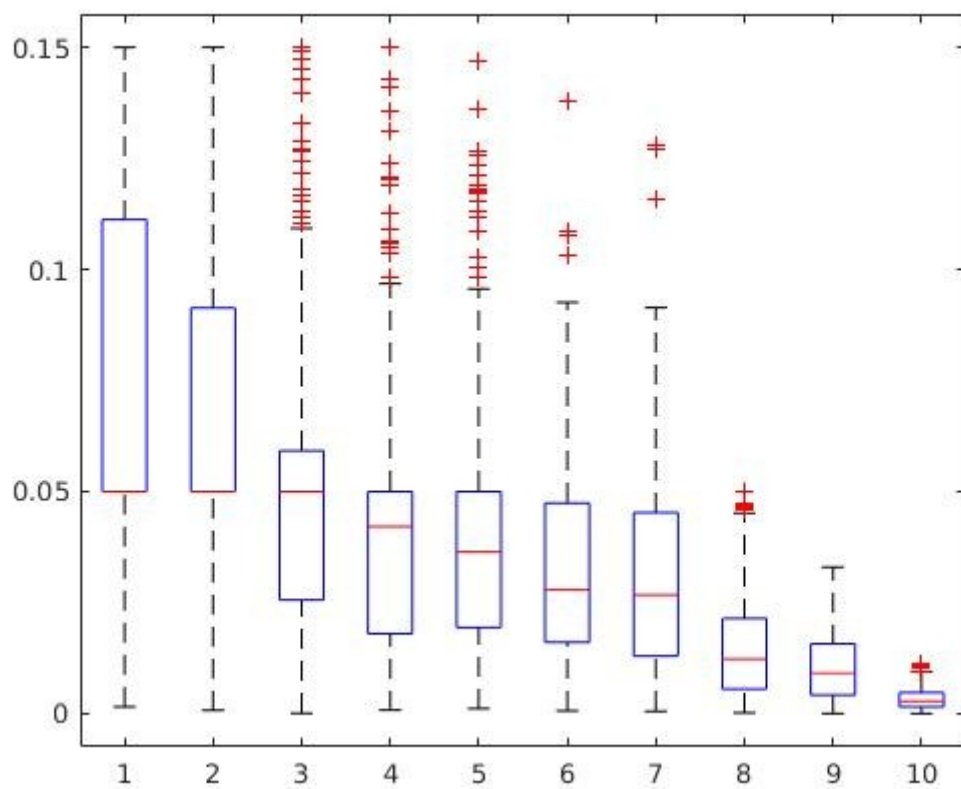
Q1.



Relative error with MAP-1



Relative error with ML



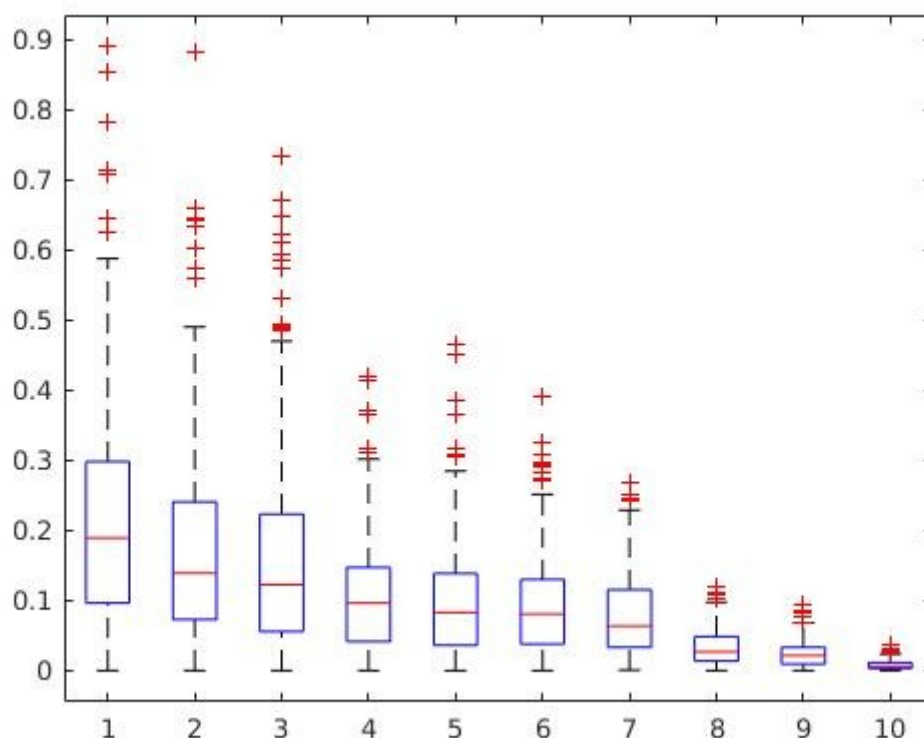
Relative error with MAP-2

Interpretation:

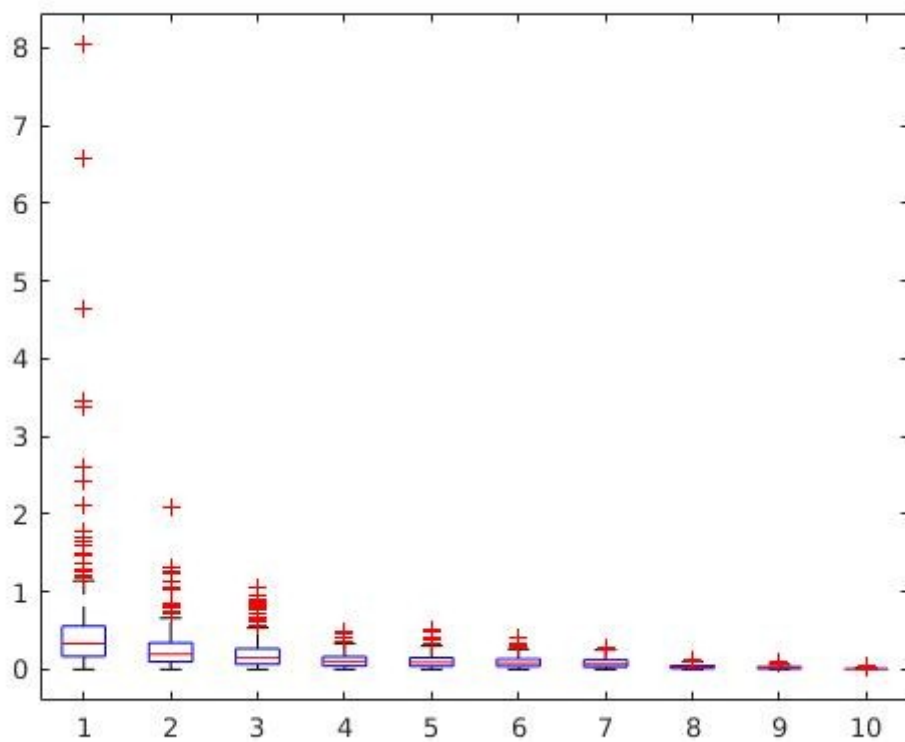
1. As N tends to infinity the Error becomes zero for all three estimators which shows their consistency
2. Gaussian Prior is preferred for small values of N because its error values are centered around zero and less scattered as it has small boxes

And for large values MLE is preferred as it has lowest mean squared error, consistency and asymptotic normality.

Q2.



Relative error when posterior mean estimator is used



Relative error with MLE

Interpretation:

1. As N tends to infinity the Error becomes zero for both the estimators which shows both estimators are consistent.
2. Posterior mean estimator is preferred for small values of N because its error values are centered around zero and less scattered as it has small boxes

$$P_{\text{prior}} = P(\lambda) = \frac{B^{\alpha} \lambda^{\alpha-1} e^{-B\lambda}}{\Gamma(\alpha)}$$

now, for the CDF of 'y'

$$F_Y(y) = P(Y \leq y)$$

$$= P\left(\frac{-1 \log x}{\lambda} \leq y\right)$$

$$= P(\log x \geq -\lambda y)$$

$$= P(x \geq e^{-\lambda y})$$

$$= 1 - P(x < e^{-\lambda y})$$

$$= 1 - e^{-\lambda y}$$

{ As 'x' is of the form (0,1) }

$$f_Y(y) = \lambda e^{-\lambda y}$$

$$P(\text{data}|\lambda) = \text{likelihood} = \lambda^n e^{-\lambda \sum_{i=1}^n y_i} \left\{ \prod_{i=1}^n \lambda e^{-\lambda y_i} \right\}$$

for M.L.E.

$$\frac{\partial (\text{likelihood})}{\partial \lambda} = 0$$

$$\Rightarrow n \lambda^{n-1} e^{-\lambda \sum y_i} - \sum y_i \lambda^n e^{-\lambda \sum y_i} = 0$$

$$\Rightarrow n = \sum y_i \lambda$$

$$\Rightarrow \hat{\lambda}^{ML} = \frac{n}{\sum_{i=1}^n y_i}$$

Probability of data can be calculated as

$$P(\text{data}) = \int_0^{\infty} P(\text{data}|\lambda) P(\lambda) d\lambda$$

$$= \int_0^{\infty} \lambda^n e^{-\lambda \sum y_i} \cdot \frac{\beta^\alpha \lambda^{\alpha-1} e^{-\beta\lambda}}{Z(\lambda)} d\lambda$$

then,

$$\hat{\lambda}^{\text{Posterior mean}} = E_{P(\lambda|\text{data})}[\lambda] \quad \theta: \text{parameter}$$

$$= \int_0^{\infty} \lambda \frac{P(\text{data}|\lambda) P(\lambda)}{P(\text{data})} d\lambda$$

$$= \frac{\int_0^{\infty} \lambda \cdot \frac{\lambda^n e^{-\lambda \sum y_i} \beta^\alpha \lambda^{\alpha-1} e^{-\beta\lambda}}{Z(\lambda)} d\lambda}{\int_0^{\infty} \frac{\lambda^n e^{-\lambda \sum y_i} \beta^\alpha \lambda^{\alpha-1} e^{-\beta\lambda}}{Z(\lambda)} d\lambda}$$

$\left\{ \begin{array}{l} \text{As } P(\text{data}) \text{ is} \\ \text{constant w.r.t.} \\ \lambda \\ \text{so is } P(\lambda) \\ \text{and } Z(\lambda) \end{array} \right\}$

$$= \frac{\int_0^{\infty} \lambda^{n+\alpha} e^{-\lambda(\beta + \sum y_i)} d\lambda}{\int_0^{\infty} \lambda^{n+\alpha-1} e^{-\lambda(\beta + \sum y_i)} d\lambda}$$

Apply integration by parts

$$\hat{\lambda}_{\text{Poisson mean}} = \frac{\int_0^{\infty} \frac{e^{-\lambda(\bar{y}_i + \beta)} \lambda^{n+\alpha} d\lambda}{-(\bar{y}_i + \beta)} - \int_0^{\infty} \frac{(n+\alpha) \lambda^{n+\alpha-1} e^{-\lambda(\bar{y}_i + \beta)} d\lambda}{-(\bar{y}_i + \beta)}}{\int_0^{\infty} \lambda^{n+\alpha-1} e^{-\lambda(\bar{y}_i + \beta)} d\lambda}$$

The first term in numerator goes to zero

$$\begin{aligned} \text{So, } \hat{\lambda}_{\text{Poisson mean}} &= \frac{(n+\alpha)}{\bar{y}_i + \beta} \frac{\int_0^{\infty} \lambda^{n+\alpha-1} e^{-\lambda(\bar{y}_i + \beta)} d\lambda}{\int_0^{\infty} \lambda^{n+\alpha-1} e^{-\lambda(\bar{y}_i + \beta)} d\lambda} \\ &= \frac{n+\alpha}{\bar{y}_i + \beta} \end{aligned}$$

Q3.

Q3:

$$P(x; \mu, C) = \frac{1}{\sqrt{2\pi|C|}} e^{-\frac{1}{2}(x-\mu)^T C^{-1}(x-\mu)}$$

The likelihood is

$$f(x|\mu, C) = \frac{1}{(\sqrt{2\pi|C|})^n} e^{-\frac{1}{2} \sum_{i=1}^n (x_i - \mu)^T C^{-1} (x_i - \mu)}$$

the log likelihood

$$\log(f(x|\mu, C)) = -\frac{n}{2} \log(2\pi|C|) - \frac{1}{2} \sum_{i=1}^n (x_i - \mu)^T C^{-1} (x_i - \mu)$$

$\therefore \frac{\partial \log(f(x|\mu, C))}{\partial \mu} = 0$ if μ doesn't depend on A ($A \equiv \text{symmetric}$)
which is the case here as covariance matrix C is symmetric

So,

$$\begin{aligned} \frac{\partial \log(f(x|\mu, C))}{\partial \mu} &= -\frac{1}{2} \sum_{i=1}^n (-1) \cdot 2 \cdot C^{-1} (x_i - \mu) \\ &= \frac{1}{2} \sum_{i=1}^n (2C^{-1} (x_i - \mu)) \end{aligned}$$

For MLE it goes to zero
 $\therefore C \neq 0$

$$\Rightarrow \sum_{i=1}^n (x_i - \mu) = 0$$

$$\Rightarrow \left[\hat{\mu}_{MLE} = \frac{\sum_{i=1}^n x_i}{n} \right]$$

as we draw value from a ring as x being $\begin{bmatrix} \mu \cos \theta \\ \mu \sin \theta \end{bmatrix}$

$$\hat{\mu}_i = \frac{\sum_{i=1}^n \begin{bmatrix} \mu \cos \theta \\ \mu \sin \theta \end{bmatrix}}{n} = 0$$

as for a large data set every θ will have such θ' that

$$(\theta = \theta + \pi)$$

$$(\cos \theta = -\cos \theta')$$

$$\sin \theta = -\sin \theta'$$

and they become zero

$\therefore (x_i - \mu)^T C^{-1} (x_i - \mu)$ will be scalar it can be equalled to the trace of a 1×1 matrix having $(x_i - \mu)^T C^{-1} (x_i - \mu)$ as element

$$(x_i - \mu)^T C^{-1} (x_i - \mu) = \text{trace}((x_i - \mu)^T C^{-1} (x_i - \mu))$$

so,

$$\begin{aligned} \frac{\partial \log f(x|\mu, C)}{\partial C^{-1}} &= \frac{\partial}{\partial C^{-1}} \left[-\frac{n}{2} \log 2\pi - \frac{n}{2} \log |C| - \frac{1}{2} \sum_{i=1}^n (x_i - \mu)^T C^{-1} (x_i - \mu) \right] \\ &= \frac{\partial}{\partial C^{-1}} \left[\left(\frac{n}{2} \log |C^{-1}| \right) - \frac{1}{2} \sum_{i=1}^n \underbrace{(x_i - \mu)^T C^{-1} (x_i - \mu)}_{\text{equivalent to}} \right] \quad \text{--- (1)} \\ &\quad \text{trace}((x_i - \mu)^T C^{-1} (x_i - \mu)) \end{aligned}$$

now,

$$\therefore \frac{\partial \log |A|}{\partial A} = A^{-T}$$

and,
g.f.

$$x^T A x = \text{trace}(x^T A x) = \text{trace}(x x^T A) \quad \left[\text{property of cyclic trace} \right]$$

so,

$$\frac{\partial}{\partial A} \text{trace}(AB) = B^T$$

$$\text{so } \frac{\partial}{\partial A} \text{trace}(C^{-1} x x^T) = x^T x$$

hence eqn (1) reduces to

$$= \frac{n}{2} C - \frac{1}{2} \sum_{i=1}^n (x_i - \mu)(x_i - \mu)^T \quad (\text{using cyclic trace})$$

equating to zero,

$$\hat{C} = \frac{1}{n} \sum_{i=1}^n (x_i - \mu)(x_i - \mu)^T$$

$$= \frac{1}{n} \sum_{i=1}^n \begin{bmatrix} \mu \cos \theta \\ \mu \sin \theta \end{bmatrix} \begin{bmatrix} \mu \cos \theta & \mu \sin \theta \end{bmatrix}$$

$$= \frac{1}{n} \sum_{i=1}^n \begin{bmatrix} \mu^2 \cos^2 \theta & \mu^2 \sin \theta \cos \theta \\ \mu^2 \sin \theta \cos \theta & \mu^2 \sin^2 \theta \end{bmatrix}$$

$$\text{avg}(\cos^2 x)_{\text{over } [0, 2\pi]} = 1/2$$

$$\text{avg}(\sin^2 x)_{\text{over } [0, 2\pi]} = 1/2$$

$$\text{so, } C = \frac{1}{2} \begin{bmatrix} \mu^2 & 0 \\ 0 & \mu^2 \end{bmatrix} \text{ as } \mu \neq 0$$

① In a gaussian model = mean

so here, model = (0,0)

but all the points are $(\mu \cos \theta, \mu \sin \theta)$ which ~~together~~ can't be (0,0) as $\mu \neq 0$

→ This doesn't fit the given data well as the model value must be something on the boundary point

→ The applied model is not correct hence the model is not good. Also points ~~are~~ are equidistant from mean so they must have the same probability so gaussian model is of no use here.

① In a unit radius circle for 10^5 points

$$\text{mean} = (0.00013, -0.00060) \quad \text{theoretical value} = (0,0)$$

(Almost equal)

$$\text{covariance matrix} = \begin{bmatrix} 0.5001 & -0.0036 \\ 0.0019 & 0.4999 \end{bmatrix} \quad \text{theoretical value} = \begin{bmatrix} 0.5 & 0 \\ 0 & 0.5 \end{bmatrix}$$

(Almost matches)

Q4.

Q.4.

$$\therefore X \sim U(0, \theta)$$

$$f_X(x) = \frac{1}{\theta} \quad 0 < x < \theta$$

$$0 \quad \text{otherwise}$$

$$f_X(x_1, x_2, \dots, x_n; \theta) = \frac{1}{\theta^n} \quad 0 < x_1, x_2, \dots, x_n < \theta$$
$$0 \quad \text{otherwise}$$

and
for
that

$$\theta \geq \max(x_1, x_2, \dots, x_n)$$

$$\Rightarrow \theta_{\min} = \max(x_1, x_2, \dots, x_n)$$

$$\hat{\theta}_{ML} = \max(x_1, x_2, \dots, x_n)$$

for ~~Posterior~~ MAP estimate

$$P(\theta | \text{data}) = \frac{P(\text{data} | \theta) P(\theta)}{P(\text{data})}$$

$$= \begin{cases} C \left(\frac{1}{\theta^n} \right) \left(\frac{\theta_m}{\theta} \right)^d \\ 0 \end{cases}$$

using the desired
prior distribution
- Prior

$$- \theta \geq x_1, x_2, \dots, x_n, \theta_m$$

otherwise

so,

$$\hat{\theta}_{MAP} = \max(x_1, x_2, \dots, x_n, \theta_m)$$

$$P(\text{data}) = \int_{\hat{\theta}_{MAP}}^{\infty} P(\text{data}|\theta) f(\theta) d\theta$$

$$= \int_{\hat{\theta}_{MAP}}^{\infty} C \left(\frac{1}{\theta}\right)^n \left(\frac{\theta m}{\theta}\right)^{\lambda} d\theta$$

$$\hat{\theta}_{MAP} \text{ Posterior mean} = E_{P(\theta|\text{data})} [\theta]$$

$$= \int_{\hat{\theta}_{MAP}}^{\infty} \theta \frac{P(\text{data}|\theta) f(\theta)}{P(\text{data})} d\theta$$

$$= \int_{\hat{\theta}_{MAP}}^{\infty} \theta \frac{\left(\frac{1}{\theta}\right)^n \left(\frac{\theta m}{\theta}\right)^{\lambda} d\theta}{\int_{\hat{\theta}_{MAP}}^{\infty} \left(\frac{1}{\theta}\right)^n \frac{\theta^{\lambda}}{\theta^{\lambda}} d\theta}$$

$$= \frac{\int_{\hat{\theta}_{MAP}}^{\infty} \theta^{1-n-\lambda} d\theta}{\int_{\hat{\theta}_{MAP}}^{\infty} \theta^{-n-\lambda} d\theta}$$

$$= \frac{\int_{\hat{\theta}_{MAP}}^{\infty} \theta^{2-n-\lambda} d\theta}{\int_{\hat{\theta}_{MAP}}^{\infty} \theta^{1-n-\lambda} d\theta} = \frac{(\hat{\theta}_{MAP})^{2-n-\lambda} (1-n-\lambda)}{(\hat{\theta}_{MAP})^{1-n-\lambda} (2-n-\lambda)}$$

$$= (\hat{\theta}_{MAP}) \left(\frac{n+\lambda-1}{n+\lambda-2} \right)$$

Part (b) and (d).

③ Let θ_{true} be the true value of θ

If $\theta_{true} > \theta_m$ then $\hat{\theta}_{MAP} \rightarrow \hat{\theta}_{MLE}$ as $n \rightarrow \infty$
 because x_i will cover whole range of $[0, \theta]$ and there will
 be some x_i in $(\theta_m, \theta_{true})$

$$\Rightarrow \hat{\theta}_{MAP} \rightarrow \hat{\theta}_{MLE} \quad [\text{Desirable}] \quad \text{good estimator for large } n$$

otherwise, if $\theta_{true} < \theta_m$

$$\Rightarrow \theta_m > \max(x_1, x_2, \dots, x_n)$$

$$\Rightarrow \hat{\theta}_{MAP} = \theta_m$$

and $\hat{\theta}_{MAP} \not\rightarrow \hat{\theta}_{MLE}$ as it will always be more than the former

[Not desirable]

④

$$\hat{\theta}_{\text{posterior mean}} = \hat{\theta}_{MAP} \left(\frac{n+\alpha-1}{n+\alpha-2} \right)$$

as $n \rightarrow \infty$

$$\hat{\theta}_{\text{posterior mean}} \rightarrow \hat{\theta}_{MAP}$$

again like in Part (b) due to similar reason

$$\text{if } \theta_m < \theta_{true} \quad \hat{\theta}_{p.m.} \rightarrow \hat{\theta}_{MLE} \quad \text{desirable}$$

$$\theta_m > \theta_{true} \quad \hat{\theta}_{p.m.} \not\rightarrow \hat{\theta}_{MLE} \quad \text{undesirable}$$