

• Reynolds transport theorem:

$$\left. \begin{array}{l} \alpha(\vec{x}, t) \text{ any property} \\ I = \int_{V(t)} \alpha d^3x \\ \chi = \begin{cases} 1 & \text{if } x \in V(t) \\ 0 & \text{else} \end{cases} \end{array} \right\} I = \int_{\mathbb{R}^3} \alpha \chi d^3x$$

$$\dot{I} = \int_{\mathbb{R}^3} \left(\frac{\partial \alpha}{\partial t} \chi + \alpha \frac{\partial \chi}{\partial t} \right) d^3x \quad \left| \quad \frac{D\chi}{Dt} = 0 = \frac{\partial \chi}{\partial t} + \underbrace{\vec{v} \cdot \vec{\nabla} \chi}_{\text{divergence}}$$

$$\Rightarrow \dot{I} = \int_{V(t)} \left[\frac{\partial \alpha}{\partial t} + \vec{\nabla} \cdot (\alpha \vec{v}) \right] d^3x$$

• Virial theorem:

inertia tensor $I = \int \rho x_i x_j d^3x$

inertia tensor $\equiv \int_{\Omega(t)} \rho \dots$

$$\hookrightarrow \frac{1}{2} \frac{dI}{dt} = \frac{1}{2} \int_{\Omega} \rho \frac{Dx^2}{Dt} d^3x = \int_{\Omega} \rho (\vec{x} \cdot \vec{v}) d^3x \quad \left| \quad \frac{1}{2} \frac{Dx^2}{Dt} = \vec{x} \cdot \frac{D\vec{x}}{Dt} \right.$$

$$\hookrightarrow \frac{1}{2} \frac{d^2 I}{dt^2} = \int_{\Omega} \rho \frac{D}{Dt} (\vec{x} \cdot \vec{v}) d^3x \quad \left| \text{use 2nd Euler equation} \right.$$

$$= \underbrace{\int_{\Omega} \rho v^2 d^3x}_{2K} + \underbrace{\int_{\Omega} \rho \vec{x} \cdot \vec{g} d^3x}_V \text{ (Virial)} - \underbrace{\int_{\Omega} \vec{x} \cdot \vec{\nabla} \underline{P} d^3x}_{\mathcal{S}}$$

• equilibrium condition:

$$\frac{1}{2} \frac{d^2 I}{dt^2} = 2K + V - \mathcal{S} = 0$$

• Spherical cow / 0D model:

$$\text{gravity: } \Delta \phi = -\vec{\nabla} \cdot \vec{g} = 4\pi G \rho$$

$$\left[\int n l d^3 \quad G \int d^3 \quad 4\pi G M \right]$$

$$\left. \begin{aligned} \int \Delta \phi d^3x &= 4\pi G \int \rho d^3x = 4\pi GM \\ \int_V \vec{\nabla} \cdot \vec{g} d^3x &= \int \vec{g} \cdot \vec{n} dS = -g_r 4\pi R^2 \end{aligned} \right\} g_r = -\frac{GM}{R^2}$$

Virial theorem:

$$\boxed{K} = \int \left(\underbrace{\frac{1}{2} \rho v^2}_{=0} + \frac{3}{2} P \right) d^3x = \frac{3}{2} P \cdot \frac{4\pi}{3} R^3$$

$$\boxed{V} = \int \rho \vec{g} \cdot \vec{x} d^3x = \rho \int_0^R -g_r \cdot r \cdot 4\pi r^2 dr = -\frac{4\pi}{3} G \rho^2 4\pi \frac{R^5}{5}$$

$$\boxed{S} = 0$$

$$\Rightarrow \frac{1}{2} \ddot{I} = \frac{3P}{2} \frac{4\pi}{3} R^3 - \frac{4\pi}{3} R^3 G \rho^2 \frac{4\pi}{5} R^2 \stackrel{\text{in equilibrium}}{=} 0$$



$$\Rightarrow \boxed{\frac{3P}{2} = \frac{4\pi}{5} G \rho^2 R^2}$$

$$\hookrightarrow 2U - V = 0 \quad \Leftrightarrow \quad 3P \cdot V = \frac{GM}{R} M$$

$$P = \rho \frac{k_B T}{m} \quad (\text{Maxwell-Boltzmann gas})$$

$$\hookrightarrow \frac{k_B T}{m} = \alpha \frac{GM}{R}$$

• Spherical / Cylindrical coordinates :

$$\frac{D}{Dt} = \frac{\partial}{\partial t} + v_r \frac{\partial}{\partial r} + v_\vartheta \frac{1}{r} \frac{\partial}{\partial \vartheta} + v_z \frac{\partial}{\partial z} \quad (\text{cylindrical})$$



$$\frac{Dv_r}{Dt} = \frac{v_\vartheta^2}{r} - \frac{1}{\rho} \frac{\partial P}{\partial r} - \frac{\partial \phi}{\partial r}$$

$$\frac{Dv_\vartheta}{Dt} = -\frac{v_r v_\vartheta}{r} - \frac{1}{\rho} \frac{\partial P}{r \partial \vartheta} - \frac{\partial \phi}{r \partial \vartheta}$$

$$\frac{Dv_z}{Dt} = -\frac{1}{\rho} \frac{\partial P}{\partial z} - \frac{\partial \phi}{\partial z}$$

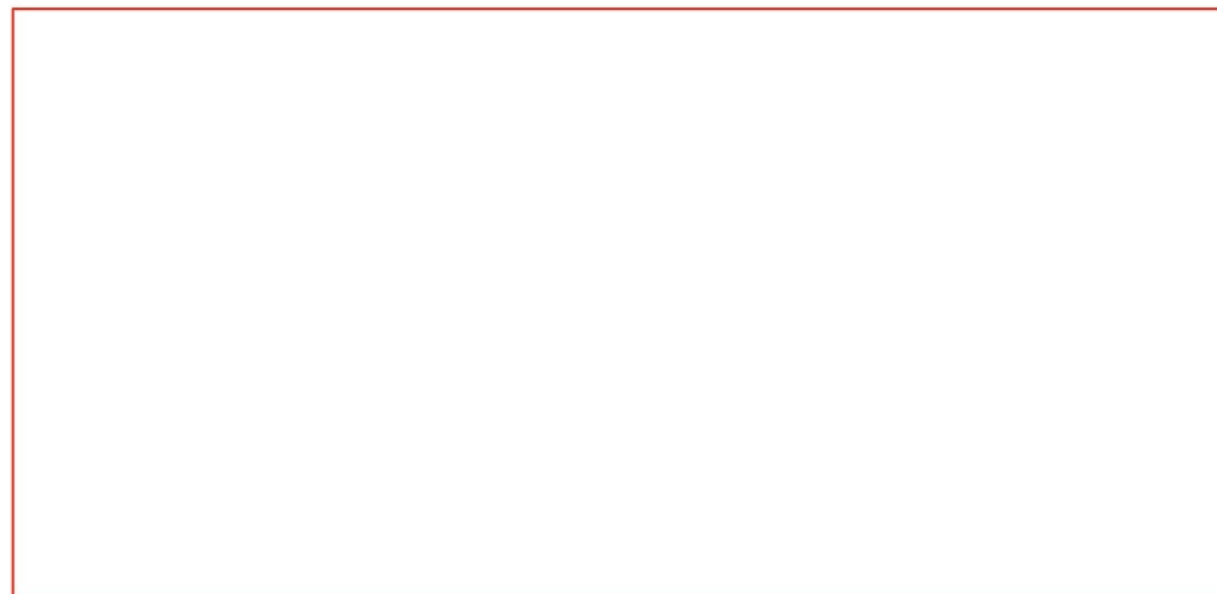
in cylindrical

coordinates

$$\vec{\nabla} \cdot \vec{v} = \frac{1}{r} \frac{\partial}{\partial r}(rv_r) + \frac{1}{r} \frac{\partial}{\partial \vartheta}(v_\vartheta) + \frac{\partial}{\partial z}(v_z)$$

• Hydrostatic equilibrium for spherical systems:

$\vec{v} = 0$; spherical symmetry ; no centrifugal forces



Euler equation:

$$-\frac{1}{\rho} \frac{\partial P}{\partial r} = \frac{\partial \phi}{\partial r}$$

Poisson equation:

$$\Delta \phi = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial \phi}{\partial r} \right) = 4\pi G \rho$$

+ EOS (e.g. isothermal $P = \rho a^2$ or polytropic $P = P_0 \left(\frac{\rho}{\rho_0} \right)^\gamma$)

$$\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{1}{\rho} \frac{\partial P}{\partial r} \right) = -4\pi G \rho$$

↳ Lane-Emden equation: (e.g. polytropic)

$$\frac{1}{x^2} \frac{d}{dx} \left(x^2 \frac{d\vartheta}{dx} \right) = -\vartheta^n$$

with $x \equiv \frac{r}{r_0}$; $\vartheta^n \equiv \left(\frac{\rho}{\rho_0} \right)$

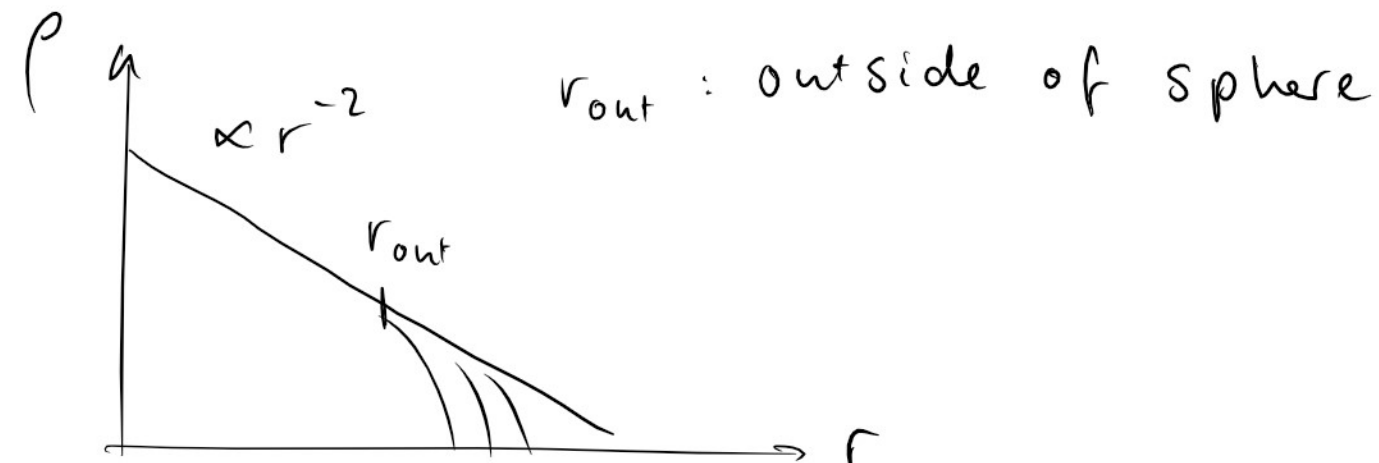
↳ $n=5$: halo structure

• in isothermal case:

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Laue - Emden \Rightarrow singular isothermal sphere

$$\rho = \frac{\sigma^2}{2\pi G r^2}$$



• Disks : (axis-symmetric)

surface density : $\Sigma(r) = \int_{-a}^{\infty} \rho(r, z) dz$

mass conservation : $\frac{\partial \Sigma}{\partial t} + \frac{1}{r} \frac{\partial}{\partial r} (r \Sigma v_r) = 0$

equilibrium of Euler equation :
(centrifugal equilibrium)

$$\frac{v_\phi^2}{r} - \frac{GM}{r^2} = \frac{1}{\Sigma} \frac{\partial P}{\partial r}$$

isothermal $P = \Sigma a^2$

$$v_\phi \approx \sqrt{\frac{GM}{r}} ; \Omega \equiv \frac{v_\phi}{r}$$

mass flux : $\dot{M} = \Sigma v_r 2\pi r$

viscosity $\rightarrow \dot{M} = -6\pi r^{1/2} \frac{\partial}{\partial r} (v \Sigma r^{1/2}) ; v = C_s \lambda$

aspect ratio: $\frac{H}{r} = \frac{a}{v_k} ; H \simeq \frac{a}{\Omega} ; \rho = \rho_0 \cdot e^{-\frac{z^2}{2H^2}}$

vertical equilibrium

• Bondi accretion: (spherical flow)

$$\frac{1}{2} m v^2 = m \frac{GM}{r} \quad \begin{matrix} v \equiv c_\infty \\ r \equiv r_B \end{matrix} \rightarrow r_B = \frac{2GM}{c_\infty^2}$$

$$\dot{M}_{acc} = A \cdot \rho \cdot v = \pi r_B^2 \cdot \rho_\infty \cdot c_\infty$$

$$\hookrightarrow \dot{M}_{acc} = 4\pi \frac{G^2 M^2}{c_\infty^3} \rho_\infty$$

• Bernoulli theorem:

1st theorem: $\frac{D}{Dt} \left(\frac{v^2}{2} + \phi + h \right) = \frac{\partial \phi}{\partial t} + \frac{1}{\rho} \frac{\partial P}{\partial t}$ on streamlines constant

1st theorem :

$$\frac{D}{Dt} \left(\frac{v}{\rho} \right) = 0$$

2nd theorem :

$$\frac{\partial \tilde{v}}{\partial t} + \tilde{v} \left(\frac{v^2}{2} + \phi + \pi \right) = 0$$

curl-free
flow
with $\pi = \frac{\tilde{v} \cdot \tilde{v}}{\rho}$