Enhancement & Denoising:

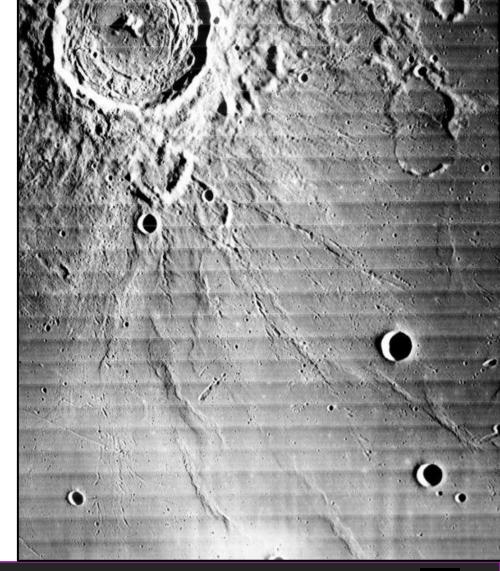
Frequency domain filtering

Dr. Tushar Sandhan



Input



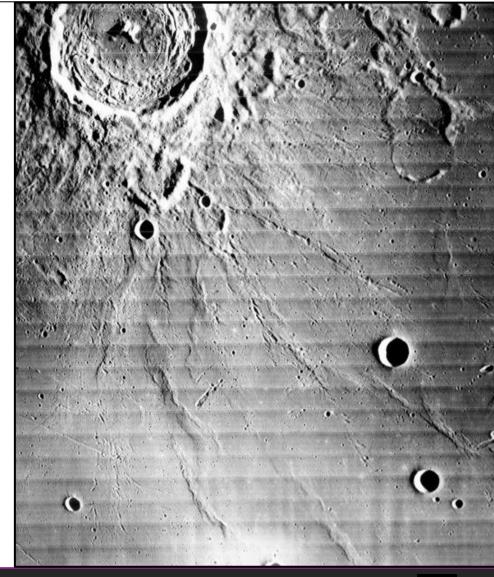


Input

Output







Input



Input



Output

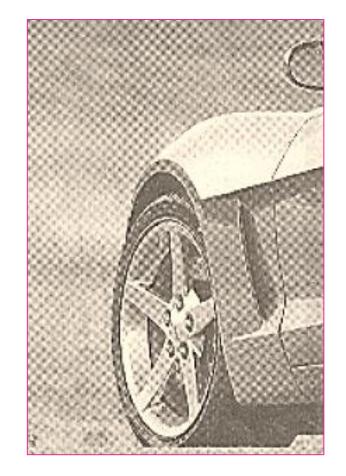


Input



Output





2D Fourier Transform

2D Fourier Transform

$$F(u,v) = \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} f(x,y) e^{-j2\pi(ux/M + vy/N)}$$

2D Fourier Transform

2D Fourier Transform

 $u = x = 0, 1, 2, \dots, M - 1$

2D Fourier Transform

u = x = 0, 1, 2, ..., M-1v = y = 0, 1, 2, ..., N-1.

2D Fourier Transform

$$\Box DFT: F(u,v) = \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} f(x,y) e^{-j2\pi(ux/M + vy/N)}$$

$$f(x,y) = \frac{1}{MN} \sum_{u=0}^{M-1} \sum_{v=0}^{N-1} F(u,v) e^{j2\pi(ux/M + vy/N)}$$

$$u = x = 0, 1, 2, ..., M-1$$

 $v = y = 0, 1, 2, ..., N-1$.

2D Fourier Transform

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2D Fourier Transform

$$\square \text{ DFT: } F(u,v) = \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} f(x,y) e^{-j2\pi(ux/M + vy/N)}$$

u = x = 0, 1, 2, ..., M-1v = y = 0, 1, 2, ..., N-1.

Translation

Translation

$$FT[f(x - x_0, y - y_0)] = F(u, v) \cdot \exp[-j2\pi(ux_0 + vy_0)/N]$$

Translation

$$FT[f(x - x_0, y - y_0)] = F(u, v) \cdot \exp[-j2\pi(ux_0 + vy_0)/N]$$

Scaling

Translation

$$FT[f(x - x_0, y - y_0)] = F(u, v) \cdot \exp[-j2\pi(ux_0 + vy_0)/N]$$

Scaling

$$FT[f(ax, by)] = \frac{1}{ab}F\left(\frac{u}{a}, \frac{v}{b}\right)$$

$$f \star g$$

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Spatial filtering to frequency filtering

$$FT[f \star g] = \sum_{n} \sum_{m} f(m)g(n-m)e^{-\frac{j2\pi nu}{N}}$$

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$$=\sum_{m}f(m)\sum_{n}g(n-m)e^{-\frac{j2\pi nu}{N}}$$

Spatial filtering to frequency filtering

$$FT[f \star g] = \sum_{n} \sum_{m} f(m)g(n-m) e^{\frac{-j2\pi nu}{N}}$$

$$= \sum_{m} f(m) \sum_{n} g(n-m) e^{\frac{-j2\pi nu}{N}}$$

$$= \sum_{m} f(m)FT[g] e^{\frac{-j2\pi nu}{N}}$$

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$$= FT[g] \sum_{n} f(m)e^{-\frac{j2\pi mu}{N}}$$

$$= FT[f] \cdot FT[g]$$

$$FT[f \star g] = \sum_{n} \sum_{m} f(m)g(n-m) e^{-\frac{j2\pi nu}{N}}$$

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$$FT[f \star g] = FT[f] \cdot FT[g]$$

sandhan@iitk.ac.in

Fast Fourier transform (FFT)

$$X[k] = \sum_{n=0}^{N-1} x[n] \, e^{-j2\pi rac{nk}{N}}$$

$$0 \le k < N$$

$$x[n] = rac{1}{N} \sum_{k=0}^{N-1} X[k] \, e^{+j2\pirac{nk}{N}}$$

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$$t = [0: 0.01:10]$$

 $x(t) = 10\sin(t) + 10\cos(t)$
 $X(\omega) = FFT(x(t))$

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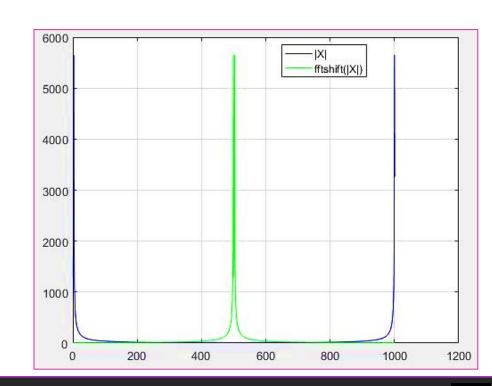
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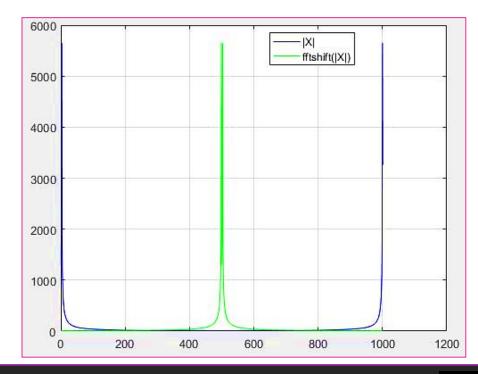
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 $X(\omega) = FFT(x(t))$

• fftshift: visualize FFT within $[-\frac{F_s}{2}, \frac{F_s}{2}]$ instead of $[0 \ F_s]$

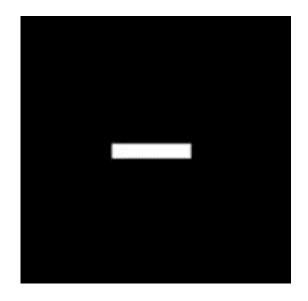


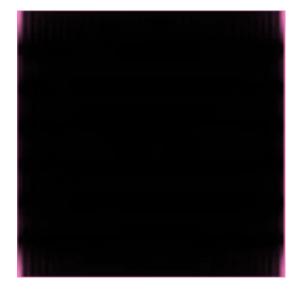
Repositioning the quadrants

Repositioning the quadrants



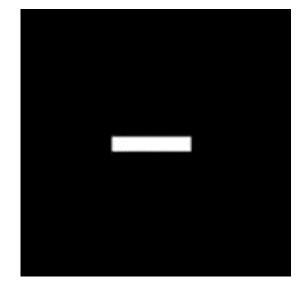
Repositioning the quadrants

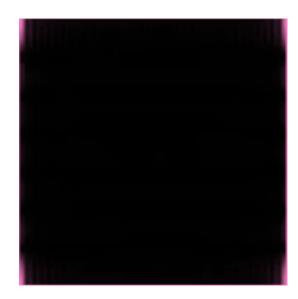




Repositioning the quadrants



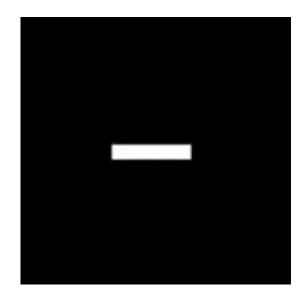




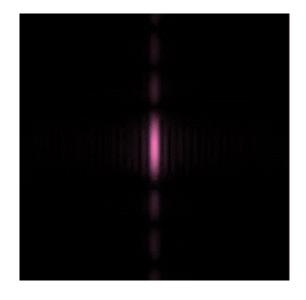
Repositioning the quadrants

f(x,y)

|F(u,v)|





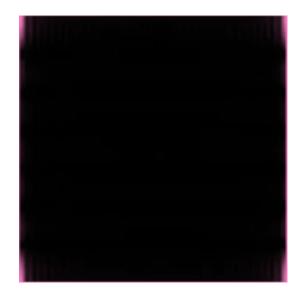


Repositioning the quadrants

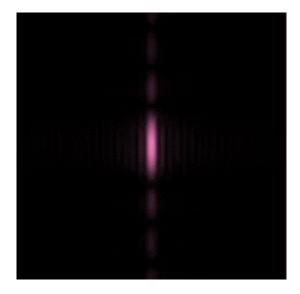
f(x,y)



|F(u,v)|



Shift(|F(u,v)|)



• FT as image & intensity transformations

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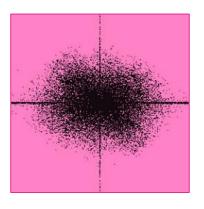




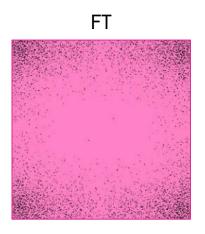
• FT as image & intensity transformations

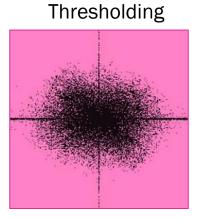
FT



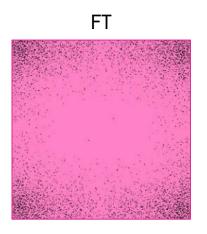


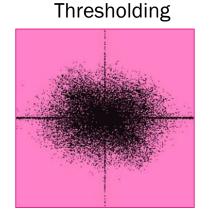
• FT as image & intensity transformations

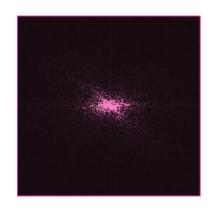




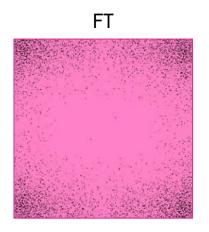
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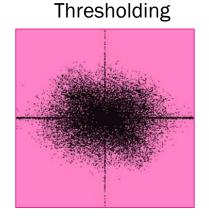


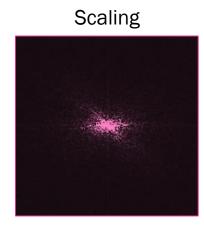




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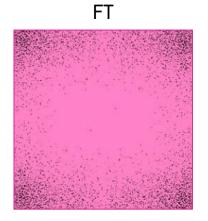




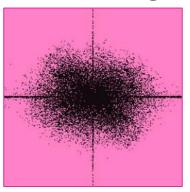


• FT as image & intensity transformations

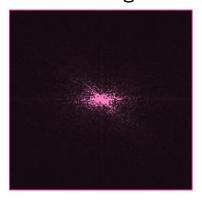
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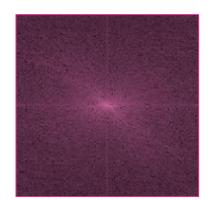


Thresholding



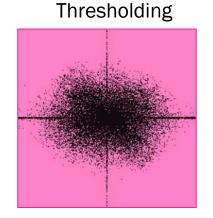
Scaling

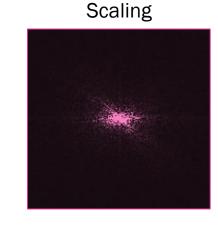


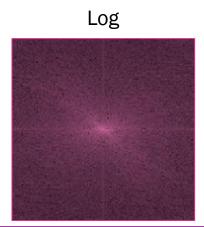


• FT as image & intensity transformations

FT

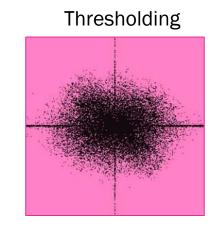


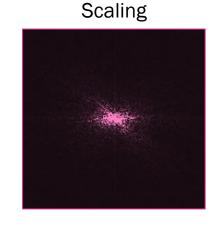


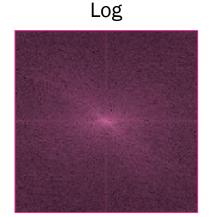


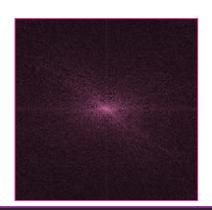
• FT as image & intensity transformations

FT

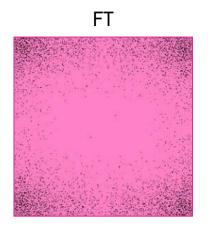


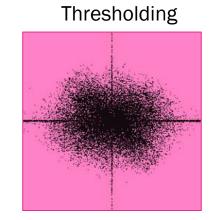


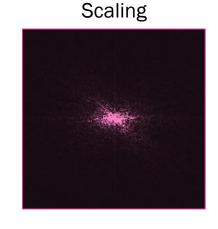


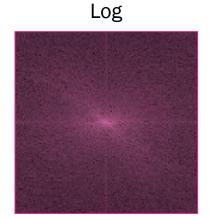


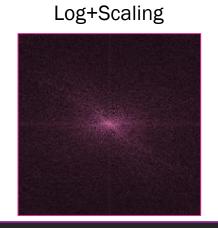
• FT as image & intensity transformations





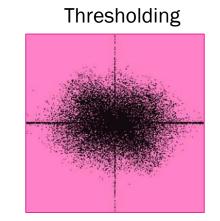


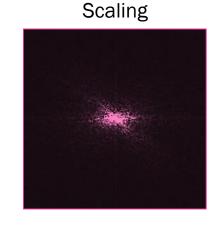


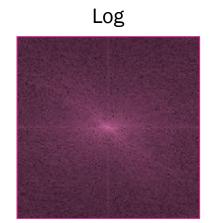


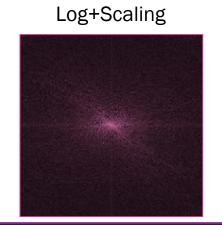
• FT as image & intensity transformations

FT







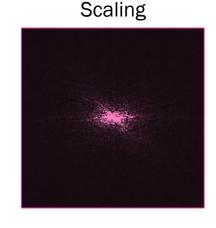


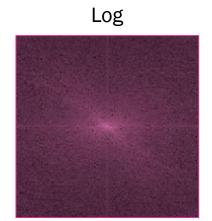


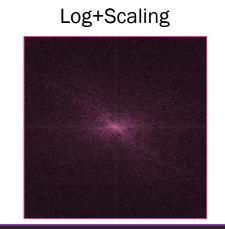
FT as image & intensity transformations

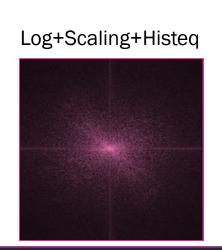
FT

Thresholding

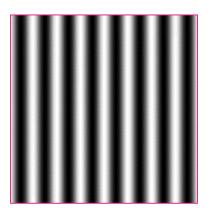




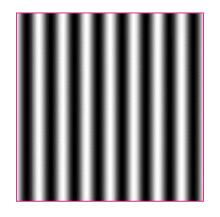




 $f_1(x,y)$

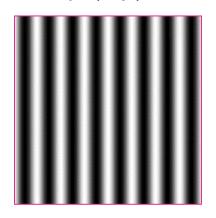


 $f_1(x,y)$





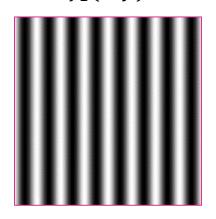
 $f_1(x,y)$



 $\log(|F_1(u,v)|)$

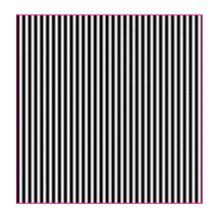


 $f_1(x,y)$

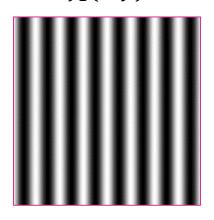


 $\log(|F_1(u,v)|)$





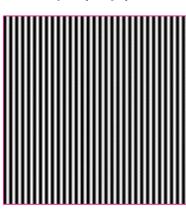
 $f_1(x,y)$



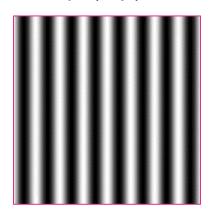
 $\log(|F_1(u,v)|)$



 $f_2(x,y)$



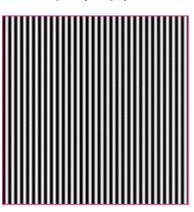
 $f_1(x,y)$



 $\log(|F_1(u,v)|)$

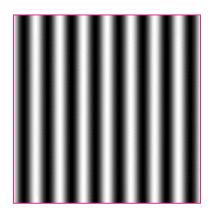


 $f_2(x,y)$





 $f_1(x,y)$



 $\log(|F_1(u,v)|)$



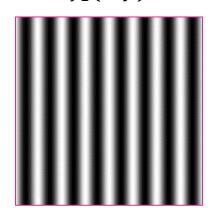
 $f_2(x,y)$



 $\log(|F_2(u,v)|)$



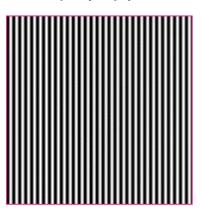
 $f_1(x,y)$



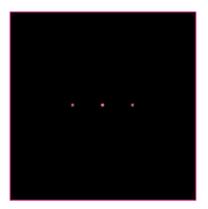
 $\log(|F_1(u,v)|)$



 $f_2(x,y)$

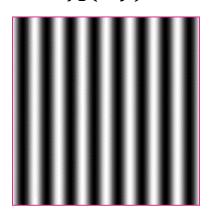


$$\log(|F_2(u,v)|)$$



$$f_1(x,y) + f_2(x,y)$$

 $f_1(x,y)$



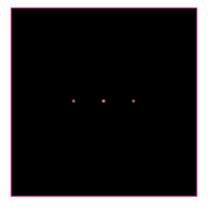
 $\log(|F_1(u,v)|)$



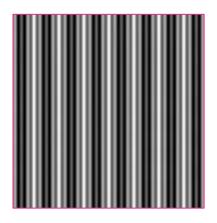
 $f_2(x,y)$



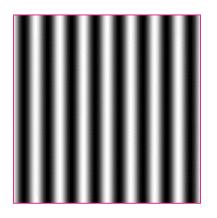
$$\log(|F_2(u,v)|)$$



 $f_1(x,y) + f_2(x,y)$



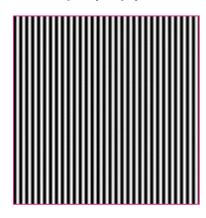
 $f_1(x,y)$



 $\log(|F_1(u,v)|)$



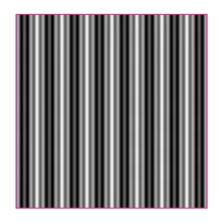
 $f_2(x,y)$



 $\log(|F_2(u,v)|)$

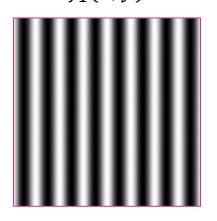


$$f_1(x,y) + f_2(x,y)$$





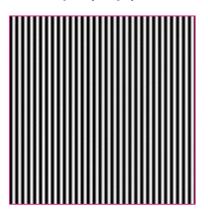
 $f_1(x,y)$



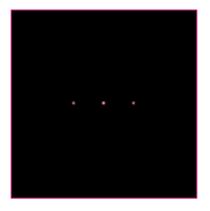
 $\log(|F_1(u,v)|)$



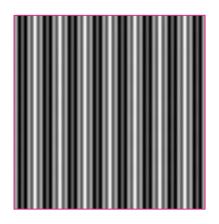
 $f_2(x,y)$



 $\log(|F_2(u,v)|)$



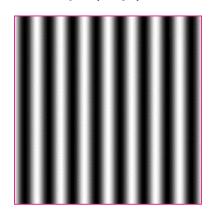
 $f_1(x,y) + f_2(x,y)$







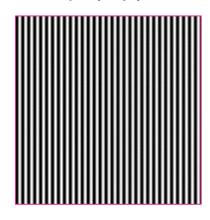
 $f_1(x,y)$



 $\log(|F_1(u,v)|)$



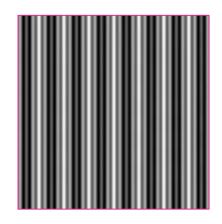
 $f_2(x,y)$



 $\log(|F_2(u,v)|)$



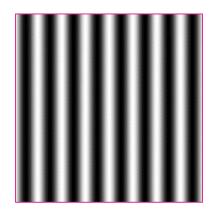
 $f_1(x,y) + f_2(x,y)$



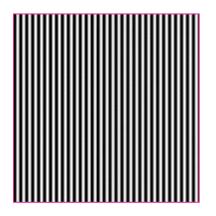




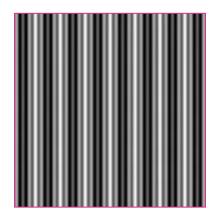
$$\log(|F_1(u,v) + F_2(u,v)|)$$



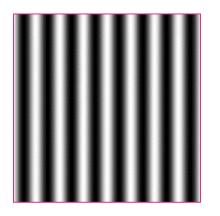




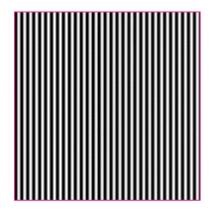


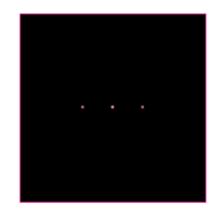


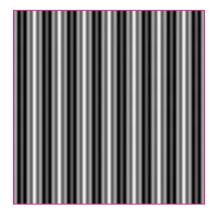






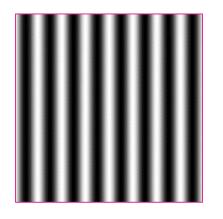


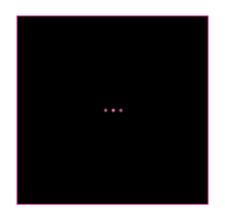


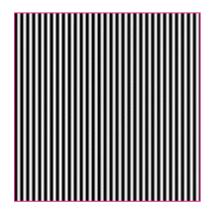


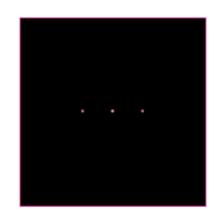






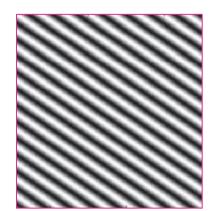


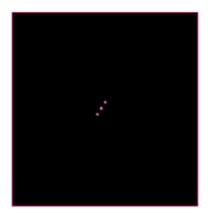


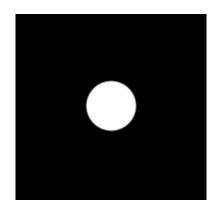


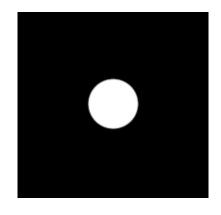


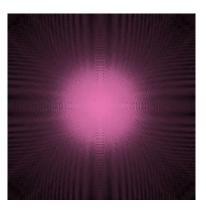


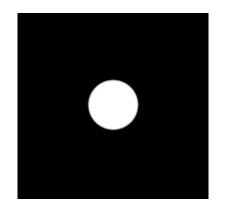


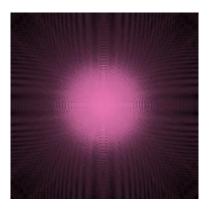


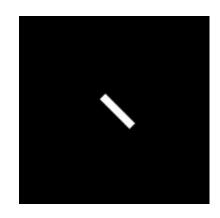


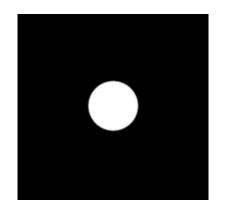


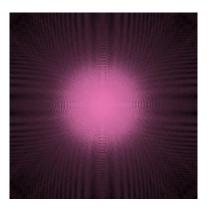


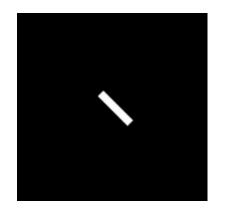


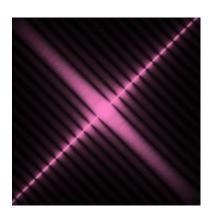


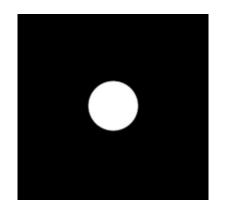


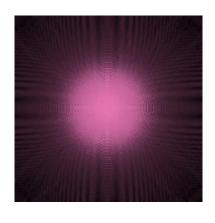


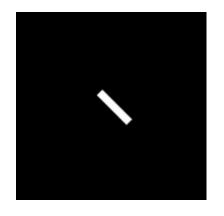


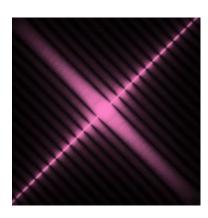




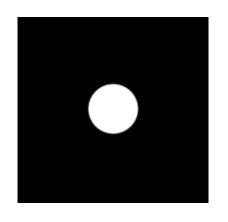


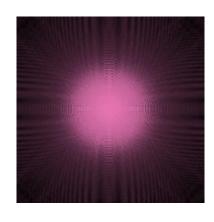


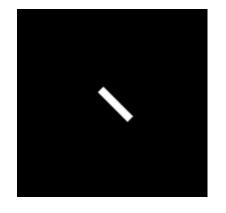


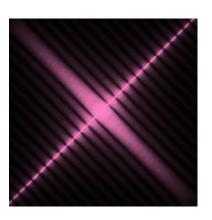






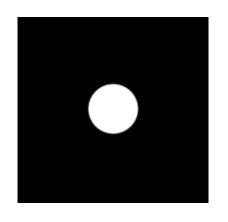


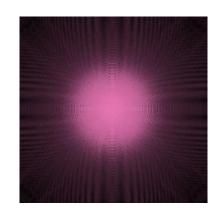


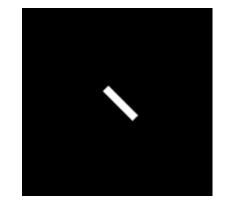


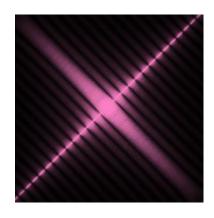




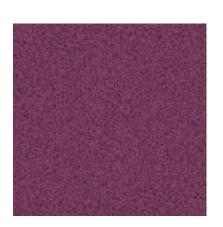




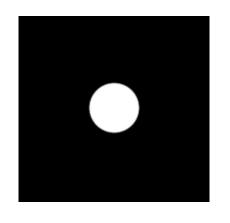


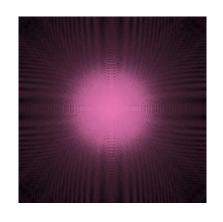


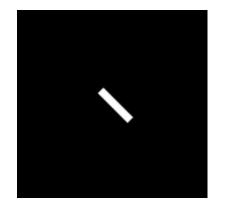


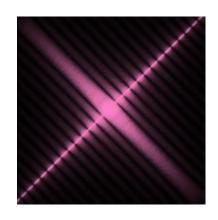








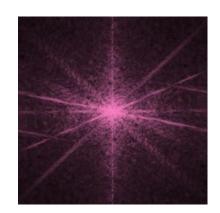






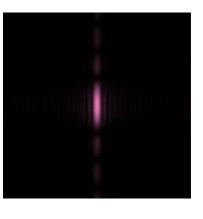


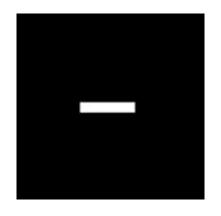


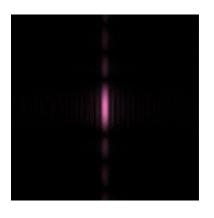


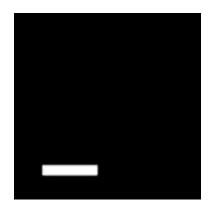




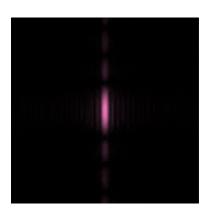




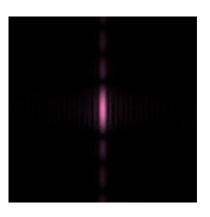


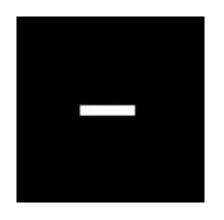


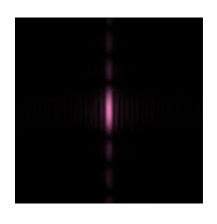




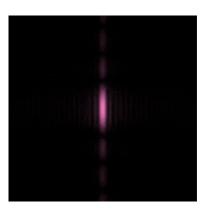




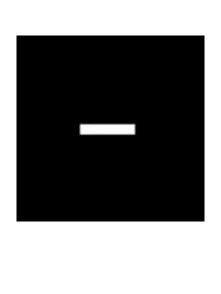


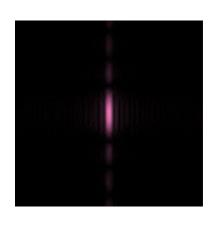


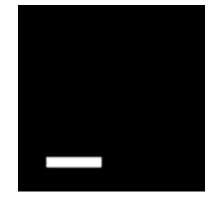


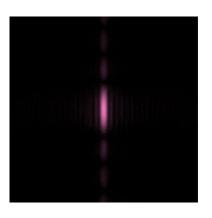




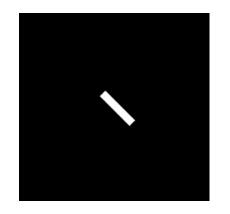




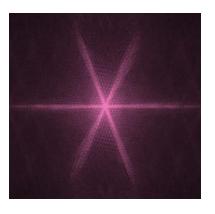




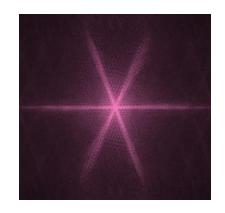


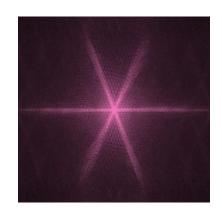




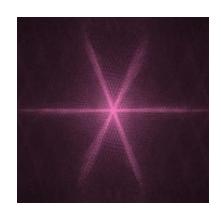


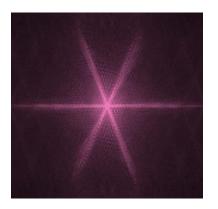


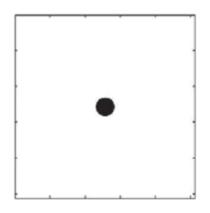


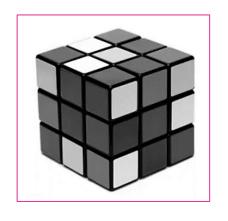


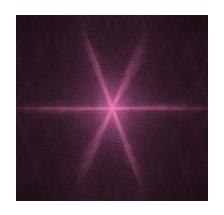


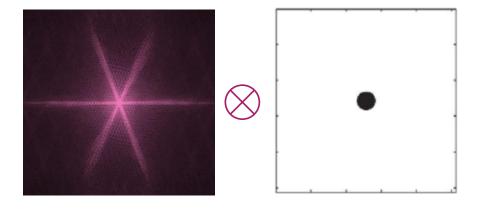




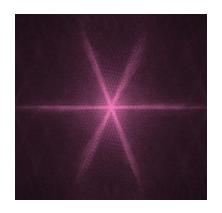


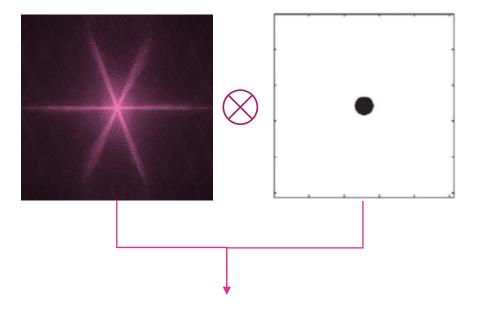




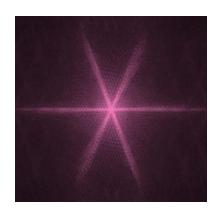


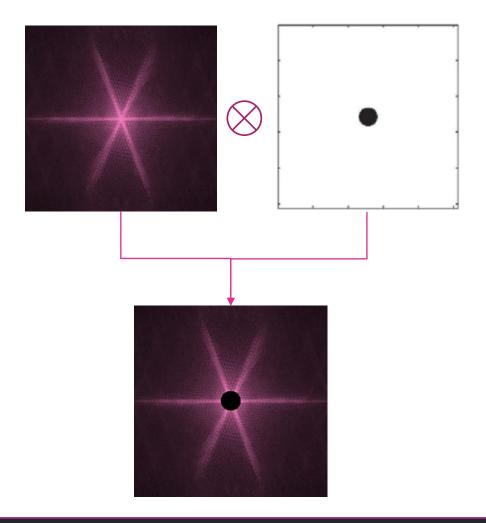




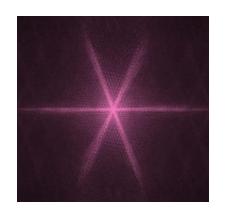


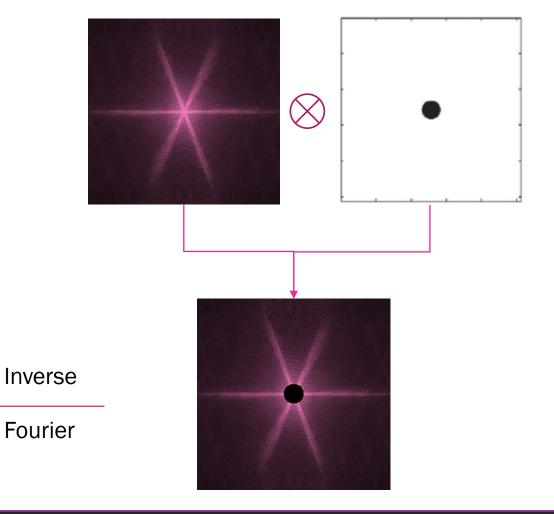




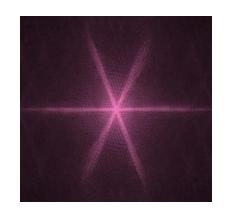


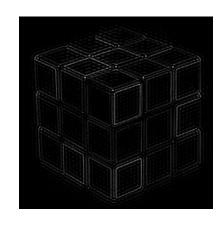


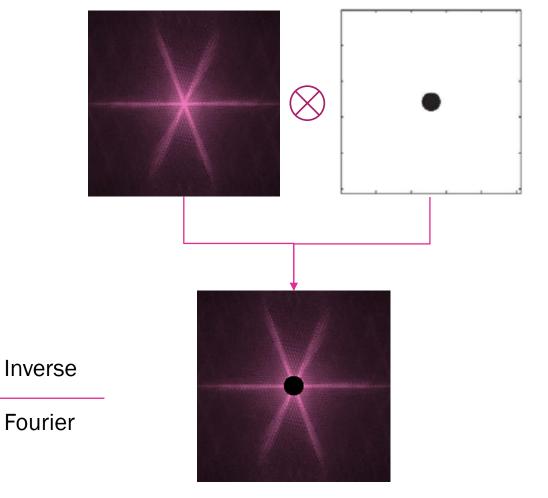


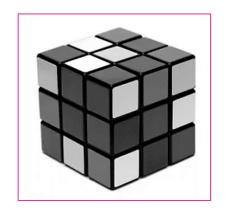


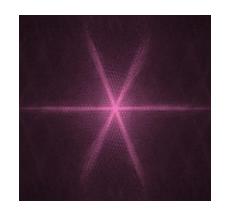




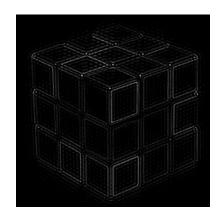




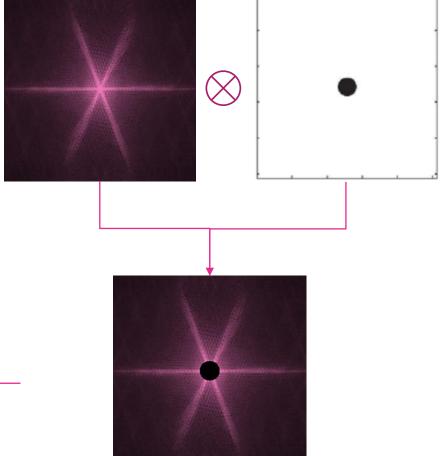




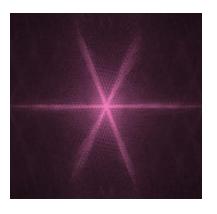
HPF



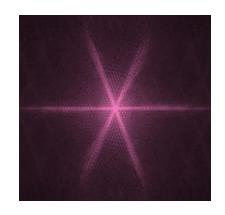
Inverse Fourier

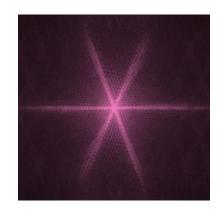




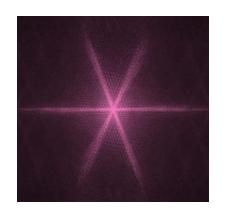


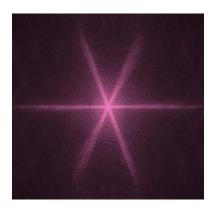


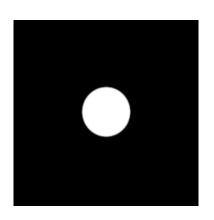




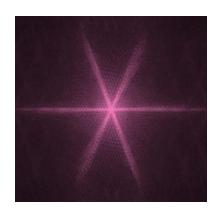


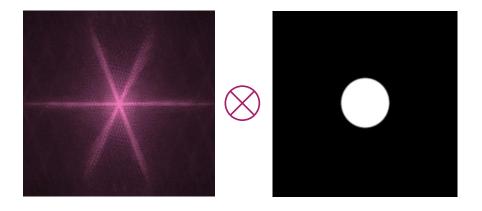




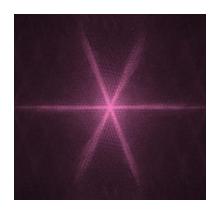


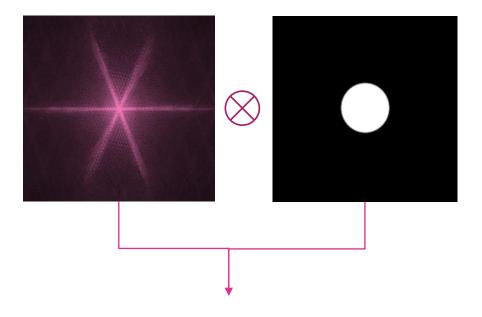




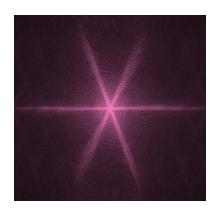


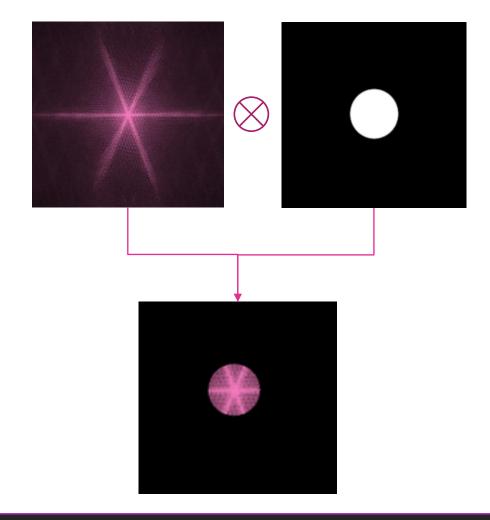




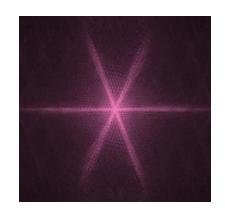


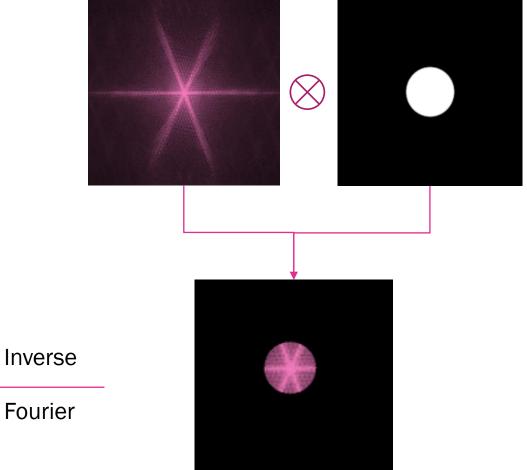




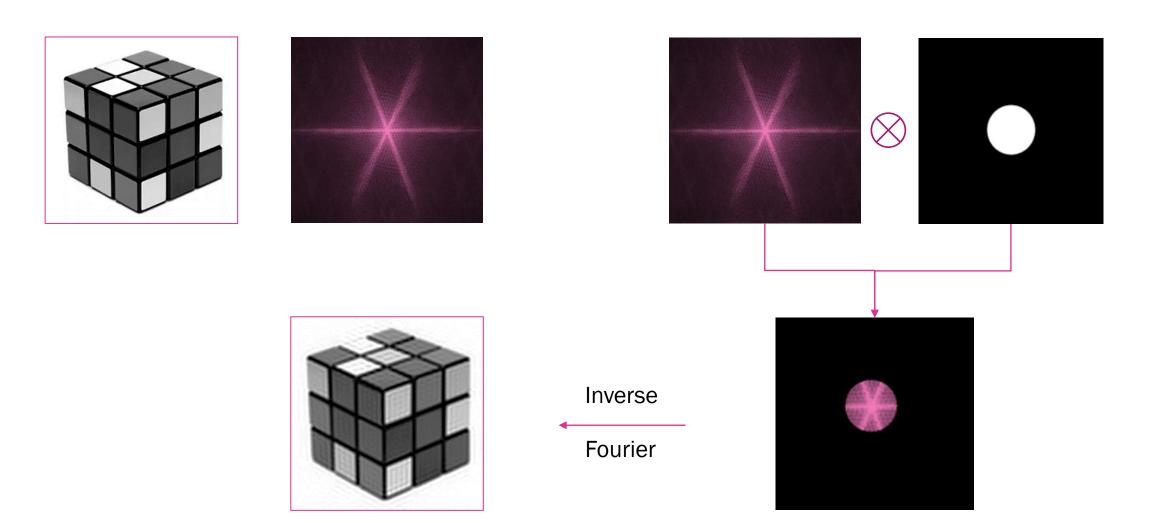


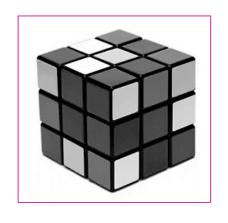


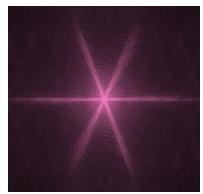




Fourier



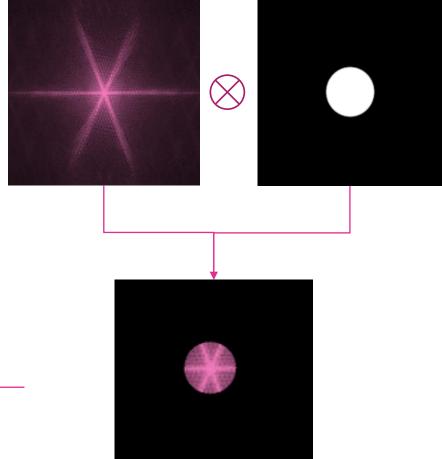




LPF



Inverse Fourier



Input



Input





Input

LPF





Input



LPF





Input





LPF





Input

LPF

HPF









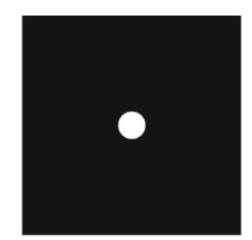
Input



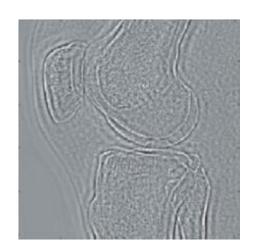


LPF



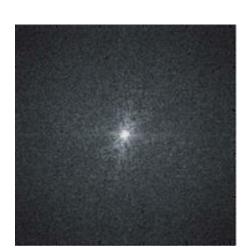


HPF



Input



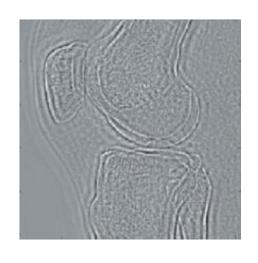


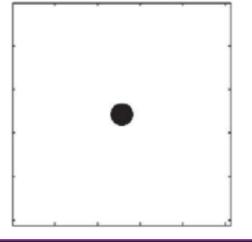
LPF





HPF





Input



JT.



HPF

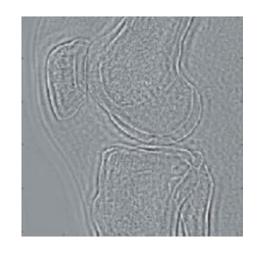


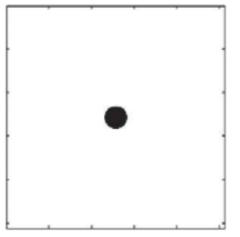












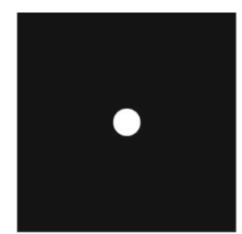
Input



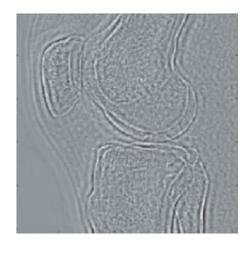


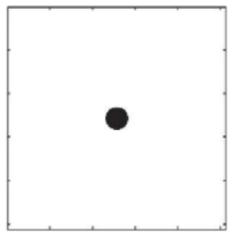
LPF





HPF





BPF

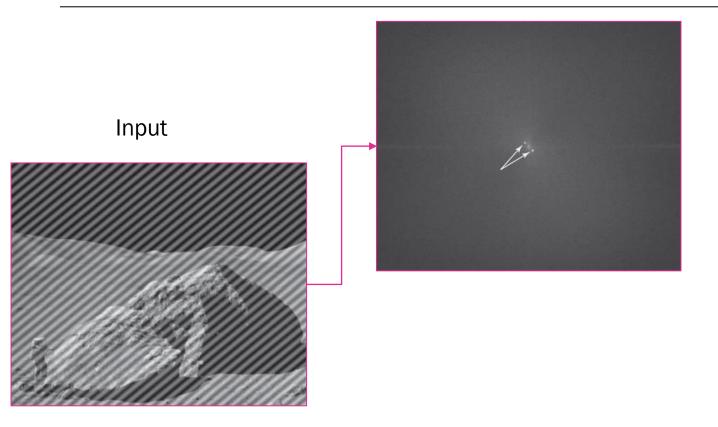


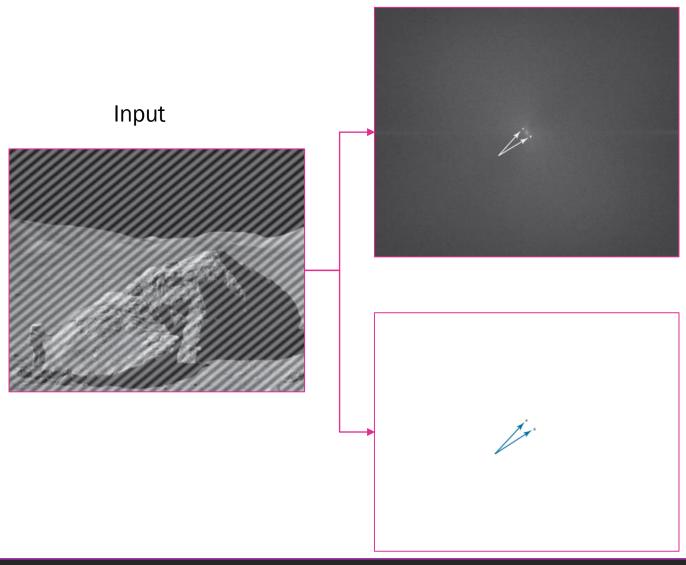
EE604: IMAGE PROCESSING

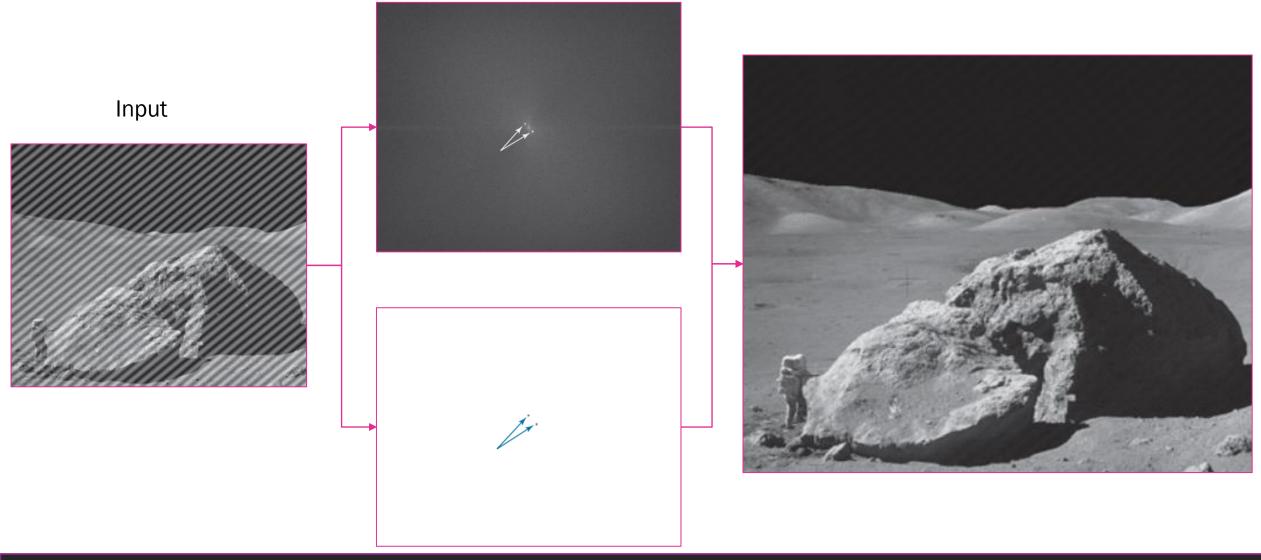
Input LPF **HPF BPF**

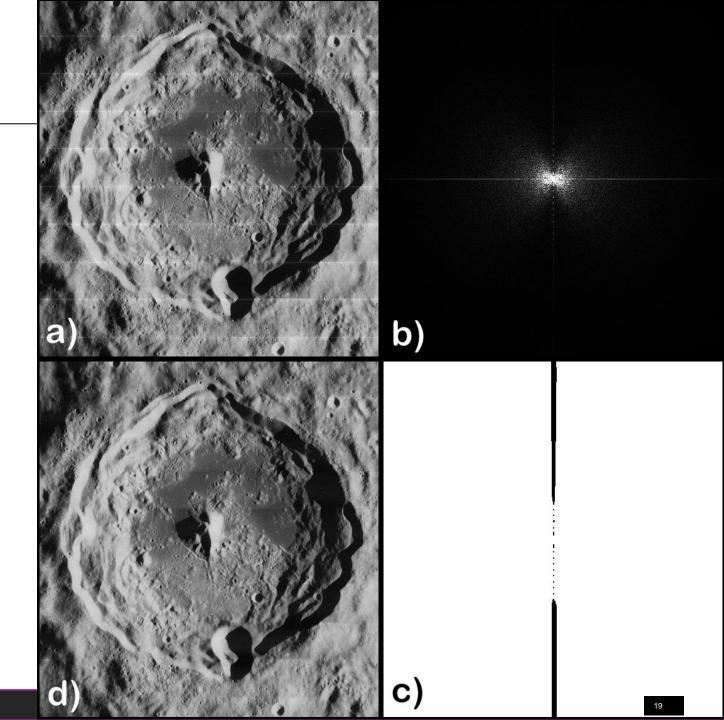
Input



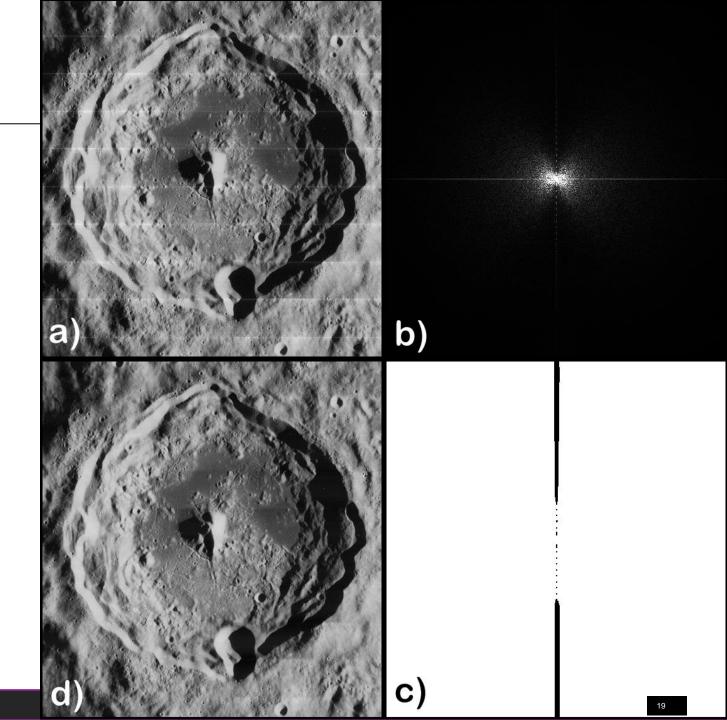








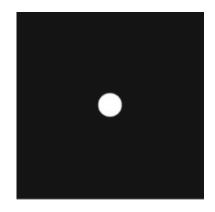
- (a) Input image
- (b) Freq representation
- (c) 2D Mask
- (d) Freq filtered image
 - Inverse Fourier transform after getting dot product between (b) and (c) image



Input f(x, y)



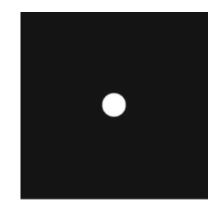
 W_1

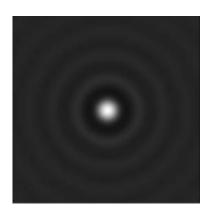


Input f(x, y)



 W_1

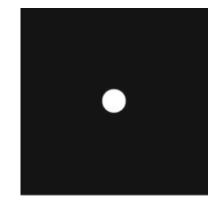




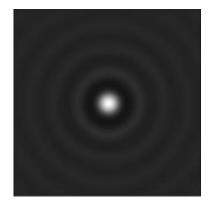
Input f(x, y)



 W_1



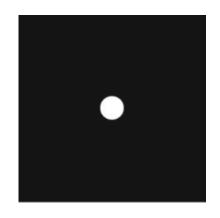
 w_1



Input f(x, y)



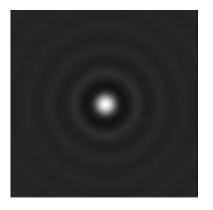
 W_1



 W_2



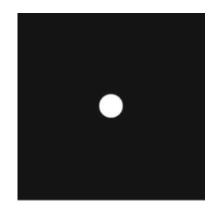
 W_1



Input f(x, y)



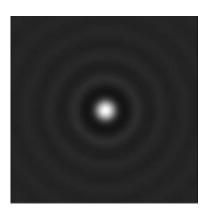
 W_1



 W_2



 W_1

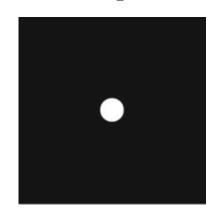


.

Input f(x, y)



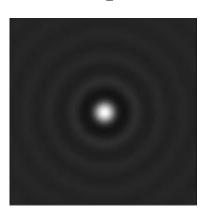
 W_1



 W_2



 W_1



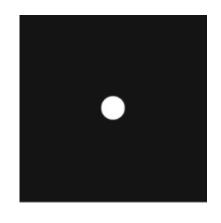
 W_2



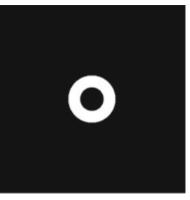
Input f(x, y)



 W_1

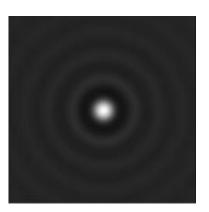


 W_2





 w_1



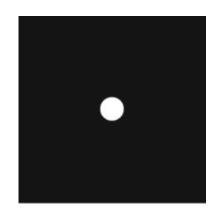
 W_2



Input f(x, y)



 W_1



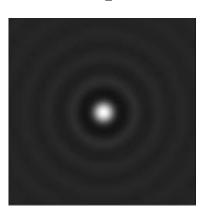
 W_2



 $w_1 \star f$



 W_1



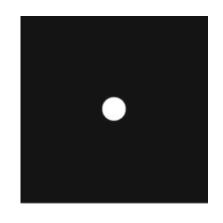
 W_2



Input f(x, y)



 W_1



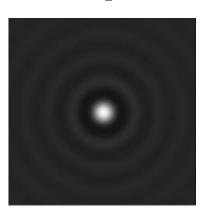
 W_2



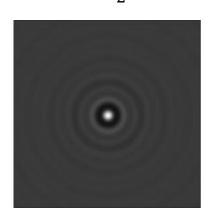
 $w_1 \star f$

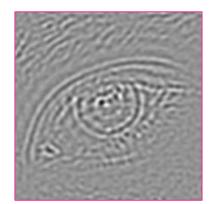


 w_1



 W_2

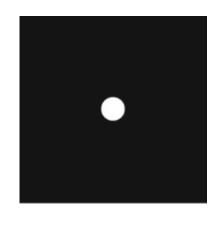




Input f(x, y)



 W_1



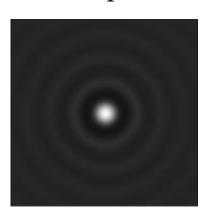
 W_2



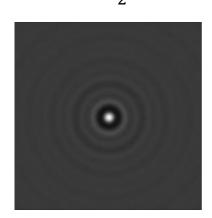
 $w_1 \star f$



 w_1



 W_2

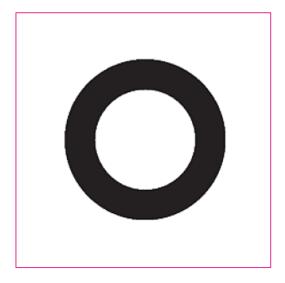


 $w_2 \star f$



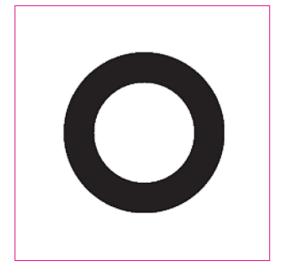
Prior smoothing to reduce ripple effects

Ideal Mask

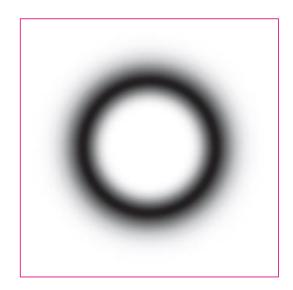


Prior smoothing to reduce ripple effects

Ideal Mask

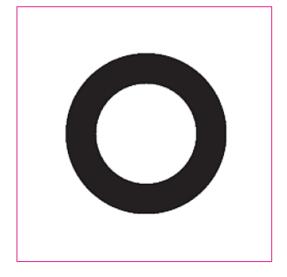


Smooth Mask-1

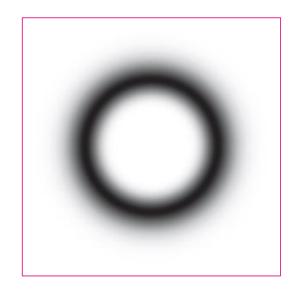


Prior smoothing to reduce ripple effects

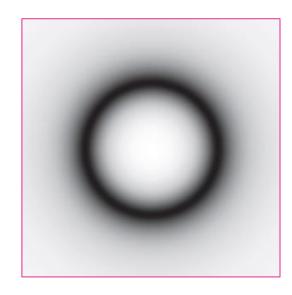
Ideal Mask



Smooth Mask-1



Smooth Mask-2

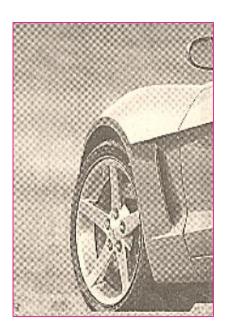


Forget me, but don't forget my car!



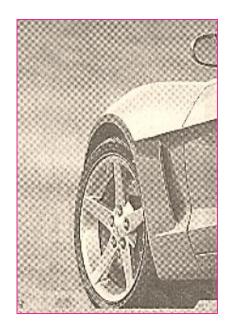
Forget me, but don't forget my car!

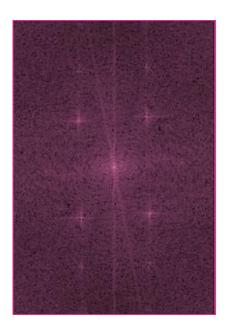




Forget me, but don't forget my car!

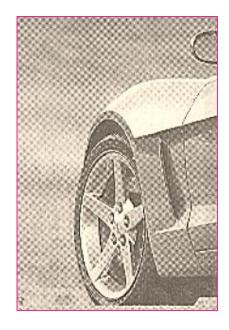


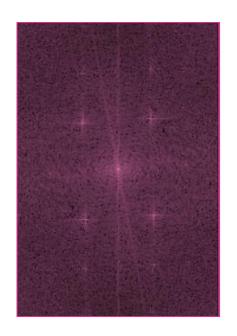


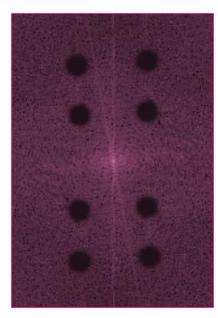


Forget me, but don't forget my car!



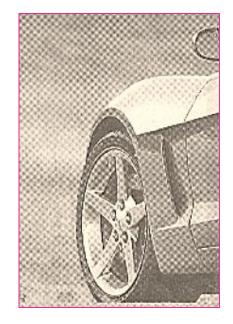


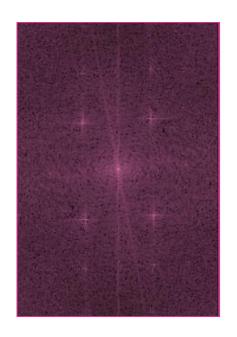


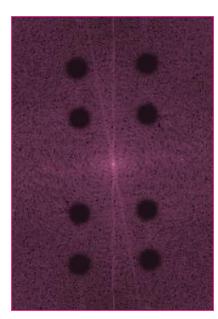


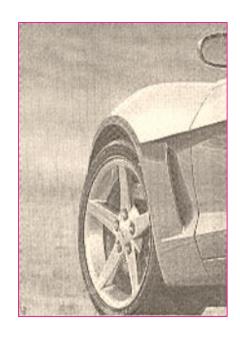
Forget me, but don't forget my car!



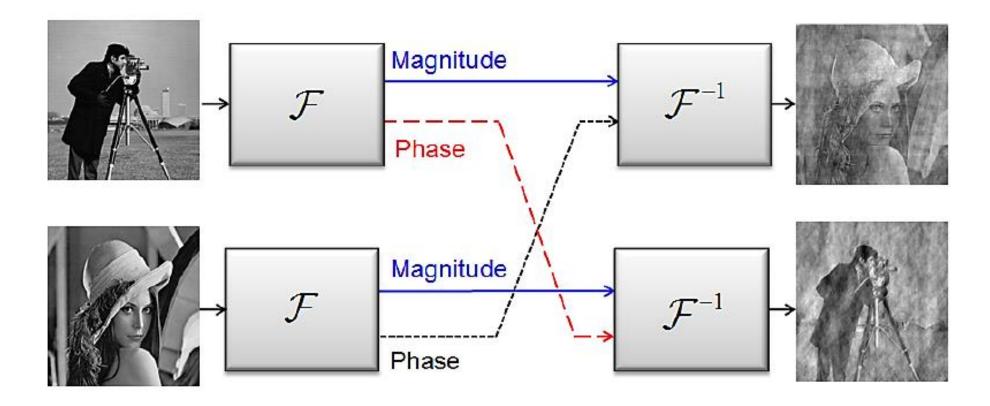








Importance of Fourier Phase

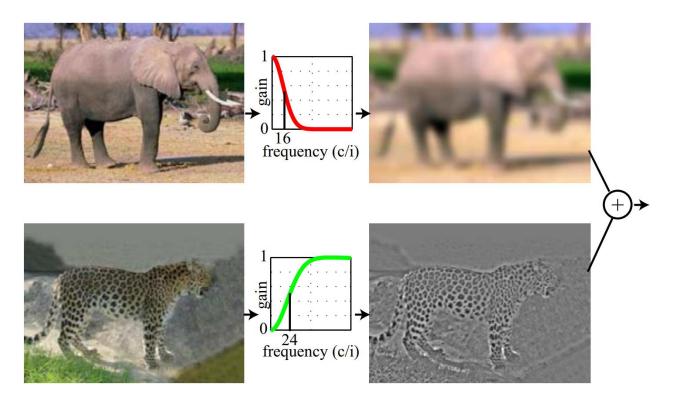


Credit: Y. Shechtman et al. 2014

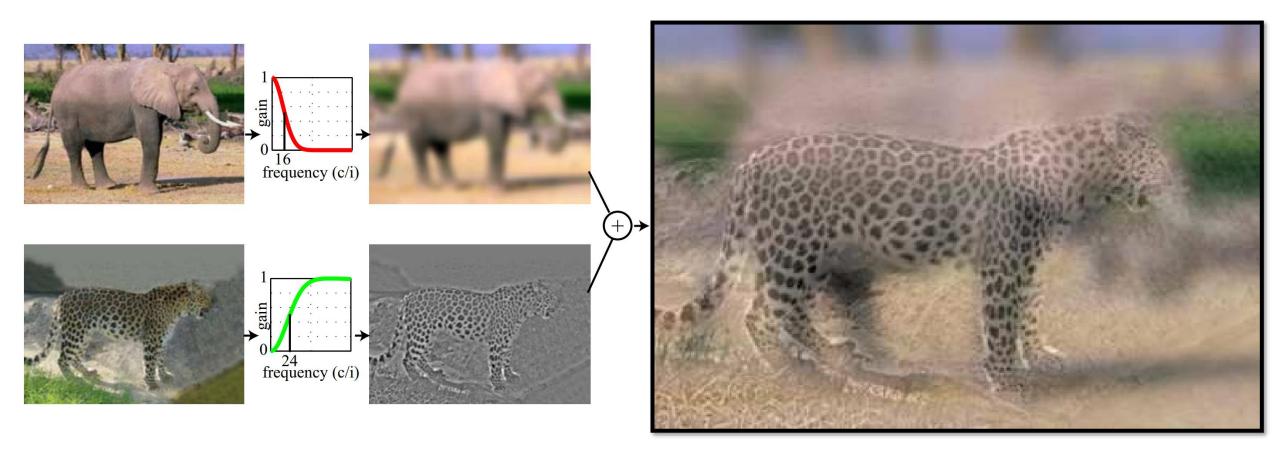
Frequency Filtering & HVS

credit: A. Oliva

Frequency Filtering & HVS



Frequency Filtering & HVS



Conclusion

- 2D FT properties & images
- Frequency filtering

Conclusion

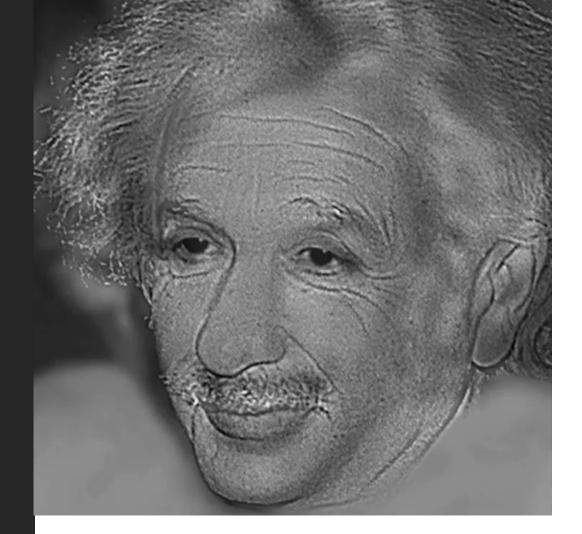
- 2D FT properties & images
- Frequency filtering

- 2D Fourier Transform
 - Properties
 - Convolution theorem
 - 2D FT images

- □ Frequency filtering
 - Filtering in FT domain
 - Freq-spatial filtering
 - Freq-mixing

Conclusion

- 2D FT properties & images
- Frequency filtering



- 2D Fourier Transform
 - Properties
 - Convolution theorem
 - 2D FT images

- Frequency filtering
 - Filtering in FT domain
 - Freq-spatial filtering
 - Freq-mixing