

# Segmentation:

## Regions & K-means

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Dr. Tushar Sandhan

# Introduction

- Goal of segmentation (multiclass)



segmented →

1: Person  
2: Purse  
3: Plants/Grass  
4: Sidewalk  
5: Building/Structures



# Introduction

- Goal of segmentation (multiclass)

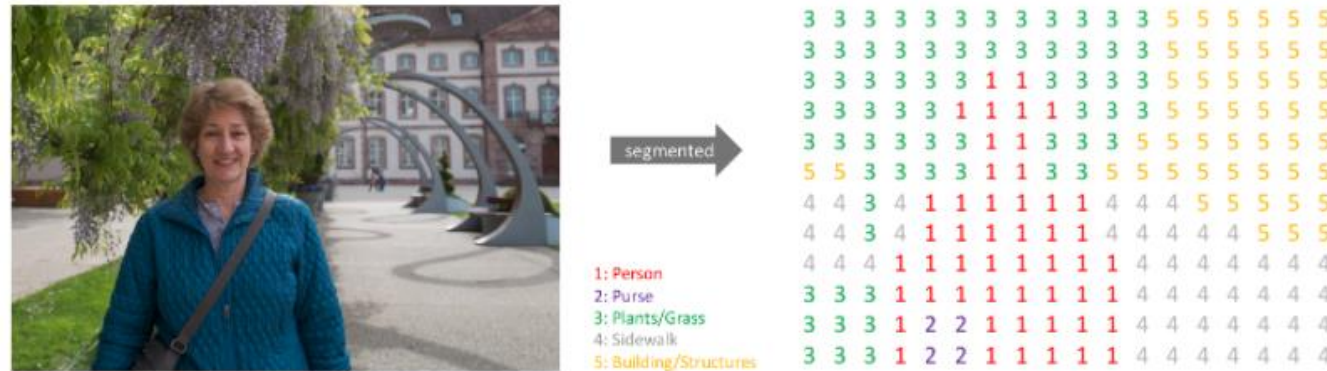


Image credit: J. Jordan

# Region growing

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- Partition the image  $I$  into  $m$  regions
  - every pix belong to some region
  - each pix is assigned to only one region
  - all pix in a region, share similar property
  - all pix in diff. regions have distinct properties
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    1. seed points
    2. similarity measures
    3. stopping criterion

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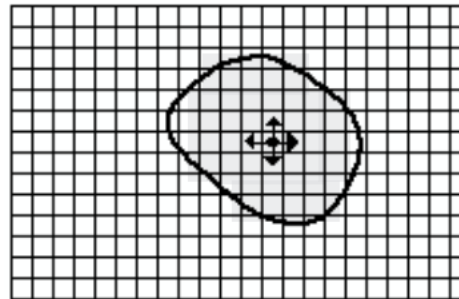
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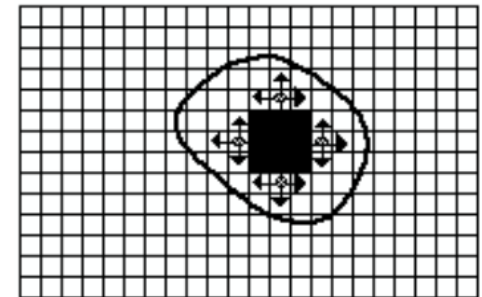
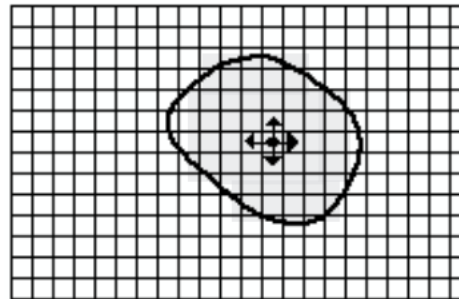


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after few iterations



# Region growing

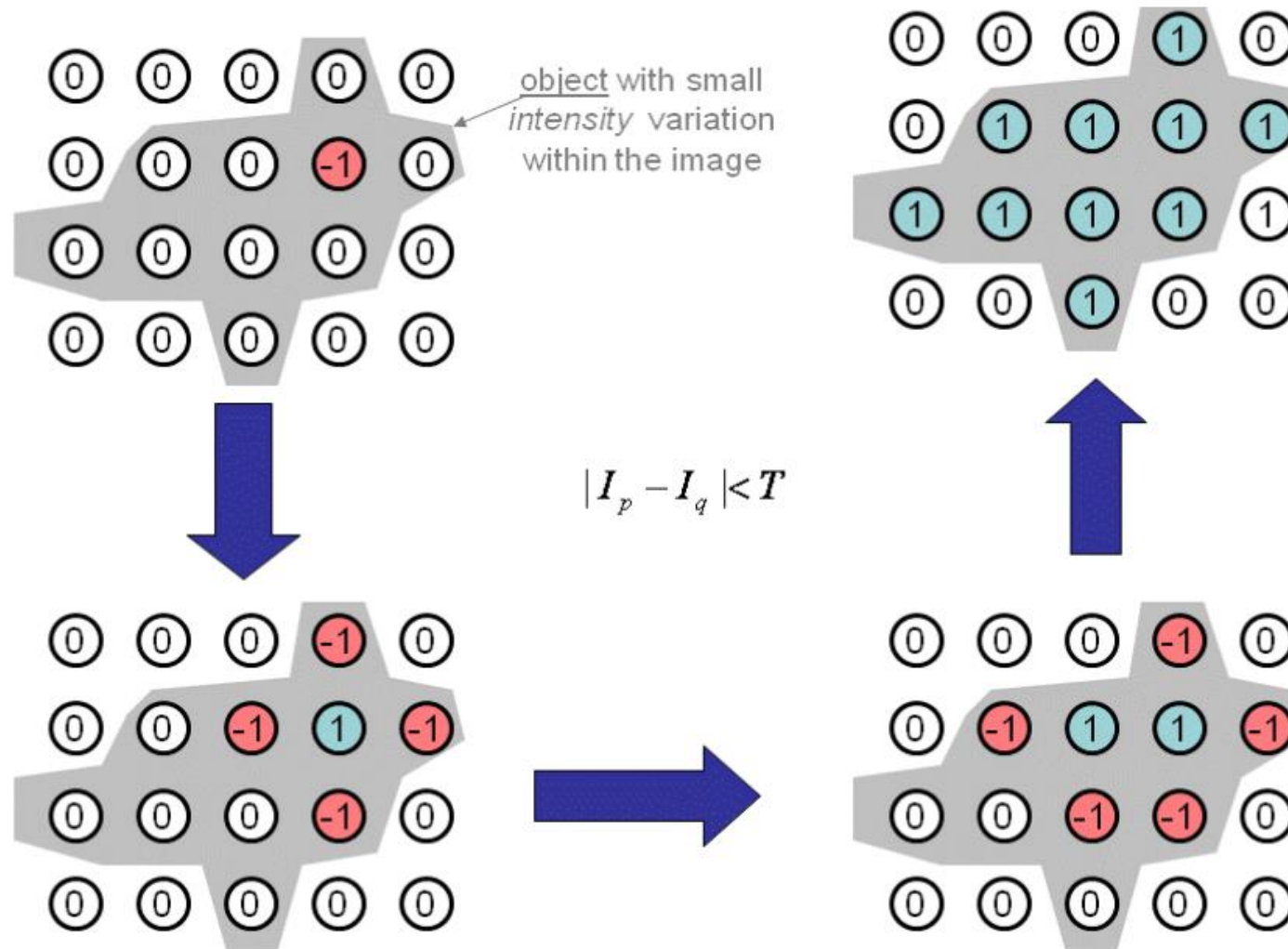
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- Partition and grow

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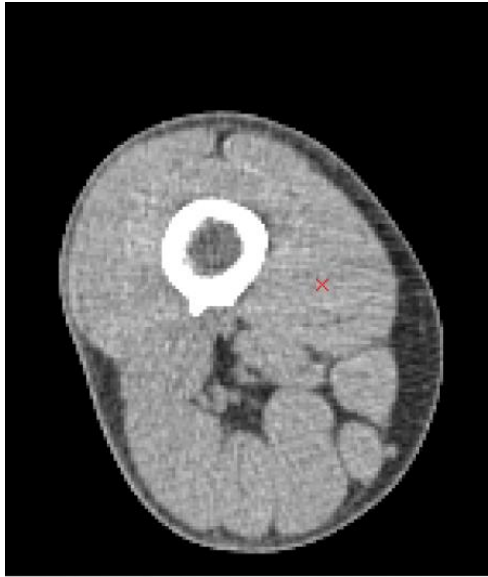
- Start with a seed point  $s_j$  for region  $R_j$
  - For every  $s_j$ 
    - Initialize mean intensity of each region:  $\mu_j = s_j$
    - Initialize region:  $R_j = \{s_j\}$
  - For each point  $p$  in  $R_j$ 
    - Get its 4-connect neighborhood:  $\mathcal{N}_i(p)$ ,  $i = 1, 2, 3, 4$
    - If  $|\mathcal{N}_i(p) - \mu_j| < \tau$ ,  $\mathcal{N}_i(p) \notin \mathcal{R}_k$   $j \neq k$ 
      - $\mathcal{R}_j \leftarrow \mathcal{R}_j \cup \mathcal{N}_i(p)$
      - update  $\mu_j$
    - Stop growing when no neighborhood pixel matches
  - Move to the next seed point, until the whole image is partitioned.
-

# Region growing



# Region growing: CT scan

- Seed-1

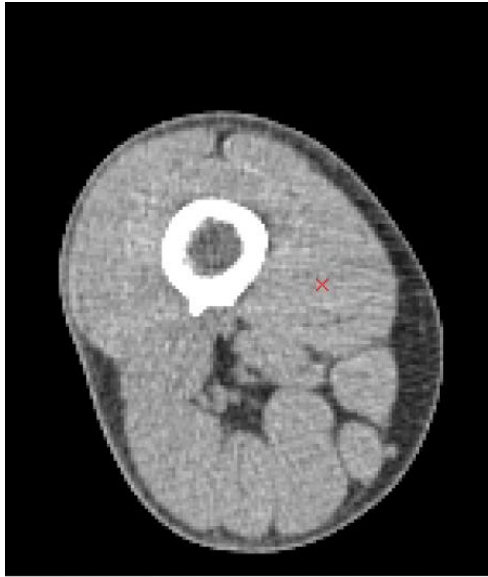


stricter  
similarity

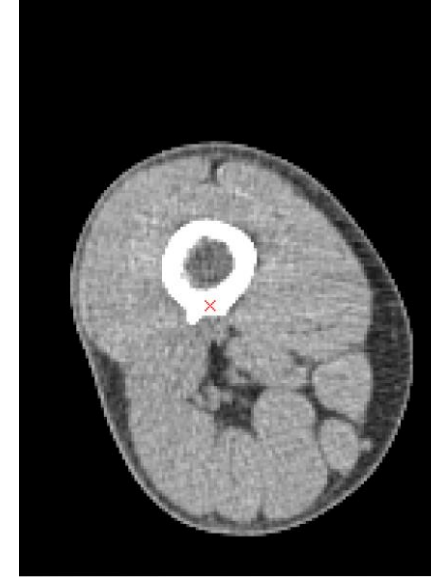


# Region growing: CT scan

■ Seed-1



■ Seed-2



stricter  
similarity



# Comparative example

3	5	7	3	4	2	1
2	4	9	10	22	9	3
3	5	12	11	15	10	3
5	6	11	9	17	19	1
2	3	11	12	18	16	2
3	6	8	10	18	9	5
4	6	7	8	3	3	1

3	5	7	3	4	2	1
2	4	9	10	22	9	3
3	5	12	11	15	10	3
5	6	11	9	17	19	1
2	3	11	12	18	16	2
3	6	8	10	18	9	5
4	6	7	8	3	3	1

threshold  $T \geq 10$

3	5	7	3	4	2	1
2	4	9	10	22	9	3
3	5	12	11	15	10	3
5	6	11	9	17	19	1
2	3	11	12	18	16	2
3	6	8	10	18	9	5
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threshold  $T \geq 11$

3	5	7	3	4	2	1
2	4	9	10	22	9	3
3	5	12	11	15	10	3
5	6	11	9	17	19	1
2	3	11	12	18	16	2
3	6	8	10	18	9	5
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threshold  $T \geq 12$

3	5	7	3	4	2	1
2	4	9	10	22	9	3
3	5	12	11	15	10	3
5	6	11	9	17	19	1
2	3	11	12	18	16	2
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region growing with variance of 2 in respect to value 11 with reference to threshold  $T \geq 11$

# Region splitting & merging

---

- Split
  - sub-quadrants
    - e.g. 4 parts: quadregions
    - quadtree (having leaves as quadregions or quadimages)
  - continuous splitting
    - adjacent quadimages will be having identical properties

# Region splitting & merging

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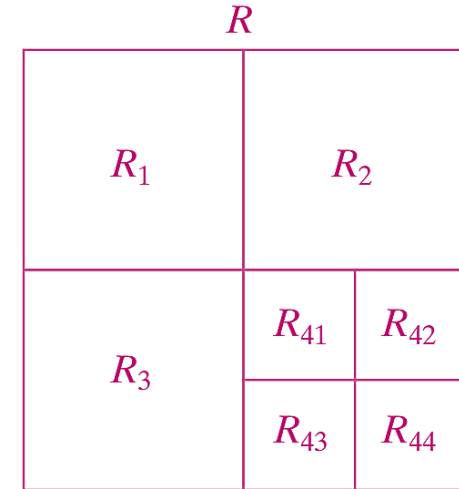
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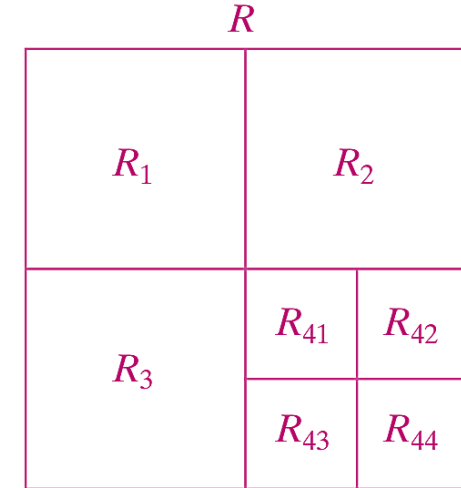
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## ■ Merging

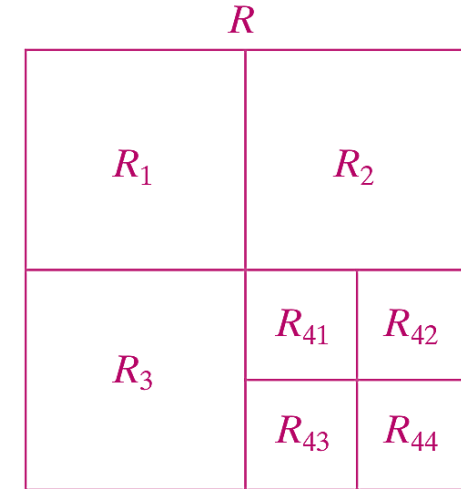
- quadimages that satisfy closeness in similarity criterion
  - quadimages to be merged should be adjacent
  - merging begins when no further splitting is possible



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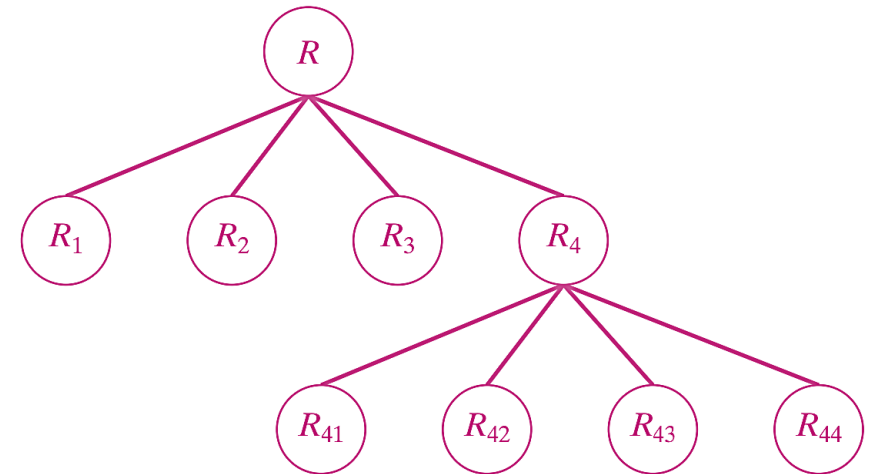
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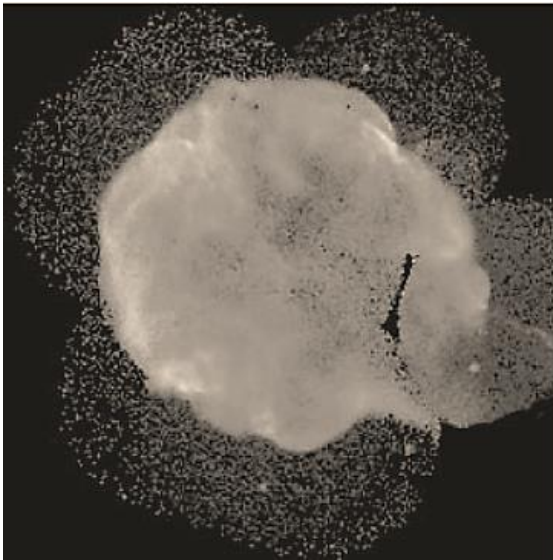


# Region splitting & merging

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- Segment the ring of supernova
  - quadimages size 32x32, 16x16 & 8x8
  - variance and mean of quadimages can be used as merging criterion

X-ray band image

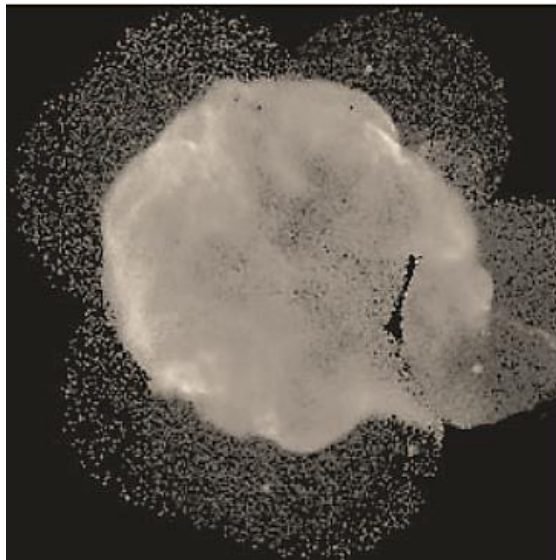


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32x32

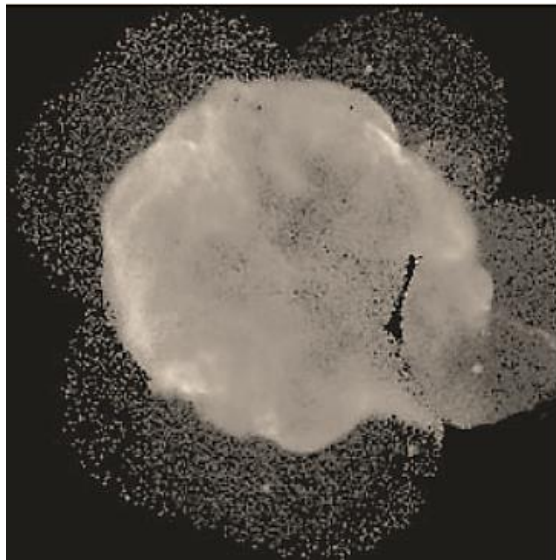


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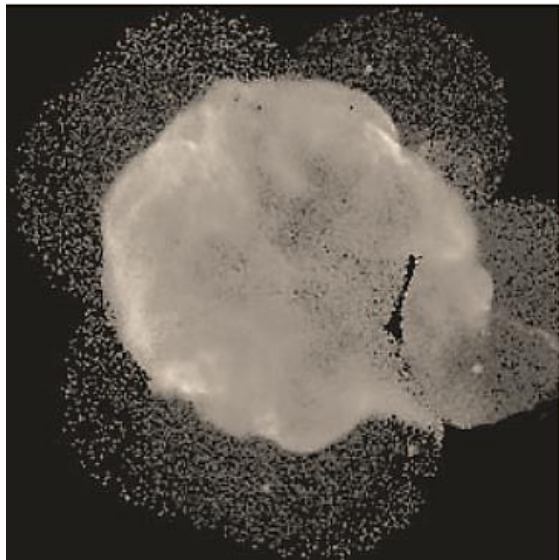
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8x8



# Clustering

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# Clustering

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- Organizing data into multiple (#clusters) classes s.t.:
  - intra-class variance is low (high similarity)
  - inter-class variance is high (low similarity)
- Unsupervised learning paradigm
  - finding class labels directly from data
  - training data labels are not available
- What are similarity measures:
  - distance
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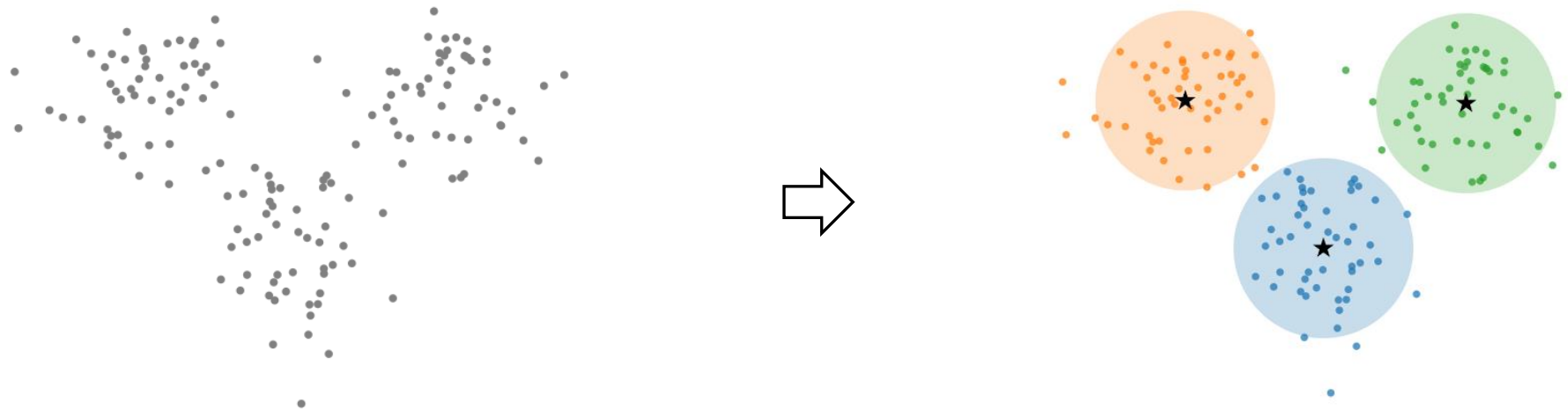




# K-Means

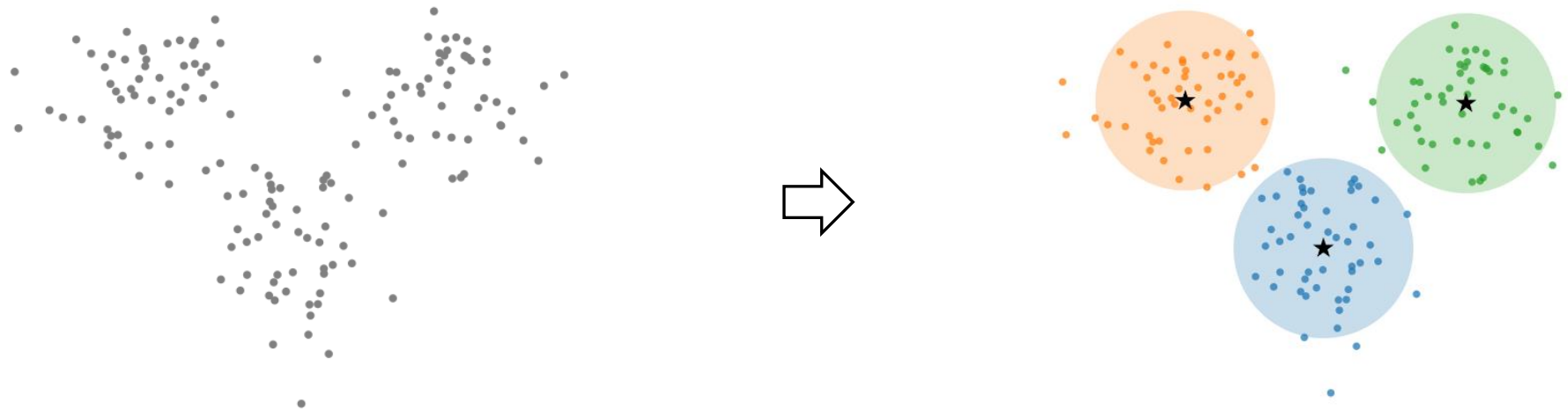
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- K-means clustering
  - unsupervised learning method: requires data but not labels
  - useful for pattern recognition, when we don't know what to look for
  - detects united patterns e.g. groups of text topics, regions of images
  - pros: simple iterative
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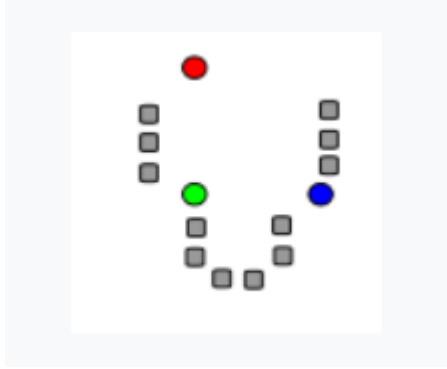
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- **Input:**  $x^{(1)}, x^{(2)}, \dots, x^{(n)}$
- **Output:** Set of clusters  $C_1, C_2, \dots, C_k$
- **Initialization:** Randomly pick  $k$  centroids  $z^{(1)}, z^{(2)}, \dots, z^{(k)}$
- **Iterate** until convergence or up to iterations  $T$ 
  - **Assignment:** Assign each point to its closest centroid  
for each  $j = 1, \dots, k$   
 $C_j = \{i | \text{s.t. } x^{(i)} \text{ is closest to } z^{(j)}\}$
  - **Update:** Recompute centroids with newly assigned points

$$z^{(j)} = \frac{1}{|C_j|} \sum_{i \in C_j} x^{(i)}$$

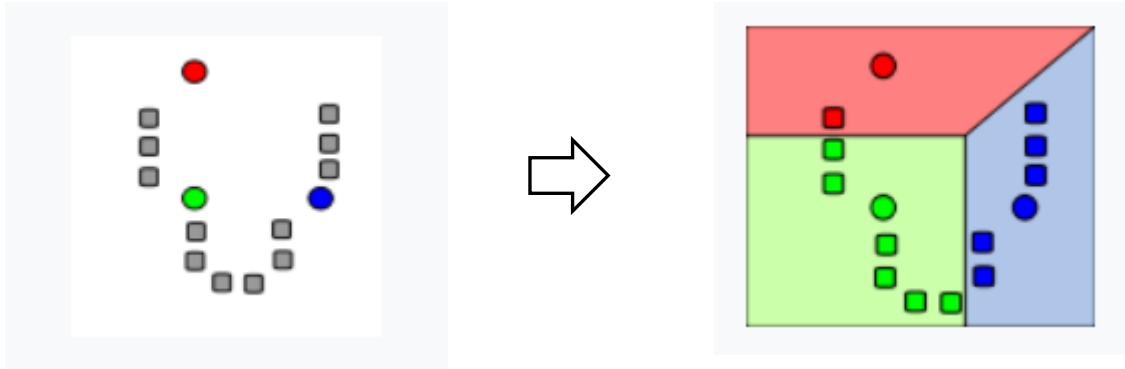
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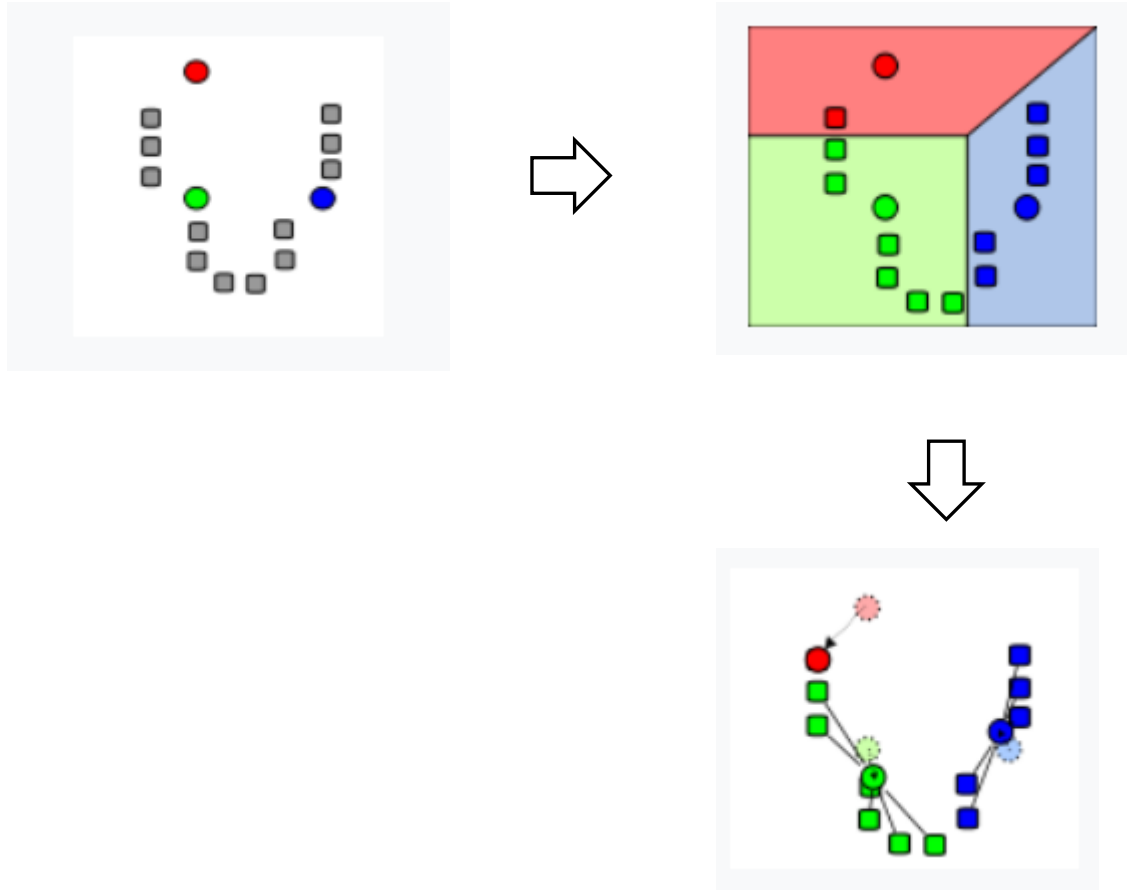
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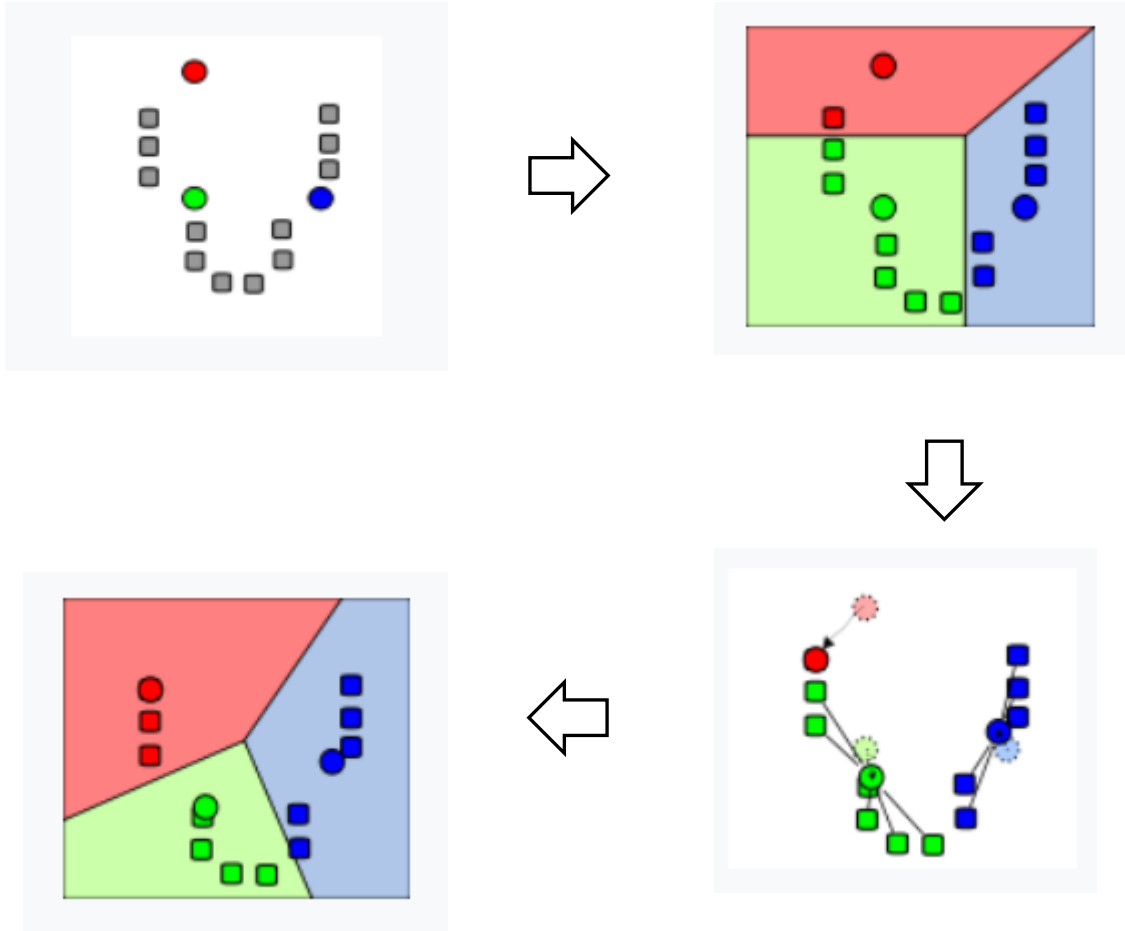
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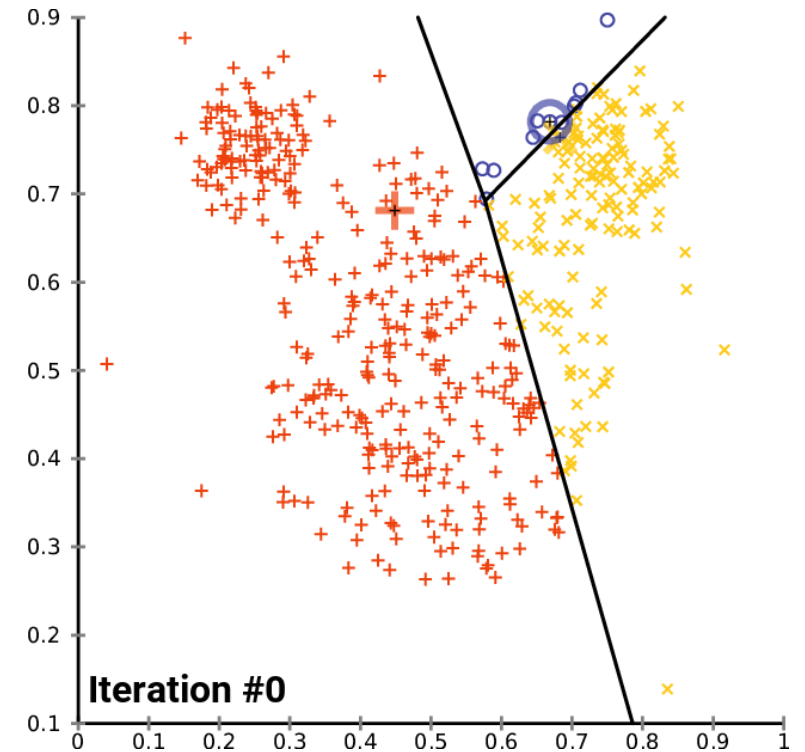
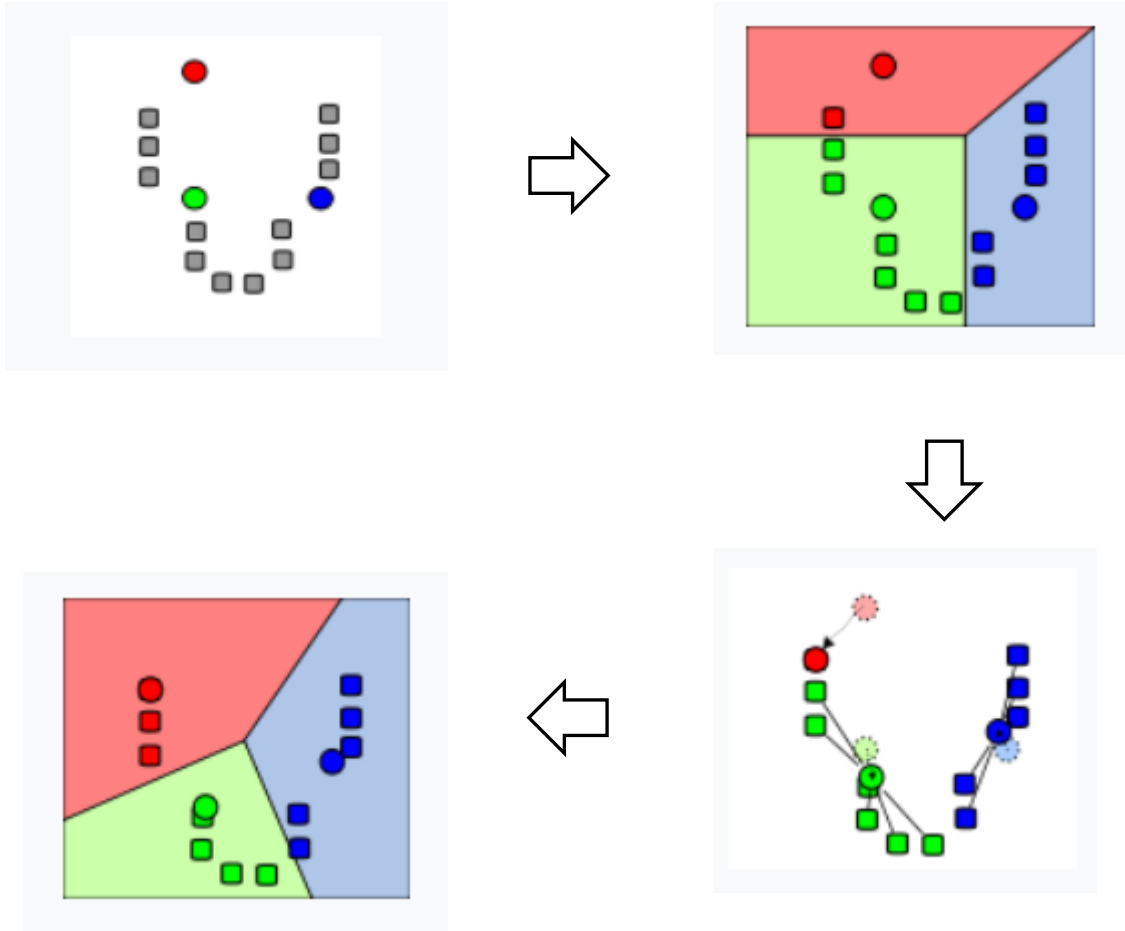


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# K-Means

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- guaranteed to converge in a finite iterations
  - at each iteration the error reduces
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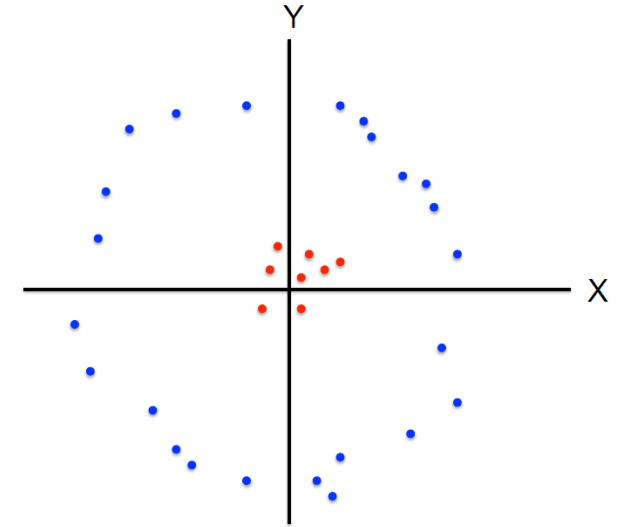
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  - euclidean
  - cosine

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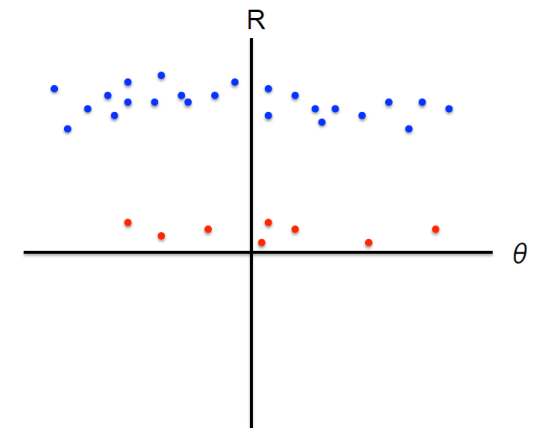
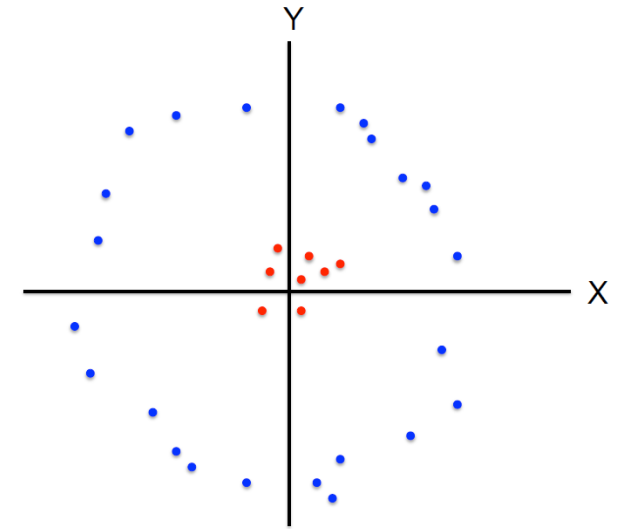
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# K-Means

---

- Convergence

$$\min_{z^{(1)}, \dots, z^{(k)}} \min_{C_1, \dots, C_k} \sum_{j=1}^k \sum_{i \in C_j} \|x^{(i)} - z^{(j)}\|^2$$

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- assignment: optimize  $C$  with fixed  $z$

$$\min_{C_1, \dots, C_k} \sum_{j=1}^k \sum_{i \in C_j} \|x^{(i)} - z^{(j)}\|^2 = \sum_{i=1}^n \min_{j=1:k} \|x^{(i)} - z^{(j)}\|^2$$

# K-Means

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- update: fix  $C$ , optimize for  $z$

$$J(z) = \min_{z^{(1)}, \dots, z^{(k)}} \sum_{j=1}^k \sum_{i \in C_j} \|x^{(i)} - z^{(j)}\|^2$$

$$z^{(j)} = \frac{1}{|C_j|} \sum_{i \in C_j} x^{(i)}$$

$$\frac{\delta J(z)}{\delta z^{(j)}} \rightarrow 0$$

# K-Means

---

input





# K-Means

---

input

$K = 2$



# K-Means

---

input



$K = 2$



# K-Means

---

input



$K = 2$



$K = 3$

# K-Means

---

input



$K = 2$



$K = 3$



# K-Means

---

input



$K = 2$



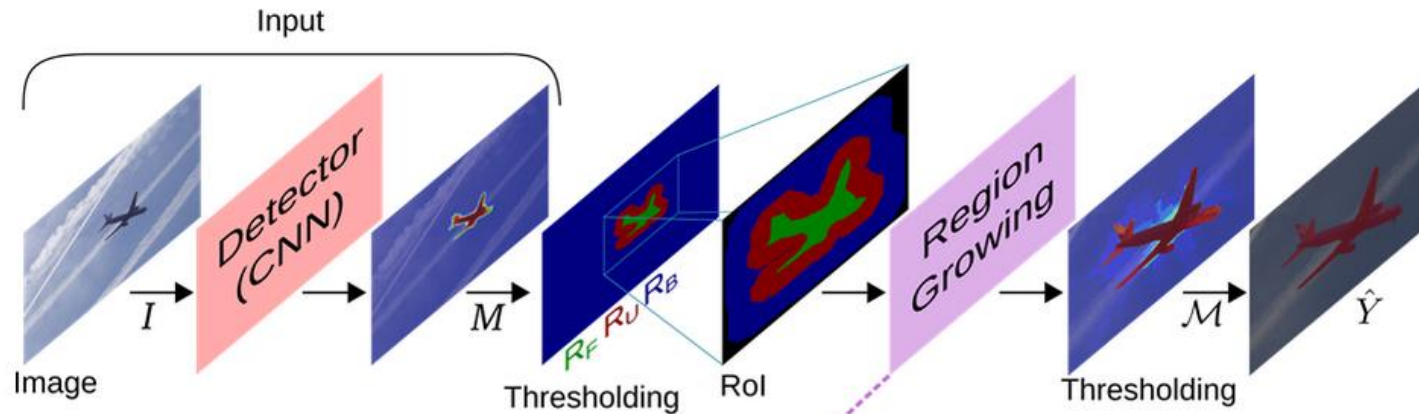
$K = 3$



$K = 10$



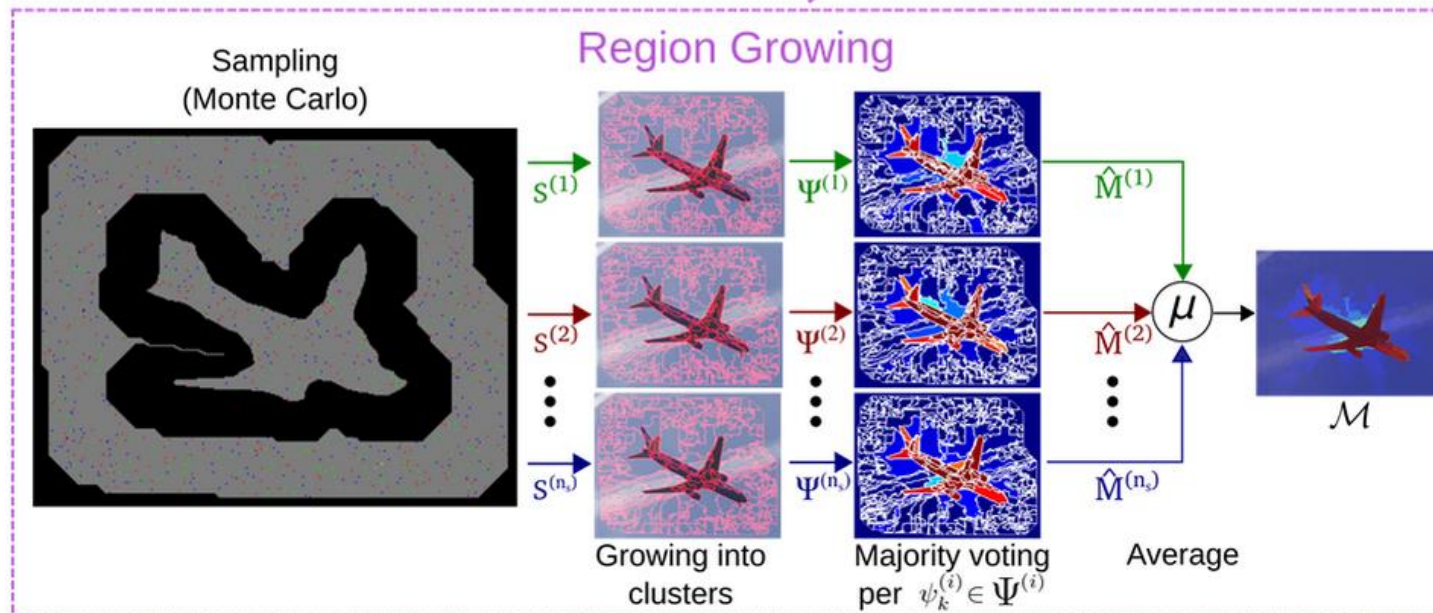
# Region growing in feature space



$$R_F = \{p_j | M(p_j) > \tau_F\},$$

$$R_U = \{p_j | \tau_B < M(p_j) < \tau_F\},$$

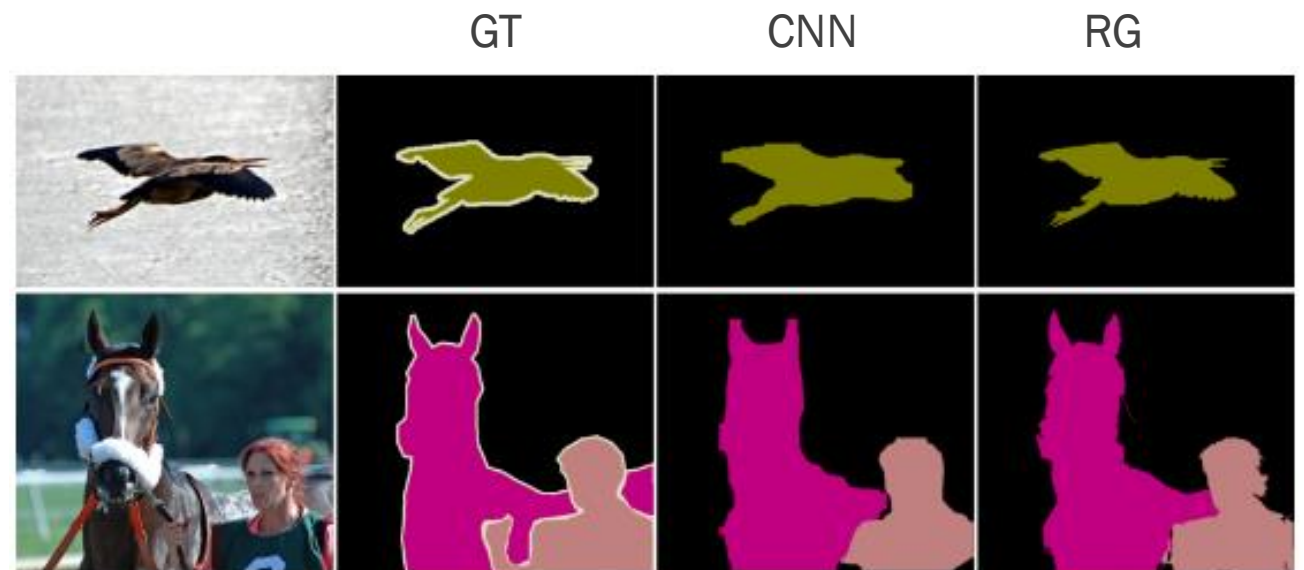
$$R_B = \{p_j | M(p_j) < \tau_B\},$$





# Conclusion

- Regions
- Clustering



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- Regions
- Clustering

- Region growing
- Region splitting & merging
- Clustering
  - K-means clustering

