# Segmentation:

Thresholding

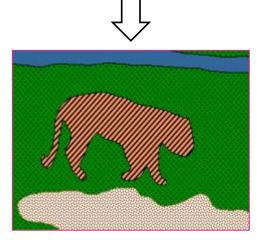
Dr. Tushar Sandhan

#### Introduction

#### Segmentation

- o aim: partition an image into set of pixels sharing common theme
  - coherent objects
  - flat structures
  - shapes





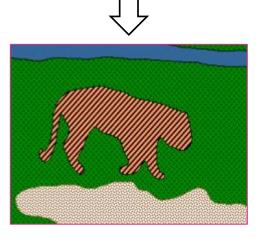
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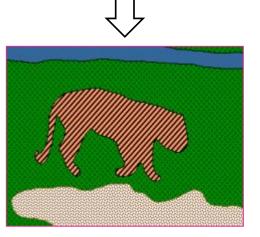
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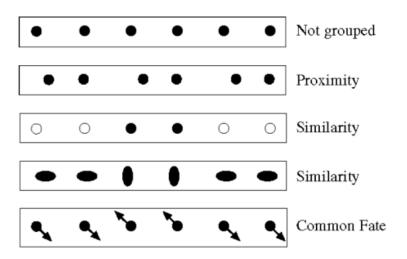


#### Gestalt

- config of things when integrated as to constitute a functional unit, with properties not derived by sum of its parts
- o whole is greater than sum of parts
- o relationship among parts are also imp. & can yield new properties
- o gestalt factors: human psychology for groupism
- o intuitive but difficult for algorithm

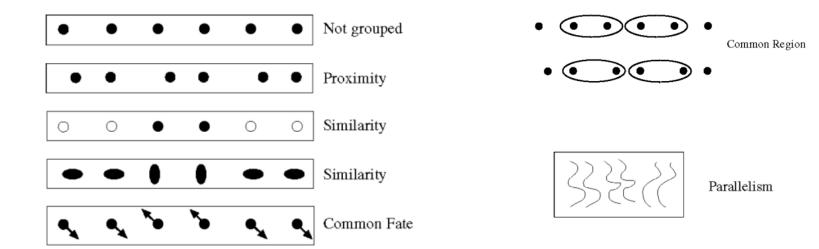
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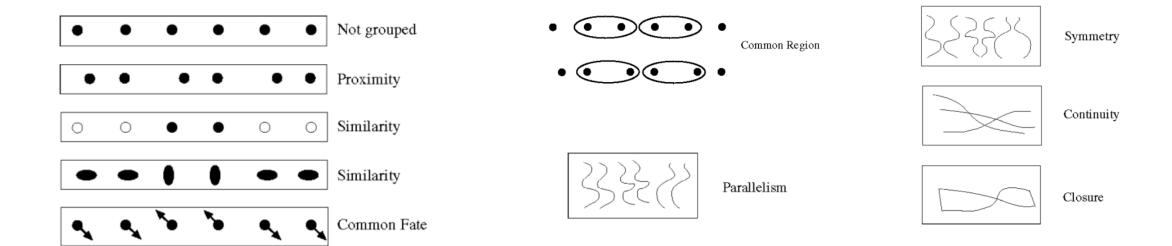
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#### Pixels

o points in high-dim space

o gray: 1D

o colors: 3D

location + colors: 5D

o group pixels into segments or chunks



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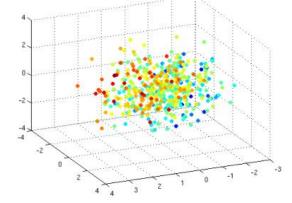
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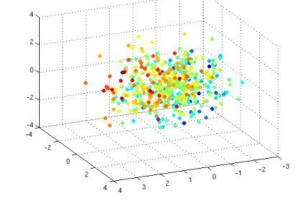


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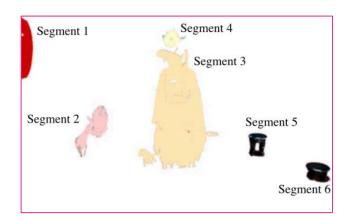
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Shape based methods

Thresholding

- Region based
  - o region-growing

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- Machine learning based
  - Unsupervised
    - K-means clustering
    - · mean shift clustering
  - Supervised
    - · feature detection and learning

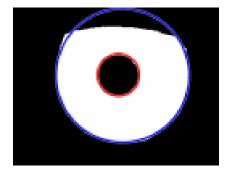
Graph & energy minimization

- Shape based methods
  - shape detection
  - Hough transform



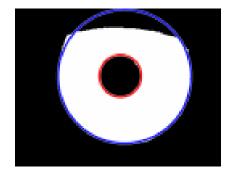
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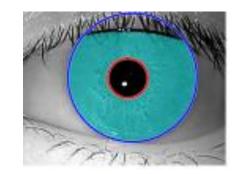




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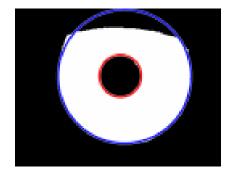


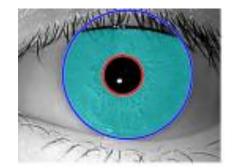




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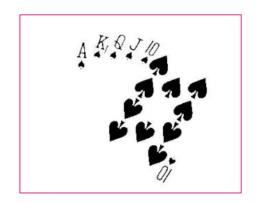


- Binarization or thresholding
  - o quick and simple
  - o partitions f(x,y) into 2 sets: foreground & background using threshold T
  - o can extend to multilevel T
  - o assumptions:
    - intensities are different in different regions
    - intensities are similar within a segment
  - o e.g. online poker

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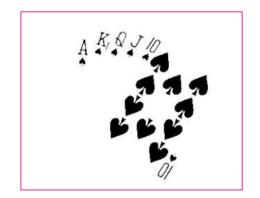


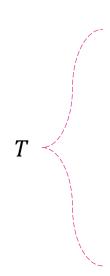


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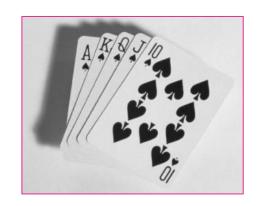




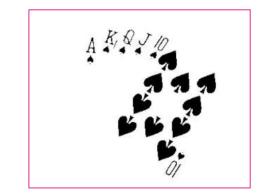




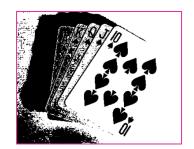
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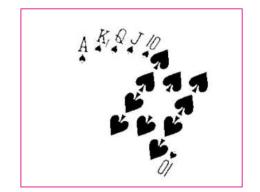




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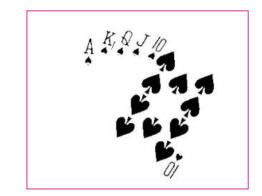


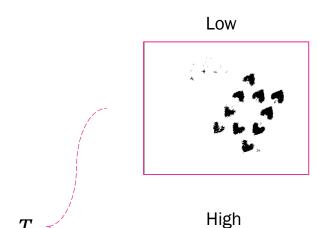


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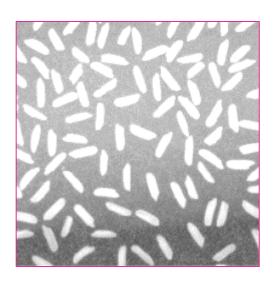




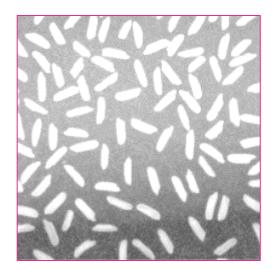




- Global: single T for entire image
- Local: blocking or tiling over the image & use different *T* for each block
- Adaptive: adjust or select T based on image content



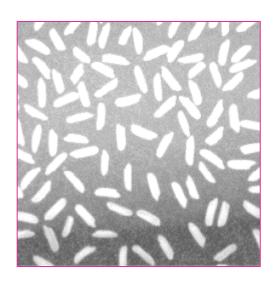
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global



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local



Global: iterative adapting threshold

- Initialize threshold *T*
- Loop until converged
  - Partition image using T
  - Compute background mean  $\mu_b$  as the average intensity of all pixels below  $extbf{ extit{T}}$
  - Compute foreground mean  $\mu_f$  as the average intensity of all pixels above T
  - Update *T*

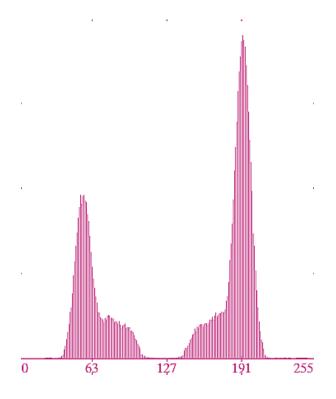
$$T = \frac{1}{2}(\mu_f + \mu_b)$$

Global: iterative adapting threshold



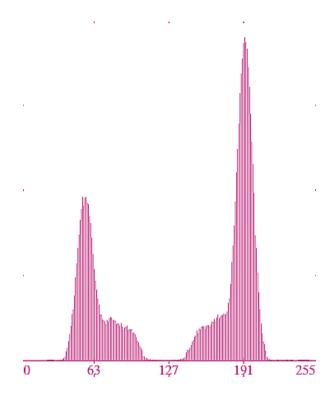
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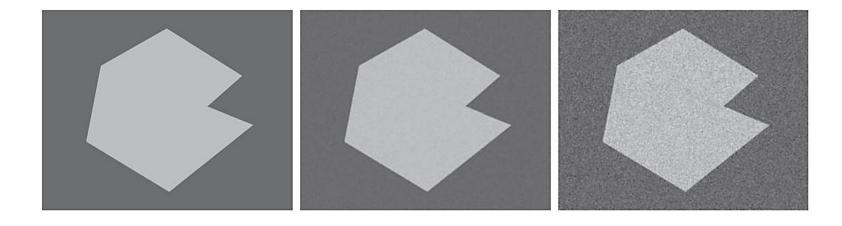
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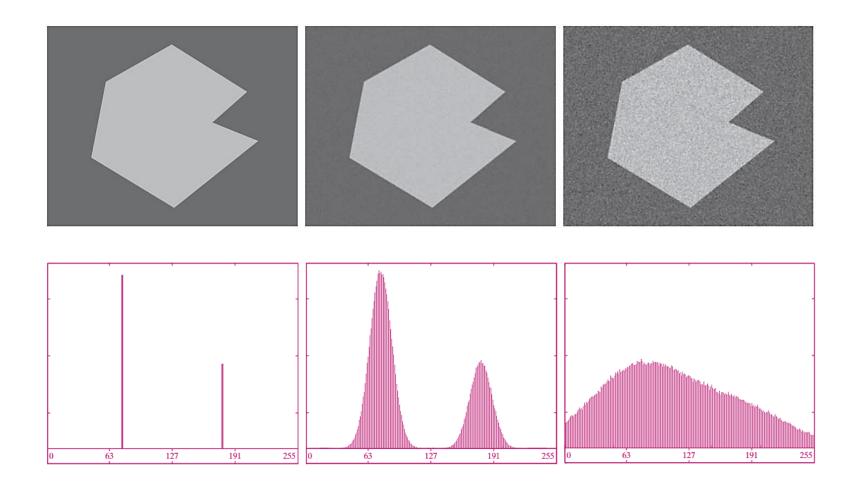




Noise



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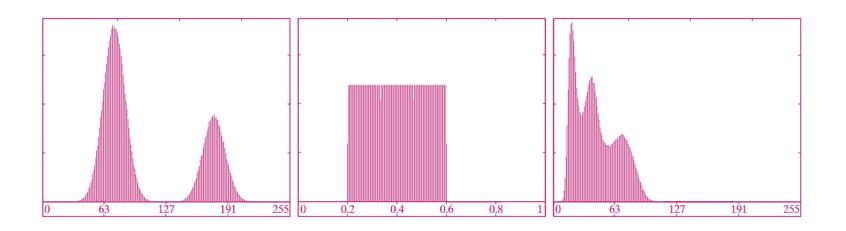


Illumination& reflectance



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Thresholding on handholding, hand folding!

#### Conclusion

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