Question-9 Solution

Part A:

Knapsack: Dynamic programming II (Knapsack II) is an optimization problem where for given Set S of nilems, with w; & vi as weights & values (profit). We seek to find subset S' & S such that weight of subset is minimized. Which

has OPT(i,v) as:- $OPT(i,v)^2$ \int_{∞}^{0} $\int_{0}^{1} \int_{0}^{1} \int_{0}^{1}$

If, above problem has to written in <u>Decision problem</u> tormat, it can be written as 1- linen a finite set <u>B</u>, non-negative weights w; and non-negative profit (values) v; if there a subset S'CS such that sum of profit/values obtains activity integer V and weights of subset is minimized.

i.e $\leq w_i \leq w$ (minimized) $s_i \in s'$ $\leq v_i = v$ $s_i \in s'$

Subset-SuM problem: - Given a finite set Z of k integers and an arbitary integer X, is there exists a subset $Z' \subseteq Z$ such that sum of elements in subset equals to X.

in $\sum_{z_i \in z'} z_i = X$

According to the question: - SUBSET-SUM problem is NP-Complete

I would like proceed proof to show decision version of knapsack
is NP-Complete using specific to Generic case reduction

To claim that " SUBSET-SUM problem to knapsack problem

i.e SUBSET-SUM = Knapsack

Proof: - Given for instance of subset (Z1, Z2... Zk), let us create knopsack instance as

 $\begin{cases} V_i = w_{i=2}, \\ V = W = X \end{cases}$

based on how professor proves the reduction in the lecture.

Based on problem depinitions that we have defined in the Start of the Pertoblem: for Knapsack

 $\begin{cases} \sum_{\substack{S \in S'}} w_i \leq w \Rightarrow \sum_{\substack{Z \in S'}} z_i \leq x \\ \sum_{\substack{S \in S'}} v_i = v \Rightarrow \sum_{\substack{Z \in S'}} z_i = x \end{cases} \Rightarrow \begin{cases} \sum_{\substack{Z \in Z'}} z_i \leq x \\ \sum_{\substack{S \in S'}} v_i \leq x \end{cases}$

which ends up as the same solution of Subset Sun problem. This proves that one should be able to reduce instance of Subset problem to instance of Enapsack problem in polynomial time.

Hence: SUBSET-SUM & p knapsack por

Based on Establish intractability, For when $X \subseteq pY$ and if $X \in NP$ -complete, Y is also NP-complete Siner, subset $\subseteq p$ knowpeak, we can derive that

Decision Verision of Knapsack problem is NP-lomplete

As mentioned, specific to generic is used here as I wanted to prove if one is able to knapsack problem [which specific to weights and value], the subset-sum problem can also be solud. [which is the generic version of knapsack problem with subset-sum equals to constant given value]

Moreover, the above reduction was not an example of equivalent or not an example of encoding with gadgets. Part B:-Optimization version of knapsæk II indicates the Dynamic programming version of it. As defined in the part A, dynamic version of Enopsack is defined as opt (i,v) = $\begin{cases} 0 & \text{if } V=0 \\ \text{if } i=0, v=0 \end{cases}$ opt (i-1,v) if v:>0min $\begin{cases} op + (i-1,v), w_i + opt (i-1, v-v_i) \end{cases}$ otherwise. As mentioned in the class/lecture, the Runtime complemity of enopsail T is $O(nV+) = O(n^{2}V man)$ n. $V^{*} = V^{*} = V^{*}$ The above algorithm is NON-POLYNOMIAL on input.

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The above algorithm is NON-Polynomial.

The above algorithm is NON-Polynomial. 1 approximation algorithm of Knapsack (I) optimal knapsack I is defined as! ρη (i, ω) = { 0 ορη (i-1, ω) for ω;>ω max ξ ορη (i-1, ω), ν; + ορη (i-1, ω-ω;) σημαν

I approximation indicates that approximation constant to be 1/2 which implies: Approximated solin = 1 Optimised Mg.

This implies there exists no optimization solution in specific but Approximated Alg using Greedy Mg techniques, which makes

Approximated Alg = (1-E) Optimised Mg

1-E = 1/2

E = 1/2

This can be proved correct using the theorem given in the lecture by professor!

that is: If s is a solution tound by our Algorithm and st is any other flavible solution then Approximate > bretter register.

Based on the betwee:-

the runtime of Algorithm the runtime of Algorithm the $O(n^3/\epsilon)$ -> $O(n^3/\epsilon)$ -> $O(n^3/\epsilon)$

Above Algorithm works based on the founding & Scaling where $\overline{V}_i : \lceil \frac{V_i}{\Theta} \rceil 0$, $\overline{V}_i : \lceil \frac{V_i}{\Theta} \rceil 0$

Vmax -> largest value of value /profit
E -> Precisions parameter

O - Scaling tactor = & Yman

0 = EVman