# Token-Based Mutual Exclusion Algorithms

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#### Overview

- This project implements two token-based mutual exclusion algorithms in a distributed network over any arbitrary topology.
- The first approach is a O(N 1 + diameter\_of\_tree) algorithm which uses logical clocks to order the requests and broadcasts messages to its neighbors when requesting the token.
- The second is a O(log (N)) tree-based algorithm based on path-reversal. When a process invokes a critical section, it sends a request to the tail of a queue. A dynamical rooted tree gives the path to this tail.

### A Distributed Algorithm for Mutual Exclusion in an Arbitrary Network.

By J. M. Helary N. Plouzeau M. Raynal

#### **Assumptions**

- Every interprocess communication line is bidirectional.
- The network has no loss of messages; no message alteration; finite transmission Delay.
- Channels need NOT be FIFO.
- No assumption is made about the network topology, except connectivity.
- The only knowledge owned by a process is local it's ID and the name of its neighbors.

#### Message Format

#### Overview of the Algorithm

- When a process wants to enter the critical section it sends a request message to its neighbors and waits for the token message.
- $\bullet \quad \text{Upon receiving a request message, a process P checks if this request is the youngest that P } \\ \text{received from P}_{\text{req\_origin}} \, . \, \text{If yes, then it broadcasts the request to its neighbors not belonging to } \\ \text{the alreadySeen array of the request message}.$ 
  - This is done to reduce message complexity by not sending requests to the nodes that have already been sent.
- The request is added to P's set of known pending requests.

  If the process P owns the token and is outside the critical section, it extracts the oldest request R from its known requests sets.
  - The oldest request R(PID, Time) is found by the following equation:
    - ▼ (PID', Time') reqArray: (Time < Time') V (Time == Time' \(\Lambda\) PID < PID')

#### Overview of the Algorithm

- P then sends the token to the creator of R through N, the neighbor of P which sent him the request R. If process P is inside the critical section, it will behave as stated above upon exiting it.
- Upon receiving the token message, process P keeps it if the token's addressee is itself.
   Otherwise, P hands it over to N, the neighbor which sent him the request being serviced.
- A process can enter the critical section only if it owns the token.

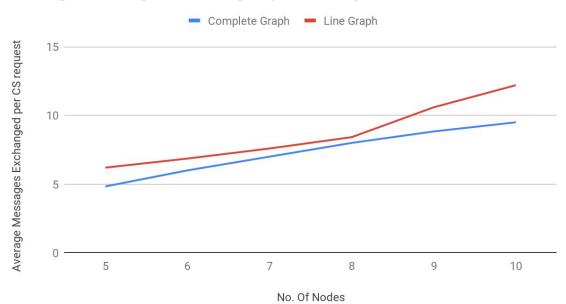
#### **Message Complexity**

- Broadcasting a request requires exactly n 1 message.
   Moving the token requires between 1 (if the sender and the addressee are neighbors) and d messages, where the diameter d is here the length of the longest path (1 < d < n I).</li>
- Thus the total number of messages per CS request:

$$n < n - 1 + d$$

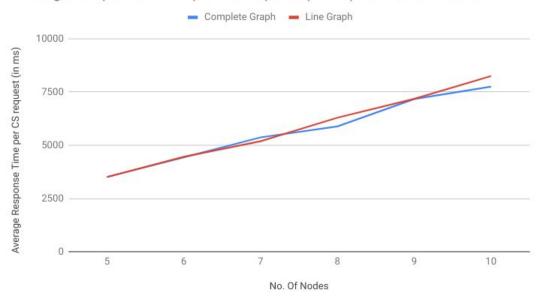
#### **Experiments**

Average Messages Exchanged per CS request vs. No. Of Nodes



#### **Experiments**

Average Response Time per CS request (in ms) vs. No. Of Nodes



#### **Observations**

- Message complexity is O(numNodes 1 + diameter).
   Therefore, the line graph has more message complexity than the complete graph.
- Number of messages increases with number of nodes.
- Response time increases with number of nodes.
   Though response time for line & complete graph is very close to each other.
- The high response time of this algorithm is due to the reason that request messages are broadcasted to all the neighbors. Since the algorithm guarantees starvation-free, sometimes a node might be asked to transfer the token to another node(with lesser clock value) even if it wants to enter the CS at that instant.

## A Log(N) Distributed Mutual Exclusion Algorithm Based on Path Reversal By M. Naimi, M. Trehel, A. Arnold

#### Assumptions of this algorithm

- The communication between the nodes is assured to be perfect(no message losses, duplications or modifications)
- Every node in a distributed setting has the information of its ID and the IDs of its neighbors.
- The channels between any two nodes are unidirectional.
- The nodes are connected in such a fashion that every node is directed to another node until we get a node with no outgoing edges in it. This node will initially have the token.
- There is no assumption regarding the topology of the processes, except connectivity.
- The channels used to communicate message along tree edges does not need to be FIFO.

#### Message Format

```
// enum for different kinds of messages
enum messageType{
   PRIVILEGE,
   REQUEST,
   TERMINATE
};

// Definition of message structure used in send and receive process
typedef struct Message{
   enum messageType type;
   int senderID;
   int reqProcess;
} Message1;
```

#### Overview of the algorithm

- For every node in the system, it maintains two pointers, father and next.
- Initially, the graph topology of the system is present in the form of a logically rooted tree, whereby the root node holds the token to enter CS and all other processes are pointing to it, either directly or indirectly.
- Father tries to maintain the node to which the request messages are sent. From 'father' to 'father', a request is transmitted to the root which has the token. Furthermore, if the requesting process is not the root, the rooted tree is transformed, the original requesting process is the new root and the processes located between the requesting process and the root will have the new root as the father.
- The next variable is responsible for passing of the token to that request which has requested for the token at the earliest. From 'next' to 'next', the token for entering CS is passed to all the requested processes in a FIFO order.

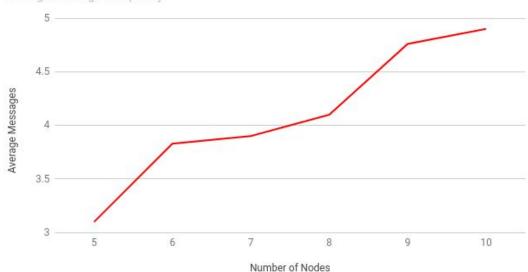
#### Message Complexity

• Since the token and requested messages are always transferred in a logical tree topology, the average number of messages for n processes is of O(log(N)) complexity where n refers to the number of nodes in the system.

#### **Experiments**

#### Naimi's Algorithm

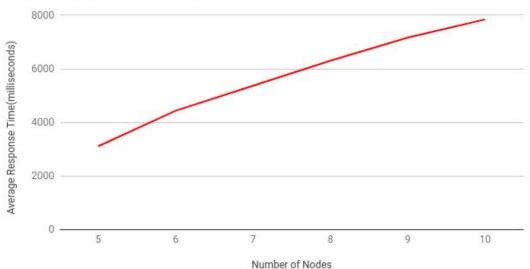
Average Message Complexity



#### **Experiments**

#### Naimi's Algorithm

Average Response Time(milliseconds)

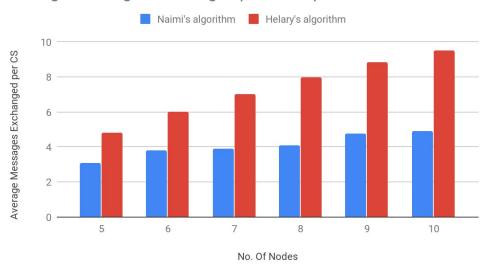


#### **Observations**

- Both message complexity and response time of the algorithm increases with the number of nodes in the distributed setting.
- The low message complexity for Naimi's algorithm is due to the reason that messages are exchanged between nodes only through the edges of the logically connected tree and the nodes also help in routing the messages sent by another node to the root of the tree.

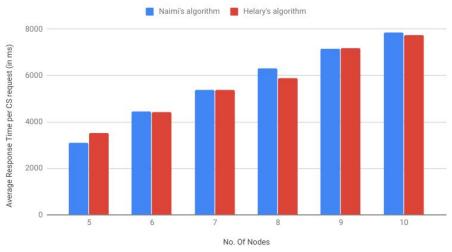
#### Comparison between Helary & Naimi

#### Average Messages Exchanged per CS request



#### Comparison between Helary & Naimi





#### **Observations**

- Helary O(n-1+d)Naimi is is and O(log(n)).Therefore, Helary exchanges more messages than Naimi. This is because of the fact that in Naimi's algorithm, messages are sent along a logically connected tree rather than broadcasting distributed the message to every other node in the setup
- The response times of both the algorithms are almost the same.

#### References

- A Distributed Algorithm for Mutual Exclusion in an Arbitrary Network -<a href="https://academic.oup.com/comjnl/article/31/4/289/380471">https://academic.oup.com/comjnl/article/31/4/289/380471</a>
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