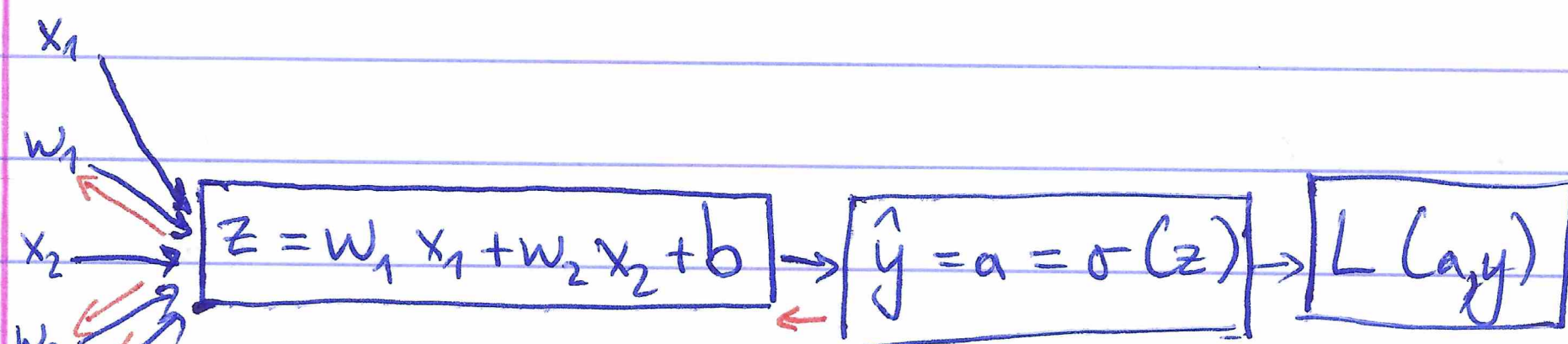


Log. Reg. GD

$$z = w^T x + b$$

$$\hat{y} = a = \sigma(z)$$

$$L(a, y) = -(y \log(a) + (1-y) \log(1-a))$$



$$"dz" = \frac{dL(a, y)}{dz} = \frac{dL}{dz}$$

$$"da" = \frac{dL(a, y)}{da}$$

$$= a - y$$

$$= -\frac{y}{a} + \frac{1-y}{1-a}$$

$$= \frac{dL}{da} \left(\frac{da}{dz} \right) = a(1-a)$$

$$"dw_1" = \frac{dL}{dw_1} = x_1 dz, \quad "dw_2" = x_2 dz, \quad "db" = dz$$

Updates:

$$w_1 := w_1 -$$

$$w_2 := w_2 -$$

$$b := b -$$

Log reg. on m examples

$$J(w, b) = \frac{1}{m} \sum_{i=1}^m L(a^{(i)}, y^{(i)})$$

$$a^{(i)} = \hat{y}^{(i)} = \sigma(z^{(i)}) = \sigma(w^T x^{(i)} + b)$$

$$dw_1^{(i)}, dw_2^{(i)}, db^{(i)}$$

$$\frac{\partial}{\partial w_1} J(w, b) = \frac{1}{m} \sum_{i=1}^m \underbrace{\frac{\partial}{\partial w_1} L(a^{(i)}, y^{(i)})}_{dw_1^{(i)} = (x_1^{(i)} - y^{(i)})}$$